

1.2 Differentiation

20.-9.-2013

$$(Tf)(x) = \int_0^x f(z) dz$$

$$\frac{d}{dx} Tf = f \rightarrow T \text{ injective}$$

Consider $T: X \rightarrow Y$ on space

$$X = \{v \in C_{per}([0,1]): \int_0^1 v(x) dx = 0\}$$

$$Y = C_{per}([0,1])$$

$\Rightarrow Tf = g$ becomes ill-posed
(i.e. T^{-1} is not bounded)

Noisy data: instead of $g \in R(T)$,
only perturbed data $g^\delta \in Y$ are available.

Assumption: $\|g - g^\delta\|_Y \leq \xi$
 \uparrow
noise level

Recovery of an approximation of f through
"numerical differentiation"

$$R(g^\delta)_x = \frac{g^\delta(x+h) - g^\delta(x-h)}{2h}$$

a family of reconstruction operators

\rightarrow a-priori information

If $\|g''\|_\infty$ bounded, then the total error can be bounded by

$$R(g^\delta - g') = \underbrace{(Rg - g')}_\text{approximation error} + \underbrace{\frac{R(g^\delta - g)}{h}}_\text{data noise error}$$

$$\|R(g^\delta - g')\|_X$$

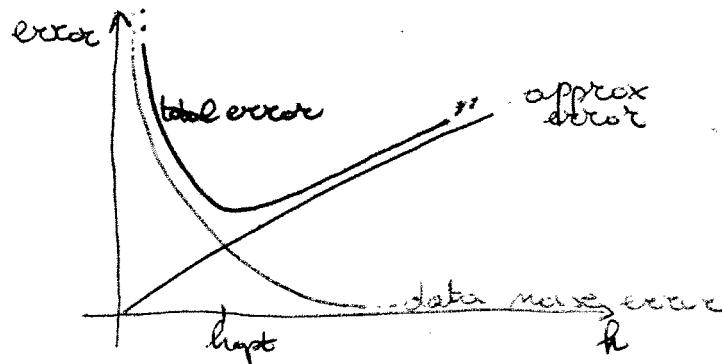
$$\|R(g^\delta - g')\|_X \leq \frac{1}{2} h \|g''\|_\infty + \frac{1}{h} \|g^\delta - g\|_Y$$

$$\lceil R\varphi(x) \leq \frac{1}{h} \max_{x \in [0,1]} |\varphi'(x)| \quad \text{for every } \varphi \in C_{per}$$

triangle inequality

Important in this estimate because it guarantees that we can compute φ for all x and all φ .

\triangleright Total error $\|R_a g^\delta - g'\|_X \leq \frac{1}{2} h \|g''\|_\infty + \frac{1}{h} \delta$



Remark 1) total error bounded from below \Rightarrow bad
2) there is an optimal total error:

$$h_{opt} = \sqrt{\frac{2}{\|g''\|_\infty}} \sqrt{\delta}$$

\triangleright Minimal total error norm

$$h = h_{opt} \quad \|R_a g^\delta - g'\|_X = O(\delta^{\frac{1}{2}})$$

Remark If T^{-1} was bounded $\|T^{-1}(g - g^\delta)\| = O(\delta)$ (*)

we could achieve a reconstruction of the same order of the perturbation $O(\delta)$.
But here we achieve less: $O(\delta^{\frac{1}{2}})$

\Rightarrow (*) is worse, reflecting the ill-posed nature of the problem.

Remark (*) remarkable, because small max seems to allow good reconstruction, but only under the assumption of extra regularity of f : If $\|f'\|_\infty$ bar this does not contradict the ill-posed nature of the problem

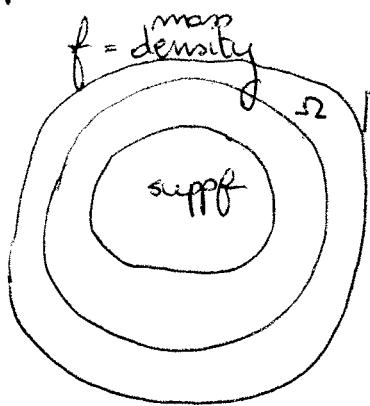
If $\|g''\|_\infty$ bounded, use $\|R_a g - g'\|_\infty = \frac{1}{6} h^2 \|g''\|_\infty$
 $\Rightarrow \|R_a g^\delta - g'\|_X \leq \frac{1}{6} h^2 \|g''\|_\infty + \frac{1}{h} \delta$

$$\Rightarrow h_{opt} = \sqrt[3]{\frac{3}{\|g''\|_\infty}} \sqrt[3]{\delta} : \|R_a g - g'\|_\infty = O(h^{\frac{2}{3}})$$

The more you constrain the solution, the closer you get to the optimum (closer but never = because the pb is ill-posed)

1.13 Gravimetry

General: Inverse source problem for $-\Delta$



On Γ we ~~measure~~ measure gravity potential

$$-\Delta u = f$$

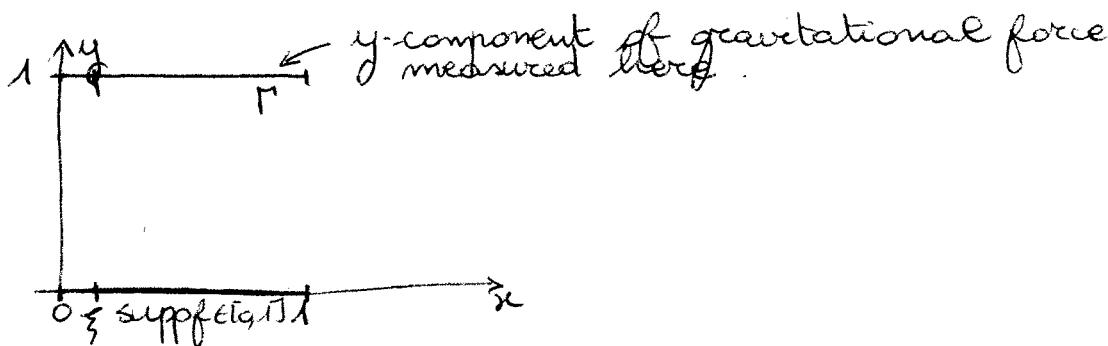
+ decay conditions

Find f , $\text{supp } f \subset \Omega$ from measured values of u , $\text{grad } u$ on Γ .

→ highly non-unique

When imposing assumptions on f , the problem becomes tractable.

1D version:



$f: [0,1] \rightarrow \mathbb{R}_+^+$ = mass density distribution on $[0,1]$.
(masses arranged on a line! : 3D!)

Forward operator

Force (y-component) generated by mass $f(x)dx$

$$\delta F_y(\xi) = f(x)dx \frac{1}{\sqrt{(x-\xi)^2 + 1}^3}$$

$$(F(x) \frac{x-x'}{\|x-x'\|^3})$$

$$\triangleright \text{Total y-force } F_y(\xi) = \int_0^1 f(x) \frac{1}{\sqrt{(x-\xi)^2 + 1}^3} dx$$

$$(Tf)(\xi) = \int_0^1 R(\xi-x) f(x) dx$$

$$\text{with } k(x) = \frac{1}{\sqrt{\xi^2 + 1}^3}$$

T = convolution operator with kernel k .

Recall: convolution , $g, f: \mathbb{R} \rightarrow \mathbb{R}$

$$(g * f)(x) = \int_{\mathbb{R}} g(x-y) f(y) dy$$

Write \tilde{f} for extension by zero of f outside $[0, 1]$

$$Tf = k * \tilde{f}$$

Result on convolution :

$$\begin{aligned} g &\in L^p(\mathbb{R}) \\ f &\in L^q(\mathbb{R}) \end{aligned}, \quad \frac{1}{p} + \frac{1}{q} = 1 + \frac{1}{r}, \quad 1 \leq r \leq \infty$$

$$\infty > p, q \geq 1$$

$$\Rightarrow g * f \in L^r(\mathbb{R}), \|g * f\|_r \leq C \|g\|_p \|f\|_q \quad \text{where } C = C_{p, q}$$

Apply this for $p=1, q=2 \Rightarrow r=2$

because $k \in L^1(\mathbb{R}) \left[\int_{-\infty}^{\infty} \frac{1}{\sqrt{x^2+1}} dx < \infty \right]$

$\Rightarrow T: \underbrace{L^2([0, 1])}_{\text{continuous}}$ is continuous

because $\|Tf\|_2 = \sqrt{\|k\|_1 \|f\|_2} = Y$

Now let us study the inverse

Tool: Fourier transform

$$(\mathcal{F}\varphi)(\xi) = \int_{\mathbb{R}} \varphi(x) e^{-2\pi i x \cdot \xi} dx$$

Isometry: $\mathcal{F}: L^2(\mathbb{R}) \rightarrow L^2(\mathbb{R})$

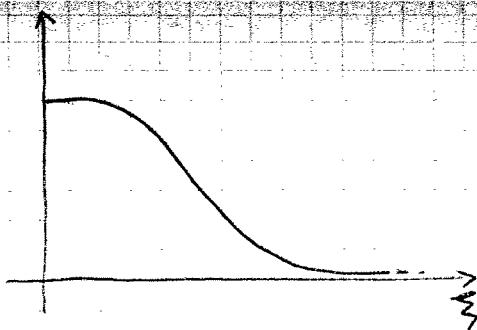
\mathcal{F} "diagonalizes convolution":

$$\mathcal{F}(g * f) = \mathcal{F}(g) \mathcal{F}(f)$$

for $g \in L^1(\mathbb{R}), f \in L^2(\mathbb{R})$

$$\triangleright \mathcal{F}(f)(\xi) = 4\pi |\xi| K_1(2\pi |\xi|)$$

2-nd kind Bessel function



$$F(k) > 0$$

Formal inverse $\hat{f} = \mathcal{F}^{-1}\left(\frac{\mathcal{Y}(g)}{\mathcal{Y}(k)}\right)^{(*)}$ for $Tf = g$

$\rightarrow T$ is injective ($T^{-1}(0) = 0$)

\rightarrow Since $(\mathcal{Y}(k)|_{\mathbb{R}}) \rightarrow 0$ as $|k| \rightarrow \infty$,

$Tf = g$ is ill-posed

choose $g = \mathcal{Y}^{-1}(X_{[m, m+1]})$ ~~characteristic function~~ $g \neq 0, g \in R(T)$

$\mathcal{Y}(g)$ supported in $[m, m+1]$ for $m \gg 1$

$\Rightarrow \underbrace{\left\| \frac{\mathcal{Y}(g)}{\mathcal{Y}(k)} \right\|_{L^2}}_{\|f\|_{L^2}} \gg \|\mathcal{Y}(g)\|_{L^2}$ for large m (because $\mathcal{Y}(k)$ is very small there). $\rightarrow \|g\|_{L^2}$

Arbitrarily small data can give rise to arbitrarily big solution

\Rightarrow ill-posed problem

\rightarrow with g arbitrarily, there is no guarantee that $\hat{f} \in \text{supp } f$.
 T is not surjective, because f from (*) not necessarily supported on $[0, 1]$.

(This is quite common for convolution operators)