

Ricci solitons on QR-hypersurfaces of a quaternionic space form \mathbb{Q}^n

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Abstract. The purpose of this paper is to study Ricci solitons on QR-hypersurfaces M of a quaternionic space form \mathbb{Q}^n such that the shape operator A with respect to N has one eigenvalue. We prove that Ricci soliton on QR-hypersurfaces M with eigenvalue zero is steady and for eigenvalue nonzero is shrinking.

1 Introduction

A Ricci soliton is defined on a Riemannian manifold (M, g) by

$$\frac{1}{2}\mathcal{L}_V g + \text{Ric} - \lambda g = 0 \quad (1)$$

where $\mathcal{L}_V g$ is the Lie-derivative of the metric tensor g with respect to V and λ is a constant on M . The Ricci soliton is a natural generalization of an Einstein metric. The Ricci soliton is said to be shrinking, steady and expanding according as $\lambda > 0$, $\lambda = 0$ and $\lambda < 0$, respectively. Compact Ricci solitons are the fixed points of the Ricci flow:

$$\frac{\partial}{\partial t} g(t) = -2\text{Ric}(g(t)) \quad (2)$$

2010 Mathematics Subject Classification: 53C25, 53C15, 53C40

Key words and phrases: Ricci soliton, quaternionic space form, QR-hypersurfaces

projected from the space of metrics onto its quotient modulo diffeomorphisms and scalings and often arise as blow-up limits for the Ricci flow on compact manifolds. We denote a Ricci soliton by $(M, g, V; \lambda)$ and call the vector field V the potential vector field of the Ricci soliton. A trivial Ricci soliton is one for which V is Killing or zero. If its potential vector field $V = \nabla f$ such that f is some smooth function on M then a Ricci soliton $(M, g, V; \lambda)$ is called a gradient Ricci soliton and the smooth function f is called the potential function. It was proved by Grigory Perelman in [15] that any compact Ricci soliton is the sum of a gradient of some smooth function f up to the addition of a Killing field. Thus compact Ricci solitons are gradient Ricci solitons. In particular, Perelman applied Ricci solitons to solve the long standing Poincare conjecture posed in 1904.

Hamilton [7] and Ivey [10] proved that a Ricci soliton on a compact manifold has constant curvature in dimension 2 and 3, respectively. In [11], Ki proved that there are no real hypersurfaces with parallel Ricci tensor in a complex space form $\widetilde{M}^n(c)$ with $c \neq 0$ when $n \geq 3$. Kim [12] proved that when $n = 2$, this is also true. In particular, these results give that there is not any Einstein real hypersurfaces in a non-flat complex space form.

In [13], Chen studied important results on Ricci solitons which occur obviously on some Riemannian submanifolds. He presented several recent new criterions of trivial compact shrinking Ricci solitons.

Cho and Kimura [3] studied on Ricci solitons of real hypersurfaces in a non-flat complex space form and showed that a real hypersurface M in a non-flat complex space form $\widetilde{M}^n(c \neq 0)$ does not admit a Ricci soliton such that the Reeb vector field ξ is potential vector field. They defined so called η -Ricci soliton, such that satisfies

$$\frac{1}{2}\mathcal{L}_V g + \text{Ric} - \lambda g - \mu \eta \otimes \eta = 0 \quad (3)$$

where λ, μ are constants. They first proved that a real hypersurface M of a non-flat complex space form $\widetilde{M}^n(c)$ which accepts an η -Ricci soliton is a Hopf-hypersurface and classified that η -Ricci soliton real hypersurfaces in a non-flat complex space form.

We study Ricci solitons on QR-hypersurfaces M of a quaternionic space form \mathbb{Q}^n such that the shape operator A with respect to N has one eigenvalues. We prove that Ricci soliton on QR- hypersurfaces M with eigenvalue zero is steady and for eigenvalue nonzero is shrinking.

2 Preliminaries

Let \overline{M} be a real $(n + p)$ -dimensional quaternionic Kähler manifold. Then, by definition, there is a 3-dimensional vector bundle V consisting with tensor fields of type $(1, 1)$ over \overline{M} satisfying the following conditions (a), (b) and (c): (a) In any coordinate neighborhood \overline{U} , there is a local basis $\{F, G, H\}$ of V such that

$$\begin{aligned} F^2 &= -I, & G^2 &= -I, & H^2 &= -I, \\ FG &= -GF = H, & MG &= -HG = F, & HF &= -FH = G. \end{aligned} \quad (4)$$

(b) There is a Riemannian metric g which is hermite with respect to all of F, G and H .

(c) For the Riemannian connection $\overline{\nabla}$ with respect to g

$$\begin{pmatrix} \overline{\nabla}F \\ \overline{\nabla}G \\ \overline{\nabla}H \end{pmatrix} = \begin{pmatrix} 0 & r & -q \\ -r & 0 & p \\ q & -p & 0 \end{pmatrix} \begin{pmatrix} F \\ G \\ H \end{pmatrix} \quad (5)$$

where p, q and r are local 1-forms defined in \overline{U} . Such a local basis $\{F, G, H\}$ is called a canonical local basis of the bundle V in \overline{U} [9].

For canonical local basis $\{F, G, H\}$ and $\{F', G', H'\}$ of V in coordinate neighborhoods of \overline{U} and \overline{U}' , it follows that in $\overline{U} \cap \overline{U}'$

$$\begin{pmatrix} F' \\ G' \\ H' \end{pmatrix} = (s_{xy}) \begin{pmatrix} F \\ G \\ H \end{pmatrix} \quad (x, y = 1, 2, 3)$$

where s_{xy} are local differentiable functions with $(s_{xy}) \in SO(3)$ as a consequence of (4). As is well known [9], every quaternionic Kähler manifold is orientable. Let \overline{M} be quaternion Kaehler manifold and M be a real submanifold of \overline{M} . Then, M is said QR-submanifold if there exists a vector subbundle ν of the normal bundle such that we have

$$\begin{aligned} F\nu_x &= \nu_x, & G\nu_x &= \nu_x, & H\nu_x &= \nu_x, \\ F\nu_x^\perp &, & G\nu_x^\perp &, & H\nu_x^\perp &\subset T_x M, \end{aligned}$$

for $x \in M$, where ν^\perp is the complementary orthogonal bundle to ν in TM^\perp . We denote by D the complementary orthogonal distribution to D^\perp in TM . Then D is invariant with respect to the action of $\{F, G, H\}$ i.e. we have

$$\begin{aligned} FD_x &= D_x, & GD_x &= D_x, & HD_x &= D_x, \\ FD_x^\perp &, & GD_x^\perp &, & HD_x^\perp &\subset T_x^\perp M, \end{aligned}$$

for any $x \in M$, where $TM = D \oplus D^\perp$ and $TM^\perp = \nu \oplus \nu^\perp$. D is called quaternion distribution.

Now let M be an n -dimensional QR-submanifold of maximal QR-dimension, that is, of $(p-1)$ QR-dimension isometrically immersed in \overline{M} . Then by definition there is a unit normal vector field N such that $\nu_x^\perp = \text{span}\{N\}$ at each point x in M . We set

$$FN = -U, \quad GN = -V, \quad HN = -W. \quad (6)$$

Denoting by D_x the maximal quaternionic invariant subspace

$$T_x M \cap FT_x M \cap GT_x M \cap HT_x M,$$

of $T_x M$, we have $D_x^\perp \supset \text{Span}\{U, V, W\}$, where D_x^\perp means the complementary orthogonal subspace to D_x in $T_x M$. But, using (4), we can prove that $D_x^\perp = \text{Span}\{U, V, W\}$ [13]. Thus we have

$$T_x M = D_x \oplus \text{Span}\{U, V, W\}, \quad \forall x \in M,$$

which together with (4) and (6) imply

$$FT_x M, GT_x M, HT_x M \subset T_x M \oplus \text{Span}\{\xi\}.$$

Therefore, for any tangent vector field X and for a local orthonormal basis $\{N_\alpha\}_{\alpha=1, \dots, p}$ ($N_1 := N$) of normal vectors to M , we have

$$FX = \varphi X + u(X)N, \quad GX = \psi X + v(X)N, \quad HX = \theta X + \omega(X)N, \quad (7)$$

$$\begin{aligned} FN_\alpha &= -U_\alpha + P_1 N_\alpha, & GN_\alpha &= -V_\alpha + P_2 N_\alpha, \\ HN_\alpha &= -W_\alpha + P_3 N_\alpha, & (\alpha &= 1, \dots, p). \end{aligned} \quad (8)$$

Then it is easily seen that $\{\varphi, \psi, \theta\}$ and $\{P_1, P_2, P_3\}$ are skew-symmetric endomorphisms acting on $T_x M$ and $T_x M^\perp$, respectively.

Moreover, the hermitian property of $\{F, G, H\}$ implies

$$\begin{aligned} g(X, \varphi U_\alpha) &= -u(X)g(N_1, P_1 N_\alpha), \\ g(X, \psi V_\alpha) &= -v(X)g(N_1, P_2 N_\alpha), \\ g(X, \theta W_\alpha) &= -w(X)g(N_1, P_3 N_\alpha), \quad (\alpha = 1, \dots, p). \end{aligned} \quad (9)$$

Also, from the hermitian properties

$$\begin{aligned} g(FX, N_\alpha) &= -g(X, FN_\alpha), & g(GX, N_\alpha) &= -g(X, GN_\alpha), \\ g(HX, N_\alpha) &= -g(X, HN_\alpha), & (\alpha &= 1, \dots, p). \end{aligned}$$

It follows that

$$g(X, U_\alpha) = u(X)\delta_{1\alpha}, \quad g(X, V_\alpha) = v(X)\delta_{1\alpha}, \quad g(X, W_\alpha) = w(X)\delta_{1\alpha},$$

and hence

$$\begin{aligned} g(X, U_1) &= u(X), \quad g(X, V_1) = v(X), \quad g(X, W_1) = w(X), \\ U_\alpha &= 0, \quad V_\alpha = 0, \quad W_\alpha = 0, \quad (\alpha = 2, \dots, p). \end{aligned} \quad (10)$$

On the other hand, comparing (6) and (8) with $\alpha = 1$, we have $U_1 = U$, $V_1 = V$, $W_1 = W$, which together with (6) and (10) imply

$$\begin{aligned} g(X, U) &= u(X), & g(X, V) &= v(X), & g(X, W) &= w(X), \\ u(U) &= 1, & v(V) &= 1, & w(W) &= 1, \\ FN &= -U, & GN &= -V, & HN &= -W \\ FN_{\alpha=P_1 N_\alpha} &, & GN_{\alpha=P_2 N_\alpha} &, & HN_{\alpha=P_3 N_\alpha}, & (\alpha = 2, \dots, p). \end{aligned}$$

from which, taking account of the skew-symmetry of P_1, P_2 and P_3 and using (9), we also have

$$\begin{aligned} u(\varphi X) &= 0, & v(\psi X) &= 0, & w(\theta X) &= 0, \\ \varphi U &= 0, & \psi V &= 0, & \theta W &= 0, \\ P_1 N &= 0, & P_2 N &= 0, & P_3 N &= 0, \end{aligned} \quad (11)$$

From the equations of (6), we also have

$$\begin{aligned} \psi U &= -W, & v(U) &= 0, & \theta U &= V, & w(U) &= 0, \\ \varphi V &= W, & u(V) &= 0, & \theta V &= -U, & w(V) &= 0, \\ \varphi W &= -V, & u(W) &= 0, & \psi W &= U, & v(W) &= 0. \end{aligned} \quad (12)$$

Now, let ∇ be the Levi-Civita connection on M and ∇^\perp the normal connection induced from $\bar{\nabla}$ in the normal bundle TM^\perp of M . The Gauss and Weingarten formula are given by

$$\begin{aligned} \bar{\nabla}_X Y &= \nabla_X Y + h(X, Y), \\ \bar{\nabla}_X N_\alpha &= -A_\alpha X + \nabla_X^\perp N_\alpha, \quad (\alpha = 1, \dots, p), \end{aligned} \quad (13)$$

for any $X, Y \in \chi(M)$ and $N_\alpha \in \Gamma^\infty(TM^\perp)$, $(\alpha = 1, \dots, p)$. h is the second fundamental form and A_α are shape operator corresponding to N_α .

Next, differentiating the equations of (6) covariantly and comparing the tangential and normal parts, we have

$$\begin{aligned}\nabla_Y U &= r(Y)V - q(Y)W + \varphi A_1 Y, \\ \nabla_Y V &= -r(Y)U + p(Y)W + \psi A_1 Y, \\ \nabla_Y W &= q(Y)U - p(Y)V + \theta A_1 Y,\end{aligned}\tag{14}$$

For QR-hypersurfaces M in a quaternionic space form \overline{M} of quaternionic sectional curvature $4k$ the Gauss and Codazzi equations are written as follow:

$$\begin{aligned}g(R(X, Y)Z, W) &= k\{g(Y, Z)X - g(X, Z)Y \\ &\quad + g(\varphi Y, Z)\varphi X - g(\varphi X, Z)\varphi Y - 2g(\varphi X, Y)\varphi Z \\ &\quad + g(\psi Y, Z)\psi X - g(\psi X, Z)\psi Y - 2g(\psi X, Y)\psi Z \\ &\quad + g(\theta Y, Z)\theta X - g(\theta X, Z)\theta Y - 2g(\theta X, Y)\theta Z\} \\ &\quad + g(AY, Z)AX - g(AX, Z)AY,\end{aligned}\tag{15}$$

$$\begin{aligned}(\nabla_X A)Y - (\nabla_Y A)X &= k\{u(X)\varphi Y - u(Y)\varphi X - 2g(\varphi X, Y)U \\ &\quad + v(X)\psi Y - v(Y)\psi X - 2g(\psi X, Y)V \\ &\quad + w(X)\theta Y - w(Y)\theta X - 2g(\theta X, Y)W\},\end{aligned}\tag{16}$$

hence the Ricci tensor is obtained as

$$\begin{aligned}\text{Ric}(X, Y) &= k\{(4n + 7)g(X, Y) - 3\{u(X)u(Y) + v(X)v(Y) + w(X)w(Y)\}\} \\ &\quad + (\text{trace } A)g(AX, Y) - g(AX, AY).\end{aligned}\tag{17}$$

for any tangent vector fields X, Y, Z on M , where R and Ric are the curvature and Ricci tensors of M , respectively.

3 Ricci soliton on QR hypersurfaces

Let M be a QR-hypersurface of a quaternionic space form \overline{M} such that the shape operator A for unit normal vector field N has only one eigenvalue and let $\{e_1, \dots, e_{4n-4}, U, V, W\}$ be a local orthonormal frame field such that $D^\perp = \text{span}\{U, V, W\}$ and $D = \text{span}\{e_1, \dots, e_{n-1}, e_n = \varphi e_1, \dots, e_{2n-2} = \varphi e_{n-1}, e_{2n-1} = \psi e_1, \dots, e_{3n-3} = \psi e_{n-1}, e_{3n-2} = \theta e_1, \dots, e_{4n-4} = \theta e_{n-1}\}$.

We first prove

Theorem 1 *If the shape operator A with respect to unit normal vector field N of M has only one eigenvalue, then \overline{M} is a quaternionic Euclidean space.*

Proof. According to the assumption, it follows that $A = 0$ or $AX = \alpha X$ for all $X \in T(M)$.

In both cases the Codazzi equation (16), we obtain

$$\begin{aligned} (X\alpha)Y - (Y\alpha)X &= k\{u(X)\varphi Y - u(Y)\varphi X - 2g(\varphi X, Y)U \\ &\quad + v(X)\psi Y - v(Y)\psi X - 2g(\psi X, Y)V \\ &\quad + w(X)\theta Y - w(Y)\theta X - 2g(\theta X, Y)W\}, \end{aligned} \quad (18)$$

for all $X, Y \in TM$. Putting $Y = U$, the equation (21) reduces to

$$(X\alpha)U - (U\alpha)X = k[-\varphi X + v(X)W - w(X)V], \quad (19)$$

also by putting $Y = V$ and $Y = W$, we have

$$\begin{aligned} (X\alpha)V - (V\alpha)X &= k[-\psi X + w(X)U - u(X)W], \\ (X\alpha)W - (W\alpha)X &= k[-\theta X + u(X)V - v(X)U]. \end{aligned} \quad (20)$$

since $\dim M \geq 7$, we can use $X, \varphi X, \psi X, \theta X, U, V$ and W in such a way that they are linearly independent and thus $k = 0$. \square

Let $AX = \alpha X$, therefore by the relation (17), we obtain

$$\begin{aligned} \text{Ric}(e_i, e_j) &= \{(4n-2)\alpha^2\}\delta_{ij}, & (i, j = 1, \dots, 4n-4), \\ \text{Ric}(U, U) &= (4n-2)\alpha^2, \\ \text{Ric}(V, V) &= (4n-2)\alpha^2, \\ \text{Ric}(W, W) &= (4n-2)\alpha^2, \\ \text{Ric}(U, V) &= 0, \\ \text{Ric}(U, W) &= 0, \\ \text{Ric}(W, V) &= 0, \\ \text{Ric}(e_i, U) &= 0, \\ \text{Ric}(e_i, V) &= 0, \\ \text{Ric}(e_i, W) &= 0, & (i = 1, \dots, 4n-4). \end{aligned} \quad (21)$$

We consider QR-hypersurface M of a quaternionic space form \mathbb{Q}^n satisfying Ricci soliton equation

$$\frac{1}{2}\mathcal{L}_{\tilde{V}}g + \text{Ric} - \lambda g = 0 \quad (22)$$

with respect to potential vector field \tilde{V} on M for constant λ .

First Put

$$\tilde{V} := fU, \quad (f : M \rightarrow \mathbb{R}, f \neq 0) \quad (23)$$

Then definition of the Lie derivative and the first relation (14) imply

$$\begin{aligned} (\mathcal{L}_{fU}g)(X, Y) &= df(X)u(Y) + df(Y)u(X) \\ &\quad + f\{r(X)v(Y) - q(X)w(Y) + r(Y)v(X) - q(Y)w(X) \\ &\quad + g((\varphi A - A\varphi)Y, X)\} \end{aligned} \quad (24)$$

We compute

$$\begin{aligned} (\mathcal{L}_{fU}g)(U, U) &= 2df(U), \\ (\mathcal{L}_{fU}g)(V, V) &= 2fr(V), \\ (\mathcal{L}_{fU}g)(W, W) &= -2fq(W), \\ (\mathcal{L}_{fU}g)(U, V) &= df(V) + fr(U), \\ (\mathcal{L}_{fU}g)(U, W) &= df(W) - fq(U), \\ (\mathcal{L}_{fU}g)(W, V) &= f\{-q(V) + r(W)\}, \\ (\mathcal{L}_{fU}g)(U, e_i) &= df(e_i), \\ (\mathcal{L}_{fU}g)(V, e_i) &= fr(e_i), \\ (\mathcal{L}_{fU}g)(W, e_i) &= -fq(e_i), \quad (i = 1, \dots, 4n - 4), \\ (\mathcal{L}_{f\xi}g)(e_i, e_j) &= 0 \quad (i, j = 1, \dots, 4n - 4). \end{aligned} \quad (25)$$

Using relations (21) and (25), Ricci soliton equation (22) is equivalent to

$$\begin{aligned} df(U) &= \lambda - (4n - 2)\alpha^2, \\ fr(V) &= \lambda - (4n - 2)\alpha^2, \\ fq(W) &= -\lambda + (4n - 2)\alpha^2, \\ df(V) &= -fr(U), \\ df(W) &= fq(U), \\ q(V) &= r(W), \\ df(e_i) &= 0, \quad (i = 1, \dots, 4n - 4), \\ r(e_i) &= 0, \\ q(e_i) &= 0, \\ \{(4n - 2)\alpha^2 - \lambda\}\delta_{ij} &= 0, \quad (i, j = 1, \dots, 4n - 4). \end{aligned} \quad (26)$$

By the last relation (26), we have $\lambda = (4n - 2)\alpha^2$ and thus the following theorem holds:

Theorem 2 *Let M be a QR-hypersurface of quaternionic space form \mathbb{Q}^n with $AX = \alpha X$. Then a Ricci soliton $(M, g, \tilde{V}, \lambda)$ with potential vector field $\tilde{V} := fU$ is shrinking Ricci soliton.*

Now, let $A = 0$, using relation (17), it follows that

$$\text{Ric} = 0 \quad (27)$$

QR-hypersurface M ($n \geq 2$) is considered in a quaternionic space form \mathbb{Q}^n satisfying Ricci soliton equation.

By relations (27) and (25), Ricci soliton equation (22) is equivalent to

$$\begin{aligned} df(U) &= \lambda, \\ fr(V) &= \lambda, \\ fq(W) &= -\lambda, \\ df(V) &= -fr(U), \\ df(W) &= fq(U), \\ q(V) &= r(W), \\ df(e_i) &= 0, \quad (i = 1, \dots, 4n - 4), \\ r(e_i) &= 0, \\ q(e_i) &= 0, \\ \lambda \delta_{ij} &= 0, \quad (i, j = 1, \dots, 4n - 4). \end{aligned} \quad (28)$$

Using the last relation (28), it follows $\lambda = 0$ and hence

Theorem 3 *Let M be a QR-hypersurface of quaternionic space form \mathbb{Q}^n with $A = 0$. Then a Ricci soliton $(M, g, \tilde{V}, \lambda)$ with potential vector field $\tilde{V} := fU$ is steady Ricci soliton.*

hence, similar results were obtained when each structural vector fields $\{V, W\}$ of structure quaternionic $\{U, V, W\}$ be the potential vector field.

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Received: April 26, 2016