

Symmetry Groups and Conservation Laws of Certain Partial Differential Equations

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*Dedicated to Prof.Dr. Constantin UDRIȘTE
on the occasion of his sixtieth birthday*

Abstract

We study partial differential equations by using invariance under transformations groups due to Sophus Lie. This method, so called the classical Lie method of infinitesimal transformations or symmetry groups theory, has been applied last years to important PDEs arising from mathematics and physics. Based on the finding of a symmetry group associated to the studied PDEs system, we can find a lot of properties related on solutions. A modern presentation of this theory using the jet functions theory is given by Olver in his book [37].

The aim of this paper is to point out the ideas of the Ph.D.Thesis [2], which contains recent results obtained by application of the Lie's method for certain PDEs systems which arises from differential geometry, especially from Țițeica (Tzitzeica) surfaces theory, and from physics. The paper is split into four parts: the symmetry group history, symmetry groups in differential geometry, the thesis ideas and original results of thesis.

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1 The Symmetry group history

The *groups theory* has an important role in a lot of domains of the science: mathematics, physics, classical mechanics, electromagnetism, relativity theory, quantum mechanics. This theory was introduced for the necessity to find a mathematical apparatus to study the properties of mathematical or physical objects. After the infinitesimal calculus invention, the concept of *group* is considered the most important discovery in mathematics.

The idea due to Sophus Lie, namely, to study the differential equations systems and the partial differential equations systems by using the transformations groups implied a new theory: the symmetry groups theory, known also as the classical Lie method of infinitesimal transformations.

The *symmetry group* of a PDEs system is the largest (connected) local Lie group of transformations acting on the space of the independent and dependent variables of the system, with the property that it conserves the set of solutions. In the Lie's theory this group consists in geometric transformations which act on the set of solutions by transforming their graphs. The infinitesimal generator is a vector field associated with a local one-parameter group of transformations, and from this it follows that the symmetry group is described by the composition of the basic one-parameter groups.

The method of finding the symmetry group associated to a PDEs system is based on the infinitesimal criterion of invariance, and in this case the prolongation of the infinitesimal generator to the derivatives space of the dependent variables of the system is very important. Lie made the remark that, for a given PDEs system, the complicated nonlinear conditions of invariance can be replaced by equivalent linear conditions: an overdetermined linear PDEs system, so-called *the defining equations* for the symmetry group.

The knowledge of the symmetry group implies a lot of properties both of the system and of their solutions: the determining of the group-invariant solutions, the construction of new solutions of the system from known ones, the classification of the group-invariant solutions - two solutions are equivalent if one can be transformed into the other by some element group - using the associated adjoint representation. Moreover, we can find a PDEs class which is invariant under a given group of transformations. In his papers, Lie found the symmetry group associated with several ordinary differential equations and respectively first and second order PDEs. He was the first which made the remark that one can determine invariant solutions under a one-parameter group of transformations. Lie introduced the concept of variational symmetry group and he got the infinitesimal variational criterion too. Cartan [16] studied the equivalence between a given set of PDEs and a set of differential forms. The Noether's theorem implied the development of this research field since 1918. Thus a lot of mathematicians and physicians became interested to study this new theory: Jacobi studied the connection of variational symmetries with the conservation laws, continued later by Shutz and Engel; Birkhoff - applied the groups theory in the study of certain PDEs which arise from hydrodynamics; Ovsiannikov and the Russian school [41] - from 1950 to 1960 - proposed an important systematic programme to apply this method in the case of the most important PDEs which arise from physics, and in that time they introduced the algorithm of classification of solutions with the adjoint representation. Bluman and Cole [13] - found again the symmetry group of the heat equation given by Lie, determined group-invariant solutions for this PDE and group-invariant PDEs invariant under this symmetry group also. Miller [30] - applied the symmetry group theory in the finding of the solutions of the second order linear PDEs by using the separable variables method. Weisner - studied the connection of certain symmetry groups with some functions. Moreover Harrison și Estabrook developed a similar theory but using differential forms [21], and this point of view was continued by Edelen. A modern exposition of the Lie method was given by Olver in his book [37], using the jet functions theory. In [39] Olver and Rosenau defined again the symmetry group like a strong symmetry group and they introduced the concept of weak symmetry group of a PDEs system. On the other hand, the algorithm to find the symmetry group of a PDEs system is a computational method. This allowed to

appear a lot of symbolic programs to eliminate the difficult calculus in the case of particular forms of PDEs [22], [37].

There are a lot of papers and books which study this subject. So we have just presented only some of the important stages of the development of this theory: [13], [21], [22], [25], [30], [37]-[40], [41], [45], [60]. In the references [14], [17], [23], [26], [27], [31], [35]-[36], [46], [47], [63] appear similar problems connected with our research work interest.

2 Symmetry groups in differential geometry

We make the remark that PDEs and the PDEs systems which arise from differential geometry were not systematically studied by using the symmetry group theory. That is our motivation to apply the modern symmetry groups theory in the case of certain PDEs connected with differential geometry. This survey is based on our recent papers in which we find the differentiable distributions for which the integral varieties are graphs of the invariant solutions of certain equations and on variational conservation laws too.

We studied Monge-Ampère PDEs, Monge-Ampère- \mathbb{T} iteica PDEs respectively, the basic results being published in the paper [57]. The study of \mathbb{T} iteica surfaces PDEs implied the finding of some infinitesimal symmetries, Lagrangians and conservation laws associated with these equations [11], [59]. All these results show that the theory of \mathbb{T} iteica surfaces becomes a theory of variational calculus.

In the chapter 4 we include the papers [10] and [9], which consider the Camassa-Holm PDE from fluid mechanics and Blair PDEs system from solar physics and contact geometry. The papers [6] and [3] contain applications of the symmetry groups theory in the study of the PDE of surfaces with constant Gaussian curvature and the minimal surfaces PDE. In [4] and [5] are shown special classes of ODEs invariant under groups of transformations.

The problem to associate connections, and metrics generated by found symmetry groups is part of our recent work.

Opposite to our published papers, the thesis [2] contains also the original results found by using the Lie Program for analysis of partial differential equations on IBM type PCs [22]. We want to make the remark that in the case of the Monge-Ampère- \mathbb{T} iteica PDEs (2.1.1) and (2.1.2) respectively, the symbolic programs cannot be applied in the n -dimensional case. Their using for the PDEs systems (3.1.6), (3.1.8) and (3.1.10), which define the \mathbb{T} iteica surfaces, is very difficult also.

3 The Thesis ideas [2]

The theory presented by Olver in his book [37], which is very known and appreciated in the mathematical literature, represents the basis of our ideas.

The first chapter of the thesis contains a short presentation of the basic results of the symmetry groups theory for the PDEs systems and variational symmetry groups theory. Also, we give the explicit formulas for the finding of the symmetry group of certain PDEs studied in the second and in the fourth chapter.

The second chapter studies the symmetries of the Monge-Ampère PDE

$$\det(u_{ij}) = f(x, u),$$

and especially in the cases $f = 1$ and $n = 2$ respectively. The second order PDE

$$u_{xx}u_{yy} - u_{xy}^2 = H(x, y, u, u_x, u_y)$$

is called the Monge-Ampère-Țițeica PDE. One proves that

$$u_{xx}u_{yy} - u_{xy}^2 = 1,$$

is the only second order Monge-Ampère-Țițeica PDE invariant under the symmetry group associated to it. One finds the group-invariant solutions and one proves that Pogorelov's solution [42] and Jörgens's solution [24] are group-invariant solutions. Moreover, one generalises the Calabi's result about the invariance of the Monge-Ampère equation, in the case $f = 1$, under the special linear group, so that this group is a subgroup of the symmetry group associated to the equation.

Studying the tetrahedral surfaces, in 1907, Țițeica introduced a new class of surfaces [48], with the property that

$$\frac{K}{d^4} = \text{constant},$$

where K is the Gauss curvature and d the distance from origin to tangent plane of the surface. Țițeica called them S -surfaces, and showed that these are invariant under the centroaffine transformations. Now the surfaces S are called Țițeica-surfaces. Țițeica was the first who discovered centroaffine properties, so he is considered one of the founders of the affine geometry which was developed later as independent domain and for which the S -surfaces were affine spheres. The results due to Mayer, Myller, Vrânceanu, Gheorghiu, etc developed the centroaffine geometry [19], [20], [28], [29], [61], [62].

The study of the Țițeica surfaces PDE

$$u_{xx}u_{yy} - u_{xy}^2 = \alpha(xu_x + yu_y - u)^4, \quad \alpha \in R^*,$$

is contained in the second chapter and it is based on the paper [59]. One shows that the symmetry group associated with this PDE is the unimodular subgroup of the centroaffine group.

One proves that the only Monge-Ampère-Țițeica PDE invariant under the unimodular group is the Țițeica surfaces PDE. Also one finds group-invariant solutions and weak symmetry groups [39] associated to this PDE. By studying the inverse problem [37], [40], one shows that the Țițeica surfaces PDE is an Euler-Lagrange equation and one determines an associated second order Lagrangian. One considers variational problem and one gets the variational symmetry group and respectively conservations laws. In this way the Țițeica theory becomes related to variational calculus on differential manifolds. Also one shows that the Țițeica surfaces PDE can be included in the following class of Euler-Lagrange equations

$$\frac{u_{xx}u_{yy} - u_{xy}^2}{(xu_x + yu_y - u)^m} = \alpha,$$

where $m \neq 0, 2, 3$ and $\alpha \neq 0$.

The third chapter of the thesis analyses infinitesimal symmetries associated to the completely integrable system

$$\begin{cases} r_{uu} &= ar_u + br_v \\ r_{uv} &= hr \\ r_{vv} &= a''r_u + b''r_v, \end{cases}$$

which define the Țițeica surfaces [49], where the functions a, b, h, a'', b'' satisfy the conditions of integrability

$$\begin{aligned} ah &= h_u, & a_v &= ba'' + h, & b_v + bb'' &= 0, \\ h_v &= b''h, & a''_u + aa'' &= 0, & h &= b''_u + a''b. \end{aligned}$$

One considers the associated scalar system

$$\begin{cases} \theta_{uu} &= a\theta_u + b\theta_v \\ \theta_{uv} &= h\theta \\ \theta_{vv} &= a''\theta_u + b''\theta_v, \end{cases}$$

and one finds associated infinitesimal symmetries. Țițeica proved that three independent solutions x, y, z of this second order completely integrable PDEs system define an S -surface, where u, v are the coordinates of the asymptotic lines of the surface [49]. Thus, one determines the following subgroups of the symmetry groups of these systems: the subgroups which act on the space of the independent variables and on the space of the dependent variables respectively associated with the system. One proves that the symmetry subgroup which acts on the space of the dependent variables, is the unimodular subgroup of the centroaffine group, and one finds again the above result.

Gheorghiu proved the existence of a space A_2 with affine connection associated to the scalar system which defines the Țițeica surfaces, and he introduced [19] a new class of affine spaces A_2^0 . New examples of these spaces were given by Udriște [52]. The problem to associate our results with the Țițeica connection [61] and the result due to Gheorghiu is still open [64].

One finds the symmetry groups associated with Liouville-Țițeica PDE

$$(\ln h)_{uv} = h,$$

and Țițeica PDE

$$(\ln h)_{uv} = h - \frac{1}{h^2},$$

respectively, the equations which defines the conditions of completely integrability of the systems which define the Țițeica ruled surfaces and Țițeica surfaces which are not ruled. One proves that these equations are Euler-Lagrange PDEs and by studying the associated variational problems, one finds variational symmetry groups and conservation laws. Our results are different from those presented in Bobenko [14] and Wolf [63]. By using the CRACK Program, in the paper [63], Wolf finds conservation laws by solving the conservation law condition directly (it is not assumed that any Lie-symmetries are known, nor that the equations are equivalent to the Euler-Lagrange equations of a variational problems).

The fourth chapter contains the study of the symmetry group associated with the third order PDE

$$uu_{xxx} + u_{xxy} + 2u_x u_{xx} - 3uu_x - u_y = 0,$$

so-called Camassa-Holm (CH) equation. This PDE was introduced by Fuchssteiner and Fokas, and Camassa and Holm [15] discovered again that it is the model of the shallow wave equation. Holm, Marsden and Ratiu [23] showed that the n -dimensional CH equation describes geodesic motion on the diffeomorphism group $Diff(R^n)$, Miśkiewicz [31] has shown that the CH equation represents a geodesic flow on the Bott-Virasoro group $Diff(S^1)$, and Kourbaeva [26] has shown that this equation is a geodesic spray of the weak Riemannian metric on the diffeomorphism group $Diff(R)$ or on $Diff(S^1)$.

For a certain class of third order PDEs, namely

$$u_y - \varepsilon u_{xxy} + 2ku_x = uu_{xxx} + \alpha uu_x + \beta u_x u_{xx}$$

which includes the CH PDE, Clarkson, Mansfield and Priestley applied the nonclassical symmetries method [18].

In 4.1 one gets again the associated Lie group to CH PDE and moreover one finds a class of third order PDEs invariant under this group [10], which included the Rosenau-Hyman PDE

$$uu_{xxx} + uu_x + 3u_x u_{xx} - u_y = 0$$

also. In the class of second order PDEs invariant under the symmetry group associated with CH PDE can be included: the nonlinear wave PDE

$$u_y = uu_x,$$

the Liouville-Teichmüller PDE

$$uu_{xy} - u_x u_y = u^3,$$

and respectively the particular Monge-Ampère-Teichmüller PDEs

$$u_{xx} u_{yy} - u_{xy}^2 = u^4 f\left(\frac{u_x}{u}, \frac{u_y}{u^2}\right).$$

In the paper [12], Blair studied the vector equation

$$\text{rot } B = |B| \cdot B.$$

A solution of it gives a conformally flat contact metric structure on \mathbf{R}^3 . Moreover if the vector field B satisfies the equation

$$\text{div } B = 0,$$

then the solutions of the system represent "force-free" models of solar physics. The system of these two equations is called Blair PDEs system. Blair found a solution of it by using the method of successive approximations. The vector fields

$$B_1 = \sin z \frac{\partial}{\partial x} + \cos z \frac{\partial}{\partial y},$$

and

$$B_2 = \frac{8(xz - y)}{(1 + x^2 + y^2 + z^2)^2} \frac{\partial}{\partial x} + \frac{8(x + yz)}{(1 + x^2 + y^2 + z^2)^2} \frac{\partial}{\partial y} + \frac{4(1 + z^2 - x^2 - y^2)}{(1 + x^2 + y^2 + z^2)^2} \frac{\partial}{\partial z},$$

satisfy the vector equation, but only the first is a solenoidal vector field. The finding of the solutions of this PDEs system is still an open problem.

In 4.2 are studied the PDEs

$$\text{rot } B = f \cdot B,$$

which arise from solar physics, in the case $f = f(u, v, w)$ and $f = |B|$ respectively. One finds the determining equations of the symmetry groups. One finds again the symmetry group associated with the Blair PDEs system [12] and one shows that the known solutions are group-invariant solutions, so using these we can find new solutions.

The annex of the thesis presents some symbolic programs for determining the symmetry group of certain PDEs systems. Also it contains the results produced by the LIE51 and BIGLIE Programs, author Head [22], in the case of some PDEs and PDEs systems studied in the thesis.

4 Original results of thesis

In this last part we shall present several original results found by using the symmetry group theory, as follows:

Theorem 2.1.1. *The Lie algebra of the infinitesimal symmetries associated to the Monge-Ampère PDE*

$$(2.1.1) \quad \det(u_{ij}) = f(x, u),$$

is described by the vector field

$$X = \sum_{i=1}^n \zeta^i(x) \frac{\partial}{\partial x^i} + \phi(x, u) \frac{\partial}{\partial u},$$

with the property that the components

$$\zeta^i(x) = x^i \sum_{j=1}^n a_j x^j + \sum_{j=1}^n b_j^i x^j + c^i, \quad i = 1, \dots, n,$$

and

$$\phi(x, u) = u \left(\sum_{j=1}^n a_j x^j + b \right) + \sum_{j=1}^n c_j x^j + c,$$

where $a_j, b_j^i, b, c_j, c^i, c \in \mathbf{R}$, are the solutions of the first order PDE

$$-\sum_{i=1}^n \zeta^i f_{x^i} - \phi f_u + n f \left(\phi_u - \frac{2}{n} \sum_{i=1}^n \zeta_{x^i}^i \right) = 0.$$

Theorem 2.1.2 *The Lie algebra of the infinitesimal symmetries associated to the Monge-Ampère PDE*

$$(2.1.2) \quad \det(u_{ij}) = 1$$

is described by the vector fields

$$(2.1.3) \quad \begin{aligned} X_{ij} &= x^i \frac{\partial}{\partial x^j} + \delta_j^i \frac{2u}{n} \frac{\partial}{\partial u}, \quad 1 \leq i, j \leq n, \\ Y_i &= x^i \frac{\partial}{\partial u}, \quad 1 \leq i \leq n, \quad Z_i = \frac{\partial}{\partial x^i}, \quad 1 \leq i \leq n, \quad V = \frac{\partial}{\partial u}. \end{aligned}$$

In the case $n = 2$, the PDE (2.1.2) turns in

$$(2.1.4) \quad u_{xx}u_{yy} - u_{xy}^2 = 1.$$

This PDE is contained in the class,

$$u_{xx}u_{yy} - u_{xy}^2 = H(x, y, u, u_x, u_y),$$

so-called *Monge-Ampère-Tițeica PDEs*.

The Theorem 2.1.2 implies that the Lie algebra of the infinitesimal symmetries associated to the PDE (2.1.4) is spanned by following vector fields

$$(2.1.5) \quad \begin{aligned} X_1 &= \frac{\partial}{\partial x}, \quad X_2 = \frac{\partial}{\partial y}, \quad X_3 = \frac{\partial}{\partial u}, \quad X_4 = y \frac{\partial}{\partial x}, \quad X_5 = x \frac{\partial}{\partial y}, \\ X_6 &= x \frac{\partial}{\partial u}, \quad X_7 = y \frac{\partial}{\partial u}, \quad X_8 = x \frac{\partial}{\partial x} + u \frac{\partial}{\partial u}, \\ X_9 &= y \frac{\partial}{\partial y} + u \frac{\partial}{\partial u}, \end{aligned}$$

where we denote $x^1 = x$, $x^2 = y$, respectively $Z_1 = X_1$, $Z_2 = X_2$, $V = X_3$, $X_{21} = X_4$, $X_{12} = X_5$, $Y_1 = X_6$, $Y_2 = X_7$, $X_{11} = X_8$ and $X_{22} = X_9$.

Theorem 2.1.3. *The second order PDE*

$$u_{xx} = H(x, y, u, u_x, u_y, u_{xy}, u_{yy}),$$

invariant under the Lie group G with the infinitesimal generators given by the relation (2.1.5), is reduced to the Monge-Ampère PDE (2.1.4).

Theorem 2.2.1. *The vector fields*

$$(2.2.5) \quad \begin{aligned} X_1 &= x \frac{\partial}{\partial x} - u \frac{\partial}{\partial u}, \quad X_2 = y \frac{\partial}{\partial y} - u \frac{\partial}{\partial u}, \quad X_3 = y \frac{\partial}{\partial x}, \quad X_4 = u \frac{\partial}{\partial x} \\ X_5 &= x \frac{\partial}{\partial y}, \quad X_6 = u \frac{\partial}{\partial y}, \quad X_7 = x \frac{\partial}{\partial u}, \quad X_8 = y \frac{\partial}{\partial u} \end{aligned}$$

describe the Lie algebra of the infinitesimal symmetries associated to the *Tițeica surface PDE*

$$(2.2.4) \quad u_{xx}u_{yy} - u_{xy}^2 = \alpha(xu_x + yu_y - u)^4.$$

Theorem 2.2.2. *The second order Monge-Ampère-Tréteica PDE of maximal rank,*

$$(2.2.3) \quad u_{xx}u_{yy} - u_{xy}^2 = H(x, y, u, u_x, u_y),$$

which admits the group G' (with X_1, X_2, X_3, X_7 as infinitesimal generators) as symmetry group, is the Tréteica surfaces PDE.

Theorem 2.3.1. *The operator T associated to the Tréteica surfaces PDE is equivalent to an Euler-Lagrange operator.*

Theorem 2.3.2. *A second order Lagrangian associated to the Tréteica surfaces PDE (2.2.4) is*

$$(2.3.1) \quad L(x, y, u^{(2)}) = \frac{u(u_{xy}^2 - u_{xx}u_{yy})}{(xu_x + yu_y - u)^4} - \alpha u.$$

Theorem 2.3.3. *The class of second order PDEs*

$$(2.3.2) \quad u_{xx}u_{yy} - u_{xy}^2 = \alpha(xu_x + yu_y - u)^m,$$

with $m \neq 0, 2, 3$ and $\alpha \neq 0$, is equivalent to a class of Euler-Lagrange PDEs.

Theorem 2.3.4. *A second order Lagrangian associated to the PDE (2.3.2) is*

$$(2.3.3) \quad L_m(x, y, u^{(2)}) = \frac{u(u_{xy}^2 - u_{xx}u_{yy})}{(xu_x + yu_y - u)^m} - \alpha(m-3)u.$$

Theorem 2.4.1. *The Lie algebra of the variational symmetry group for the functional (2.4.1) is described by the vectors fields*

$$(2.4.2) \quad Y_1 = x \frac{\partial}{\partial x} - u \frac{\partial}{\partial u}, \quad Y_2 = y \frac{\partial}{\partial y} - u \frac{\partial}{\partial u},$$

$$Y_3 = y \frac{\partial}{\partial x}, \quad Y_4 = x \frac{\partial}{\partial y}.$$

Theorem 3.1.3. *The Lie algebra g_1 of the Lie symmetry group G_1 , which acts on the space of the dependent variables of the PDEs system*

$$(3.1.11) \quad \begin{cases} x_{uu} = ax_u + bx_v \\ x_{uv} = hx \\ x_{vv} = a''x_u + b''x_v \\ y_{uu} = ay_u + by_v \\ y_{uv} = hy \\ y_{vv} = a''y_u + b''y_v \\ z_{uu} = az_u + bz_v \\ z_{uv} = hz \\ z_{vv} = a''z_u + b''z_v, \end{cases}$$

$$(3.1.12) \quad (y_uz_v - z_uy_v)x - (x_uz_v - x_vz_u)y + (x_uy_v - x_vy_u)z = f,$$

where the functions a, b, h, a'', b'' satisfy the relations

$$(3.1.5) \quad \begin{aligned} ah &= h_u, \quad a_v = ba'' + h, \quad b_v + bb'' = 0, \\ h_v &= b''h, \quad a''_u + aa'' = 0, \quad h = b''_u + a''b, \end{aligned}$$

and $f = f(u, v)$ is a nonidentically zero function, is described by the vector fields

$$(3.1.13) \quad \begin{aligned} X_1 &= x \frac{\partial}{\partial x} - z \frac{\partial}{\partial z}, \quad X_2 = y \frac{\partial}{\partial y} - z \frac{\partial}{\partial z}, \quad X_3 = y \frac{\partial}{\partial x}, \quad X_4 = z \frac{\partial}{\partial x} \\ X_5 &= x \frac{\partial}{\partial y}, \quad X_6 = z \frac{\partial}{\partial y}, \quad X_7 = x \frac{\partial}{\partial z}, \quad X_8 = y \frac{\partial}{\partial z}. \end{aligned}$$

The Lie symmetry group G_1 is the unimodular subgroup of the centroaffine group.

Theorem 3.1.4. The general vector field of the Lie algebra of infinitesimal symmetries of the group G_2 associated with the second order PDEs system (3.1.11)+(3.1.12), is

$$Z = \zeta(u) \frac{\partial}{\partial u} + \eta(v) \frac{\partial}{\partial v},$$

where the components ζ and η satisfy the following PDEs

$$(3.1.14) \quad \left\{ \begin{array}{l} \zeta a_u + \eta a_v + a \zeta_u + \zeta_{uu} = 0 \\ \zeta b_u + \eta b_v - b \eta_v + 2b \zeta_u = 0 \\ \zeta h_u + \eta h_v + h(\zeta_u + \eta_v) = 0 \\ \zeta a''_u + \eta a''_v - a'' \zeta_u + 2a'' \eta_v = 0 \\ \zeta b''_u + \eta b''_v + b'' \eta_v + \eta_{vv} = 0. \end{array} \right.$$

Proposition 3.1.3. The function

$$(3.1.16) \quad h(u, v) = \frac{3}{2 \operatorname{sh}^2 \frac{(u+v)\sqrt{3}}{2}} + 1$$

gives a Tîţeica revolution surface. Moreover, there is a Tîţeica ruled surface associated to it.

Proposition 3.1.4. The Tîţeica's solution marked in [2] by (3.1.17) is invariant under the subgroup G_2 , for which

$$Z = C_1 \frac{\partial}{\partial u} + C_2 \frac{\partial}{\partial v},$$

is an infinitesimal generator, in the case of Tîţeica surfaces which are not ruled.

Theorem 3.2.2. The general vector field which describes the algebra of infinitesimal symmetries associated to Liouville-Tîţeica equation

$$(3.2.1) \quad \omega_{uv} = e^\omega,$$

is

$$(3.2.5) \quad W = f \frac{\partial}{\partial u} + g \frac{\partial}{\partial v} - (f' + g') \frac{\partial}{\partial \omega},$$

where $f = f(u)$ and $g = g(v)$.

Theorem 3.2.3. *The vector fields which describe the Lie algebra of infinitesimal symmetries associated to T̄īteica surfaces PDE*

$$(3.2.2) \quad \omega_{uv} = e^\omega - e^{-2\omega},$$

are the following

$$(3.2.6) \quad U_1 = u \frac{\partial}{\partial u} - v \frac{\partial}{\partial v}, \quad U_2 = \frac{\partial}{\partial u}, \quad U_3 = \frac{\partial}{\partial v}.$$

Theorem 3.2.4. *A second order PDE invariant under the symmetry group associated to T̄īteica PDE (3.2.2) takes the form*

$$(3.2.7) \quad H(\omega, \omega_u \omega_v, \omega_{uv}, \omega_{uu} \omega_{vv}) = 0.$$

In particular, if the PDE is a Monge-Ampère-T̄īteica PDE (2.2.3), then one finds the PDE

$$(3.2.8) \quad \omega_{uu} \omega_{vv} - \omega_{uv}^2 = f(\omega, \omega_u \omega_v).$$

Theorem 3.3.1. *The operators*

$$T_1(\omega) = \omega_{uv} - e^\omega,$$

and respectively

$$T_2(\omega) = \omega_{uv} - e^\omega - e^{-2\omega},$$

associated to the PDEs (3.2.1) and (3.2.2) respectively, are identically with the Euler-Lagrange operators, for which the associated Lagrangians are

$$(3.3.1) \quad L_1(u, v, \omega^{(1)}) = -\frac{1}{2} \omega_u \omega_v - e^\omega,$$

and respectively

$$(3.3.2) \quad L_2(u, v, \omega^{(1)}) = -\frac{1}{2} \omega_u \omega_v - e^\omega - \frac{1}{2} e^{-2\omega}.$$

Theorem 3.3.2. *The Lie algebras of the variational symmetry groups for the functionals*

$$\mathcal{L}_i[\omega] = \int \int_D L_i(u, v, \omega^{(1)}) du dv, \quad i = 1, 2,$$

where L_1 and L_2 are given by (3.3.1) and (3.3.2) respectively are generated by the vector fields

$$(3.3.5) \quad W_1 = u \frac{\partial}{\partial u} - \frac{\partial}{\partial \omega}, \quad W_2 = v \frac{\partial}{\partial v} - \frac{\partial}{\partial \omega}, \quad W_3 = \frac{\partial}{\partial u}, \quad W_4 = \frac{\partial}{\partial v},$$

respectively

$$(3.3.6) \quad U_1 = u \frac{\partial}{\partial u} - v \frac{\partial}{\partial v}, \quad U_2 = \frac{\partial}{\partial u}, \quad U_3 = \frac{\partial}{\partial v}.$$

Proposition 3.3.1. *The fluxes P^1 and respectively the conserved densities P^2 associated to the conservation laws for Liouville-Țițeica PDE (3.2.1), are contained in the following table*

$-W_i$	P^1	P^2
$-W_1$	$\frac{1}{2}\omega_v - ue^\omega$	$\frac{1}{2}\omega_u(1 + u\omega_u)$
$-W_2$	$\frac{1}{2}\omega_v(1 + v\omega_v)$	$\frac{1}{2}\omega_u - ve^\omega$
$-W_3$	$-e^\omega$	$\frac{1}{2}\omega_u^2$
$-W_4$	$\frac{1}{2}\omega_v^2$	$-e^\omega$

Proposition 3.3.2. *The flux P^1 and respectively the conserved density P^2 associated to the conservation laws for Țițeica PDE (3.2.2), are contained in the following table*

$-U_i$	P^1	P^2
$-U_1$	$-\frac{1}{2}ue^{-2\omega} - \frac{1}{2}v\omega_v^2 - ue^\omega$	$\frac{1}{2}u\omega_u^2 + ve^\omega + \frac{1}{2}ve^{-2\omega}$
$-U_2$	$-e^\omega - \frac{1}{2}e^{-2\omega}$	$\frac{1}{2}\omega_u^2$
$-U_3$	$\frac{1}{2}\omega_v^2$	$-e^\omega - \frac{1}{2}e^{-2\omega}$

Theorem 4.1.1. *The Lie algebra \mathfrak{g} of the infinitesimal symmetries associated to Camassa-Holm PDE*

$$(4.1.1) \quad uu_{xxx} + u_{xxy} + 2u_x u_{xx} - 3uu_x - u_y = 0$$

is generated by the vector fields

$$(4.1.2) \quad X_1 = \frac{\partial}{\partial x}, \quad X_2 = \frac{\partial}{\partial y}, \quad X_3 = y \frac{\partial}{\partial y} - u \frac{\partial}{\partial u}.$$

Theorem 4.1.2. *A third order PDE*

$$H(x, y, u^{(3)}) = 0$$

for which the Lie algebra of associated infinitesimal symmetries is described by the vector fields (4.1.2) can be written in the following form

$$(4.1.3) \quad h \left(\frac{u_x}{u}, \frac{u_y}{u^2}, \frac{u_{xx}}{u}, \frac{u_{xy}}{u^2}, \frac{u_{yy}}{u^3}, \frac{u_{xxx}}{u}, \frac{u_{xxy}}{u^2}, \frac{u_{xyy}}{u^3}, \frac{u_{yyy}}{u^3} \right) = 0.$$

Theorem 4.2.1. *The Lie algebra of infinitesimal symmetries associated to PDEs system (4.2.4) is described by the vector field*

$$X = \zeta \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} + \theta \frac{\partial}{\partial z} + \phi \frac{\partial}{\partial u} + \lambda \frac{\partial}{\partial v} + \psi \frac{\partial}{\partial w},$$

for which the components $\zeta, \eta, \theta, \phi, \lambda, \psi$, functions of x, y, z, u, v, w , are the solutions of the following PDEs system

$$\begin{aligned} &\psi_y - \lambda_z - \phi(uf_u + f) - u\lambda f_v - u\psi f_w - v f \lambda_u + w f \zeta_z + \\ &+ u f(\psi_w - \eta_y) + v w f^2 \zeta_u - u^2 f^2 \eta_w = 0 \end{aligned}$$

$$\begin{aligned}
& \phi_z - \psi_x - v f_u \phi - (v f_v + f) \lambda - v f_w \psi + v f(\phi_u - \theta_z) - \\
& \quad - w f \psi_v + u f \eta_x - v^2 f^2 \theta_u + u w f^2 \eta_v = 0 \\
& \lambda_x - \phi_y - w \phi f_u - w \lambda f_v - (w f_w + f) \psi + v f \theta_y + w f(\lambda_v - \zeta_x) - \\
& \quad - u f \phi_w - w^2 f^2 \zeta_v + u v f^2 \theta_w = 0 \\
& \phi_v = -\eta_x + f(v \eta_w - w \eta_v) \\
(4.2.7) \quad & \phi_w = -\theta_x + f(v \theta_w - w \theta_v) \\
& \lambda_u = -\zeta_y + f(w \zeta_u - u \zeta_w) \\
& \lambda_w = -\theta_y + f(w \theta_u - u \theta_w) \\
& \psi_u = -\zeta_z + f(u \zeta_v - v \zeta_u) \\
& \psi_v = -\eta_z + f(u \eta_v - v \eta_u) \\
& \phi_u - \psi_w = -\zeta_x + \theta_z + f(2v \theta_u - w \zeta_v - u \eta_w) \\
& \psi_w - \lambda_v = -\theta_z + \eta_y + f(2u \eta_w - v \theta_u - w \zeta_v) \\
& \eta_u = \zeta_v \quad \theta_v = \eta_w \quad \zeta_w = \theta_u.
\end{aligned}$$

Theorem 4.2.2. *A Lie subalgebra of the Lie algebra of infinitesimal symmetries associated to the PDEs system (4.2.5) is described by the following vector fields:*

$$\begin{aligned}
X_1 &= -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} - v \frac{\partial}{\partial u} + u \frac{\partial}{\partial v}, \quad X_2 = -z \frac{\partial}{\partial y} + y \frac{\partial}{\partial z} - w \frac{\partial}{\partial v} + v \frac{\partial}{\partial w}, \\
X_3 &= -z \frac{\partial}{\partial x} + x \frac{\partial}{\partial z} - w \frac{\partial}{\partial u} + u \frac{\partial}{\partial w}, \quad X_4 = \frac{\partial}{\partial x}, \quad X_5 = \frac{\partial}{\partial y}, \quad X_6 = \frac{\partial}{\partial z}. \\
(4.2.8) \quad X_7 &= x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z} - u \frac{\partial}{\partial u} - v \frac{\partial}{\partial v} - w \frac{\partial}{\partial w}, \\
X_8 &= 2xz \frac{\partial}{\partial x} + 2yz \frac{\partial}{\partial y} + (z^2 - x^2 - y^2) \frac{\partial}{\partial z} + 2(xw - zu) \frac{\partial}{\partial u} + \\
& \quad + 2(yw - zv) \frac{\partial}{\partial v} - 2(xu + yv + zw) \frac{\partial}{\partial w}, \\
X_9 &= xy \frac{\partial}{\partial x} + \frac{1}{2}(y^2 - x^2 - z^2) \frac{\partial}{\partial y} + yz \frac{\partial}{\partial z} + (xv - yu) \frac{\partial}{\partial u} - \\
& \quad - (xu + yv + zw) \frac{\partial}{\partial v} + (zv - yw) \frac{\partial}{\partial w}, \\
X_{10} &= \frac{1}{2}(x^2 - y^2 - z^2) \frac{\partial}{\partial x} + xy \frac{\partial}{\partial y} + xz \frac{\partial}{\partial z} - (xu + yv + zw) \frac{\partial}{\partial u} + \\
& \quad + (yu - xv) \frac{\partial}{\partial v} + (zu - xw) \frac{\partial}{\partial w}.
\end{aligned}$$

Theorem 4.2.3. *The following vector fields*

$$(4.2.9) \quad X_1 = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} - v \frac{\partial}{\partial u} + u \frac{\partial}{\partial v}, \quad X_2 = -z \frac{\partial}{\partial y} + y \frac{\partial}{\partial z} - w \frac{\partial}{\partial v} + v \frac{\partial}{\partial w},$$

$$X_3 = -z \frac{\partial}{\partial x} + x \frac{\partial}{\partial z} - w \frac{\partial}{\partial u} + u \frac{\partial}{\partial w}, \quad X_4 = \frac{\partial}{\partial x}, \quad X_5 = \frac{\partial}{\partial y},$$

$$X_6 = \frac{\partial}{\partial z}, \quad X_7 = x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z} - u \frac{\partial}{\partial u} - v \frac{\partial}{\partial v} - w \frac{\partial}{\partial w},$$

described the Lie algebra \mathfrak{g} of infinitesimal symmetries associated to Blair PDEs system

$$(4.2.6) \quad \begin{cases} w_y - v_z & = u\sqrt{u^2 + v^2 + w^2} \\ u_z - w_x & = v\sqrt{u^2 + v^2 + w^2} \\ v_x - u_y & = w\sqrt{u^2 + v^2 + w^2} \\ u_x + v_y + w_z & = 0. \end{cases}$$

Theorem 4.2.4. *Let $f = f(u, v, w)$. The only first order PDEs system*

$$(4.2.14) \quad \begin{cases} w_y - v_z & = uf \\ u_z - w_x & = vf \\ v_x - u_y & = wf \\ u_x + v_y + w_z & = 0, \end{cases}$$

invariant under the symmetry group G associated to the Blair PDEs system (4.2.6), is the Blair PDEs system.

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