

WARPED PRODUCT SUBMANIFOLDS IN QUATERNION SPACE FORMS

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ABSTRACT. B.Y. Chen [3] established a sharp inequality for the warping function of a warped product submanifold in a Riemannian space form in terms of the squared mean curvature. For a survey on warped product submanifolds we refer to [4].

In [8], we established a similar relationship between the warping function f (intrinsic structure) and the squared mean curvature and the holomorphic sectional curvature (extrinsic structures) for warped product submanifolds $M_1 \times_f M_2$ in any complex space form.

In the present paper, we investigate warped product submanifolds in quaternion space forms $\widetilde{M}^m(4c)$. We obtain several estimates of the mean curvature in terms of the warping function, whether $c < 0$, $c = 0$ and $c > 0$, respectively. Equality cases are considered and certain examples are given.

As applications, we derive obstructions to minimal warped product submanifolds in quaternion space forms. As an example, the non-existence of minimal proper warped product submanifolds $M_1 \times_f M_2$ in the m -dimensional quaternion Euclidean space \mathbf{Q}^m with M_1 compact is proved.

2000 *Mathematics Subject Classification*: 53C40, 53C25, 53C42.

INTRODUCTION

The notion of *warped product* plays some important role in differential geometry as well as in physics [3]. For instance, the best relativistic model of the Schwarzschild space-time that describes the out space around a massive star or a black hole is given as a warped product.

One of the most important problems in the theory of submanifolds is the immersibility (or non-immersibility) of a Riemannian manifold in a Euclidean

¹Supported by the CNCSIS grant 886 / 2005.

space (or, more generally, in a space form). According to a well-known theorem of Nash, every Riemannian manifold can be isometrically immersed in some Euclidean spaces with sufficiently high codimension.

Nash's theorem implies, in particular, that every warped product $M_1 \times_f M_2$ can be immersed as a Riemannian submanifold in a certain Euclidean space. Moreover, many important submanifolds in real, complex and quaternion space forms are expressed as warped products.

Every Riemannian manifold of constant curvature c can be locally expressed as a warped product whose warping function satisfies $\Delta f = cf$. For example, $S^n(1)$ is locally isometric to $(0, \pi) \times_{\cos t} S^{n-1}(1)$, \mathbf{E}^n is locally isometric to $(0, \infty) \times_x S^{n-1}(1)$ and $H^n(-1)$ is locally isometric to $\mathbf{R} \times_{e^x} \mathbf{E}^{n-1}$ (see [4]).

1. PRELIMINARIES

Let \overline{M}^m be a $4m$ -dimensional Riemannian manifold with metric g . \overline{M}^m is called a *quaternion Kaehlerian manifold* if there exists a 3-dimensional vector space E of tensors of type $(1, 1)$ with local basis of almost Hermitian structures ϕ_1, ϕ_2 and ϕ_3 , such that

- (i) $\phi_1\phi_2 = -\phi_2\phi_1 = \phi_3, \phi_2\phi_3 = -\phi_3\phi_2 = \phi_1, \phi_3\phi_1 = -\phi_1\phi_3 = \phi_2,$
- (ii) for any local cross-section ϕ of E and any vector X tangent to \overline{M} , $\overline{\nabla}_X \phi$ is also a cross-section in E (where $\overline{\nabla}$ denotes the Riemannian connection in \overline{M}) or, equivalently, there exist local 1-forms p, q, r such that

$$\overline{\nabla}_X \phi_1 = r(X)\phi_2 - q(X)\phi_3,$$

$$\overline{\nabla}_X \phi_2 = -r(X)\phi_1 + p(X)\phi_3,$$

$$\overline{\nabla}_X \phi_3 = q(X)\phi_1 - p(X)\phi_2.$$

If X is a unit vector in \overline{M} , then $X, \phi_1 X, \phi_2 X$ and $\phi_3 X$ form an orthonormal set on \overline{M} and one denotes by $Q(X)$ the 4-plane spanned by them. For any orthonormal vectors X, Y on \overline{M} , if $Q(X)$ and $Q(Y)$ are orthogonal, the 2-plane $\pi(X, Y)$ spanned by X, Y is called a *totally real plane*. Any 2-plane in $Q(X)$ is called a *quaternionic plane*. The sectional curvature of a quaternionic plane π is called a *quaternionic sectional curvature*. A quaternion Kaehler manifold \overline{M} is a *quaternion space form* if its quaternionic sectional curvatures are constant.

It is well known that a quaternion Kaehlerian manifold \overline{M} is a quaternion space form $\overline{M}(c)$ if and only if its curvature tensor \overline{R} has the following form (see [6])

$$\begin{aligned} \bar{R}(X, Y)Z &= \frac{c}{4}\{g(Y, Z)X - g(X, Z)Y + \\ &+g(\phi_1 Y, Z)\phi_1 X - g(\phi_1 X, Z)\phi_1 Y + 2g(X, \phi_1 Y)\phi_1 Z + \\ &+g(\phi_2 Y, Z)\phi_2 X - g(\phi_2 X, Z)\phi_2 Y + 2g(X, \phi_2 Y)\phi_2 Z + \\ &+g(\phi_3 Y, Z)\phi_3 X - g(\phi_3 X, Z)\phi_3 Y + 2g(X, \phi_3 Y)\phi_3 Z\}, \end{aligned} \quad (1)$$

for vectors X, Y, Z tangent to \bar{M} .

A submanifold M of a quaternion Kaehler manifold \bar{M} is called *quaternion* (resp. *totally real*) submanifold if each tangent space of M is carried into itself (resp. the normal space) by each section in E .

The curvature tensor R of M is related to the curvature tensor \bar{R} of \bar{M} by the Gauss equation

$$\bar{R}(X, Y, Z, W) = R(X, Y, Z, W) - g(h(X, Z), h(Y, W)) + g(h(X, W), h(Y, Z)), \quad (2)$$

where h is the second fundamental form of M .

DEFINITION [1]. *A submanifold M of a quaternion Kaehler manifold \bar{M} is called a quaternion CR-submanifold if there exist two orthogonal complementry distributions D and D^\perp such that D is invariant under quaternion structures, that is, $\phi_i(D_x) \subseteq D_x$, $i = 1, 2, 3, \forall x \in M$, and D^\perp is totally real, that is, $\phi_i(D_x^\perp) \subseteq T_x^\perp M$, $i = 1, 2, 3, \forall i = 1, 2, 3$.*

A submanifold M of a quaternion Kaehler manifold \bar{M} is a quaternion submanifold (resp. totally real submanifold) if $\dim D^\perp = 0$ (resp. $\dim D = 0$).

For any vector field X tangent to M , we put

$$\phi_i X = P_i X + F_i X, \quad i = 1, 2, 3. \quad (3)$$

where $P_i X$ (resp. $F_i X$) denotes tangential (resp. normal) component of $\phi_i X$.

Let M be an n -dimensional submanifold in a quaternion space form $\bar{M}(c)$. Let ∇ be the Riemannian connection of M , h the second fundamental form and R the Riemann curvature tensor of M .

Let $p \in M$ and let $\{e_1, \dots, e_n, \dots, e_{4m}\}$ be an orthonormal basis of the tangent space $T_p\overline{M}$, such that e_1, \dots, e_n are tangent to M at p . One denotes by H the mean curvature vector, that is

$$H(p) = \frac{1}{n} \sum_{i=1}^n h(e_i, e_i). \quad (4)$$

For a differentiable function f on M , the Laplacian Δf of f is defined by

$$\Delta f = \sum_{j=1}^n \{(\nabla_{e_j} e_j) f - e_j e_j f\}. \quad (5)$$

We recall the following result of Chen for later use.

LEMMA 1. [2]. Let $n \geq 2$ and a_1, \dots, a_n, b real numbers such that

$$\left(\sum_{i=1}^n a_i \right)^2 = (n-1) \left(\sum_{i=1}^n a_i^2 + b \right).$$

Then $2a_1 a_2 \geq b$, with equality holding if and only if

$$a_1 + a_2 = a_3 = \dots = a_n.$$

Let M be a quaternion CR-submanifold of a quaternion space form $\overline{M}(c)$. Then from Gauss equation one derives

$$\begin{aligned} R(X, Y, Z, W) &= \frac{c}{4} \{g(Y, Z)g(X, W) - g(X, Z)g(Y, W) + \\ &+ \sum_{i=1}^3 [g(P_i Y, Z)g(P_i X, W) - g(P_i X, Z)g(P_i Y, W) + 2g(X, P_i Y)g(P_i Z, W)]\} \\ &+ g(h(X, W), h(Y, Z)) - g(h(X, Z), h(Y, W)). \end{aligned}$$

for any vector fields X, Y, Z, W tangent to M .

2. WARPED PRODUCT SUBMANIFOLDS

Chen established a sharp relationship between the warping function f of a warped product $M_1 \times_f M_2$ isometrically immersed in a real space form $\widetilde{M}(c)$ and the squared mean curvature $\|H\|^2$ (see [3]). In [8], we gave a corresponding relationship between the warping function f (intrinsic structure) and the

squared mean curvature and the holomorphic sectional curvature (extrinsic structures) for warped product submanifolds $M_1 \times_f M_2$ in any complex space form.

Let (M_1, g_1) and (M_2, g_2) be two Riemannian manifolds and f a positive differentiable function on M_1 . The *warped product* of M_1 and M_2 is the Riemannian manifold

$$M_1 \times_f M_2 = (M_1 \times M_2, g),$$

where $g = g_1 + f^2 g_2$ (see, for instance, [3]).

Let $x : M_1 \times_f M_2 \rightarrow \overline{M}(c)$ be an isometric immersion of a warped product $M_1 \times_f M_2$ into a quaternion space form $\overline{M}(c)$. We denote by h the second fundamental form of x and $H_i = \frac{1}{n_i} \text{trace } h_i$, where $\text{trace } h_i$ is the trace of h restricted to M_i and $n_i = \dim M_i$ ($i = 1, 2$). The vector fields H_i are called *partial mean curvatures*.

For a warped product $M_1 \times_f M_2$, we denote by \mathcal{D}_1 and \mathcal{D}_2 the distributions given by the vectors tangent to leaves and fibres, respectively. Thus, \mathcal{D}_1 is obtained from the tangent vectors of M_1 via the horizontal lift and \mathcal{D}_2 by tangent vectors of M_2 via the vertical lift.

Let $M_1 \times_f M_2$ be a warped product submanifold into a quaternion space form $\overline{M}(c)$.

Since $M_1 \times_f M_2$ is a warped product, it is known that

$$\nabla_X Z = \nabla_Z X = \frac{1}{f}(Xf)Z, \quad (6)$$

for any vector fields X, Z tangent to M_1, M_2 , respectively.

If X and Z are unit vector fields, it follows that the sectional curvature $K(X \wedge Z)$ of the plane section spanned by X and Z is given by

$$K(X \wedge Z) = g(\nabla_Z \nabla_X X - \nabla_X \nabla_Z X, Z) = \frac{1}{f}\{(\nabla_X X)f - X^2 f\}. \quad (7)$$

Using the above Lemma and the Gauss equation (see [9]), one gets the following.

LEMMA 2. *Let $x : M_1 \times_f M_2 \rightarrow \overline{M}(c)$ be an isometric immersion of an n -dimensional warped product into a $4m$ -dimensional quaternion space form $\overline{M}(c)$. Then*

$$n_2 \frac{\Delta f}{f} \leq \frac{n^2}{4} \|H\|^2 + n_1 n_2 \frac{c}{4} + 3 \frac{c}{4} \sum_{\alpha=1}^3 \sum_{i=1}^{n_1} \sum_{s=n_1+1}^n g^2(P_\alpha e_i, e_s), \quad (8)$$

where Δ is the Laplacian operator of M_1 .

We distinguish the following cases:

THEOREM 1. *Let $x : M_1 \times_f M_2 \rightarrow \overline{M}(c)$ be an isometric immersion of an n -dimensional warped product into a $4m$ -dimensional quaternion space form $\overline{M}(c)$ with $c < 0$. Then*

$$\frac{\Delta f}{f} \leq \frac{n^2}{4n_2} \|H\|^2 + n_1 \frac{c}{4}.$$

Moreover, the equality case holds identically if and only if x is a mixed totally geodesic immersion, $n_1 H_1 = n_2 H_2$ and $\phi_k \mathcal{D}_1 \perp \mathcal{D}_2$, for any $k = 1, 2, 3$.

As applications, one derives certain obstructions to the existence of minimal warped product submanifolds in quaternion hyperbolic space.

COROLLARY 1.1. *If f is a harmonic function on M_1 , then the warped product $M_1 \times_f M_2$ does not admit any isometric minimal immersion into a quaternion hyperbolic space.*

COROLLARY 1.2. *There do not exist minimal warped product submanifolds in a quaternion hyperbolic space with M_1 compact.*

THEOREM 2. *Let $x : M_1 \times_f M_2 \rightarrow \overline{M}(c)$ be an isometric immersion of an n -dimensional warped product into a $4m$ -dimensional flat quaternion space form. Then*

$$\frac{\Delta f}{f} \leq \frac{n^2}{4n_2} \|H\|^2.$$

Moreover, the equality case holds identically if and only if x is a mixed totally geodesic immersion and $n_1 H_1 = n_2 H_2$.

COROLLARY 2.1. *If f is an eigenfunction of Laplacian on M_1 with corresponding eigenvalue $\lambda > 0$, then the warped product $M_1 \times_f M_2$ does not admit any isometric minimal immersion into a quaternion hyperbolic space or a quaternion Euclidean space.*

A warped product is said to be proper if the warping function is non-constant.

COROLLARY 2.2. *There do not exist minimal proper warped product submanifold in the quaternion Euclidean space \mathbf{Q}^m with M_1 compact.*

THEOREM 3. *Let $x : M_1 \times_f M_2 \rightarrow \overline{M}(c)$ be an isometric immersion of an n -dimensional warped product into a $4m$ -dimensional quaternion space form $\overline{M}(c)$ with $c > 0$. Then*

$$\frac{\Delta f}{f} \leq \frac{n^2}{4n_2} \|H\|^2 + n_1 \frac{c}{4} + 3 \frac{c}{4} \min\left\{\frac{n_1}{n_2}, 1\right\}.$$

Moreover, the equality case holds identically if and only if x is a mixed totally geodesic immersion, $n_1 H_1 = n_2 H_2$ and $\phi_k \mathcal{D}_1 \perp \mathcal{D}_2$, for any $k = 1, 2, 3$.

Also, Lemma 2 implies another inequality for certain submanifolds (in particular quaternion CR-submanifolds) in quaternion space forms with $c > 0$.

THEOREM 4. *Let $x : M_1 \times_f M_2 \rightarrow \overline{M}(c)$ be an isometric immersion of an n -dimensional warped product into a $4m$ -dimensional quaternion space form $\overline{M}(c)$ with $c > 0$, such that $\phi_k \mathcal{D}_1 \perp \mathcal{D}_2$, for any $k = 1, 2, 3$. Then*

$$\frac{\Delta f}{f} \leq \frac{n^2}{4n_2} \|H\|^2 + n_1 \frac{c}{4}.$$

Moreover, the equality case holds identically if and only if x is a mixed totally geodesic immersion and $n_1 H_1 = n_2 H_2$.

Next, we will give some examples which satisfy identically the equality case of the inequality given in Theorem 4.

EXAMPLE 1. *Let $\psi : S^n \rightarrow S^{4n+3}$ be an immersion defined by*

$$\psi(x^1, \dots, x^{n+1}) = (x^1, 0, 0, 0, x^2, 0, 0, 0, \dots, x^{n+1}, 0, 0, 0),$$

and $\pi : S^{4n+3} \rightarrow P^n(\mathbf{Q})$ the Hopf submersion.

Then $\pi \circ \psi : S^n \rightarrow P^n(\mathbf{Q})$ satisfies the equality case.

EXAMPLE 2. *On $S^{n_1+n_2}$ let consider the spherical coordinates $u_1, \dots, u_{n_1+n_2}$ and on S^{n_1} the function*

$$f(u_1, \dots, u_n) = \cos u_1 \dots \cos u_{n_1},$$

(f is an eigenfunction of Δ).

Then $S^{n_1+n_2} = S^{n_1} \times_f S^{n_2}$.

Let $\psi : S^{n_1+n_2} \rightarrow S^{4(n_1+n_2)+3}$ be the above standard immersion and π the Hopf submersion $\pi : S^{4(n_1+n_2)+3} \rightarrow P^{n_1+n_2}(\mathbf{Q})$.

Then $\pi \circ \psi : S^{n_1+n_2} \rightarrow P^{n_1+n_2}(\mathbf{Q})$ satisfies the equality case.

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