

Def 1.5.2. B: Hilbert space process (HSP) is a bdd linear mapping  $Y \rightarrow L^2(\Omega, \mathbb{R})$

If  $\hat{Z}$  is  $Y$ -valued RV, bdd variance

$\Rightarrow Z : Y \rightarrow L^2(\Omega, \mathbb{R})$  is a HSP with  
 $g \mapsto (\omega \mapsto (\hat{Z}(\omega), g)_Y)$

$$\|Z\| \leq \int_{\Omega} \|\hat{Z}(\omega)\|_Y^2 dP(\omega)$$

$$\sup_{\substack{g \in Y \\ \|g\|_Y \leq 1}} \|\hat{Z}(g)\|_{L^2(\Omega, \mathbb{R})}$$

White noise (generalized)

$\{g_j\}$  ONB of  $Y$ ,

$$z_w(g) := \sum_j x_j(\omega) (g, g_j)_Y$$

iid, finite range  $(-1, 1)$ ,  $E(x_j) = 0$

$$\begin{aligned} \int_{\Omega} |z_w(g)(\omega)|^2 dP(\omega) &= \text{Var}(z_w(g)) = \sum_j (g, g_j)_Y^2 \text{Var}(x_j) \\ &= \text{Var}(X_1) \|g\|_Y^2 \end{aligned}$$

2. HSP:  $\underbrace{(E(z), g)}_{\in Y} = E(z(g))$ ,  $g \in Y$

$$\text{Cov}(z)(g_1, g_2) := \text{Cov}(z(g_1), z(g_2))$$

[=  $\text{Cov}(\hat{Z})$ , if  $z$  generated by  $Y$ -RV  $\hat{Z}$ ]

$$\begin{aligned} \text{Cov}(z)(g_1, g_2) &= \text{Cov}\left(\sum_j x_j(\omega) (g_1, g_j)_Y, \sum_c x_c(\omega) (g_2, g_c)_Y\right) \\ &= \sum_j \sum_c (g_1, g_j) (g_2, g_c) \text{Cov}(x_j, x_c) \end{aligned}$$

$$\begin{aligned} \text{independence} \Rightarrow &= \sum_j \text{Cov}(x_j, x_j) (g_1, g_j)_Y (g_2, g_j)_Y \\ &= \text{Var}(X) (g_1, g_2)_Y \end{aligned}$$

$$\Rightarrow \underbrace{\text{Cov}(z_w)}_{\text{defines a white noise HSP}} = \text{Var}(X) \cdot \text{Id} \notin \mathcal{L}_1(Y)$$

defines a white noise HSP

"Variance" of a HSP:

$$\begin{aligned} \widehat{\mathbf{z}} - \mathbf{R}\mathbf{v} &\Rightarrow \text{HSP } \mathbf{z} \quad (\mathbb{E}(\mathbf{z}) = \mathbb{E}(\widehat{\mathbf{z}}) = \mathbf{0}) \\ \mathbb{E}(\|\widehat{\mathbf{z}}\|_Y^2) &= \mathbb{E}\left(\sum_j (\widehat{z}_j(\omega), g_j)_Y^2\right) \\ &= \sum_j \mathbb{E}((\widehat{z}_j(g_j))_Y^2) \end{aligned}$$

$$\begin{aligned} \text{Var}(\mathbf{x}) &= \mathbb{E}(x^2) - \mathbb{E}(x)^2 \\ &= \sum_j \text{Var}(z_j(g_j)) + \mathbb{E}((\widehat{z}(\omega), g_j)_Y)^2 \\ &= \sum_j (\text{Cov}(z) g_j, g_j)_Y = \text{tr}(\text{Cov}(z)) \end{aligned}$$

- If  $\text{tr}(\text{Cov}(z)) < \infty$ , then use it as a norm for HSP
- Meaning of  $\|\cdot\|$

Thus  $\mathbf{z}$  HSP,  $\text{Cov}(\mathbf{z})$  is nuclear

$$\widehat{\mathbf{z}}(\omega) := \sum_j z(g_j) g_j, \text{ where}$$

$(\sigma_j, g_j, g_j)$  = SVD of  $\text{Cov}(\mathbf{z})$   
is a  $y$ -valued RV with bdd variance

Operators acting on HSP

$$\begin{array}{c} \mathbf{R} \in \mathcal{L}(Y, X) \\ \widehat{\mathbf{z}} \text{ } Y\text{-RV} \rightarrow (\mathbf{R}\widehat{\mathbf{z}})(\omega) := \mathbf{R}(\widehat{z}(\omega)) \\ \downarrow \text{HSP } \mathbf{z} \qquad \qquad \qquad \mathbf{L}_D \times RV \\ \qquad \qquad \qquad \qquad \qquad \downarrow \\ \qquad \qquad \qquad \qquad \qquad \text{HSP } \mathbf{Rz} \end{array}$$

$$\begin{aligned} (\mathbf{R}\mathbf{z})(f)(\omega) &= (\mathbf{R}\widehat{z}(\omega), f)_X \\ &= (\widehat{z}(\omega), \mathbf{R}^*f)_Y = \mathbf{z}(\mathbf{R}^*f)(\omega) \end{aligned}$$

Def:  $\mathbf{z}$  HSP  $(\mathbf{R}\mathbf{z})(f)(\omega) := \mathbf{z}(\mathbf{R}^*f)(\omega)$

$$\rightarrow \text{Cov}(\mathbf{R}\mathbf{z})(f_1, f_2) = \text{Cov}(\mathbf{z})(\mathbf{R}^*f_1, \mathbf{R}^*f_2)$$

$$\Leftrightarrow \boxed{\text{Cov}(\mathbf{R}\mathbf{z}) = \mathbf{R} \circ \text{Cov}(\mathbf{z}) \circ \mathbf{R}^*}$$

Back to stochastic inverse problems:

Reconstruction error (risk) for reconstruction operator  $R \in \mathcal{L}(Y, X)$ , if noise is HSP

$$\|R(g+z) - f^+\|_X^2$$

Here:  $\|\cdot\| \hat{=} \text{norm on } X - \text{HSP}$

$$z \in Y - \text{HSP} \Rightarrow g+z \in Y - \text{HSP}$$

$$R(g+z) \in X - \text{HSP}$$

If  $z \in Y - RV \Rightarrow \|R(g+z) - f^+\|_X^2 = \mathbb{E}(\|R(g+z(\omega)) - f^+\|_X^2)$

In order to obtain finite risk (error), we demand that  $Rz$  has nuclear covariance

When is  $R \text{Cov}(z) R^*$  nuclear for general  $\text{Cov}(z) \in \mathcal{L}(Y)$ ?

$$Tf = g + z, \quad T \in K(X, Y)$$

$$Y - RV \xrightarrow{\quad} Y - \text{HSP}$$

$$\int_{\Omega} \|Z(\omega)\|_X^2 dP(\omega) = \text{tr}(\text{Cov}(z)) \quad (\text{white noise: } \text{Cov}(z) \sim I d)$$

"benign noise"

"nasty noise"

Reconstruction operator  $R \in \mathcal{L}(X, Y)$

$$\mathbb{E}(\|R(g+z) - f^+\|_X^2) < \infty \text{ is desired}$$

Necessary:  $Rz$  is a  $X - RV$  with finite variance

$$\text{Cov}(Rz) = R \text{Cov}(z) R^* \in \mathcal{L}_1(X)$$

Def:  $R \in \mathcal{L}(Y, X)$  is Hilbert-Schmidt ( $R \in \mathcal{L}_2(Y, X)$ )

$$\Leftrightarrow \sum_j \|R e_j\|_X^2 = \|R\|_{\mathcal{L}_2}^2 < \infty \text{ for an ONB } \{e_j\} \text{ of } Y$$

Facts: •  $\mathcal{L}_2(Y, X) \subset K(Y, X)$

•  $\|R\|_{\mathcal{L}_2}^2 = \sum_i \sigma_i^2$ , where  $\{\sigma_i\}$  are the singular values of  $R$

Thm: •  $R \in \mathcal{L}_2(Y, X)$ ,  $S \in \mathcal{L}(Y) \Rightarrow RS \in \mathcal{L}_2(Y, X)$

•  $R \in \mathcal{L}_2(Y, X)$ ,  $S \in \mathcal{L}_2(Y) \Rightarrow RS \in \mathcal{L}_1(Y, X)$