

g-QUASI-FROBENIUS LIE ALGEBRAS

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ABSTRACT. A Lie version of Turaev's \overline{G} -Frobenius algebras from 2-dimensional homotopy quantum field theory is proposed. The foundation for this Lie version is a structure we call a \mathfrak{g} -quasi-Frobenius Lie algebra for \mathfrak{g} a finite dimensional Lie algebra. The latter consists of a quasi-Frobenius Lie algebra (\mathfrak{q}, β) together with a left \mathfrak{g} -module structure which acts on \mathfrak{q} via derivations and for which β is \mathfrak{g} -invariant. Geometrically, \mathfrak{g} -quasi-Frobenius Lie algebras are the Lie algebra structures associated to symplectic Lie groups with an action by a Lie group G which acts via symplectic Lie group automorphisms. In addition to geometry, \mathfrak{g} -quasi-Frobenius Lie algebras can also be motivated from the point of view of category theory. Specifically, \mathfrak{g} -quasi-Frobenius Lie algebras correspond to quasi-Frobenius Lie objects in $\mathbf{Rep}(\mathfrak{g})$. If \mathfrak{g} is now equipped with a Lie bialgebra structure, then the categorical formulation of \overline{G} -Frobenius algebras given in [16] suggests that the Lie version of a \overline{G} -Frobenius algebra is a quasi-Frobenius Lie object in $\mathbf{Rep}(D(\mathfrak{g}))$, where $D(\mathfrak{g})$ is the associated (semiclassical) Drinfeld double. We show that if \mathfrak{g} is a quasitriangular Lie bialgebra, then every \mathfrak{g} -quasi-Frobenius Lie algebra has an induced $D(\mathfrak{g})$ -action which gives it the structure of a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra.

1. INTRODUCTION

Renewed interest in Frobenius algebras arose shortly after Witten's introduction of *Topological Quantum Field Theory* (TQFT) in [28]. Shortly afterwards, Atiyah proposed a set of axioms for TQFT [3], thus making Witten's work more accessible to the mathematical community. Working from Atiyah's axioms, L. Abrams showed that 2-dimensional TQFTs are classified by commutative Frobenius algebras [1]. Hence, in the 2-dimensional case, the algebraic structure of a TQFT is that of a Frobenius algebra.

The notion of a $(d+1)$ -dimensional TQFT was generalized to a $(d+1)$ -dimensional *Homotopy Quantum Field Theory* (HQFT) by V. Turaev in [25] by equipping closed d -manifolds and $(d+1)$ -dimensional cobordisms with homotopy classes of maps into a target space X . In the special case when X is a $K(\overline{G}, 1)$ -space for \overline{G} a finite group,

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one finds that the 2-dimensional HQFTs are classified by Frobenius algebras with a \overline{G} -grading and a \overline{G} -action which satisfies a number of conditions [15, 25]. These Frobenius algebras came to be called \overline{G} -Frobenius algebras (or crossed \overline{G} -algebras).

In [16], a categorical formulation of \overline{G} -Frobenius algebras was presented where \overline{G} -Frobenius algebras were shown to correspond to certain types of Frobenius objects in $\mathbf{Rep}(D(k[\overline{G}]))$, the braided monoidal category of finite dimensional left $D(k[\overline{G}]$)-modules, where $D(k[\overline{G}])$ is the Drinfeld double of the group ring $k[\overline{G}]$ with its usual Hopf structure. Now the semiclassical analogue of $D(k[\overline{G}])$ (or more generally $D(H)$ for H a finite dimensional Hopf algebra) is $D(\mathfrak{g})$, the Drinfeld double of a finite dimensional Lie bialgebra (\mathfrak{g}, γ) [7, 9, 10, 18]. The relationship between \overline{G} -Frobenius algebras and $D(k[\overline{G}])$ in [16] motivates the following question:

With (\mathfrak{g}, γ) fixed, what structure plays the role of a \overline{G} -Frobenius algebra for $D(\mathfrak{g})$?

Since $D(\mathfrak{g})$ is the Lie version of $D(k[\overline{G}])$, the structure in question should be the Lie version of a \overline{G} -Frobenius algebra. To answer the aforementioned question, we introduce the notion of \mathfrak{g} -quasi-Frobenius Lie algebras for \mathfrak{g} a finite dimensional Lie algebra. A \mathfrak{g} -quasi-Frobenius Lie algebra consists of a quasi-Frobenius Lie algebra (\mathfrak{q}, β) together with a left \mathfrak{g} -module structure which acts on \mathfrak{q} via derivations and for which β is \mathfrak{g} -invariant. Geometrically, \mathfrak{g} -quasi-Frobenius Lie algebras are the Lie algebra structures of symplectic Lie groups with an action by a Lie group G which acts via symplectic Lie group automorphisms. We call the aforementioned structures G -symplectic Lie groups.

Interestingly, \mathfrak{g} -quasi-Frobenius Lie algebras have a categorical formulation. To obtain this formulation, we introduce the notion of a *quasi-Frobenius Lie object* for any additive symmetric monoidal category. The work of Goyvaerts and Vercuysse on the categorification of Lie algebras [12] provides the foundation for defining quasi-Frobenius Lie objects. The latter then yields an alternate (yet equivalent) definition of a \mathfrak{g} -quasi-Frobenius Lie algebra: *a \mathfrak{g} -quasi Frobenius Lie algebra is simply a quasi Frobenius Lie object in $\mathbf{Rep}(\mathfrak{g})$, where $\mathbf{Rep}(\mathfrak{g})$ is the category of finite dimensional representations of \mathfrak{g} .* Using the categorical formulation of [16] as motivation, we obtain the Lie version of a \overline{G} -Frobenius algebra: for a fixed finite dimensional Lie bialgebra (\mathfrak{g}, γ) , the Lie version of a \overline{G} -Frobenius algebra is a quasi-Frobenius Lie object in $\mathbf{Rep}(D(\mathfrak{g}))$. In other words, with respect to (\mathfrak{g}, γ) , a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra is the Lie version of a \overline{G} -Frobenius algebra. The definition of $D(\mathfrak{g})$ implies that a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra is equivalent to a quasi-Frobenius Lie algebra (\mathfrak{q}, β) which is both a \mathfrak{g} and \mathfrak{g}^* -quasi-Frobenius Lie algebra where the \mathfrak{g} and \mathfrak{g}^* actions satisfy a certain compatibility condition.

The rest of the paper is organized as follows. In Section 2, we give a brief review of quasi-Frobenius Lie algebras, symplectic Lie groups, Lie bialgebras, and the Drinfeld double. In Section 3, we formally define \mathfrak{g} -quasi-Frobenius Lie algebras and prove a general result for their construction. We conclude the section with the categorical formulation of these structures. In Section 4, G -symplectic Lie groups are introduced. We show that \mathfrak{g} -quasi-Frobenius Lie algebras are the Lie algebra

structures of G -symplectic Lie groups. In addition, we show that the category of finite dimensional \mathfrak{g} -quasi-Frobenius Lie algebras is equivalent to the category of simply connected G -symplectic Lie groups where G is also simply connected. In Section 5, we focus our attention on $D(\mathfrak{g})$ -quasi-Frobenius Lie algebras. We show that if \mathfrak{g} is a quasitriangular Lie bialgebra, then every \mathfrak{g} -quasi-Frobenius Lie algebra has an induced $D(\mathfrak{g})$ -action which extends the original \mathfrak{g} -action and gives the underlying quasi-Frobenius Lie algebra the structure of a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra. In particular, for any finite dimensional Lie algebra \mathfrak{g} (viewed as a Lie bialgebra with co-bracket $\gamma \equiv 0$), every \mathfrak{g} -quasi-Frobenius Lie algebra is a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra, where $D(\mathfrak{g})$ is the Drinfeld double of $(\mathfrak{g}, 0)$.

2. PRELIMINARIES

In this section, we briefly review some of the relevant background for the current paper. Throughout this section, k is a field of characteristic zero.

2.1. Quasi-Frobenius Lie Algebras. The definition of a *Frobenius Lie algebra* [22, 23] is modeled after the definition of a Frobenius algebra. Formally, a Frobenius Lie algebra is defined as follows:

Definition 2.1. A *Frobenius Lie algebra* over k is a pair (\mathfrak{g}, α) where \mathfrak{g} is a Lie algebra and $\alpha: \mathfrak{g} \rightarrow k$ is a linear map with the property that the skew-symmetric bilinear form β on \mathfrak{g} defined by

$$\beta(x, y) := \alpha([x, y]) \quad \forall x, y \in \mathfrak{g}$$

is nondegenerate.

As a consequence of the Jacobi identity, the skew-symmetric bilinear form β in Definition 2.1 satisfies the following identity:

$$(2.1) \quad \beta([x, y], z) + \beta([y, z], x) + \beta([z, x], y) = 0, \quad \forall x, y, z \in \mathfrak{g}.$$

Equation (2.1) is equivalent to the statement that β is a 2-cocycle in the Lie algebra cohomology of \mathfrak{g} with values in k (where \mathfrak{g} acts trivially on k). This motivates the following generalization of Definition 2.1:

Definition 2.2. A *quasi-Frobenius Lie algebra* over k is a pair (\mathfrak{g}, β) where \mathfrak{g} is a Lie algebra over k and β is a nondegenerate 2-cocycle in the Lie algebra cohomology of \mathfrak{g} with values in k (where \mathfrak{g} acts trivially on k).

Remark 2.3. A quasi-Frobenius Lie algebra (\mathfrak{g}, β) is a Frobenius Lie algebra iff β is exact, i.e., $\beta(x, y) = (-\delta\alpha)(x, y) := \alpha([x, y])$ for some linear map $\alpha: \mathfrak{g} \rightarrow k$.

Proposition 2.4. *Every 2-dimensional non-abelian Lie algebra admits the structure of a Frobenius Lie algebra. In particular, every 2-dimensional non-abelian quasi-Frobenius Lie algebra is Frobenius.*

Proof. Let \mathfrak{g} be a 2-dimensional non-abelian Lie algebra. Then \mathfrak{g} admits a basis u_1, u_2 such that $[u_1, u_2] = u_2$. Let $\alpha: \mathfrak{g} \rightarrow k$ be the linear map defined by $\alpha(u_1) = 0$ and $\alpha(u_2) = 1$. Then (\mathfrak{g}, α) is a Frobenius Lie algebra.

If (\mathfrak{g}, β) is a quasi-Frobenius Lie algebra, set $\alpha(u_1) = 0$ and $\alpha(u_2) = \beta(u_1, u_2)$. Then it's easy to see that $\beta(x, y) = \alpha([x, y])$ for all $x, y \in \mathfrak{g}$. Hence, (\mathfrak{g}, β) is Frobenius. \square

Remark 2.5. Since every finite dimensional quasi-Frobenius Lie algebra (\mathfrak{g}, β) is also a symplectic vector space, it follows that the dimension of \mathfrak{g} is necessarily even.

Proposition 2.6. *Let \mathfrak{g} be a Lie algebra of dimension n over k and let e_1, e_2, \dots, e_n be a basis of \mathfrak{g} . Then the following statements are equivalent:*

- (1) *There exists $\alpha \in \mathfrak{g}^*$ such that (\mathfrak{g}, α) is a Frobenius Lie algebra.*
- (2) *There exists $\alpha \in \mathfrak{g}^*$ such that $\det(\alpha([e_i, e_j])) \neq 0$*
- (3) *$\det([e_i, e_j]) \neq 0$, where $[e_i, e_j] \in \mathfrak{g}$ are viewed as elements of the symmetric algebra $S(\mathfrak{g})$.*

Proof. (1) \Leftrightarrow (2) Immediate.

(2) \Rightarrow (3) Recall that $S(\mathfrak{g})$ is naturally isomorphic to the polynomial ring in n -variables where the variables are taken to be the basis e_1, e_2, \dots, e_n . Extend the linear map $\alpha: \mathfrak{g} \rightarrow k$ to a unit preserving algebra map $\alpha: S(\mathfrak{g}) \rightarrow k$ via

$$\alpha(v_1 v_2 \cdots v_r) := \alpha(v_1) \alpha(v_2) \cdots \alpha(v_r)$$

for $v_1, \dots, v_r \in \mathfrak{g}$. Then

$$\alpha(\det([e_i, e_j])) = \det(\alpha([e_i, e_j])) \neq 0,$$

which implies that $\det([e_i, e_j]) \neq 0$.

(2) \Leftarrow (3) Let $p = \det([e_i, e_j]) \in S(\mathfrak{g})$. Since $p = p(e_1, \dots, e_n) \neq 0$ and k is infinite, there exists $\lambda_i \in k$ such that $p(\lambda_1, \dots, \lambda_n) \neq 0$ (see Theorem 3.76 of [26]). Let $\alpha: \mathfrak{g} \rightarrow k$ be the linear map defined by $\alpha(e_i) = \lambda_i$ for $i = 1, \dots, n$. As before, extend $\alpha: \mathfrak{g} \rightarrow k$ to an algebra map $\alpha: S(\mathfrak{g}) \rightarrow k$. Then

$$\begin{aligned} \det(\alpha([e_i, e_j])) &= \alpha(\det([e_i, e_j])) \\ &= \alpha(p(e_1, \dots, e_n)) \\ &= p(\alpha(e_1), \dots, \alpha(e_n)) \\ &= p(\lambda_1, \dots, \lambda_n) \\ &\neq 0. \end{aligned}$$

\square

We now recall two examples. The first is Frobenius and the second is quasi-Frobenius but not Frobenius [6, 22].

Example 2.7. Let \mathfrak{g} be the 4-dimensional Lie algebra with basis $\{x_1, \dots, x_4\}$ and non-zero commutator relations:

$$[x_1, x_2] = \frac{1}{2}x_2 + x_3, \quad [x_1, x_3] = \frac{1}{2}x_3, \quad [x_1, x_4] = x_4, \quad [x_2, x_3] = x_4.$$

Then $\det([x_i, x_j]) = (x_4)^4 \neq 0$, where $[x_i, x_j]$ are regarded as elements of the symmetric algebra $S(\mathfrak{g})$. By Proposition 2.6, there exists a linear map $\alpha: \mathfrak{g} \rightarrow k$ for which (\mathfrak{g}, α) is a Frobenius Lie algebra.

Example 2.8. Let \mathfrak{q} be the 4-dimensional Lie algebra with basis $\{x_1, \dots, x_4\}$ and non-zero commutator relations:

$$[x_1, x_2] = x_3, \quad [x_1, x_3] = x_4.$$

Since $\det([x_i, x_j]) = 0$, \mathfrak{q} cannot be Frobenius by Proposition 2.6. However, it does admit the structure of a quasi-Frobenius Lie algebra. As an example of this, let β be the nondegenerate, skew-symmetric bilinear form given by

$$\beta = x_1^* \wedge x_4^* + x_2^* \wedge x_3^*$$

where $\{x_1^*, \dots, x_4^*\}$ is the dual basis. A direct calculation shows that β satisfies the 2-cycle condition. Hence, (\mathfrak{q}, β) is quasi-Frobenius.

Definition 2.9. Let $(\mathfrak{g}_1, \beta_1)$ and $(\mathfrak{g}_2, \beta_2)$ be quasi-Frobenius Lie algebras. A *quasi-Frobenius Lie algebra homomorphism* from $(\mathfrak{g}_1, \beta_1)$ to $(\mathfrak{g}_2, \beta_2)$ is a Lie algebra homomorphism $\varphi : \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ such that $\varphi^* \beta_2 = \beta_1$, that is,

$$(2.2) \quad \beta_1(u, v) = \beta_2(\varphi(u), \varphi(v)), \quad \forall u, v \in \mathfrak{g}_1.$$

If $\varphi : \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ satisfies (2.2) and is also a Lie algebra isomorphism, then φ is an isomorphism of quasi-Frobenius Lie algebras.

Proposition 2.10. *Let $\varphi : (\mathfrak{g}_1, \beta_1) \rightarrow (\mathfrak{g}_2, \beta_2)$ be a quasi-Frobenius Lie algebra map. If $\dim \mathfrak{g}_1 = \dim \mathfrak{g}_2 < \infty$, then φ is an isomorphism of quasi-Frobenius Lie algebras.*

Proof. Since $\dim \mathfrak{g}_1 = \dim \mathfrak{g}_2 < \infty$, it suffices to show that φ is injective. Let $u \in \mathfrak{g}_1$ be any nonzero element. Since β is nondegenerate, there exists $v \in \mathfrak{g}_1$ such that $\beta(u, v) \neq 0$. Hence,

$$\beta_2(\varphi(u), \varphi(v)) = \beta_1(u, v) \neq 0,$$

which implies that $\varphi(u) \neq 0$. This completes the proof. □

2.2. Symplectic Lie Groups. In this section, we recall the correspondence between *symplectic Lie groups* [4, 8] and quasi-Frobenius Lie algebras.

Definition 2.11. A *symplectic Lie group* is a pair (G, ω) where G is a Lie group and ω is a left-invariant symplectic form on G .

The next result shows that the Lie algebra of a symplectic Lie group is naturally a quasi-Frobenius Lie algebra.

Proposition 2.12. *Let (G, ω) be a symplectic Lie group. Then (\mathfrak{g}, ω_e) is a quasi-Frobenius Lie algebra.*

Proof. Let $\mathfrak{X}_l(G)$ denote the space of left-invariant vector fields on G and endow $\mathfrak{g} := T_e G$ with the Lie algebra structure of $\mathfrak{X}_l(G)$. Also, let \tilde{x} denote the left-invariant vector field associated with $x \in \mathfrak{g}$. We now show that (\mathfrak{g}, ω_e) is a quasi-Frobenius Lie algebra. Since $\omega_g|_{T_g G}$ is nondegenerate for all $g \in G$ (in particular for $g = e$), it only remains to show that ω_e is a 2-cocycle of \mathfrak{g} with values in \mathbb{R} (where \mathfrak{g} acts trivially on \mathbb{R}).

First, note that for any $x, y \in \mathfrak{g}$, $\omega(\tilde{x}, \tilde{y})$ is a constant function on G . Indeed, for $g \in G$

$$\begin{aligned} (\omega(\tilde{x}, \tilde{y}))(g) &:= \omega_g(\tilde{x}_g, \tilde{y}_g) \\ &= \omega_g((l_g)_*x, (l_g)_*y) \\ &= (l_g^*\omega)_e(x, y) \\ &= \omega_e(x, y) \end{aligned}$$

where the last equality follows from the fact that ω is left-invariant. This fact along with the fact the ω is closed implies that $\omega_e \in Z^2(\mathfrak{g}; \mathbb{R})$:

$$\begin{aligned} 0 &= d\omega(\tilde{x}, \tilde{y}, \tilde{z}) \\ &= \tilde{x}(\omega(\tilde{y}, \tilde{z})) - \tilde{y}(\omega(\tilde{x}, \tilde{z})) + \tilde{z}(\omega(\tilde{x}, \tilde{y})) \\ &\quad - \omega([\tilde{x}, \tilde{y}], \tilde{z}) + \omega([\tilde{x}, \tilde{z}], \tilde{y}) - \omega([\tilde{y}, \tilde{z}], \tilde{x}) \\ &= -\omega([\tilde{x}, \tilde{y}], \tilde{z}) - \omega([\tilde{z}, \tilde{x}], \tilde{y}) - \omega([\tilde{y}, \tilde{z}], \tilde{x}). \end{aligned}$$

Evaluating the last equality at $e \in G$ and multiplying by -1 gives the 2-cocycle condition on ω_e :

$$\omega_e([x, y], z) + \omega_e([z, x], y) + \omega_e([y, z], x) = 0.$$

Hence, (\mathfrak{g}, ω_e) is a quasi-Frobenius Lie algebra. □

Proposition 2.13. *Let G be a Lie group whose Lie algebra \mathfrak{g} carries the structure of a quasi-Frobenius Lie algebra with 2-cocycle β . Define $\tilde{\beta} \in \Omega^2(G)$ by*

$$\tilde{\beta}_g := (l_{g^{-1}})^*\beta \in \wedge^2 T_g^*G, \quad \forall g \in G$$

where $l_g: G \rightarrow G$ is left translation by g . Then $(G, \tilde{\beta})$ is a symplectic Lie group whose associated quasi-Frobenius Lie algebra is $(\mathfrak{g}, \tilde{\beta}_e) = (\mathfrak{g}, \beta)$.

Proof. It follows immediately from the definition that $\tilde{\beta}$ is left-invariant, that is, $(l_g)^*\tilde{\beta} = \tilde{\beta}$ for all $g \in G$. Moreover, since β is nondegenerate, $\tilde{\beta}$ must be nondegenerate as well. To see that $d\tilde{\beta} = 0$, it suffices to show that $d\tilde{\beta}(\tilde{x}, \tilde{y}, \tilde{z}) = 0$ for all left-invariant vector fields \tilde{x}, \tilde{y} , and \tilde{z} . Since $\tilde{\beta}$ is left-invariant, it follows that $\tilde{\beta}(\tilde{x}, \tilde{y}) = \tilde{\beta}_e(x, y) = \beta(x, y)$ is a constant function on G for all left-invariant vector fields \tilde{x} and \tilde{y} , where $\tilde{x}_e = x$ and $\tilde{y}_e = y$. In particular,

$$\tilde{\beta}([\tilde{x}, \tilde{y}], \tilde{z}) = \beta([x, y], z).$$

The proof of Proposition 2.12 shows that if $\tilde{\beta}$ is left-invariant, we have

$$\begin{aligned} d\tilde{\beta}(\tilde{x}, \tilde{y}, \tilde{z}) &= -\tilde{\beta}([\tilde{x}, \tilde{y}], \tilde{z}) - \tilde{\beta}([\tilde{z}, \tilde{x}], \tilde{y}) - \tilde{\beta}([\tilde{y}, \tilde{z}], \tilde{x}) \\ &= -\beta([x, y], z) - \beta([z, x], y) - \beta([y, z], x). \end{aligned}$$

Since $\beta \in Z^2(\mathfrak{g}; \mathbb{R})$, the last equality must be zero. Hence, $(G, \tilde{\beta})$ is a symplectic Lie group. □

Definition 2.14. Let (G, ω) and (H, σ) be symplectic Lie groups. A homomorphism of symplectic Lie groups is a Lie group homomorphism $\varphi: G \rightarrow H$ such that $\varphi^*\sigma = \omega$.

Lemma 2.15. *Let (G, ω) and (H, σ) be symplectic Lie groups and let $\varphi: G \rightarrow H$ be a Lie group homomorphism. Then $\varphi^* \sigma = \omega$ iff $(\varphi^* \sigma)_e = \omega_e$.*

Proof. (\Rightarrow) Suppose $(\varphi^* \sigma) = \omega$. By definition, $(\varphi^* \sigma)_g = \omega_g$ for all $g \in G$. In particular, the equality holds for $g = e$.

(\Leftarrow) Now suppose $(\varphi^* \sigma)_e = \omega_e$. Let $g \in G$ and $x, y \in T_g G$. Then

$$\begin{aligned} (\varphi^* \sigma)_g(x, y) &= \sigma_{\varphi(g)}(\varphi_{*,g}(x), \varphi_{*,g}(y)) \\ &= [(l_{\varphi(g^{-1})})^* \sigma_e](\varphi_{*,g}(x), \varphi_{*,g}(y)) \\ &= \sigma_e((l_{\varphi(g^{-1})} \circ \varphi)_{*,g}(x), (l_{\varphi(g^{-1})} \circ \varphi)_{*,g}(y)) \\ &= \sigma_e((\varphi \circ l_{g^{-1}})_{*,g}(x), (\varphi \circ l_{g^{-1}})_{*,g}(y)) \\ &= (\varphi^* \sigma)_e((l_{g^{-1}})_{*,g}(x), (l_{g^{-1}})_{*,g}(y)) \\ &= \omega_e((l_{g^{-1}})_{*,g}(x), (l_{g^{-1}})_{*,g}(y)) \\ &= [(l_{g^{-1}})^* \omega_e](x, y) \\ &= \omega_g(x, y), \end{aligned}$$

where the second and last equalities follow from the left-invariance of σ and ω respectively and the fourth equality follows from the fact that φ is a group homomorphism. This completes the proof. \square

Proposition 2.16. *Let $\varphi: (G, \omega) \rightarrow (H, \sigma)$ be a homomorphism of symplectic Lie groups. Then*

$$\varphi_{*,e}: (\mathfrak{g}, \omega_e) \rightarrow (\mathfrak{h}, \sigma_e)$$

is a homomorphism of quasi-Frobenius Lie algebras.

Proof. This follows immediately from the properties of φ . \square

Proposition 2.17. *Let $\psi: (\mathfrak{g}, \beta) \rightarrow (\mathfrak{h}, \sigma)$ be a homomorphism of quasi-Frobenius Lie algebras. Let G be the simply connected Lie group whose Lie algebra is \mathfrak{g} and let H be any Lie group whose Lie algebra is \mathfrak{h} . Let $(G, \tilde{\beta})$ and $(H, \tilde{\sigma})$ be the symplectic Lie groups associated to (\mathfrak{g}, β) and (\mathfrak{h}, σ) respectively (see Proposition 2.13). Then there exists a unique symplectic Lie group homomorphism*

$$\widehat{\psi}: (G, \tilde{\beta}) \rightarrow (H, \tilde{\sigma})$$

such that $\widehat{\psi}_{,e} = \psi$.*

Proof. Since G is simply connected, there exists a unique Lie group homomorphism $\widehat{\psi}: G \rightarrow H$ such that $\widehat{\psi}_{*,e} = \psi$. It only remains to show that $\widehat{\psi}^* \tilde{\sigma} = \tilde{\beta}$. By Lemma 2.15, it suffices to show that $(\widehat{\psi}^* \tilde{\sigma})_e = \tilde{\beta}_e = \beta$. To do this, let $x, y \in \mathfrak{g}$. Then

$$\begin{aligned} (\widehat{\psi}^* \tilde{\sigma})_e(x, y) &= \tilde{\sigma}_{\widehat{\psi}(e)}(\widehat{\psi}_{*,e}(x), \widehat{\psi}_{*,e}(y)) \\ &= \tilde{\sigma}_e(\psi(x), \psi(y)) \\ &= \sigma(\psi(x), \psi(y)) \\ &= (\psi^* \sigma)(x, y) \\ &= \beta(x, y). \end{aligned}$$

This completes the proof. □

Theorem 2.18. *Let **SCSLG** be the category of simply connected symplectic Lie groups and let **qFLA** be the category of finite dimensional quasi-Frobenius Lie algebras. Let F be the functor from **SCSLG** to **qFLA** which sends (G, ω) to (\mathfrak{g}, ω_e) and $\varphi: (G, \omega) \rightarrow (H, \sigma)$ to $\varphi_{*,e}: (\mathfrak{g}, \omega_e) \rightarrow (\mathfrak{h}, \sigma_e)$. Then F is an equivalence of categories.*

Proof. Theorem 2.18 follows from the well known correspondence between simply connected Lie groups and finite dimensional Lie algebras combined with Proposition 2.12, Proposition 2.13, Proposition 2.16, and Proposition 2.17. □

As an example, we now recall the symplectic Lie group structure on the affine Lie group $A(n, \mathbb{R})$ (c.f., [2, 21, 22]).

Example 2.19. Recall that $A(n, \mathbb{R})$ is the Lie group consisting of $(n + 1) \times (n + 1)$ matrices of the form

$$A(n, \mathbb{R}) = \left\{ \begin{pmatrix} A & v \\ 0 & 1 \end{pmatrix} \mid A \in GL(n, \mathbb{R}), v \in \mathbb{R}^n \right\}.$$

The associated Lie algebra is then

$$\mathfrak{a}(n, \mathbb{R}) = \left\{ \begin{pmatrix} A & v \\ 0 & 0 \end{pmatrix} \mid A \in \mathfrak{gl}(n, \mathbb{R}), v \in \mathbb{R}^n \right\}.$$

From the definition of $A(n, \mathbb{R})$, we see that $A(n, \mathbb{R})$ is even dimensional with $\dim A(n, \mathbb{R}) = \dim \mathfrak{a}(n, \mathbb{R}) = n^2 + n = n(n + 1)$. Let E_{ij} denote the $(n + 1) \times (n + 1)$ matrix with 1 in the (i, j) -component and all other components zero. Then $\{E_{ij}\}_{1 \leq i \leq n, 1 \leq j \leq n+1}$ is a basis on $\mathfrak{a}(n, \mathbb{R})$. Let $\{E_{ij}^*\}_{1 \leq i \leq n, 1 \leq j \leq n+1}$ denote the corresponding dual basis. Define

$$\alpha = E_{12}^* + E_{23}^* + \cdots + E_{n,n+1}^*$$

and $\beta(X, Y) := -\delta\alpha(X, Y) = \alpha([X, Y])$ for all $X, Y \in \mathfrak{a}(n, \mathbb{R})$. Since

$$[E_{ij}, E_{kl}] = \delta_{jk}E_{il} - \delta_{li}E_{kj},$$

we see that

$$(2.3) \quad \beta(E_{ij}, E_{kl}) = \delta_{jk}\delta_{l,i+1} - \delta_{li}\delta_{j,k+1}.$$

Careful consideration of (2.3) shows that $\beta := -\delta\alpha \in Z^2(\mathfrak{a}(n, \mathbb{R}); \mathbb{R})$ is nondegenerate. Hence, $(\mathfrak{a}(n, \mathbb{R}), \alpha)$ is a Frobenius Lie algebra. (In particular, $(\mathfrak{a}(n, \mathbb{R}), \beta)$ is a quasi-Frobenius Lie algebra.) Let $\tilde{\beta} \in \Omega^2(A(n, \mathbb{R}))$ be the left-invariant 2-form on $A(n, \mathbb{R})$ associated to β . Then $(A(n, \mathbb{R}), \tilde{\beta})$ is a symplectic Lie group. Furthermore, since $\beta := -\delta\alpha$, it follows that $\tilde{\beta}$ is exact. Specifically,

$$\tilde{\beta} = -d\tilde{\alpha}$$

where $\tilde{\alpha} \in \Omega^1(A(n, \mathbb{R}))$ is the left-invariant 1-form on $A(n, \mathbb{R})$ associated to α .

2.3. Lie bialgebras & the Drinfeld Double.

Definition 2.20. A *Lie bialgebra* over a field k is a pair (\mathfrak{g}, γ) where \mathfrak{g} is a Lie algebra over k and $\gamma: \mathfrak{g} \rightarrow \mathfrak{g} \wedge \mathfrak{g} \subset \mathfrak{g} \otimes \mathfrak{g}$ is a skew-symmetric linear map such that

- (1) $\gamma^*: \mathfrak{g}^* \otimes \mathfrak{g}^* \rightarrow \mathfrak{g}^*$ is a Lie bracket on \mathfrak{g}^* , where the dual map γ^* is restricted to $\mathfrak{g}^* \otimes \mathfrak{g}^* \subset (\mathfrak{g} \otimes \mathfrak{g})^*$;
- (2) γ is a 1-cocycle on \mathfrak{g} with values in $\mathfrak{g} \otimes \mathfrak{g}$, where \mathfrak{g} acts on $\mathfrak{g} \otimes \mathfrak{g}$ via the adjoint action.

γ is called the *cobracket* or *co-commutator*.

Condition 2 in Definition 2.20 is equivalent to the condition

$$\gamma([x, y]) = ad_x^{(2)} \gamma(y) - ad_y^{(2)} \gamma(x), \quad \forall x, y \in \mathfrak{g}$$

where the linear map $ad_x^{(2)}: \mathfrak{g} \otimes \mathfrak{g} \rightarrow \mathfrak{g} \otimes \mathfrak{g}$ is the adjoint action of $x \in \mathfrak{g}$ on $\mathfrak{g} \otimes \mathfrak{g}$. Explicitly, $ad_x^{(2)}$ is defined via

$$ad_x^{(2)}(y \otimes z) = ad_x(y) \otimes z + y \otimes ad_x(z) = [x, y] \otimes z + y \otimes [x, z]$$

for $y, z \in \mathfrak{g}$.

Definition 2.21. Let $(\mathfrak{g}, \gamma_{\mathfrak{g}})$ and $(\mathfrak{h}, \gamma_{\mathfrak{h}})$ be Lie bialgebras. A *Lie bialgebra homomorphism* from $(\mathfrak{g}, \gamma_{\mathfrak{g}})$ to $(\mathfrak{h}, \gamma_{\mathfrak{h}})$ is a Lie algebra map $\varphi: \mathfrak{g} \rightarrow \mathfrak{h}$ such that

$$(\varphi \otimes \varphi) \circ \gamma_{\mathfrak{g}} = \gamma_{\mathfrak{h}} \circ \varphi.$$

Example 2.22. Any Lie algebra \mathfrak{g} can be turned into a Lie bialgebra by taking the cobracket $\gamma \equiv 0$. $(\mathfrak{g}, 0)$ is the *trivial* Lie bialgebra structure on \mathfrak{g} .

The next result shows that the notion of a Lie bialgebra is self-dual for the finite dimensional case.

Proposition 2.23. Let $(\mathfrak{g}, \gamma_{\mathfrak{g}})$ be a finite dimensional Lie bialgebra and let $\gamma_{\mathfrak{g}^*}: \mathfrak{g}^* \rightarrow \mathfrak{g}^* \otimes \mathfrak{g}^*$ be the dual of the Lie bracket on \mathfrak{g} . Then $(\mathfrak{g}^*, \gamma_{\mathfrak{g}^*})$ is a Lie bialgebra, where the Lie bracket on \mathfrak{g}^* is given by the dual of $\gamma_{\mathfrak{g}}$.

For a Lie algebra \mathfrak{g} , the simplest way to obtain an element of $Z_{ad}^1(\mathfrak{g}; \mathfrak{g} \otimes \mathfrak{g})$ is to turn to the 0-cochains and take their coboundaries. This raises the following natural question: given $r \in \mathfrak{g} \otimes \mathfrak{g}$, when does $\delta r \in Z_{ad}^1(\mathfrak{g}; \mathfrak{g} \otimes \mathfrak{g})$ define a Lie bialgebra structure on \mathfrak{g} ? To answer this question, let

$$r = \sum_i a_i \otimes b_i,$$

and define

$$(2.4) \quad [[r, r]] := [r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}],$$

where

$$(2.5) \quad [r_{12}, r_{13}] := \sum_{i,j} [a_i, a_j] \otimes b_i \otimes b_j,$$

$$(2.6) \quad [r_{12}, r_{23}] := \sum_{i,j} a_i \otimes [b_i, a_j] \otimes b_j,$$

$$(2.7) \quad [r_{13}, r_{23}] := \sum_{i,j} = a_i \otimes a_j \otimes [b_i, b_j].$$

Definition 2.24. A *coboundary Lie bialgebra* is a Lie bialgebra (\mathfrak{g}, γ) such that $\gamma = \delta r$ for some $r \in \mathfrak{g} \otimes \mathfrak{g}$. The element r is called the *r-matrix*.

The next result provides a necessary and sufficient condition for an element $r \in \mathfrak{g} \otimes \mathfrak{g}$ to define a Lie bialgebra structure on \mathfrak{g} .

Proposition 2.25. *Let \mathfrak{g} be a Lie algebra. Then $(\mathfrak{g}, \delta r)$ is a Lie bialgebra iff*

- (i) $r + \sigma(r)$ is invariant under the adjoint action of \mathfrak{g} on $\mathfrak{g} \otimes \mathfrak{g}$, where $\sigma : \mathfrak{g} \otimes \mathfrak{g} \rightarrow \mathfrak{g} \otimes \mathfrak{g}$ is the unique linear map defined by $x \otimes y \mapsto y \otimes x$ for $x, y \in \mathfrak{g}$;
- (ii) $[[r, r]]$ is invariant under the adjoint action of \mathfrak{g} on $\mathfrak{g} \otimes \mathfrak{g} \otimes \mathfrak{g}$.

Proof. See pp. 51–54 of [7]. □

The simplest way to ensure that condition (ii) of Proposition 2.25 is satisfied is to demand that

$$(2.8) \quad [[r, r]] = 0.$$

Equation 2.8 is called the *classical Yang-Baxter equation* (CYBE). The CYBE motivates the following definition:

Definition 2.26. A coboundary Lie bialgebra $(\mathfrak{g}, \delta r)$ is *quasitriangular* if r is a solution of the CYBE. Furthermore, if r is skew-symmetric, that is, $r \in \mathfrak{g} \wedge \mathfrak{g} \subset \mathfrak{g} \otimes \mathfrak{g}$, then $(\mathfrak{g}, \delta r)$ is said to be *triangular*.

Example 2.27. Let \mathfrak{g} be the two dimensional Lie algebra with basis x, y and commutator relation $[x, y] = x$. Define $r = y \wedge x$. Then $(\mathfrak{g}, \delta r)$ is a triangular Lie bialgebra, where $\gamma := \delta r$ is given explicitly by

$$\gamma(x) = 0, \quad \gamma(y) = x \wedge y.$$

Before turning to the Drinfeld double, we recall the following notion:

Definition 2.28. Let \mathfrak{g} be a Lie algebra and let $\langle \cdot, \cdot \rangle$ be a bilinear form on \mathfrak{g} . \mathfrak{g} is *ad-invariant* with respect to $\langle \cdot, \cdot \rangle$ if

$$(2.9) \quad \langle [x, y], z \rangle = \langle x, [y, z] \rangle, \quad \forall x, y, z \in \mathfrak{g}.$$

Now let $(\mathfrak{g}, \gamma_{\mathfrak{g}})$ be a finite dimensional Lie bialgebra and let $(\mathfrak{g}^*, \gamma_{\mathfrak{g}^*})$ be the associated dual Lie bialgebra. Consider the direct sum

$$\mathfrak{g} \oplus \mathfrak{g}^*$$

and equip it with the symmetric, nondegenerate bilinear form $\langle \cdot, \cdot \rangle$ defined by

$$\langle x + \xi, y + \eta \rangle = \xi(y) + \eta(x),$$

where we write $x + \xi$ and $y + \eta$ for $(x, \xi), (y, \eta) \in \mathfrak{g} \oplus \mathfrak{g}^*$. The Drinfeld double of $(\mathfrak{g}, \gamma_{\mathfrak{g}})$, denoted by $D(\mathfrak{g})$, is the unique quasitriangular Lie bialgebra which satisfies the following conditions:

(1) As a vector space,

$$D(\mathfrak{g}) = \mathfrak{g} \oplus \mathfrak{g}^* .$$

(2) As a Lie algebra, $D(\mathfrak{g})$ is ad-invariant with respect to the inner product $\langle \cdot, \cdot \rangle$ and contains \mathfrak{g} and \mathfrak{g}^* as Lie subalgebras.

(3) The cobracket on $D(\mathfrak{g})$ is defined by $\gamma_D := \gamma_{\mathfrak{g}} - \gamma_{\mathfrak{g}^*}$.

Let $[\cdot, \cdot]_D, [\cdot, \cdot]_{\mathfrak{g}}$, and $[\cdot, \cdot]_{\mathfrak{g}^*}$ denote the Lie brackets on $D(\mathfrak{g}), \mathfrak{g}$, and \mathfrak{g}^* respectively. Condition (2) implies that

$$[x, y]_D = [x, y]_{\mathfrak{g}}, \quad [\xi, \eta]_D = [\xi, \eta]_{\mathfrak{g}^*}, \quad [x, \xi]_D = ad_x^* \xi - ad_{\xi}^* x$$

for all $x, y \in \mathfrak{g}$ and $\xi, \eta \in \mathfrak{g}^*$, where ad^* denotes the coadjoint action of \mathfrak{g} on \mathfrak{g}^* and \mathfrak{g}^* on \mathfrak{g} . Explicitly, $ad_x^*: \mathfrak{g}^* \rightarrow \mathfrak{g}^*$ and $ad_{\xi}^*: \mathfrak{g} \rightarrow \mathfrak{g}$ are defined by $ad_x^* := -ad_x^t$ and $ad_{\xi}^* := -ad_{\xi}^t$ where ad_x^t and ad_{ξ}^t are the ordinary duals of $ad_x: \mathfrak{g} \rightarrow \mathfrak{g}$ and $ad_{\xi}: \mathfrak{g}^* \rightarrow \mathfrak{g}^*$. In dealing with the Drinfeld double, we will drop the “ D ”, “ \mathfrak{g} ”, and “ \mathfrak{g}^* ” that appear as subscripts in the Lie brackets of $D(\mathfrak{g}), \mathfrak{g}$, and \mathfrak{g}^* respectively. Condition (2) implies that the triple $(D(\mathfrak{g}), \mathfrak{g}, \mathfrak{g}^*)$ is a *Manin triple* with respect to the inner product $\langle \cdot, \cdot \rangle$. In fact, there is a one to one correspondence between finite dimensional Lie bialgebras and Manin triples (see [7]).

Lastly, condition (3) implies that $D(\mathfrak{g})$ is quasitriangular with r -matrix

$$r = \sum_i e_i \otimes e_i^*$$

where e_1, \dots, e_n is any basis on \mathfrak{g} and e_1^*, \dots, e_n^* is the corresponding dual basis.

Example 2.29. Let (\mathfrak{g}, γ) be the 2-dimensional Lie bialgebra with basis x, y satisfying $[x, y] = x$ and cobracket $\gamma(x) = 0$ and $\gamma(y) = x \wedge y$. Let x^*, y^* denote the corresponding dual basis. The commutator relations on $D(\mathfrak{g})$ are

$$\begin{aligned} [x, y] &= x, & [x^*, y^*] &= y^*, & [x, x^*] &= -y^*, & [x, y^*] &= 0 \\ [y, x^*] &= x^* + y, & [y, y^*] &= -x. \end{aligned}$$

The r -matrix is $r = x \otimes x^* + y \otimes y^*$.

3. \mathfrak{g} -QUASI-FROBENIUS LIE ALGEBRAS

We begin with the formal definition:

Definition 3.1. A \mathfrak{g} -quasi-Frobenius Lie algebra is a triple $(\mathfrak{q}, \beta, \rho)$ such that (\mathfrak{q}, β) is a quasi-Frobenius Lie algebra and $\rho: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{q}), x \mapsto \rho_x$ is a left \mathfrak{g} -module structure on \mathfrak{q} such that

- (i) ρ_x is a derivation on \mathfrak{q} for all $x \in \mathfrak{g}$,
- (ii) $\beta(\rho_x(u), v) + \beta(u, \rho_x(v)) = 0$ for all $x \in \mathfrak{g}, u, v \in \mathfrak{q}$ (\mathfrak{g} -invariance).

In this section, we prove a result for the general construction of \mathfrak{g} -quasi-Frobenius Lie algebras. Before doing so, we make the following observation:

Proposition 3.2. *Let (\mathfrak{q}, β) be a quasi-Frobenius Lie algebra and let $\text{Aut}(\mathfrak{q}, \beta)$ be the automorphism group of (\mathfrak{q}, β) . Then $\text{Aut}(\mathfrak{q}, \beta)$ is an embedded Lie subgroup of $GL(\mathfrak{q})$.*

Proof. As a set, $\text{Aut}(\mathfrak{q}, \beta) = \text{Aut}(\mathfrak{q}) \cap \text{Sp}(\mathfrak{q}, \beta)$ where $\text{Aut}(\mathfrak{q})$ is the group of automorphisms of the Lie algebra \mathfrak{q} and $\text{Sp}(\mathfrak{q}, \beta)$ is the group of linear symplectomorphisms of (\mathfrak{q}, β) , where the latter is regarded as a symplectic vector space. Since $\text{Aut}(\mathfrak{q})$ and $\text{Sp}(\mathfrak{q}, \beta)$ are both closed subgroups of $GL(\mathfrak{q})$, each being the zero set of a collection of polynomials, $\text{Aut}(\mathfrak{q}, \beta)$ is also a closed subgroup of $GL(\mathfrak{q})$. By the closed subgroup theorem [27], $\text{Aut}(\mathfrak{q}, \beta)$ is an embedded Lie subgroup of $GL(\mathfrak{q})$. \square

Proposition 3.3. *Let (\mathfrak{q}, β) be a quasi-Frobenius Lie algebra and let*

$$\rho: G \rightarrow \text{Aut}(\mathfrak{q}, \beta) \subset GL(\mathfrak{q}), \quad g \mapsto \rho_g$$

be a Lie group homomorphism. Define

$$\rho' := \rho_{*,e}: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{q}), \quad x \mapsto \rho'_x.$$

Then $(\mathfrak{q}, \beta, \rho')$ is a \mathfrak{g} -quasi-Frobenius Lie algebra. In particular, if G is any Lie subgroup of $\text{Aut}(\mathfrak{q}, \beta)$, then (\mathfrak{q}, β) admits the structure of a \mathfrak{g} -quasi-Frobenius Lie algebra.

Proof. Since ρ is a Lie group homomorphism, it immediately follows that $\rho': \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{q})$ is a representation of \mathfrak{g} on \mathfrak{q} . We now show that

$$(3.1) \quad \rho_x([u, v]) = [\rho_x(u), v] + [u, \rho_x(v)]$$

and

$$(3.2) \quad \beta(\rho_x(u), v) + \beta(u, \rho_x(v)) = 0$$

for all $x \in \mathfrak{g}$ and $u, v \in \mathfrak{q}$. To do this, fix a basis e_1, e_2, \dots, e_n on \mathfrak{q} . Since $\rho_{\exp(tx)}(u), \rho_{\exp(tx)}(v) \in \mathfrak{q}$, we have

$$(3.3) \quad \rho_{\exp(tx)}(u) = \sum_i a_i(t)e_i, \quad \rho_{\exp(tx)}(v) = \sum_i b_i(t)e_i$$

for some smooth functions $a_i(t), b_i(t), i = 1, \dots, n$. Hence,

$$(3.4) \quad \rho'_x(u) = \sum_i \dot{a}_i(0)e_i, \quad \rho'_x(v) = \sum_i \dot{b}_i(0)e_i.$$

Since $\rho_g \in \text{Aut}(\mathfrak{q}, \beta)$ for all $g \in G$, we have

$$(3.5) \quad \rho_{\exp(tx)}([u, v]) = [\rho_{\exp(tx)}(u), \rho_{\exp(tx)}(v)].$$

Substituting (3.3) into the right side of (3.5) and applying $\frac{d}{dt} \Big|_{t=0}$ to both sides of (3.5) gives

$$\begin{aligned}
 \rho'_x([u, v]) &= \frac{d}{dt} \Big|_{t=0} [\rho_{\exp(tx)}(u), \rho_{\exp(tx)}(v)] \\
 &= \frac{d}{dt} \Big|_{t=0} \sum_{i,j} a_i(t)b_j(t)[e_i, e_j] \\
 &= \sum_{i,j} (\dot{a}_i(0)b_j(0)[e_i, e_j] + a_i(0)\dot{b}_j(0)[e_i, e_j]) \\
 (3.6) \qquad &= [\rho'_x(u), v] + [u, \rho'_x(v)],
 \end{aligned}$$

which proves (3.1).

For equation (3.2), note that

$$(3.7) \qquad \beta(\rho_{\exp(tx)}(u), \rho_{\exp(tx)}(v)) = \beta(u, v)$$

since $\rho_g \in \text{Aut}(\mathfrak{q}, \beta)$ for all $g \in G$. Substituting (3.3) into the left side of (3.7) and applying $\frac{d}{dt} \Big|_{t=0}$ to both sides of (3.7) gives

$$\beta(\rho'_x(u), v) + \beta(u, \rho'_x(v)) = 0.$$

This completes the proof. □

A trivial example of a \mathfrak{g} -quasi-Frobenius Lie algebra is obtained by equipping any quasi-Frobenius Lie algebra with the trivial \mathfrak{g} -action. We now consider a more interesting example which is an application of Proposition 3.3.

Example 3.4. Let \mathfrak{q} be the 4-dimensional Lie algebra $\{e_1, e_2, e_3, e_4\}$ whose non-zero commutator relations are given by [6]:

$$[e_1, e_2] = e_2, \quad [e_1, e_3] = e_3, \quad [e_1, e_4] = 2e_4, \quad [e_2, e_3] = e_4.$$

Let $\alpha: \mathfrak{q} \rightarrow \mathbb{R}$ be the linear map defined by $\alpha(e_i) = 0$ for $i = 1, 2, 3$ and $\alpha(e_4) = 1$. Define $\beta(u, v) := \alpha([u, v])$ for all $u, v \in \mathfrak{q}$. Then the matrix representation of β with respect to the basis $\{e_1, e_2, e_3, e_4\}$ is

$$(\beta_{ij}) = \begin{pmatrix} 0 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ -2 & 0 & 0 & 0 \end{pmatrix}.$$

Hence, β is nondegenerate which shows that (\mathfrak{q}, α) is a Frobenius Lie algebra. Let G be the set of linear isomorphisms on \mathfrak{q} whose matrix representations with respect to $\{e_1, e_2, e_3, e_4\}$ is given by

$$(3.8) \qquad \left\{ \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & b & c & 0 \\ 0 & 0 & 1/b & 0 \\ a & 0 & 0 & 1 \end{pmatrix} \mid a, c \in \mathbb{R}, b > 0 \right\}.$$

A direct calculation shows that G is a 3-dimensional non-abelian, connected Lie subgroup of $\text{Aut}(\mathfrak{q}, \beta)$. Let $\rho: G \rightarrow \text{Aut}(\mathfrak{q}, \beta) \subset GL(\mathfrak{q})$ be the inclusion map (which

is clearly a Lie group homomorphism). Proposition 3.3 implies that $(\mathfrak{q}, \beta, \rho')$ is a \mathfrak{g} -quasi-Frobenius Lie algebra, where $\rho' := \rho_{*,e}$. As a Lie algebra, \mathfrak{g} has basis

$$(3.9) \quad x_1 := \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}, \quad x_2 := \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad x_3 := \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix},$$

where we have identified G with its matrix representations in (3.8). The non-zero commutator relations are

$$[x_2, x_3] = 2x_3.$$

Let $a = a_1x_1 + a_2x_2 + a_3x_3 \in \mathfrak{g}$. Since $\rho: G \rightarrow \text{Aut}(\mathfrak{q}, \beta) \subset GL(\mathfrak{q})$ is just the inclusion map, it follows that the matrix representation of $\rho'_a: \mathfrak{q} \rightarrow \mathfrak{q}$ with respect to the basis $\{e_1, e_2, e_3, e_4\}$ is simply

$$(3.10) \quad \rho'_a = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & a_2 & a_3 & 0 \\ 0 & 0 & -a_2 & 0 \\ a_1 & 0 & 0 & 0 \end{pmatrix}.$$

Since $(\mathfrak{q}, \beta, \rho')$ is a \mathfrak{g} -quasi-Frobenius Lie algebra by Proposition 3.3, ρ'_a acts on \mathfrak{q} via derivations and satisfies

$$\beta(\rho'_a(u), v) + \beta(u, \rho'_a(v)) = 0$$

for all $u, v \in \mathfrak{q}$.

For later use, we conclude this section with the following natural definition:

Definition 3.5. Let $(\mathfrak{q}, \beta, \phi)$ and $(\mathfrak{r}, \sigma, \mu)$ be \mathfrak{g} -quasi-Frobenius Lie algebras. A homomorphism from $(\mathfrak{q}, \beta, \phi)$ to $(\mathfrak{r}, \sigma, \mu)$ is a homomorphism

$$\psi: (\mathfrak{q}, \beta) \rightarrow (\mathfrak{r}, \sigma)$$

of quasi-Frobenius Lie algebras which is also \mathfrak{g} -equivariant, that is,

$$\psi \circ \phi_x = \mu_x \circ \psi$$

for all $x \in \mathfrak{g}$.

3.1. Categorical Formulation. In this section, we apply the idea of categorification to quasi-Frobenius Lie algebras. The upshot of this is the notion of a *quasi-Frobenius Lie object*, which can be viewed as the analogue of a Frobenius object in the current setting. The starting point for this particular step is the categorification of Lie algebra due to Goyvaerts and Vercauteren [12]:

Definition 3.6. A *Lie object* in an additive symmetric monoidal category $(\mathcal{C}, \otimes, I, \Phi, l, r, c)$ is a pair (L, b) where L is an object of \mathcal{C} and $b: L \otimes L \rightarrow L$ is a morphism such that

- (i) $b + b \circ c = 0_{L \otimes L, L}$,
- (ii) $b \circ (\text{id}_L \otimes b) \circ (\text{id}_{L \otimes (L \otimes L)} + c_{L \otimes L, L} \circ \Phi_{L, L, L}^{-1} + \Phi_{L, L, L} \circ c_{L, L \otimes L}) = 0_{L \otimes (L \otimes L), L}$.

Remark 3.7. With regard to the notation in Definition 3.6, \otimes is the monoidal product; I is the unit object; Φ is the associator; l and r are the left and right unit maps respectively; and c is the braiding.

Example 3.8. Let \mathbf{Vect}_k be the symmetric monoidal additive category of finite dimensional vector spaces over k . It follows readily from Definition 3.6 that a Lie object (L, b) in \mathbf{Vect}_k is precisely a finite dimensional Lie algebra L over k with Lie bracket $[x, y] := b(x, y)$.

Definition 3.9. A *quasi-Frobenius Lie object* in an additive symmetric monoidal category $(\mathcal{C}, \otimes, I, \Phi, l, r, c)$ is a triple $(L, b, \bar{\beta})$ such that

- (1) (L, b) is a Lie object.
- (2) L has a left dual object L^* (where $\varepsilon: L^* \otimes L \rightarrow I$ and $\eta: I \rightarrow L \otimes L^*$ denote the evaluation and coevaluation morphisms respectively).
- (3) $\bar{\beta}: L \xrightarrow{\sim} L^*$ is an isomorphism such that the induced morphism

$$\beta := \varepsilon \circ (\bar{\beta} \otimes \text{id}_L): L \otimes L \rightarrow I,$$

satisfies

$$\beta + \beta \circ c_{L,L} = 0_{L \otimes L, I}$$

and

$$\beta \circ (b \otimes \text{id}_L) \circ [\text{id}_{(L \otimes L) \otimes L} + \Phi_{L,L,L}^{-1} \circ c_{L \otimes L, L} + c_{L, L \otimes L} \circ \Phi_{L,L,L}] = 0_{(L \otimes L) \otimes L, I}.$$

If there exists a morphism $\alpha: L \rightarrow I$ such that $\beta = \alpha \circ b$, then $(L, b, \bar{\beta})$ is called a *Frobenius Lie object*.

Example 3.10. Let $(L, b, \bar{\beta})$ be a quasi-Frobenius Lie object in \mathbf{Vect}_k . Then its easy to see that L is a quasi-Frobenius Lie algebra over k with Lie bracket $[x, y] := b(x, y)$ and $\beta: L \otimes L \rightarrow k$ (as defined in (3) of Definition 3.9) is the nondegenerate 2-cocycle in the Lie algebra cohomology of L . Likewise, a Frobenius Lie object in \mathbf{Vect}_k is just a Frobenius Lie algebra.

Proposition 3.11. *The category $\mathbf{Rep}(\mathfrak{g})$ of finite dimensional left \mathfrak{g} -modules over k is an additive symmetric monoidal category where every object has a left dual and*

- (i) *the monoidal product is the usual tensor product of left \mathfrak{g} -modules and \mathfrak{g} -linear maps;*
- (ii) *the unit object is k with the trivial \mathfrak{g} -action;*
- (iii) *the associator Φ is the trivial one;*
- (iv) *for any object (V, ρ) in $\mathbf{Rep}(\mathfrak{g})$, the left and right morphisms $l_V: k \otimes V \xrightarrow{\sim} V$ and $r_V: V \otimes k \xrightarrow{\sim} V$ are the trivial ones;*
- (v) *for objects $(V, \rho), (W, \phi)$ in $\mathbf{Rep}(\mathfrak{g})$, the braiding $c_{V,W}: V \otimes W \xrightarrow{\sim} W \otimes V$ is simply the linear map that sends $v \otimes w \in V \otimes W$ to $w \otimes v \in W \otimes V$;*
- (vi) *the left dual of an object (V, ρ) in $\mathbf{Rep}(\mathfrak{g})$ is the dual representation (V^*, ρ^*) (i.e., $\rho_x^* := -\rho_x^t: V^* \rightarrow V^*$ for $x \in \mathfrak{g}$, where ρ_x^t is the dual or transpose of $\rho_x: V \rightarrow V$);*

(vii) *the evaluation morphism is $\varepsilon: V^* \otimes V \rightarrow k$, $\varepsilon(\xi, v) := \xi(v)$ and the coevaluation morphism is $\eta: k \rightarrow V \otimes V^*$, $1 \mapsto \sum_i e_i \otimes \delta^i$ where e_i is any basis of V and δ^i is the corresponding dual basis.*

Proof. It is an easy exercise to verify that $(\mathbf{Rep}(\mathfrak{g}), \otimes, k, \Phi, l, r, c)$ satisfies all the axioms of an additive symmetric monoidal category. \square

The next result establishes the categorical formulation of \mathfrak{g} -quasi-Frobenius Lie algebras.

Proposition 3.12. *A quasi-Frobenius Lie object in $\mathbf{Rep}(\mathfrak{g})$ is a \mathfrak{g} -quasi-Frobenius Lie algebra.*

Proof. By definition, a quasi-Frobenius Lie object in $\mathbf{Rep}(\mathfrak{g})$ consists of a representation (\mathfrak{q}, ρ) of \mathfrak{g} together with \mathfrak{g} -linear maps

$$b : \mathfrak{q} \otimes \mathfrak{q} \rightarrow \mathfrak{q}, \quad \bar{\beta} : \mathfrak{q} \xrightarrow{\sim} \mathfrak{q}^*,$$

which satisfy conditions (1) and (3) of Definition 3.9.

We begin by verifying that (\mathfrak{q}, β) is a quasi-Frobenius Lie algebra. To start, note that condition (1) of Definition 3.9 implies that \mathfrak{q} is a Lie algebra with Lie bracket $[u, v] := b(u, v)$. From Definition 3.9, the morphism $\beta: \mathfrak{q} \otimes \mathfrak{q} \rightarrow k$ is given explicitly as

$$\beta(u, v) = \varepsilon(\bar{\beta}(u), v) = \bar{\beta}(u)(v).$$

Condition (3) of Definition 3.9 implies that β is a 2-cocycle of \mathfrak{q} with values in k (where \mathfrak{q} acts trivially on k). Furthermore, since $\bar{\beta}: \mathfrak{q} \xrightarrow{\sim} \mathfrak{q}^*$ is an isomorphism, it follows that β is nondegenerate. Hence, (\mathfrak{q}, β) is a quasi-Frobenius Lie algebra.

Since $\bar{\beta}$ is \mathfrak{g} -linear (being a morphism of $\mathbf{Rep}(\mathfrak{g})$), we have

$$(3.11) \quad \bar{\beta}(\rho_x(u))(v) = \rho_x^*(\bar{\beta}(u))(v) = -\bar{\beta}(u)(\rho_x(v)), \quad \forall u, v \in \mathfrak{q}$$

where we recall that $\rho_x^* := -\rho_x^t$. Expressing the left and right most sides of (3.11) in terms of β gives

$$\beta(\rho_x(u), v) = -\beta(u, \rho_x(v)),$$

which proves the \mathfrak{g} -invariance of β , that is, $\beta(\rho_x(u), v) + \beta(u, \rho_x(v)) = 0$.

Since b is also \mathfrak{g} -linear, we also have

$$\begin{aligned} \rho_x([u, v]) &= \rho_x(b(u \otimes v)) \\ &= b(\bar{\rho}_x(u \otimes v)) \\ &= b(\rho_x(u) \otimes v) + b(u \otimes \rho_x(v)) \\ &= [\rho_x(u), v] + [u, \rho_x(v)], \end{aligned}$$

where $\bar{\rho}_x$ in the second equality denotes the induced left \mathfrak{g} -module structure on $\mathfrak{q} \otimes \mathfrak{q}$. Hence, $(\mathfrak{q}, \beta, \rho)$ is a \mathfrak{g} -quasi-Frobenius Lie algebra. \square

4. THE GEOMETRY OF \mathfrak{g} -QUASI-FROBENIUS LIE ALGEBRAS

4.1. G -Symplectic Lie groups.

Definition 4.1. Let G be a Lie group. A G -symplectic Lie group is a triple (Q, ω, φ) where (Q, ω) is a symplectic Lie group and

$$\varphi: G \times Q \rightarrow Q, \quad (g, q) \mapsto \varphi_g(q) := \varphi(g, q)$$

is a smooth left action on Q such that $\varphi_g: (Q, \omega) \rightarrow (Q, \omega)$ is an isomorphism of symplectic Lie groups.

Notation 4.2. When dealing with multiple Lie groups, we will denote the identity element of each group simply as e as opposed to e_G for G , e_Q for Q , and so on when there is no risk of confusion.

Proposition 4.3. Let (Q, ω, φ) be a G -symplectic Lie group with action

$$\varphi: G \times Q \rightarrow Q, \quad (g, q) \mapsto \varphi_g(q) := \varphi(g, q).$$

Define

$$\varphi': G \rightarrow GL(\mathfrak{q}), \quad g \mapsto \varphi'_g := (\varphi_g)_{*,e}: \mathfrak{q} \rightarrow \mathfrak{q}$$

$$\varphi'': \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{q}), \quad x \mapsto \varphi''_x := (\varphi')_{*,e}(x): \mathfrak{q} \rightarrow \mathfrak{q}.$$

Then

- (i) φ' is a representation of G on \mathfrak{q} such that $\varphi'_g \in \text{Aut}(\mathfrak{q}, \omega_e)$ for all $g \in G$.
- (ii) $(\mathfrak{q}, \omega_e, \varphi'')$ is a \mathfrak{g} -quasi-Frobenius Lie algebra.

Proof. Since φ is a left action of G on Q and $\varphi_g(e) = e$ for all $g \in G$, we have

$$\begin{aligned} \varphi'_g \circ \varphi'_h &= (\varphi_g)_{*,e} \circ (\varphi_h)_{*,e} \\ &= (\varphi_g \circ \varphi_h)_{*,e} \\ &= (\varphi_{gh})_{*,e} = \varphi'_{gh}. \end{aligned}$$

Hence, φ' is a representation of G on \mathfrak{q} . Furthermore, since $\varphi_g: Q \rightarrow Q$ is both a Lie group isomorphism and a symplectomorphism, it follows that $\varphi'_g: \mathfrak{q} \rightarrow \mathfrak{q}$ is a Lie algebra isomorphism and

$$\omega_e(u, v) = ((\varphi_g)^*\omega)_e(u, v) = \omega_e((\varphi_g)_{*,e}(u), (\varphi_g)_{*,e}(v)) = \omega_e(\varphi'_g(u), \varphi'_g(v)),$$

which shows that $\varphi'_g \in \text{Aut}(\mathfrak{q}, \omega_e)$ for all $g \in G$. This proves (i).

Statement (ii) follows from an application of Proposition 3.3 to the quasi-Frobenius Lie algebra (\mathfrak{q}, ω_e) with Lie group homomorphism $\varphi': G \rightarrow \text{Aut}(\mathfrak{q}, \omega_e) \subset GL(\mathfrak{q})$. This completes the proof. \square

Remark 4.4. We will refer to $(\mathfrak{q}, \omega_e, \varphi'')$ in Proposition 4.3 as the \mathfrak{g} -quasi-Frobenius Lie algebra associated to the G -symplectic Lie group (Q, ω, φ) .

The next result provides a means of constructing G -symplectic Lie groups.

Proposition 4.5. *Let (Q, ω) be a simply connected symplectic Lie group, let G be a Lie group, and let $\rho: G \rightarrow \text{Aut}(\mathfrak{q}, \omega_e)$, $g \mapsto \rho_g$ be a Lie group homomorphism. Then there exists a unique smooth left- G action*

$$\widehat{\rho}: G \times Q \rightarrow Q, \quad (g, q) \mapsto \widehat{\rho}_g(q),$$

such that $(Q, \omega, \widehat{\rho})$ is a G -symplectic Lie group and $(\widehat{\rho}_g)_{*,e} = \rho_g$. In particular, if G is any Lie subgroup of $\text{Aut}(\mathfrak{q}, \omega_e)$ and $G \neq \{e\}$, then (Q, ω) admits the structure of a G -symplectic Lie group with a nontrivial G -action.

Proof. Let $\rho: G \rightarrow \text{Aut}(\mathfrak{q}, \omega_e)$, $g \mapsto \rho_g$ be a Lie group homomorphism. Since Q is simply connected and $\rho_g \in \text{Aut}(\mathfrak{q}, \omega_e)$ for all $g \in G$, it follows from Proposition 2.17 that there exists a unique homomorphism of symplectic Lie groups

$$\widehat{\rho}_g: (Q, \omega) \rightarrow (Q, \omega)$$

such that $(\widehat{\rho}_g)_{*,e} = \rho_g$ for all $g \in G$. Furthermore, for $g, h \in G$, we have

$$\begin{aligned} (\widehat{\rho}_g \circ \widehat{\rho}_h)_{*,e} &= (\widehat{\rho}_g)_{*,e} \circ (\widehat{\rho}_h)_{*,e} \\ (4.1) \qquad \qquad &= \rho_g \circ \rho_h = \rho_{gh} = (\widehat{\rho}_{gh})_{*,e}. \end{aligned}$$

Since $\widehat{\rho}_g \circ \widehat{\rho}_h$ and $\widehat{\rho}_{gh}$ are Lie group homomorphisms and Q is connected, equation (4.1) implies that

$$(4.2) \qquad \qquad \widehat{\rho}_g \circ \widehat{\rho}_h = \widehat{\rho}_{gh}.$$

Hence,

$$\widehat{\rho}: G \times Q \rightarrow Q, \quad (g, q) \mapsto \widehat{\rho}_g(q)$$

is a left (not necessarily smooth) G -action. We now show that $\widehat{\rho}$ is smooth. To do this, set $\widehat{\rho}(g, q) = \widehat{\rho}_g(q)$ for $g \in G$, $q \in Q$ and let U be an open neighborhood of $0 \in \mathfrak{q}$ such that

$$\exp|_U: U \xrightarrow{\sim} \exp(U)$$

is a diffeomorphism. The naturality of the exponential map implies that

$$(4.3) \qquad \widehat{\rho}(g, q) = \exp \circ \rho_g \circ (\exp|_U)^{-1}(q), \quad \forall (g, q) \in G \times \exp(U).$$

Since the right side of (4.3) is smooth on $G \times \exp(U)$, it follows that $\widehat{\rho}|_{G \times \exp(U)}$ is also smooth. Now fix an arbitrary element q_0 of Q and define

$$f: G \rightarrow Q, \quad g \mapsto \widehat{\rho}(g, q_0).$$

We now show that f is smooth. Since Q is connected, $\exp(U)$ generates Q . Hence, there exists $q_{0,1}, \dots, q_{0,k} \in \exp(U)$ such that

$$q_0 = q_{0,1}q_{0,2} \dots q_{0,k}.$$

Since $\widehat{\rho}_g: Q \rightarrow Q$ is a Lie group homomorphism for all $g \in G$, we have

$$(4.4) \qquad f(g) := \widehat{\rho}(g, q_0) = \widehat{\rho}(g, q_{0,1})\widehat{\rho}(g, q_{0,2}) \dots \widehat{\rho}(g, q_{0,k}) \in Q.$$

Since $(g, q_{0,i}) \in G \times \exp(U)$ for $i = 1, \dots, k$, it follows that the right side of (4.4) depends smoothly on g . Hence, f is smooth. Now, for all $(g, q) \in G \times (q_0 \exp(U))$, we have

$$\begin{aligned}
 \widehat{\rho}(g, q) &= \widehat{\rho}(g, q_0 q_0^{-1} q) \\
 &= \widehat{\rho}(g, q_0) \widehat{\rho}(g, q_0^{-1} q) \\
 (4.5) \qquad &= f(g) [(\widehat{\rho}|_{G \times \exp(U)}) \circ (\text{id}_G \times l_{q_0^{-1}})(g, q)],
 \end{aligned}$$

where $l_{q_0^{-1}}: Q \rightarrow Q$ is left translation by q_0^{-1} . Since f and $\widehat{\rho}|_{G \times \exp(U)}$ are both smooth, it follows that the right side of (4.5) is smooth on $G \times (q_0 \exp(U))$. Hence, $\widehat{\rho}|_{G \times (q_0 \exp(U))}$ is smooth. Since $q_0 \in Q$ is arbitrary, it follows that $\widehat{\rho}$ is smooth on $G \times Q$. This completes the proof. \square

We now illustrate Proposition 4.5 with a simple example:

Example 4.6. Let Q be the 2-dimensional non-abelian Lie group

$$(4.6) \qquad Q = \left\{ \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} \mid a > 0, b \in \mathbb{R} \right\}.$$

Note that Q is simply connected, being diffeomorphic to $\mathbb{R}_+ \times \mathbb{R}$. The associated Lie algebra is

$$(4.7) \qquad \mathfrak{q} = \left\{ \begin{pmatrix} \bar{a} & \bar{b} \\ 0 & 0 \end{pmatrix} \mid \bar{a}, \bar{b} \in \mathbb{R} \right\}.$$

A convenient basis for \mathfrak{q} is then

$$(4.8) \qquad e_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad e_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix},$$

where we note that

$$(4.9) \qquad [e_1, e_2] = e_2.$$

Let $\alpha: \mathfrak{q} \rightarrow \mathbb{R}$ be the linear map defined by $\alpha(e_1) = 0$ and $\alpha(e_2) = 1$. Then (\mathfrak{q}, α) is a Frobenius Lie algebra. Let $\widetilde{\beta}$ be the left-invariant symplectic form on Q defined by $\widetilde{\beta}_e = \beta$, where $\beta(u, v) := \alpha([u, v])$ for $u, v \in \mathfrak{q}$.

For $\lambda \in \mathbb{R}$, let $\rho_\lambda: \mathfrak{q} \rightarrow \mathfrak{q}$ be the linear isomorphism defined by

$$\rho_\lambda(e_1) := e_1 + \lambda e_2, \quad \rho_\lambda(e_2) := e_2.$$

Then it is a straightforward exercise to show that $\rho_\lambda \in \text{Aut}(\mathfrak{q}, \omega_e)$ and

$$\rho: \mathbb{R} \xrightarrow{\sim} \text{Aut}(\mathfrak{q}, \omega_e), \quad \lambda \mapsto \rho_\lambda$$

is a Lie group isomorphism. Proposition 4.5 implies that (Q, ω) admits the structure of an \mathbb{R} -symplectic Lie group with unique action $\widehat{\rho}: \mathbb{R} \times Q \rightarrow Q$ satisfying $(\widehat{\rho}_\lambda)_{*,e} = \rho_\lambda$.

We now compute the action $\widehat{\rho}$ explicitly. Let $u \in \mathfrak{q}$. Then

$$(4.10) \qquad u = \bar{a}e_1 + \bar{b}e_2 = \begin{pmatrix} \bar{a} & \bar{b} \\ 0 & 0 \end{pmatrix}$$

for some $a, b \in \mathbb{R}$. Using the naturality of the exponential map, we have

$$(4.11) \quad \widehat{\rho}_\lambda \circ \exp(u) = \exp \circ \rho_\lambda(u).$$

A direct calculation shows that

$$(4.12) \quad \exp(u) = \begin{pmatrix} e^{\bar{a}} & \mu(\bar{a})\bar{b} \\ 0 & 1 \end{pmatrix},$$

where $\mu: \mathbb{R} \rightarrow \mathbb{R}_+$ is the nonzero smooth function given by $\mu(t) = \frac{1}{t}(e^t - 1)$ for $t \neq 0$ and $\mu(0) = 1$. Note that every element of Q is in the image of the exponential map. Indeed, given

$$q = \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix}$$

for $a > 0, b \in \mathbb{R}$, one simply sets $\bar{a} = \ln a$ and $\bar{b} = b/\mu(\ln a)$ in (4.12) to obtain $\exp(u) = q$. The left side of (4.11) is

$$(4.13) \quad \exp \circ \rho_\lambda(u) = \exp \begin{pmatrix} \bar{a} & \lambda\bar{a} + \bar{b} \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} e^{\bar{a}} & \mu(\bar{a})(\lambda\bar{a} + \bar{b}) \\ 0 & 1 \end{pmatrix}.$$

Hence,

$$(4.14) \quad \widehat{\rho}_\lambda \begin{pmatrix} e^{\bar{a}} & \mu(\bar{a})\bar{b} \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} e^{\bar{a}} & \mu(\bar{a})(\lambda\bar{a} + \bar{b}) \\ 0 & 1 \end{pmatrix}.$$

Setting $\bar{a} = \ln a$ and $\bar{b} = b/\mu(\ln a)$ for $a > 0$ and $b \in \mathbb{R}$, we obtain

$$(4.15) \quad \widehat{\rho}_\lambda \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} a & \lambda(a - 1) + b \\ 0 & 1 \end{pmatrix}.$$

Since (Q, ω, φ) is an \mathbb{R} -symplectic Lie group by Proposition 4.5, $\widehat{\rho}_\lambda$ is both a Lie group isomorphism and a symplectomorphism of (Q, ω) which satisfies $(\widehat{\rho}_\lambda)_{*,e} = \rho_\lambda$.

In anticipation of the next section, we introduce the following definition:

Definition 4.7. Let (Q, ω, φ) and (R, τ, χ) be G -symplectic Lie groups. A homomorphism of G -symplectic Lie groups from (Q, ω, φ) to (R, τ, χ) is a homomorphism

$$\Psi: (Q, \omega) \rightarrow (R, \tau)$$

of symplectic Lie groups which is also G -equivariant, that is, $\Psi(\varphi_g(q)) = \chi_g(\Psi(q))$ for all $g \in G$ and $q \in Q$.

4.2. The Equivalence. In this section, we show that the category of finite dimensional \mathfrak{g} -quasi-Frobenius Lie algebras is equivalent to the category of simply connected G -symplectic Lie groups, where G is also simply connected. We begin with the following result.

Proposition 4.8. Let $\Psi: (Q, \omega, \varphi) \rightarrow (R, \tau, \chi)$ be a homomorphism of G -symplectic Lie groups. Then

$$\Psi_{*,e}: (\mathfrak{q}, \omega_e, \varphi'') \rightarrow (\mathfrak{r}, \tau_e, \chi'')$$

is a homomorphism of \mathfrak{g} -quasi-Frobenius Lie algebras, where φ'' and χ'' are defined as in Proposition 4.3.

Proof. By definition, $\Psi: (Q, \omega) \rightarrow (R, \tau)$ is a homomorphism of symplectic Lie groups. This implies that

$$\Psi_{*,e}: (\mathfrak{q}, \omega_e) \rightarrow (\mathfrak{r}, \tau_e)$$

is a homomorphism of quasi-Frobenius Lie algebras. It only remains to show that $\Psi_{*,e}$ is \mathfrak{g} -equivariant. Since Ψ is G -equivariant, we have

$$\Psi \circ \varphi_g = \chi_g \circ \Psi, \quad \forall g \in G.$$

This in turn implies that

$$(4.16) \quad \Psi_{*,e} \circ \varphi'_g = \chi'_g \circ \Psi_{*,e}, \quad \forall g \in G,$$

where $\varphi'_g := (\varphi_g)_{*,e}: \mathfrak{q} \rightarrow \mathfrak{q}$ and $\chi'_g := (\chi_g)_{*,e}: \mathfrak{r} \rightarrow \mathfrak{r}$. Let $x \in \mathfrak{g}$ and set $g = \exp(tx)$ in (4.17). Applying $\frac{d}{dt} |_{t=0}$ to both sides then gives

$$(4.17) \quad \Psi_{*,e} \circ \varphi''_x = \chi''_x \circ \Psi_{*,e}.$$

This in turn completes the proof. □

Lemma 4.9. *Let $(\mathfrak{q}, \beta, \phi)$ be a \mathfrak{g} -quasi-Frobenius Lie algebra and let G be the simply connected Lie group whose Lie algebra is \mathfrak{g} . Then there exists a unique Lie group homomorphism $f: G \rightarrow GL(\mathfrak{q})$, $g \mapsto f_g$ such that $f_{*,e} = \phi$ and $f_g \in \text{Aut}(\mathfrak{q}, \beta)$ for all $g \in G$.*

Proof. Since G is simply connected and $\phi: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{q})$ is a Lie algebra map, there exists a unique Lie group homomorphism $f: G \rightarrow GL(\mathfrak{q})$ such that $f_{*,e} = \phi$. We now show that $f_g \in \text{Aut}(\mathfrak{q}, \beta)$ for all $g \in G$. Fix $x \in \mathfrak{g}$. To simplify notation, let

$$(4.18) \quad f_t := f_{\exp(tx)}: \mathfrak{q} \rightarrow \mathfrak{q}.$$

Define $A: \mathbb{R} \times \mathfrak{q} \times \mathfrak{q} \rightarrow \mathbb{R}$ by

$$(4.19) \quad A(t, u, v) := \beta(f_t(u), f_t(v)) - \beta(u, v).$$

Since $f_{*,e} = \phi$ and $(\mathfrak{q}, \beta, \phi)$ is a \mathfrak{g} -quasi-Frobenius Lie algebra, we have

$$(4.20) \quad \frac{d}{dt} |_{t=0} A(t, u, v) = \beta(\phi_x(u), v) + \beta(u, \phi_x(v)) = 0, \quad \forall u, v \in \mathfrak{q}.$$

Furthermore, since f is a group homomorphism and

$$\exp((t + s)x) = \exp(tx) \exp(sx),$$

we have

$$(4.21) \quad A(t + s, u, v) = A(t, f_s(u), f_s(v)) + A(s, u, v), \quad \forall u, v \in \mathfrak{q}.$$

Equations (4.20) and (4.21) imply

$$(4.22) \quad \frac{d}{dt} |_{t=s} A(t, u, v) = \frac{d}{dt} |_{t=0} A(t + s, u, v) = 0 + 0 = 0.$$

Hence, for fixed $u, v \in \mathfrak{q}$, $A(t, u, v)$ is a constant. Since $A(0, u, v) = 0$, it follows that $A(t, u, v) = 0$ for all $t \in \mathbb{R}$. Hence,

$$(4.23) \quad \beta(f_t(u), f_t(v)) = \beta(u, v), \quad \forall t \in \mathbb{R}.$$

In particular,

$$(4.24) \quad \beta(f_{\exp(x)}(u), f_{\exp(x)}(v)) = \beta(u, v).$$

Now define $B: \mathbb{R} \times \mathfrak{q} \times \mathfrak{q} \times \mathfrak{q} \rightarrow \mathfrak{q}$ by

$$(4.25) \quad B(t, u, v, w) = \beta([f_t(u), f_t(v)] - f_t([u, v]), f_t(w)).$$

Equation (4.23) implies that

$$(4.26) \quad B(t, u, v, w) = \beta([f_t(u), f_t(v)], f_t(w)) - \beta([u, v], w).$$

Using (4.26) and the fact that $(\mathfrak{q}, \beta, \phi)$ is a \mathfrak{g} -quasi-Frobenius Lie algebra, we have

$$(4.27) \quad \begin{aligned} \frac{d}{dt} \Big|_{t=0} B(t, u, v, w) &= \beta([\phi_x(u), v], w) + \beta([u, \phi_x(v)], w) + \beta([u, v], \phi_x(w)) \\ &= \beta(\phi_x([u, v]), w) + \beta([u, v], \phi_x(w)) \\ &= 0, \quad \forall u, v, w. \end{aligned}$$

From (4.26), we also have

$$(4.28) \quad \begin{aligned} B(t + s, u, v, w) &= \beta([f_t(f_s(u)), f_t(f_s(v))], f_t(f_s(w))) - \beta([u, v], w) \\ &= B(t, f_s(u), f_s(v), f_s(w)) + \beta([f_s(u), f_s(v)], f_s(w)) - \beta([u, v], w) \end{aligned}$$

Equations (4.27) and (4.28) now imply

$$(4.29) \quad \frac{d}{dt} \Big|_{t=s} B(t, u, v, w) = \frac{d}{dt} \Big|_{t=0} B(t + s, u, v, w) = 0 + 0 + 0 = 0.$$

From (4.29), it follows that for fixed u, v, w , $B(t, u, v, w)$ is a constant for all $t \in \mathbb{R}$. Hence, $B(t, u, v, w) = B(0, u, v, w) = 0$ for all $t \in \mathbb{R}$ and $u, v, w \in \mathfrak{q}$. In particular,

$$(4.30) \quad B(1, u, v, w) = \beta([f_1(u), f_1(v)] - f_1([u, v]), f_1(w)) = 0, \quad \forall u, v, w \in \mathfrak{q}.$$

Since β is non-degenerate and $f_1 := f_{\exp(x)} \in GL(\mathfrak{q})$, it follows that

$$(4.31) \quad f_{\exp(x)}([u, v]) = [f_{\exp(x)}(u), f_{\exp(x)}(v)].$$

Since G is connected, $x \in \mathfrak{g}$ is arbitrary, and f is a group homomorphism, equations (4.24) and (4.31) imply that

$$(4.32) \quad \beta(f_g(u), f_g(v)) = \beta(u, v), \quad f_g([u, v]) = [f_g(u), f_g(v)]$$

for all $g \in G$. Hence, $f_g \in \text{Aut}(\mathfrak{q}, \beta)$ for all $g \in G$. This completes the proof. \square

Proposition 4.10. *Let $(\mathfrak{q}, \beta, \phi)$ be a \mathfrak{g} -quasi-Frobenius Lie algebra. Let G and Q be the simply connected Lie groups associated to \mathfrak{g} and \mathfrak{q} respectively and let $\tilde{\beta} \in \Omega^2(Q)$ be the left-invariant 2-form associated to β . Then there exists a unique left action $\bar{\phi}: G \times Q \rightarrow Q$ such that $(Q, \tilde{\beta}, \bar{\phi})$ is a G -symplectic Lie group whose associated \mathfrak{g} -quasi-Frobenius Lie algebra is*

$$(\mathfrak{q}, \tilde{\beta}_e, \bar{\phi}'') = (\mathfrak{q}, \beta, \phi),$$

where $\bar{\phi}''$ is defined as in Proposition 4.3.

Proof. By Proposition 2.13, $(Q, \tilde{\beta})$ is a symplectic Lie group. Since G is simply connected, Lemma 4.9 shows that there exists a unique Lie group homomorphism

$$f: G \rightarrow GL(\mathfrak{q}), \quad g \mapsto f_g$$

such that $f_{*,e} = \phi: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{q})$ and $f_g \in \text{Aut}(\mathfrak{q}, \beta)$ for all $g \in G$. Since Q is simply connected, Proposition 4.5 shows that there exists a unique smooth left G -action

$$\bar{\phi}: G \times Q \rightarrow Q, \quad (g, q) \mapsto \bar{\phi}_g(q)$$

such that $(Q, \tilde{\beta}, \bar{\phi})$ is a G -symplectic Lie group and $(\bar{\phi}_g)_{*,e} = f_g$. Setting $\bar{\phi}'_g := (\bar{\phi}_g)_{*,e}$ as in Proposition 4.3, we have

$$\bar{\phi}'' := \bar{\phi}'_{*,e} = f_{*,e} = \phi.$$

This completes the proof. □

Proposition 4.11. *Let $\psi: (\mathfrak{q}, \beta, \phi) \rightarrow (\mathfrak{r}, \sigma, \hat{\mu})$ be a homomorphism of \mathfrak{g} -quasi-Frobenius Lie algebras. Let G be the simply connected Lie group whose Lie algebra is \mathfrak{g} and let $(Q, \tilde{\beta}, \bar{\phi})$ and $(R, \tilde{\sigma}, \bar{\mu})$ be the simply connected G -symplectic Lie groups associated to $(\mathfrak{q}, \beta, \phi)$ and $(\mathfrak{r}, \sigma, \mu)$ respectively by Proposition 4.10. Then there exists a unique homomorphism of G -symplectic Lie groups*

$$\hat{\psi}: (Q, \tilde{\beta}, \bar{\phi}) \rightarrow (R, \tilde{\sigma}, \bar{\mu})$$

such that $\hat{\psi}_{*,e} = \psi$.

Proof. By Proposition 2.17, there exists a unique homomorphism of symplectic Lie groups $\hat{\psi}: (Q, \tilde{\beta}) \rightarrow (R, \tilde{\sigma})$ such that $\hat{\psi}_{*,e} = \psi$. We now verify that $\hat{\psi}$ is G -equivariant.

Let $\bar{\phi}' : G \rightarrow \text{Aut}(\mathfrak{q}, \beta)$, $g \mapsto \bar{\phi}'_g$ and $\bar{\mu}' : G \rightarrow \text{Aut}(\mathfrak{r}, \sigma)$, $g \mapsto \bar{\mu}'_g$ be defined as in Proposition 4.3. Fix $x \in \mathfrak{g}$. To simplify notation, let

$$\bar{\phi}'_t := \bar{\phi}'_{\exp(tx)}, \quad \bar{\mu}'_t := \bar{\mu}'_{\exp(tx)}.$$

Define $B: \mathbb{R} \times \mathfrak{q} \times \mathfrak{r} \rightarrow \mathbb{R}$ by

$$\begin{aligned} B(t, u, v) &:= \sigma(\psi \circ \bar{\phi}'_t(u) - \bar{\mu}'_t \circ \psi(u), \bar{\mu}'_t(v)) \\ &= \sigma(\psi \circ \bar{\phi}'_t(u), \bar{\mu}'_t(v)) - \sigma(\bar{\mu}'_t \circ \psi(u), \bar{\mu}'_t(v)) \\ (4.33) \quad &= \sigma(\psi \circ \bar{\phi}'_t(u), \bar{\mu}'_t(v)) - \sigma(\psi(u), v), \end{aligned}$$

where the third equality follows from the fact that $\bar{\mu}'_t \in \text{Aut}(\mathfrak{r}, \sigma)$. Hence,

$$\begin{aligned} \frac{d}{dt} \Big|_{t=0} B(t, u, v) &= \sigma(\psi \circ \phi_x(u), v) + \sigma(\psi(u), \mu_x(v)) \\ &= \sigma(\mu_x \circ \psi(u), v) + \sigma(\psi(u), \mu_x(v)) \\ (4.34) \quad &= 0, \quad \forall u \in \mathfrak{q}, v \in \mathfrak{r} \end{aligned}$$

where the second equality follows from the fact that ψ is \mathfrak{g} -equivariant (i.e., $\psi \circ \phi_x = \mu_x \circ \psi$) and the third equality follows from the fact that $(\mathfrak{r}, \sigma, \mu)$ is a \mathfrak{g} -quasi-Frobenius Lie algebra with 2-cocycle σ and \mathfrak{g} -action μ . Next note that

$$(4.35) \quad B(t + s, u, v) = B(t, \bar{\phi}'_s(u), \bar{\mu}'_s(v)) + \sigma(\psi(\bar{\phi}'_s(u)), \bar{\mu}'_s(v)) - \sigma(\psi(u), v).$$

Hence,

$$(4.36) \quad \frac{d}{dt} \Big|_{t=s} B(t, u, v) = \frac{d}{dt} \Big|_{t=0} B(t + s, u, v) = 0 + 0 - 0 = 0,$$

where the first zero follows from (4.34). Hence,

$$(4.37) \quad B(t, u, v) = B(0, u, v) = 0, \quad \forall t \in \mathbb{R}, u \in \mathfrak{q}, v \in \mathfrak{r}.$$

In particular, $B(1, u, v) = 0$ for all $u, v \in \mathfrak{r}$. Since σ is nondegenerate and $\bar{\mu}'_t: \mathfrak{r} \rightarrow \mathfrak{r}$ is also a linear isomorphism for all t , it follows that

$$(4.38) \quad \psi \circ \bar{\phi}'_t = \bar{\mu}'_t \circ \psi, \quad \forall t \in \mathbb{R}.$$

In particular, we have

$$(4.39) \quad \psi \circ \bar{\phi}'_{\exp(x)} = \bar{\mu}'_{\exp(x)} \circ \psi.$$

Since $x \in \mathfrak{g}$ was arbitrary, (4.39) must hold for all $x \in \mathfrak{g}$. Since G is connected, every element $g \in G$ is of the form $g = \exp(x_1) \dots \exp(x_k)$ for some $x_i \in \mathfrak{g}, i = 1, \dots, k$. It follows from this and the fact that $\bar{\phi}'$ and $\bar{\mu}'$ are group homomorphisms that

$$(4.40) \quad \psi \circ \bar{\phi}'_g = \bar{\mu}'_g \circ \psi, \quad \forall g \in G.$$

Equation (4.40) combined with the fact that (1) Q is connected, (2) $\widehat{\psi} \circ \bar{\phi}_g$ and $\bar{\mu}_g \circ \widehat{\psi}$ are both Lie group homomorphisms $\forall g \in G$, and (3)

$$(4.41) \quad (\widehat{\psi} \circ \bar{\phi}_g)_{*,e} = \psi \circ \bar{\phi}'_g = \bar{\mu}'_g \circ \psi = (\bar{\mu}_g \circ \widehat{\psi})_{*,e}, \quad \forall g \in G$$

imply that $\widehat{\psi} \circ \bar{\phi}_g = \bar{\mu}_g \circ \widehat{\psi}$ for all $g \in G$. In other words, $\widehat{\psi}$ is G -equivariant and this completes the proof. \square

We conclude the paper with the following generalization of Theorem 2.18.

Theorem 4.12. *Let G be a simply connected Lie group and let G -SCSLG be the category of simply connected G -symplectic Lie groups and let \mathfrak{g} -qFLA be the category of finite dimensional \mathfrak{g} -quasi-Frobenius Lie algebras. Let \widehat{F} be the functor from G -SCSLG to \mathfrak{g} -qFLA which sends the object (Q, ω, φ) to $(\mathfrak{q}, \omega_e, \varphi'')$, where φ'' is defined as in Proposition 4.3 and the morphism $\Psi: (Q, \omega, \varphi) \rightarrow (R, \tau, \chi)$ to*

$$\Psi_{*,e}: (\mathfrak{q}, \omega_e, \varphi'') \mapsto (\mathfrak{r}, \tau_e, \chi'').$$

Then \widehat{F} is an equivalence of categories.

Proof. Theorem 4.12 follows from Theorem 2.18, Proposition 4.3, Proposition 4.8, Proposition 4.10, and Proposition 4.11. \square

5. $D(\mathfrak{g})$ -QUASI-FROBENIUS LIE ALGEBRAS

Let (\mathfrak{g}, γ) be a finite dimensional Lie bialgebra. We begin with the following observation:

Proposition 5.1. *Let V be a vector space over k and let $\rho: D(\mathfrak{g}) \rightarrow \mathfrak{gl}(V)$ be a linear map (not necessarily a representation). Define*

$$\varphi := \rho|_{\mathfrak{g}}: \mathfrak{g} \rightarrow \mathfrak{gl}(V), \quad \psi := \rho|_{\mathfrak{g}^*}: \mathfrak{g}^* \rightarrow \mathfrak{gl}(V).$$

The following statements are equivalent.

- (i) ρ is a representation of $D(\mathfrak{g})$ on V .

(ii) φ and ψ are representations of \mathfrak{g} and \mathfrak{g}^* on V which satisfy

$$(5.1) \quad \psi_{ad_x^* \xi} - \varphi_{ad_x^* x} = \varphi_x \circ \psi_\xi - \psi_\xi \circ \varphi_x, \quad \forall x \in \mathfrak{g}, \xi \in \mathfrak{g}^*.$$

Proof. (i) \Rightarrow (ii) Since ρ is a representation of $D(\mathfrak{g})$ on V , it follows immediately that φ and ψ must be representations of \mathfrak{g} and \mathfrak{g}^* on V respectively. For (5.1), we note that

$$[x, \xi] = ad_x^* \xi - ad_\xi^* x \quad \forall x \in \mathfrak{g}, \xi \in \mathfrak{g}^*.$$

Since ρ is a representation and $\varphi := \rho|_{\mathfrak{g}}$ and $\psi := \rho|_{\mathfrak{g}^*}$, we have

$$\psi_{ad_x^* \xi} - \varphi_{ad_x^* x} = \rho_{[x, \xi]} = \rho_x \rho_\xi - \rho_\xi \rho_x = \varphi_x \psi_\xi - \psi_\xi \varphi_x,$$

which proves (5.1).

(i) \Leftarrow (ii) Let $a = x + \xi \in D(\mathfrak{g})$. Then

$$\begin{aligned} \rho_{[x+\xi, y+\eta]} &= \rho_{[x, y]} + \rho_{[x, \eta]} + \rho_{[\xi, y]} + \rho_{[\xi, \eta]} \\ &= \varphi_{[x, y]} + \psi_{ad_x^* \eta} - \varphi_{ad_\eta^* x} + \varphi_{ad_\xi^* y} - \psi_{ad_y^* \xi} + \psi_{[\xi, \eta]} \\ &= \varphi_x \circ \varphi_y - \varphi_y \circ \varphi_x + \varphi_x \circ \psi_\eta - \psi_\eta \circ \varphi_x \\ &\quad + \psi_\xi \circ \varphi_y - \varphi_y \circ \psi_\xi + \psi_\xi \circ \psi_\eta - \psi_\eta \circ \psi_\xi \\ &= (\varphi_x + \psi_\xi) \circ (\varphi_y + \psi_\eta) - (\varphi_y + \psi_\eta) \circ (\varphi_x + \psi_\xi) \\ &= \rho_{x+\xi} \circ \rho_{y+\eta} - \rho_{y+\eta} \circ \rho_{x+\xi}. \end{aligned}$$

This proves that $\rho: D(\mathfrak{g}) \rightarrow \mathfrak{gl}(V)$ is a representation of $D(\mathfrak{g})$ on V . □

Proposition 5.2. *Let (\mathfrak{q}, β) be a quasi-Frobenius Lie algebra and let $\rho: D(\mathfrak{g}) \rightarrow \mathfrak{gl}(\mathfrak{q})$ be a linear map (not necessarily a representation). Define $\varphi := \rho|_{\mathfrak{g}}$ and $\psi := \rho|_{\mathfrak{g}^*}$. Then $(\mathfrak{q}, \beta, \rho)$ is a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra iff the following conditions are satisfied:*

- (a) $\psi_{ad_x^* \xi} - \varphi_{ad_x^* x} = \varphi_x \circ \psi_\xi - \psi_\xi \circ \varphi_x, \quad \forall x \in \mathfrak{g}, \xi \in \mathfrak{g}^*$
- (b) $(\mathfrak{q}, \beta, \varphi)$ is a \mathfrak{g} -quasi-Frobenius Lie algebra.
- (c) $(\mathfrak{q}, \beta, \psi)$ is a \mathfrak{g}^* -quasi-Frobenius Lie algebra.

Proof. By Proposition 5.1, ρ is left $D(\mathfrak{g})$ -module structure on \mathfrak{q} iff φ and ψ are left \mathfrak{g} and \mathfrak{g}^* -module structures on \mathfrak{q} respectively which satisfy condition (a). Since $D(\mathfrak{g}) = \mathfrak{g} \oplus \mathfrak{g}^*$ as a vector space, it follows that $\rho: D(\mathfrak{g}) \rightarrow \mathfrak{gl}(\mathfrak{q})$ satisfies conditions (i) and (ii) of Definition 3.1 iff $\phi: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{q})$ and $\psi: \mathfrak{g}^* \rightarrow \mathfrak{gl}(\mathfrak{q})$ both satisfy conditions (i) and (ii) of Definition 3.1. This completes the proof. □

Proposition 5.3. *Let \mathfrak{g} be a finite dimensional quasitriangular Lie bialgebra with r -matrix $r = \sum_i a_i \otimes b_i$. Let $\varphi: \mathfrak{g} \rightarrow \mathfrak{gl}(V), x \mapsto \varphi(x)$ be a representation of \mathfrak{g} on V . Define $\psi: \mathfrak{g}^* \rightarrow \mathfrak{gl}(V), \xi \mapsto \psi(\xi)$ by*

$$(5.2) \quad \psi(\xi) := \sum_i \xi(a_i) \varphi(b_i), \quad \forall \xi \in \mathfrak{g}^*.$$

Then ψ is a representation of \mathfrak{g}^* on V .

Proof. We need to show that

$$(5.3) \quad \psi([\xi, \eta]) = \psi(\xi)\psi(\eta) - \psi(\eta)\psi(\xi).$$

We now expand the left side of (5.3):

$$\begin{aligned}
 \psi([\xi, \eta]) &= \sum_j [\xi, \eta](a_j) \varphi(b_j) \\
 &= \sum_j (\xi \otimes \eta)((\delta r)(a_j)) \varphi(b_j) \\
 (5.4) \quad &= \sum_{i,j} \xi([a_j, a_i]) \eta(b_i) \varphi(b_j) + \sum_{i,j} \xi(a_i) \eta([a_j, b_i]) \varphi(b_j).
 \end{aligned}$$

The right side of (5.3) expands as

$$\begin{aligned}
 \psi(\xi)\psi(\eta) - \psi(\eta)\psi(\xi) &= \sum_{i,j} \xi(a_i) \eta(a_j) \varphi(b_i) \varphi(b_j) - \sum_{i,j} \eta(a_j) \xi(a_i) \varphi(b_j) \varphi(b_i) \\
 (5.5) \quad &= \sum_{i,j} \xi(a_i) \eta(a_j) \varphi([b_i, b_j]).
 \end{aligned}$$

The CYBE can be rewritten as

$$(5.6) \quad \sum_{i,j} a_i \otimes a_j \otimes [b_i, b_j] = \sum_{i,j} [a_j, a_i] \otimes b_i \otimes b_j + \sum_{i,j} a_i \otimes [a_j, b_i] \otimes b_j.$$

Applying $\xi \otimes \eta \otimes \varphi$ to both sides of (5.6) gives

$$(5.7) \quad \sum_{i,j} \xi(a_i) \eta(a_j) \varphi([b_i, b_j]) = \sum_{i,j} \xi([a_j, a_i]) \eta(b_i) \varphi(b_j) + \sum_{i,j} \xi(a_i) \eta([a_j, b_i]) \varphi(b_j).$$

Equations (5.4), (5.5), and (5.7) imply

$$\psi(\xi)\psi(\eta) - \psi(\eta)\psi(\xi) = \psi([\xi, \eta]).$$

This completes the proof. □

Corollary 5.4. *Let \mathfrak{g} be a finite dimensional quasitriangular Lie bialgebra with r -matrix $r = \sum_i a_i \otimes b_i$ and let $(\mathfrak{q}, \beta, \varphi)$ be a \mathfrak{g} -quasi-Frobenius Lie algebra. Define $\psi: \mathfrak{g}^* \rightarrow \mathfrak{gl}(\mathfrak{q})$, $\xi \mapsto \psi(\xi)$ by*

$$\psi(\xi) := \sum_i \xi(a_i) \varphi(b_i),$$

where $\varphi(b_i) := \varphi_{b_i}: \mathfrak{q} \rightarrow \mathfrak{q}$. Then $(\mathfrak{q}, \beta, \psi)$ is a \mathfrak{g}^* -quasi-Frobenius Lie algebra.

Proof. Immediate. □

Proposition 5.5. *Let \mathfrak{g} be a finite dimensional quasitriangular Lie bialgebra with r -matrix $r = \sum_i a_i \otimes b_i$. Let $\varphi: \mathfrak{g} \rightarrow \mathfrak{gl}(V)$, $x \mapsto \varphi(x)$ be a representation of \mathfrak{g} on V . Define $\psi: \mathfrak{g}^* \rightarrow \mathfrak{gl}(V)$, $\xi \mapsto \psi(\xi)$ according to Proposition 5.3. Define $\rho: D(\mathfrak{g}) \rightarrow \mathfrak{gl}(V)$, $a \mapsto \rho(a)$ by*

$$(5.8) \quad \rho(x + \xi) := \varphi(x) + \psi(\xi), \quad \forall x \in \mathfrak{g}, \xi \in \mathfrak{g}^*.$$

Then ρ is a representation of $D(\mathfrak{g})$ on V .

Proof. By Proposition 5.1, it suffices to show that

$$(5.9) \quad \psi(ad_x^* \xi) - \varphi(ad_\xi^* x) = \varphi(x)\psi(\xi) - \psi(\xi)\varphi(x).$$

We begin by expanding the left side of (5.9). First,

$$(5.10) \quad \begin{aligned} \psi(ad_x^* \xi) &= \sum_i (ad_x^* \xi)(a_i)\varphi(b_i) \\ &= \sum_i \xi([a_i, x])\varphi(b_i). \end{aligned}$$

By Proposition 2.25, $\sum_i a_i \otimes b_i + \sum_i b_i \otimes a_i$ is invariant under the adjoint action of \mathfrak{g} . Hence,

$$(5.11) \quad \sum_i [a_i, x] \otimes b_i = \sum_i a_i \otimes [x, b_i] + \sum_i [x, b_i] \otimes a_i + \sum_i b_i \otimes [x, a_i].$$

Equations (5.10) and (5.11) now imply

$$(5.12) \quad \psi(ad_x^* \xi) = \sum_i \xi(a_i)\varphi([x, b_i]) + \sum_i \xi([x, b_i])\varphi(a_i) + \sum_i \xi(b_i)\varphi([x, a_i]).$$

Next, we note that

$$(5.13) \quad ad_\xi^* x = \sum_i \xi(b_i)[x, a_i] + \sum_i \xi([x, b_i])a_i.$$

From (5.12) and (5.13), we have

$$(5.14) \quad \psi(ad_x^* \xi) - \varphi(ad_\xi^* x) = \sum_i \xi(a_i)\varphi([x, b_i]).$$

For the right side of (5.9), we have

$$(5.15) \quad \begin{aligned} \varphi(x)\psi(\xi) - \psi(\xi)\varphi(x) &= \sum_i \xi(a_i)\varphi(x)\varphi(b_i) - \sum_i \xi(a_i)\varphi(b_i)\varphi(x) \\ &= \sum_i \xi(a_i)\varphi([x, b_i]) \\ &= \psi(ad_x^* \xi) - \varphi(ad_\xi^* x), \end{aligned}$$

where the last equality follows from (5.14). This completes the proof. □

Theorem 5.6. *Let \mathfrak{g} be a finite dimensional quasitriangular Lie bialgebra. Let $(\mathfrak{q}, \beta, \varphi)$ be any \mathfrak{g} -quasi-Frobenius Lie algebra. Then there exists a representation $\rho : D(\mathfrak{g}) \rightarrow \mathfrak{gl}(\mathfrak{q})$ such that $\rho|_{\mathfrak{g}} = \varphi$ and $(\mathfrak{q}, \beta, \rho)$ is a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra.*

Proof. Let $r \in \mathfrak{g} \otimes \mathfrak{g}$ be the r-matrix associated to \mathfrak{g} and let $\psi : \mathfrak{g}^* \rightarrow \mathfrak{gl}(\mathfrak{q})$ be the representation of \mathfrak{g}^* on \mathfrak{q} determined by φ and r according to Proposition 5.3. By Corollary 5.4, $(\mathfrak{q}, \beta, \psi)$ is a \mathfrak{g}^* -quasi-Frobenius Lie algebra. Define $\rho : D(\mathfrak{g}) \rightarrow \mathfrak{gl}(\mathfrak{q})$ by

$$\rho(x + \xi) := \varphi(x) + \psi(\xi), \quad \forall x \in \mathfrak{g}, \xi \in \mathfrak{g}^*.$$

By Proposition 5.5, ρ is a representation of $D(\mathfrak{g})$ on \mathfrak{q} . Since $(\mathfrak{q}, \beta, \varphi)$ and $(\mathfrak{q}, \beta, \psi)$ are \mathfrak{g} and \mathfrak{g}^* -quasi-Frobenius Lie algebras and $\rho|_{\mathfrak{g}} = \varphi$ and $\rho|_{\mathfrak{g}^*} = \psi$ (by definition), it follows that $(\mathfrak{q}, \beta, \rho)$ is a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra. □

Corollary 5.7. *Let \mathfrak{g} be any finite dimensional Lie algebra and let $(\mathfrak{q}, \beta, \varphi)$ be any \mathfrak{g} -quasi-Frobenius Lie algebra. Let $D(\mathfrak{g})$ be the Drinfeld double of the Lie bialgebra (\mathfrak{g}, γ) where $\gamma \equiv 0$. Define $\rho: D(\mathfrak{g}) \rightarrow \mathfrak{gl}(\mathfrak{q})$ by $\rho(x + \xi) = \varphi(x)$ for all $x \in \mathfrak{g}, \xi \in \mathfrak{g}^*$. Then $(\mathfrak{q}, \beta, \rho)$ is a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra.*

Proof. (\mathfrak{g}, γ) is naturally a quasitriangular Lie bialgebra with r-matrix $r \equiv 0 \in \mathfrak{g} \otimes \mathfrak{g}$. Corollary 5.7 now follows as a special case of the proof of Theorem 5.6. \square

We conclude the paper with an example.

Example 5.8. Let (\mathfrak{q}, β) be the 4-dimensional quasi-Frobenius Lie algebra from Example 3.4. For convenience, we recall its structure: \mathfrak{q} has basis $\{e_1, e_2, e_3, e_4\}$ with non-zero commutator relations given by

$$[e_1, e_2] = e_2, \quad [e_1, e_3] = e_3, \quad [e_1, e_4] = 2e_4, \quad [e_2, e_3] = e_4,$$

and the matrix representation of β with respect to $\{e_1, e_2, e_3, e_4\}$ is

$$(\beta_{ij}) = \begin{pmatrix} 0 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ -2 & 0 & 0 & 0 \end{pmatrix}.$$

Let $(\mathfrak{g}, \delta r)$ be the 2-dimensional triangular Lie bialgebra from Examples 2.27 and 2.29. Once again, we recall the structure for convenience. \mathfrak{g} has basis $\{x, y\}$ with commutator relation $[x, y] = x$ and r-matrix $r = y \wedge x$. Let $\{x^*, y^*\}$ denote the corresponding dual basis. The commutator relations on $D(\mathfrak{g})$ are

$$\begin{aligned} [x, y] &= x, & [x^*, y^*] &= y^*, & [x, x^*] &= -y^*, & [x, y^*] &= 0 \\ [y, x^*] &= x^* + y, & [y, y^*] &= -x. \end{aligned}$$

Let $\varphi: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{q})$ be the linear map defined by

$$\begin{aligned} \varphi_x(e_1) &= 0, & \varphi_x(e_2) &= 0, & \varphi_x(e_3) &= e_2, & \varphi_x(e_4) &= 0 \\ \varphi_y(e_1) &= 0, & \varphi_y(e_2) &= -\frac{1}{2}e_2, & \varphi_y(e_3) &= \frac{1}{2}e_3, & \varphi_y(e_4) &= 0. \end{aligned}$$

Consideration of Example 3.4 (or a direct calculation) shows that $(\mathfrak{q}, \beta, \varphi)$ is a \mathfrak{g} -quasi-Frobenius Lie algebra. By Theorem 5.6, there exists a representation $\rho: D(\mathfrak{g}) \rightarrow \mathfrak{gl}(\mathfrak{q})$ such that $\rho|_{\mathfrak{g}} = \varphi$ and $(\mathfrak{q}, \beta, \rho)$ is a $D(\mathfrak{g})$ -quasi-Frobenius Lie algebra. We now compute ρ explicitly. From the proof of Theorem 5.6, this amounts to computing the representation $\psi: \mathfrak{g}^* \rightarrow \mathfrak{gl}(\mathfrak{q})$ which is determined by φ and $r = y \wedge x$ according to Proposition 5.3:

$$\psi_{x^*} = -\varphi_y, \quad \psi_{y^*} = \varphi_x.$$

ρ is then uniquely defined by $\rho|_{\mathfrak{g}} = \varphi$ and $\rho|_{\mathfrak{g}^*} = \psi$.

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