

On Mappings Preserving a Family of Star Bodies

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Abstract. The paper concerns the star mappings understood as topological embedding of \mathbb{R}^n into itself preserving the class of bodies which are star shaped at point 0. The main result is full characterization of star mappings (Theorem 2.8). At the end we give a solution of some related problem.

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1. Introduction

This paper consists of two different parts, both related to [1]. Moszyńska in [1] defined a set $GS(n)$ of transformations called “generalized star mappings”. They are positively homogeneous homeomorphisms of \mathbb{R}^n onto itself. That class of mappings is suitable for the notion of quotient star body (comp. [1], Prop. 2.6), however (in contrary to the statement in [1], p. 47) it is not the largest possible family of maps preserving the class \mathcal{S}^n of star bodies under consideration. Section 2 concerns the structure of the largest family Ω^n of maps preserving \mathcal{S}^n . In Section 3 we give a solution of Problem 1 in [1].

We use the following terminology and notation: By \mathbb{R}_+ we denote the set $\{r \in \mathbb{R}; r \geq 0\}$, by Σ the set of topological embeddings of \mathbb{R}_+ into \mathbb{R}_+ preserving 0. For affine independent points x_1, \dots, x_n in \mathbb{R}^n the simplex with vertices x_1, \dots, x_n is denoted by $\Delta(x_1, \dots, x_n)$. As usually, \mathbb{B}^n and S^{n-1} are the unit ball and the unit sphere. Let A be a nonempty compact subset of \mathbb{R}^n ; then A is a body if and only if $A = \text{cl}(\text{int}(A))$; the set A is called star shaped

at 0 if $\Delta(a, 0) \subset A$ for every $a \in A$. The radial function $\rho_A : \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}_+$ of a set A star shaped at 0 is defined by the formula

$$\rho_A(x) = \sup \{ \lambda \geq 0; \lambda x \in A \}. \quad (1)$$

A set $A \subset \mathbb{R}^n$ will be called a star body whenever A is star shaped at 0 and its radial function restricted to S^{n-1} is continuous. The set of all star bodies in \mathbb{R}^n is denoted by \mathcal{S}^n . The set of all halflines in \mathbb{R}^n starting at 0 will be denoted by \mathcal{L}^n . To every $x \in \mathbb{R}^n$ such that $x \neq 0$ we assign the halfline $\text{pos}(x) \in \mathcal{L}^n$ defined by the formula

$$\text{pos}(x) = \{ y \in \mathbb{R}^n; \exists \lambda \in \mathbb{R}_+ y = \lambda x \}. \quad (2)$$

2. Star mappings

In this section we shall describe the structure of the family Ω^n of *generalized star mappings* defined as follows:

Definition 2.1. Ω^n is the family of all topological embeddings of \mathbb{R}^n into itself, preserving the point 0 and the class \mathcal{S}^n .

Lemma 2.2. Let $\omega \in \Omega^n$. Then

- (i) for every $B \in \mathcal{L}^n$ there exists $C \in \mathcal{L}^n$ with $\omega(B) \subset C$;
- (ii) for every $B, B', C \in \mathcal{L}^n$ if $\omega(B) \subset C$ and $\omega(B') \subset C$, then $B = B'$.

Proof. First we prove that the image of every closed segment starting at 0 is again a closed segment starting at 0. Let $g \in \mathbb{R}^n$, $g \neq 0$ and $h = \omega(g)$. Let $G = \Delta(0, g)$ and $H = \Delta(0, h)$. Since, evidently, for every $\varepsilon > 0$ the set G_ε belongs to \mathcal{S}^n , it follows that $\omega(G_\varepsilon) \in \mathcal{S}^n$. Further, since $h = \omega(g) \in \omega(G) \subset \omega(G_\varepsilon)$, we get:

$$\forall \varepsilon > 0 \quad H \subset \omega(G_\varepsilon). \quad (3)$$

Let $\{\varepsilon_k\}_{k=0}^\infty$ be a sequence convergent to 0 such that $\varepsilon_k > 0$ for every k . The set G is compact; thus $G = \bigcap_{k=0}^\infty G_{\varepsilon_k}$. The mapping ω is a topological embedding; thus

$$\omega(G) = \bigcap_{k=0}^\infty \omega(G_{\varepsilon_k}). \quad (4)$$

From (3) and (4) we obtain:

$$H \subset \omega(G). \quad (5)$$

Since the arc $\omega(G)$ and the segment H have common ends, it follows that

$$H = \omega(G). \quad (6)$$

If the second part of the lemma is false, then there exist points $g, h \neq 0$ such that $\omega(g), \omega(h)$ belong to one halfline from \mathcal{L}^n though g, h do not belong to such a halfline. We may assume that $\|\omega(g)\| \geq \|\omega(h)\|$. Using the first part of lemma, we get $\omega(h) \in \omega(\Delta(0, g))$. So there

exists $c \in \Delta(0, g)$ such that $\omega(h) = \omega(c)$. Since ω is a topological embedding, it follows that $c = h$. Hence g, h belong to one halfline. \square

Corollary 2.3. *Let $\omega \in \Omega^n$ then for all $x, y \in \mathbb{R}^n$*

$$\frac{x}{\|x\|} = \frac{y}{\|y\|} \Leftrightarrow \frac{\omega(x)}{\|\omega(x)\|} = \frac{\omega(y)}{\|\omega(y)\|}.$$

Proof. (\Rightarrow) Let us assume that $\frac{x}{\|x\|} = \frac{y}{\|y\|}$. That means that x and y belong to one element of \mathcal{L}^n . Using Lemma 2.2(i) we infer that also $\omega(x)$ and $\omega(y)$ belong to one element of \mathcal{L}^n . This is equivalent to the condition $\frac{\omega(x)}{\|\omega(x)\|} = \frac{\omega(y)}{\|\omega(y)\|}$.

(\Leftarrow) If we assume now that $\frac{x}{\|x\|} \neq \frac{y}{\|y\|}$, then in similar way, using Lemma 2.2(ii), we get $\frac{\omega(x)}{\|\omega(x)\|} \neq \frac{\omega(y)}{\|\omega(y)\|}$. \square

It is now clear that we can look at \mathbb{R}^n as the union of halflines starting at 0, which will be called “hairs”. What $\omega \in \Omega^n$ can do with a hair? First, it can move any point different from 0 along the hair. It can even map a hair on a subset of some hair of a finite length. The way the points are moved along the hair will be described in terms of mappings from the family Φ^n defined as follows:

Definition 2.4. $\Phi^n = \{ \phi : S^{n-1} \rightarrow \Sigma; \forall_{r \in \mathbb{R}_+} \forall_{u_k, u \in S^{n-1}} u_k \rightarrow u \Rightarrow (\phi(u_k))(r) \rightarrow (\phi(u))(r) \}$.

The arguments of Φ are points in S^{n-1} , which determine the hair. Each value is a topological embedding of \mathbb{R}^n into itself; it gives us full information about $\|x\|$ and $\|\omega(x)\|$ for any $x \in \mathbb{R}^n$. A hair can also change its direction. To describe it we shall use mappings from the class Ψ^n defined as follows:

Definition 2.5. *Let Ψ^n be the class of homeomorphisms of S^{n-1} onto itself.*

The information stored in such mappings is direction of a hair and its image under ω . To every mapping from Φ^n and Ψ^n we shall assign mappings of \mathbb{R}^n into itself.

Definition 2.6. *To every $\phi \in \Phi^n$ we assign the mapping $\hat{\phi} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ satisfying the condition*

$$\forall_{u \in S^{n-1}} \forall_{r \in \mathbb{R}_+} \hat{\phi}(ru) = (\phi(u))(r)u. \quad (7)$$

Similarly, for every $\psi \in \Psi^n$ the mapping $\tilde{\psi} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is defined by the condition

$$\forall_{u \in S^{n-1}} \forall_{r \in \mathbb{R}_+} \tilde{\psi}(ru) = r\psi(u). \quad (8)$$

It seems to be clear that

$$\forall_{\phi \in \Phi^n} \forall_{\psi \in \Psi^n} \forall_{u \in S^{n-1}} (\phi(u))(0)u = 0 = 0\psi(u); \quad (9)$$

so we do not have to worry about the choice of u when $x = 0$ in Definition 2.6. These mappings have a property which is very useful for us:

Lemma 2.7. For every $\phi \in \Phi^n$ and $\psi \in \Psi^n$ the mappings $\widehat{\phi}, \widetilde{\psi}$ defined in 2.6 are in the class Ω^n .

Proof. First we prove that $\widehat{\phi}, \widetilde{\psi}$ are topological embeddings. We begin with $\widehat{\phi}$ proving that

$$\forall_{x_k, x \in \mathbb{R}^n} x_k \rightarrow x \Leftrightarrow \widehat{\phi}(x_k) \rightarrow \widehat{\phi}(x). \quad (10)$$

Case 1. Let $x = 0$ then $\widehat{\phi}(x) = 0$.

(\Rightarrow) For every $\varepsilon > 0$ let us consider the function $h^\varepsilon : S^{n-1} \rightarrow \mathbb{R}_+$ defined as follows:

$$h^\varepsilon(v) = \phi(v)(\varepsilon).$$

Evidently, $h^\varepsilon(v) = \|\widehat{\phi}(\varepsilon v)\|$. By Definition 2.4 the function h^ε is positive and continuous. Moreover

$$\forall_{v \in S^{n-1}} \forall_{\alpha, \beta > 0} \alpha \geq \beta \Leftrightarrow h^\alpha(v) \geq h^\beta(v), \quad (11)$$

$$\forall_{v \in S^{n-1}} \lim_{\alpha \searrow 0} h^\alpha(v) = 0. \quad (12)$$

So $\lim_{\varepsilon \searrow 0} h^\varepsilon = 0$ pointwise; by (11), since S^{n-1} is compact, the convergence is uniform. We get:

$$\forall_{\delta > 0} \exists_{\mu > 0} \forall_{0 \leq \varepsilon < \mu} \forall_{v \in S^{n-1}} h^\varepsilon(v) < \delta. \quad (13)$$

Since $h^\varepsilon(v) = \|\widehat{\phi}(\varepsilon v)\|$, the previous condition can be reformulated as follows:

$$\forall_{\delta > 0} \exists_{\mu > 0} \forall_{z \in \mathbb{R}^n} \|z\| < \mu \Rightarrow \|\widehat{\phi}(z)\| < \delta. \quad (14)$$

(\Leftarrow) Let $\delta > 0$ and $\mu = \min_{v \in S^{n-1}} h^\delta(v) = \min_{v \in S^{n-1}} \|\widehat{\phi}(\delta v)\|$. By Definition 2.4 mapping $v \mapsto \|\widehat{\phi}(\delta v)\| = \phi(v)(\delta)$ is continuous, moreover the set S^{n-1} is compact so $\mu > 0$. Let $z \in \mathbb{R}^n$, $u \in S^{n-1}$, $r \in \mathbb{R}_+$ be such that $z = ru$ and $\|\widehat{\phi}(z)\| < \mu$. Since $\|\widehat{\phi}(\delta u)\| > \mu$, it follows that $\|\widehat{\phi}(\delta u)\| > \|\widehat{\phi}(z)\|$. Using (11) we obtain $\|z\| < \|\delta u\| = \delta$. Thus

$$\forall_{z \in \mathbb{R}^n} \|\widehat{\phi}(z)\| < \mu \Rightarrow \|z\| < \delta, \quad (15)$$

which completes the proof of (10) for $x = 0$.

Case 2. Let $x \neq 0$; then $\widehat{\phi}(x) \neq 0$.

(\Leftarrow) We may assume that $x_k \neq 0$ which implies $\widehat{\phi}(x_k) \neq 0$. By Definition 2.5

$$\forall_{y \in \mathbb{R}^n \setminus \{0\}} \frac{y}{\|y\|} = \frac{\widehat{\phi}(y)}{\|\widehat{\phi}(y)\|}. \quad (16)$$

Thus

$$\frac{x_k}{\|x_k\|} \rightarrow \frac{x}{\|x\|} \Leftrightarrow \frac{\widehat{\phi}(x_k)}{\|\widehat{\phi}(x_k)\|} \rightarrow \frac{\widehat{\phi}(x)}{\|\widehat{\phi}(x)\|}. \quad (17)$$

It remains to prove that

$$\|x_k\| \rightarrow \|x\| \Leftrightarrow \left\| \widehat{\phi}(x_k) \right\| \rightarrow \left\| \widehat{\phi}(x) \right\|. \quad (18)$$

Let $r = \|x\|$ and $u \in S^{n-1}$ be such that $x = ru$. For every $\varepsilon \in (0; r)$ we consider the functions $h_1^\varepsilon, h_2^\varepsilon : S^{n-1} \rightarrow \mathbb{R}_+$ defined as follows:

$$h_1^\varepsilon(v) = \phi(v)(r + \varepsilon) - \phi(v)(r), \quad (19)$$

$$h_2^\varepsilon(v) = \phi(v)(r) - \phi(v)(r - \varepsilon). \quad (20)$$

Like the mapping h^ε , both $h_1^\varepsilon, h_2^\varepsilon$ are positive, continuous and uniformly convergent to 0 when $\varepsilon \searrow 0$. For every $\delta > 0$ there exists $\mu > 0$ such that $\varepsilon < \mu \Rightarrow h_i^\varepsilon < \frac{\delta}{2}$ for $i \in \{1, 2\}$. This means that

$$\forall_{y \in \mathbb{R}^n} 0 \leq \|y\| - r < \mu \Rightarrow \left\| \left\| \widehat{\phi}(y) \right\| - \left\| \widehat{\phi}\left(r \frac{y}{\|y\|}\right) \right\| \right\| = h_1^{\|y\| - r}\left(\frac{y}{\|y\|}\right) < \frac{\delta}{2}, \quad (21)$$

$$\forall_{y \in \mathbb{R}^n} 0 \leq r - \|y\| < \mu \Rightarrow \left\| \left\| \widehat{\phi}(y) \right\| - \left\| \widehat{\phi}\left(r \frac{y}{\|y\|}\right) \right\| \right\| = h_2^{r - \|y\|}\left(\frac{y}{\|y\|}\right) < \frac{\delta}{2}. \quad (22)$$

So

$$\forall_{y \in \mathbb{R}^n} \left| \|y\| - r \right| < \mu \Rightarrow \left\| \left\| \widehat{\phi}(y) \right\| - \left\| \widehat{\phi}\left(r \frac{y}{\|y\|}\right) \right\| \right\| < \frac{\delta}{2}, \quad (23)$$

First we prove (\Rightarrow) in (18). Since the mapping $\phi(\bullet)(r)$ is continuous, it follows that there exists $U \subset S^{n-1}$, an open neighborhood of u , satisfying

$$\forall_{v \in U} |\phi(u)(r) - \phi(v)(r)| < \frac{\delta}{2}. \quad (24)$$

Since $x = \lim x_k$, there exists l such that

$$\forall_{k \geq l} \frac{x_k}{\|x_k\|} \in U \ \& \ \left| \|x_k\| - r \right| < \mu \quad (25)$$

and for any $k \geq l$

$$\begin{aligned} \left| \left\| \widehat{\phi}(x_k) \right\| - \left\| \widehat{\phi}(x) \right\| \right| &\leq \left| \left\| \widehat{\phi}(x_k) \right\| - \left\| \widehat{\phi}\left(r \frac{x_k}{\|x_k\|}\right) \right\| \right| + \left| \left\| \widehat{\phi}\left(r \frac{x_k}{\|x_k\|}\right) \right\| - \left\| \widehat{\phi}(x) \right\| \right| \leq \\ &\leq \frac{\delta}{2} + \left| \phi\left(\frac{x_k}{\|x_k\|}\right)(r) - \phi(u)(r) \right| \leq \delta. \end{aligned} \quad (26)$$

This proves (\Rightarrow) in (18).

Let now $\delta \in (0; r)$. Let $\mu = \frac{1}{2} \min \{ \min_{v \in S^{n-1}} h_1^\delta(v), \min_{v \in S^{n-1}} h_2^\delta(v) \}$ and $U \subset S^{n-1}$ be an open neighborhood of u such that

$$\forall_{v \in U} |\phi(u)(r) - \phi(v)(r)| < \mu. \quad (27)$$

We get:

$$\begin{aligned} & \forall v \in U \forall t \geq r + \delta \quad \left| \left\| \widehat{\phi}(tv) \right\| - \left\| \widehat{\phi}(x) \right\| \right| = |\phi(v)(t) - \phi(u)(r)| \geq \\ & \geq |\phi(v)(t) - \phi(v)(r)| - |\phi(v)(r) - \phi(u)(r)| \geq |\phi(v)(r + \delta) - \phi(u)(r)| - \mu \geq (2\mu) - \mu = \mu \end{aligned} \quad (28)$$

and

$$\begin{aligned} & \forall v \in U \forall t \leq r - \delta \quad \left| \left\| \widehat{\phi}(tv) \right\| - \left\| \widehat{\phi}(x) \right\| \right| = |\phi(v)(t) - \phi(u)(r)| \geq \\ & \geq |\phi(v)(t) - \phi(v)(r)| - |\phi(v)(r) - \phi(u)(r)| \geq |\phi(v)(r - \delta) - \phi(u)(r)| - \mu \geq (2\mu) - \mu = \mu \end{aligned} \quad (29)$$

By (28) and (29) we obtain:

$$\forall v \in U \forall t > 0 \quad |t - r| \geq \delta \Rightarrow \left| \left\| \widehat{\phi}(tv) \right\| - \left\| \widehat{\phi}(x) \right\| \right| \geq \mu. \quad (30)$$

In other words

$$\frac{\widehat{\phi}(x_k)}{\left\| \widehat{\phi}(x_k) \right\|} \in U \ \& \ \left| \left\| \widehat{\phi}(x_k) \right\| - \left\| \widehat{\phi}(x) \right\| \right| < \mu \Rightarrow \|x_k\| - \|x\| < \delta. \quad (31)$$

This proves (18); thus the proof of (10) is complete. Now we look at the mapping $\widetilde{\psi}$. We are going to show that:

$$\forall x_k, x \in \mathbb{R}^n \quad x_k \rightarrow x \Leftrightarrow \widetilde{\psi}(x_k) \rightarrow \widetilde{\psi}(x). \quad (32)$$

From (8) we get

$$\forall y \in \mathbb{R}^n \quad \left\| \widetilde{\psi}(y) \right\| = \|y\|, \quad (33)$$

which implies (32) for $x = 0$ (i.e. for $\widetilde{\psi}(x) = 0$). Let $x \neq 0$. From (8) we get

$$\forall y \in \mathbb{R}^n \setminus \{0\} \quad \frac{\widetilde{\psi}(y)}{\left\| \widetilde{\psi}(y) \right\|} = \psi \left(\frac{y}{\|y\|} \right). \quad (34)$$

By 2.5, (8), and (34) we obtain

$$\frac{x_k}{\|x_k\|} \rightarrow \frac{x}{\|x\|} \Leftrightarrow \frac{\widetilde{\psi}(x_k)}{\left\| \widetilde{\psi}(x_k) \right\|} \rightarrow \frac{\widetilde{\psi}(x)}{\left\| \widetilde{\psi}(x) \right\|}. \quad (35)$$

Combining (33) and (35), we get (32) for $x \neq 0$.

We proved that both $\widehat{\phi}$ and $\widetilde{\psi}$ are topological embeddings. So if $A = \text{cl}(\text{int}(A))$, then $\widehat{\phi}(A) = \text{cl}(\text{int}(\widehat{\phi}(A)))$ and $\widetilde{\psi}(A) = \text{cl}(\text{int}(\widetilde{\psi}(A)))$. Moreover, it is easy to show that both $\widehat{\phi}$ and $\widetilde{\psi}$ take every segment starting at 0 to segment starting at 0 too. Hence if A is star shaped at 0 then $\widehat{\phi}(A)$ and $\widetilde{\psi}(A)$ are star shaped at 0 too. Finally, it can be proved that for every $v \in S^{n-1}$:

$$\rho_{\widehat{\phi}(A)}(v) = \phi(v)(\rho_A(v)) \quad (36)$$

and

$$\rho_{\tilde{\psi}(A)}(v) = \rho_A(\psi^{-1}(v)). \tag{37}$$

So if A is a star body and $\rho_A|_{S^{n-1}}$ is continuous, then $\rho_{\widehat{\phi}(A)}|_{S^{n-1}}$ and $\rho_{\tilde{\psi}(A)}|_{S^{n-1}}$ are continuous. \square

Now we are ready to prove the main result:

Theorem 2.8. *The mapping $(\phi, \psi) \mapsto (\tilde{\psi} \circ \widehat{\phi})$ is a biunique correspondence between the sets $(\Phi^n \times \Psi^n)$ and Ω^n .*

Proof. Let $\omega \in \Omega^n$. The mappings ϕ and ψ will be defined as follows:

$$\phi(v)(r) = \|\omega(rv)\|, \tag{38}$$

$$\psi(v) = \frac{\omega(v)}{\|\omega(v)\|} \tag{39}$$

for any $v \in S^{n-1}$ and $r \in \mathbb{R}_+$. At the beginning we shall prove that $\phi \in \Phi^n$. Let $u \in S^{n-1}$; let $B = \text{pos}(u)$ and $C = \text{pos}(\omega(u))$. The mapping $\phi(u)(\bullet)$ can be expressed as the composition of three mappings. The first of them goes from \mathbb{R}_+ to B . It is given by the formula $t \mapsto tu$. The second is the restriction of ω to B . The third one $x \mapsto \|x\|$ goes from C to \mathbb{R}_+ . The first and the last one are homeomorphisms. The second is a topological embedding. That means that $\phi(u)(\bullet) \in \Sigma$. Let $u_k \in S^{n-1}$; $r > 0$. We know that

$$u_k \rightarrow u \Leftrightarrow ru_k \rightarrow ru \Leftrightarrow \omega(ru_k) \rightarrow \omega(ru) \Rightarrow \|\omega(ru_k)\| \rightarrow \|\omega(ru)\| \Leftrightarrow \phi(r)(u_k) \rightarrow \phi(r)(u).$$

So $\phi \in \Phi^n$.

Now it is time to prove that $\psi \in \Psi^n$. We know that $0 = \omega(0) \in \omega(\text{int}(\mathbb{B}^n))$ and $\omega(\mathbb{B}^n)$ is bounded. So for every halfline C starting at 0 the set $C \cap \text{bd}(\omega(\mathbb{B}^n))$ is not empty. Since $\text{bd}(\omega(\mathbb{B}^n)) = \omega(S^{n-1})$ then ψ is surjective. By Corollary 2.3, ψ is injective. By (39), ψ is continuous. Let $\lambda > 0$ be such that $2\lambda\mathbb{B}^n \subset \omega(\mathbb{R}^n)$ and mapping $h : S^{n-1} \rightarrow S^{n-1}$ satisfies the condition

$$h(v) = \frac{\omega^{-1}(\lambda v)}{\|\omega^{-1}(\lambda v)\|}. \tag{40}$$

The mapping h is continuous. Moreover:

$$\psi h(v) = \frac{\omega\left(\frac{\omega^{-1}(\lambda v)}{\|\omega^{-1}(\lambda v)\|}\right)}{\left\|\omega\left(\frac{\omega^{-1}(\lambda v)}{\|\omega^{-1}(\lambda v)\|}\right)\right\|}. \tag{41}$$

By Corollary 2.3

$$\frac{\omega\left(\frac{1}{\|\omega^{-1}(\lambda v)\|}\omega^{-1}(\lambda v)\right)}{\left\|\omega\left(\frac{1}{\|\omega^{-1}(\lambda v)\|}\omega^{-1}(\lambda v)\right)\right\|} = \frac{\omega(\omega^{-1}(\lambda v))}{\|\omega(\omega^{-1}(\lambda v))\|} = \frac{\lambda v}{\|\lambda v\|} = v; \tag{42}$$

so ψ^{-1} is continuous. That means that $\psi \in \Psi^n$. Let us notice that

$$\begin{aligned} \widetilde{\psi} \circ \widehat{\varphi}(ru) &= \widetilde{\psi}(\widehat{\varphi}(ru)) = \widetilde{\psi}(\varphi(u)(r)u) = \varphi(u)(r)\psi(u) = \\ &= \|\omega(ru)\| \frac{\omega(u)}{\|\omega(u)\|} = \|\omega(ru)\| \frac{\omega(ru)}{\|\omega(ru)\|} = \omega(ru). \end{aligned} \quad (43)$$

We proved that the mapping $(\varphi, \psi) \mapsto \widetilde{\psi} \circ \widehat{\varphi}$ is surjective. It remains to show that it is injective. Let $\phi_1, \phi_2 \in \Phi^n$, $\psi_1, \psi_2 \in \Psi^n$, and

$$\widetilde{\psi}_1 \circ \widehat{\phi}_1 = \widetilde{\psi}_2 \circ \widehat{\phi}_2. \quad (44)$$

Then

$$\widetilde{\psi}_2^{-1} \circ \widetilde{\psi}_1 \circ \widehat{\phi}_1 = \widehat{\phi}_2. \quad (45)$$

Since $\widehat{\phi}_2$ preserves directions, it follows that so does $\widetilde{\psi}_2^{-1} \circ \widetilde{\psi}_1 \circ \widehat{\phi}_1$. So $\widetilde{\psi}_2^{-1} \circ \widetilde{\psi}_1 = \text{id}$; hence $\widehat{\phi}_1 = \widehat{\phi}_2$. \square

It may seem that the mappings from the classes Φ^n and Ψ^n are very simple. So we may think that so are the mappings from Ω^n . To help the reader to realize how complicated they are we shall give two examples:

Example 2.9. Let $\phi(u)(r) = 1 - \exp(-r)$ and $\omega = \widehat{\phi}$. It is easy to see that

$$\forall_{u \in S^{n-1}} \forall_{r \in \mathbb{R}_+} \|\omega(ru)\| = \phi(u)(r) < 1. \quad (46)$$

So we cannot expect that $\omega(\mathbb{R}^n) = \mathbb{R}^n$. I think that it is not very surprising because after applying ω image of every hair has finite lengths. It seems to be more interesting that there exists a generalized star mapping ω for which images of some hairs have finite lengths and images of another hairs have infinite lengths.

Example 2.10. Let $n = 2$ and $e_1 = (1, 0)$. Let the $\mu(u) = \angle(u, e_1)$. Let mapping $\phi(u)(r) = \mu(u)r + (1 - \exp(-r))$ and $\omega = \widehat{\phi}$. It is easy to see that if $u \neq e_1$, then $\phi(u)(r)$ can be arbitrarily large while $\phi(e_1)(r) < 1$ for every r .

3. A solution of Problem 1 in [1]

To every $A \in \mathcal{S}^n$ we assign the subset S_A of the unit sphere:

$$S_A = \{u \in S^{n-1}; \rho_A(u) > 0\}. \quad (47)$$

M. Moszyńska proved that if $A, B \in \mathcal{S}^n$ and there exists $\omega \in GS(n)$ such that $\omega(A) = B$, then S_A is homeomorphic to S_B . She asked if the existence of a homeomorphism between S_A and S_B suffices for A, B to be star equivalent in sense of [1].

Proposition 3.1. *If $A, B \in \mathcal{S}^n$ and there exists $\omega \in \Omega^n$ such that $\omega(A) = B$, then $S^{n-1} \setminus S_A$ is homeomorphic to $S^{n-1} \setminus S_B$.*

Proof. By Theorem 1.8 there exist $\phi \in \Phi^n$ and $\psi \in \Psi^n$ such that $\tilde{\psi} \circ \hat{\phi} = \omega$. It can be easily proved that if $\omega(A) = B$ then $\psi(S^{n-1} \setminus S_A) = S^{n-1} \setminus S_B$ (and $\psi(S_A) = S_B$). The mapping ψ is a homeomorphism; thus the restriction of ψ to $S^{n-1} \setminus S_A$ is a homeomorphism as well. This completes the proof. \square

The following example shows that the answer to the above question is negative even for the larger family Ω^n .

Example 3.2. Let $n = 2$ and let $A, B \in \mathcal{S}^n$ be defined by the values of their radial functions restricted to S^{n-1} :

$$\rho_A(u) = |\langle u; e_1 \rangle|, \quad (48)$$

$$\rho_B(u) = \max \left\{ |\langle u; e_1 \rangle| - \frac{1}{2}, 0 \right\}. \quad (49)$$

The set $S^{n-1} \setminus S_A$ consists of two points, while the set $S^{n-1} \setminus S_B$ consists of two closed arcs. In this case there is no star mapping $\omega \in \Omega^n$ such that $\omega(A) = B$. On the other hand, each of S_A and S_B consists of two open arcs. So they are homeomorphic.

This example can be generalized to any $n \geq 2$ showing that the answer is no even if we look in family Ω^n . Moreover it can be proved that even if S_A is homeomorphic to S_B and $S^{n-1} \setminus S_A$ is homeomorphic to $S^{n-1} \setminus S_B$ we cannot expect that A, B are star equivalent.

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