

**ON THE SOLVABILITY OF THE MULTIDIMENSIONAL  
VERSION OF THE FIRST DARBOUX PROBLEM FOR A  
MODEL SECOND-ORDER DEGENERATING HYPERBOLIC  
EQUATION**

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ABSTRACT. A multidimensional version of the first Darboux problem is considered for a model second order degenerating hyperbolic equation. Using the technique of functional spaces with a negative norm, the correct formulation of this problem in the Sobolev weighted space is proved.

In a space of variables  $x_1, x_2, t$  let us consider a second-order degenerating hyperbolic equation of the type

$$Lu \equiv u_{tt} - |x_2|^m u_{x_1 x_1} - u_{x_2 x_2} + a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u = F, \quad (1)$$

where  $a_i, i = 1, \dots, 4, F$  are given real functions and  $u$  is an unknown real function,  $m = \text{const} > 0$ .

Denote by  $D : x_2 < t < 1 - x_2, 0 < x_2 < \frac{1}{2}$ , an unbounded domain lying in a space  $x_2 > 0$  and bounded by characteristic surfaces  $S_1 : t - x_2 = 0, 0 < x_2 < \frac{1}{2}, S_2 : t + x_2 - 1 = 0, 0 < x_2 < \frac{1}{2}$ , of equation (1) and by a plane surface  $S_0 : x_2 = 0, 0 < t < 1$ , of time type with an equation degenerating on it. The coefficients  $a_i, i = 1, \dots, 4$ , of equation (1) in the domain  $D$  are assumed to be bounded functions of the class  $C^1(\overline{D})$ .

For equation (1) let us consider a multidimensional version of the first Darboux problem formulated as follows: find in the domain  $D$  a solution  $u(x_1, x_2, t)$  of equation (1) satisfying the boundary condition

$$u|_{S_0 \cup S_1} = 0. \quad (2)$$

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The problem in the domain  $D$  for the equation

$$L^*v \equiv v_{tt} - x_2^m v_{x_1 x_1} - v_{x_2 x_2} - (a_1 v)_{x_1} - (a_2 v)_{x_2} - (a_3 v)_t + a_4 v = F \quad (3)$$

is posed analogously by the boundary condition

$$v|_{S_0 \cup S_2} = 0, \quad (4)$$

where  $L^*$  is a formally conjugate operator of  $L$ .

Note that similar problems for  $m = 0$ , when equation (1) is not degenerating and contains, in its principal part, a wave operator, were studied in [1–6]. Other versions of multidimensional Darboux problems can be found in [7–9].

Denote by  $E, E^*$  the classes of functions from the Sobolev space  $W_2^2(D)$  satisfying respectively the boundary condition (2) and the boundary condition (4). Let  $W_+(W_+^*)$  be the weighted Hilbert space obtained by closing the space  $E(E^*)$  in the norm

$$\|u\|_{1,+}^2 = \int_D (u_t^2 + x_2^m u_{x_1}^2 + u_{x_2}^2 + u^2) dD.$$

Denote by  $W_-(W_-^*)$  the space with a negative norm constructed with respect to  $L_2(D)$  and  $W_+(W_+^*)$  [10].

Consider the condition

$$M = \sup_D |x_2^{-\frac{m}{2}} a_1(x_1, x_2, t)| < \infty \quad (5)$$

imposed on the lowest coefficient  $a_1$  in equation (1).

The uniqueness theorem required for solving problem (1), (2) of the class  $W_2^2(D)$  follows from

**Lemma 1.** *Let condition (5) be fulfilled. Then for every  $u \in W_2^2(D)$  satisfying the homogeneous boundary condition*

$$u|_{S_0} = 0 \quad (6)$$

the a priori estimate

$$\|u\|_{1,+} \leq c(\|f\|_{1,*} + \|F\|_{L_2(D)}) \quad (7)$$

is valid, where the positive constant  $c$  does not depend on  $u$ ;  $f = u|_{S_1}$ ,  $F = Lu$ ,

$$\|f\|_{1,*}^2 = \int_{S_1} \left[ x_2^m f_{x_1}^2 + \left( \frac{\partial f}{\partial N} \right)^2 \right] ds,$$

and  $\frac{\partial}{\partial N} = -\frac{1}{2} \left( \frac{\partial}{\partial x_2} + \frac{\partial}{\partial t} \right)$  is the derivative with respect to the conormal which is the inner differential operator on the characteristic surface  $S_1$ .

*Proof.* Let  $n = (\nu_1, \nu_2, \nu_0)$  be the outer unit vector to  $\partial D$ , i.e.,  $\nu_1 = \cos(\widehat{n, x_1})$ ,  $\nu_2 = \cos(\widehat{n, x_2})$ ,  $\nu_0 = \cos(\widehat{n, t})$ . For the function  $u \in W_2^2(D)$  satisfying the boundary condition (6) and  $\lambda = \text{const} > 0$  a simple integration by parts gives

$$\begin{aligned}
 2 \int_D e^{-\lambda t} u_{tt} u_t dD &= \int_{\partial D} e^{-\lambda t} u_t^2 \nu_0 ds + \int_D \lambda e^{-\lambda t} u_t^2 dD, \quad (8) \\
 -2 \int_D e^{-\lambda t} (x_2^m u_{x_1 x_1} u_t + u_{x_2 x_2} u_t) dD &= \\
 &= -2 \int_{\partial D} e^{-\lambda t} (x_2^m u_{x_1} u_t \nu_1 + u_{x_2} u_t \nu_2) ds + \\
 + \int_D D e^{-\lambda t} (x_2^m u_{x_1}^2 + u_{x_2}^2) \nu_0 ds + \int_D e^{-\lambda t} (\lambda x_2^m u_{x_1}^2 + \lambda u_{x_2}^2) dD. \quad (9)
 \end{aligned}$$

It can be easily seen that

$$\begin{aligned}
 u|_{S_0} = u_t|_{S_0} = \nu_0|_{S_0} = 0, \quad n|_{S_1} = \left(0, \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right), \quad (10) \\
 \nu_0|_{S_2} > 0, \quad (\nu_0^2 - x_2^m \nu_1^2 - \nu_2^2)|_{S_1 \cup S_2} = 0.
 \end{aligned}$$

Taking into account (8)–(10), multiplying both parts of equation (1) by  $2e^{-\lambda t} u_t$ , where  $F = Lu$ , and integrating the obtained expression with respect to  $D$ , we obtain

$$\begin{aligned}
 2(Lu, e^{-\lambda t} u_t)_{L_2(D)} &= \int_D e^{-\lambda t} [\lambda(u_t^2 + x_2^m u_{x_1}^2 + u_{x_2}^2) + \\
 + 2(a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u) u_t] dD + \int_{S_1 \cup S_2} e^{-\lambda t} \nu_0^{-1} [x_2^m (\nu_0 u_{x_1} - \\
 - \nu_1 u_t)^2 + (\nu_0 u_{x_2} - \nu_2 u_t)^2 + (\nu_0^2 - x_2^m \nu_1^2 - \nu_2^2) u_t^2] ds &\geq \\
 \geq \int_D e^{-\lambda t} [\lambda(u_t^2 + x_2^m u_{x_1}^2 + u_{x_2}^2) + 2(a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + \\
 + a_4 u) u_t] dD - \sqrt{2} \int_{S_1} e^{-\lambda t} [x_2^m u_{x_1}^2 + \left(\frac{\partial u}{\partial N}\right)^2] ds. \quad (11)
 \end{aligned}$$

Owing to condition (6) and the structure of  $D$ , one can easily verify that the inequality

$$\int_D u^2 dD \leq c_0 \int_D u_{x_2}^2 dD \tag{12}$$

is valid for some  $c_0 = \text{const} > 0$  not depending on  $u \in W_2^2(D)$ .

Using inequality (5), we can show that

$$|2a_1 u_{x_1} u_t| \leq 2M(x_2^{\frac{m}{2}} u_{x_1}) u_t \leq M(x_2^m u_{x_1}^2 + u_t^2). \tag{13}$$

By virtue of (12) and (13), from (11) for sufficiently large  $\lambda$  we get

$$\begin{aligned} 2(Lu, e^{-\lambda t} u_t)_{L_2(D)} &\geq c_1 \int_D (u_t^2 + x_2^m u_{x_1}^2 + u_{x_2}^2 + u^2) dD - \\ &- c_2 \int_{S_1} \left[ x_2^m u_{x_1}^2 + \left( \frac{\partial u}{\partial N} \right)^2 \right] ds, \end{aligned} \tag{14}$$

where the positive constants  $c_1$  and  $c_2$  do not depend on  $u$ ; note that depending on  $\lambda$ , the constant  $c_1$  can be chosen arbitrarily large. Therefore estimate (7) follows obviously from (14).  $\square$

*Remark 1.* Since for the principal part of the operator  $L$  the derivative with respect to the conormal  $\frac{\partial}{\partial N} = \nu_0 \frac{\partial}{\partial t} - x_2^m \nu_1 \frac{\partial}{\partial x_1} - \nu_2 \frac{\partial}{\partial x_2}$  is the inner differential operator on the characteristic surfaces of equation (1), by (2) and (4) we have

$$\frac{\partial u}{\partial N} \Big|_{S_1} = 0, \quad \frac{\partial v}{\partial N} \Big|_{S_2} = 0 \tag{15}$$

for the functions  $u \in E$  and  $v \in E^*$ .

**Lemma 2.** *Let condition (5) be fulfilled. Then for all functions  $u \in E, v \in E^*$  the inequalities*

$$\|Lu\|_{W_-^*} \leq c_1 \|u\|_{W_+}, \tag{16}$$

$$\|L^*v\|_{W_-} \leq c_2 \|v\|_{W_+^*} \tag{17}$$

are fulfilled, where the positive constants  $c_1$  and  $c_2$  do not depend respectively on  $u$  and  $v$ ,  $\|\cdot\|_{W_+} = \|\cdot\|_{W_+^*} = \|\cdot\|_{1,+}$ .

*Proof.* According to the definition of a negative norm and because of (2), (4), and (15), we have

$$\begin{aligned} \|Lu\|_{W_-^*} &= \sup_{v \in W_+^*} \|v\|_{W_+^*}^{-1} (Lu, v)_{L_2(D)} = \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} (Lu, v)_{L_2(D)} = \\ &= \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} \int_{\partial D} [u_t v \nu_0 - x_2^m u_{x_1} v \nu_1 - u_{x_2} v \nu_2] ds + \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} \int_D [-u_t v_t + \\ &\quad + x_2^m u_{x_1} v_{x_1} + u_{x_2} v_{x_2} + a_1 u_{x_1} v + a_2 u_{x_2} v + a_3 u_t v + a_4 uv] dD = \\ &= \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} \int_{S_1 \cup S_2} \frac{\partial}{\partial N} v ds + \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} \int_D [-u_t v_t + x_2^m u_{x_1} v_{x_1} + \\ &\quad + u_{x_2} v_{x_2} + a_1 u_{x_1} v + a_2 u_{x_2} v + a_3 u_t v + a_4 uv] dD = \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} \int_D [-u_t v_t + \\ &\quad + x_2^m u_{x_1} v_{x_1} + u_{x_2} v_{x_2} + a_1 u_{x_1} v + a_2 u_{x_2} v + a_3 u_t v + a_4 uv] dD. \end{aligned} \tag{18}$$

Due to condition (5) and the Schwartz inequality we obtain

$$\begin{aligned} \left| \int_D [-u_t v_t + x_2^m u_{x_1} v_{x_1} + u_{x_2} v_{x_2}] dD \right| &\leq 3 \left[ \int_D (u_t^2 + x_2^m u_{x_1}^2 + u_{x_2}^2) dD \right]^{\frac{1}{2}} \times \\ &\quad \times \left[ \int_D (v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2) dD \right]^{\frac{1}{2}} \leq 3 \|u\|_{W_+} \|v\|_{W_+^*}, \end{aligned} \tag{19}$$

$$\begin{aligned} \left| \int_D (a_1 u_{x_1} v + a_2 u_{x_2} v + a_3 u_t v + a_4 uv) dD \right| &\leq M \left( \int_D x_2^m u_{x_1}^2 dD \right)^{\frac{1}{2}} \|v\|_{L_2(D)} + \\ &\quad + \sup_D |a_2| \|u_{x_2}\|_{L_2(D)} \|v\|_{L_2(D)} + \sup_D |a_3| \|u_t\|_{L_2(D)} \|v\|_{L_2(D)} + \\ &\quad + \sup_D |a_4| \|u\|_{L_2(D)} \|v\|_{L_2(D)} \leq \left( M + \sum_{i=1}^4 \sup_D |a_i| \right) \|u\|_{W_+} \|v\|_{W_+^*}. \end{aligned} \tag{20}$$

From (18)–(20) it follows that

$$\begin{aligned} \|Lu\|_{W_-^*} &\leq \left( 3 + M + \sum_{i=2}^4 \sup_D |a_i| \right) \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} \|u\|_{W_+} \|v\|_{W_+^*} = \\ &= \left( 3 + M + \sum_{i=2}^4 \sup_D |a_i| \right) \|u\|_{W_+}, \end{aligned}$$

which proves inequality (16). Thus Lemma 2 is completely proved, since the proof of inequality (17) repeats that of the inequality (16).  $\square$

*Remark 2.* By inequalities (16) and (17), the operator  $L : W_+ \rightarrow W_-^*$  ( $L : W_+^* \rightarrow W_-$ ) with a dense domain of definition  $E(E^*)$  admits a closure which is a continuous operator from  $W_+(W_+^*)$  to  $W_-(W_-)$ . Denoting this closure as previously by  $L(L^*)$ , we note that it is defined on the whole Hilbert space  $W_+(W_+^*)$ .

**Lemma 3.** *Problems (1), (2) and (3), (4) are self-conjugate, i.e., the equality*

$$(Lu, v) = (u, L^*v) \quad (21)$$

holds for every  $u \in W_+$  and  $v \in W_+^*$ .

*Proof.* By Remark 2 it suffices to prove equality (21) when  $u \in E$  and  $v \in E^*$ . We have

$$\begin{aligned} (Lu, v) &= (Lu, v)_{L_2(D)} = \int_{\partial D} [u_t v \nu_0 - x_2^m u_{x_1} v \nu_1 - u_{x_2} v \nu_2] ds + \\ &+ \int_{\partial D} [a_1 \nu_1 + a_2 \nu_2 + a_3 \nu_0] uv ds + \int_D [-u_t v_t + x_2^m u_{x_1} v_{x_1} + u_{x_2} v_{x_2} - \\ &- u(a_1 v)_{x_1} - u(a_2 v)_{x_2} - u(a_3 v)_t + a_4 uv] dD = \int_{\partial D} [u_t v \nu_0 - x_2^m u_{x_1} v \nu_1 - \\ &- u_{x_2} v \nu_2] ds + \int_{\partial D} [a_1 \nu_1 + a_2 \nu_2 + a_3 \nu_0] uv ds - \int_{\partial D} [u v_t \nu_0 - x_2^m u v_{x_1} \nu_1 - \\ &- u v_{x_2} \nu_2] ds + \int_D [u v_{tt} - x_2^m u v_{x_1 x_1} - u v_{x_2 x_2} - u(a_1 v)_{x_1} - \\ &- u(a_2 v)_{x_2} - u(a_3 v)_t + a_4 uv] dD = \int_{\partial D} \left[ \left( v \frac{\partial u}{\partial N} - u \frac{\partial v}{\partial N} \right) + \right. \\ &\left. + (a_1 \nu_1 + a_2 \nu_2 + a_3 \nu_3) uv \right] ds + (u, L^*v)_{L_2(D)}. \quad (22) \end{aligned}$$

By (2), (4), and (15), equality (21) follows directly from (22), which proves Lemma 3.  $\square$

**Lemma 4.** *Let condition (5) be fulfilled. Then for every  $u \in W_+$  we have the inequality*

$$c \|u\|_{L_2(D)} \leq \|Lu\|_{W_-^*} \quad (23)$$

with the positive constant  $c$  not depending on  $u$ .

*Proof.* By Remark 2 it suffices to prove the inequality (23) when  $u \in E$ . If  $u \in E$ , then it can be easily verified that the function

$$v(x_1, x_2, t) = \int_t^{\varphi_2(x_1, x_2)} e^{-\lambda\tau} u(x_1, x_2, \tau) d\tau, \quad \lambda = \text{const} > 0,$$

where  $t = \varphi_2(x_1, x_2)$  is the equation of the characteristic surface  $S_2$ , belongs to the space  $E^*$ , and the equalities

$$v_t(x_1, x_2, t) = -e^{-\lambda t} u(x_1, x_2, t), \quad u(x_1, x_2, t) = -e^{\lambda t} v_t(x_1, x_2, t) \quad (24)$$

are valid. By (10), (15) and (24) we have

$$\begin{aligned} (Lu, v)_{L_2(D)} &= \int_D \left[ v \frac{\partial u}{\partial N} + (a_1 v_1 + a_2 v_2 + a_3 v_0) uv \right] ds + \\ &+ \int_D [-u_t v_t + x_2^m u_{x_1} v_{x_1} + u_{x_2} v_{x_2} - u a_{1x_1} v - u a_{1x_2} v - u a_{2x_2} v - \\ &\quad - u a_{2x_1} v - u a_{3t} v - u a_{3v} v + a_4 u v] dD = \int_D e^{-\lambda t} u_t u dD + \\ &+ \int_D e^{\lambda t} [-x_2^m v_{x_1 t} v_{x_1} - v_{x_2 t} v_{x_2} + a_{1x_1} v_t v + a_{1x_2} v_t v + a_{2x_2} v_t v + \\ &\quad + a_{2x_1} v_t v + a_{3t} v_t v + a_3 v_t^2 - a_4 v_t v] dD. \end{aligned} \quad (25)$$

Analogously to (8) and (9), because of (2) we have

$$\begin{aligned} \int_D e^{-\lambda t} u_t u dD &= \frac{1}{2} \int_{\partial D} e^{-\lambda t} u^2 \nu_0 ds + \frac{1}{2} \int_D e^{-\lambda t} \lambda u^2 dD = \\ &= \frac{1}{2} \int_{S_2} e^{-\lambda t} u^2 \nu_0 ds + \frac{1}{2} \int_D e^{\lambda t} \lambda v_t^2 dD = \\ &= \frac{1}{2} \int_{S_2} e^{\lambda t} v_t^2 \nu_0 ds + \frac{1}{2} \int_D e^{\lambda t} \lambda v_t^2 dD, \end{aligned} \quad (26)$$

$$\begin{aligned} \int_D e^{\lambda t} [-x_2^m v_{x_1 t} v_{x_1} - v_{x_2 t} v_{x_2}] dD &= -\frac{1}{2} \int_{\partial D} e^{\lambda t} [x_2^m v_{x_1}^2 + v_{x_2}^2] \nu_0 ds + \\ &+ \frac{1}{2} \int_D e^{\lambda t} \lambda [x_2^m v_{x_1}^2 + v_{x_2}^2] dD. \end{aligned} \quad (27)$$

Since  $v|_{S_2} = 0$ , for some  $\alpha$  on  $S_2$  we have

$$v_t = \alpha\nu_0, \quad v_{x_1} = \alpha\nu_1, \quad v_{x_2} = \alpha\nu_2.$$

Therefore, since the surface  $S_2$  is characteristic, we have

$$(v_t^2 - x_2^m v_{x_1}^2 - v_{x_2}^2)|_{S_2} = \alpha^2(\nu_0^2 - x_2^m \nu_1^2 - \nu_2^2)|_{S_2} = 0. \quad (28)$$

Due to the fact that  $\nu_0|_{S_0} = 0$ ,  $\nu_0|_{S_1} < 0$  and owing to equalities (4) and (28), we find that

$$\begin{aligned} & \frac{1}{2} \int_{S_2} e^{\lambda t} v_t^2 \nu_0 \, ds - \frac{1}{2} \int_{\partial D} e^{\lambda t} [x_2^m v_{x_1}^2 + v_{x_2}^2] \nu_0 \, ds = \\ & = \frac{1}{2} \int_{S_2} e^{\lambda t} v_t^2 \nu_0 \, ds - \frac{1}{2} \int_{S_1} e^{\lambda t} [x_2^m v_{x_1}^2 + v_{x_2}^2] \nu_0 \, ds - \\ & - \frac{1}{2} \int_{S_2} e^{\lambda t} [x_2^m v_{x_1}^2 + v_{x_2}^2] \nu_0 \, ds \geq \frac{1}{2} \int_{S_2} e^{\lambda t} v_t^2 \nu_0 \, ds - \frac{1}{2} \int_{S_2} e^{\lambda t} [x_2^m v_{x_1}^2 + \\ & + v_{x_2}^2] \nu_0 \, ds = \frac{1}{2} \int_{S_2} e^{\lambda t} [v_t^2 - x_2^m v_{x_1}^2 - v_{x_2}^2] \nu_0 \, ds = 0. \end{aligned} \quad (29)$$

Taking into consideration (26), (27), and (29), from (25) we get

$$\begin{aligned} (Lu, v)_{L_2(D)} &= \frac{1}{2} \int_{S_2} e^{\lambda t} v_t^2 \nu_0 \, ds + \frac{1}{2} \int_D e^{\lambda t} \lambda v_t^2 \, dD - \\ & - \frac{1}{2} \int_{\partial D} e^{\lambda t} [x_2^m v_{x_1}^2 + v_{x_2}^2] \nu_0 \, ds + \frac{1}{2} \int_D e^{\lambda t} \lambda [x_2^m v_{x_1}^2 + v_{x_2}^2] \, dD + \\ & + \int_D e^{\lambda t} [a_1 v_t v_{x_1} + a_2 v_t v_{x_2} + a_3 v_t^2 + (a_{1x_1} + a_{2x_2} + a_{3t} - a_4) v_t v] \, dD \geq \\ & \geq \frac{\lambda}{2} \int_D e^{\lambda t} [v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2] \, dD - \left| \int_D e^{\lambda t} [a_1 v_t v_{x_1} + \right. \\ & \left. + a_2 v_t v_{x_2} + a_3 v_t^2 + (a_{1x_1} + a_{2x_2} + a_{3t} - a_4) v_t v] \, dD \right|. \end{aligned} \quad (30)$$

Putting

$$\mu = \max \left( \sup_D |a_2|, \sup_D |a_3|, \sup_D |a_{1x_1} + a_{2x_2} + a_{3t} - a_4| \right)$$



and taking into account (5), we find that

$$\begin{aligned}
 & \left| \int_D e^{\lambda t} [a_1 v_t v_{x_1} + a_2 v_t v_{x_2} + a_3 v_t^2 + (a_{1x_1} + a_{2x_2} + a_{3t} - a_4) v_t v] dD \right| \leq \\
 & \leq \int_D e^{\lambda t} \left[ M \frac{1}{2} (x_2^m v_{x_1}^2 + v_t^2) + \frac{\mu}{2} (v_{x_2}^2 + v_t^2) + \mu v_t^2 + \frac{\mu}{2} (v^2 + v_t^2) \right] dD = \\
 & = \int_D e^{\lambda t} \left[ \left( \frac{1}{2} M + 2\mu \right) v_t^2 + \frac{1}{2} M x_2^m v_{x_1}^2 + \frac{\mu}{2} v_{x_2}^2 + \frac{\mu}{2} v^2 \right] dD \leq \\
 & \leq \left( \frac{1}{2} M + 2\mu \right) \int_D e^{\lambda t} [v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2 + v^2] dD. \tag{31}
 \end{aligned}$$

Since the function  $e^{\frac{\lambda}{2}t} v|_{S_0} = 0$ , by virtue of inequality (12) we have

$$\int_D e^{\lambda t} v^2 dD \leq c_0 \int_D e^{\lambda t} v_{x_2}^2 dD \leq c_0 \int_D e^{\lambda t} [v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2] dD$$

and, consequently,

$$\int_D e^{\lambda t} [v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2] dD \geq \frac{1}{1 + c_0} \int_D e^{\lambda t} [v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2 + v^2] dD. \tag{32}$$

By (31), (32), and (24) from (30) we obtain

$$\begin{aligned}
 (Lu, v)_{L_2(D)} & \geq \frac{\lambda}{2(1 + c_0)} \int_D e^{\lambda t} [v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2 + v^2] dD - \\
 & - \left( \frac{1}{2} M + 2\mu \right) \int_D e^{\lambda t} [v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2 + v^2] dD = \\
 & = \left( \frac{\lambda}{2(1 + c_0)} - \frac{1}{2} M - 2\mu \right) \int_D e^{\lambda t} [v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2 + v^2] dD \geq \\
 & \geq \sigma \left[ \int_D e^{\lambda t} v_t^2 dD \right]^{\frac{1}{2}} \left[ \int_D [v_t^2 + x_2^m v_{x_1}^2 + v_{x_2}^2 + v^2] dD \right]^{\frac{1}{2}} = \\
 & = \sigma \left[ \int_D e^{-\lambda t} u^2 dD \right]^{\frac{1}{2}} \|v\|_{W_+^*} \geq \sigma \cdot \inf_D e^{-\lambda t} \|u\|_{L_2(D)} \|v\|_{W_+^*}, \tag{33}
 \end{aligned}$$

where  $\sigma = \left( \frac{\lambda}{2(1 + c_0)} - \frac{1}{2} M - 2\mu \right) > 0$  for sufficiently large  $\lambda$ , while  $\inf_D e^{-\lambda t} = \text{const} > 0$  owing to the structure of the domain  $D$ .

If now we apply the generalized Schwartz inequality

$$(Lu, v)_{L_2(D)} \leq \|Lu\|_{W_-^*} \|v\|_{W_-^*}$$

to the left-hand side of (33), then after reduction by  $\|v\|_{W_+^*}$  we obtain inequality (23), where  $c = \sigma \inf_D e^{-\lambda t} = \text{const} > 0$ .  $\square$

**Lemma 5.** *Let condition (5) be fulfilled. Then for every  $v \in W_+^*$  the inequality*

$$c\|v\|_{L_2(D)} \leq \|L^*v\|_{W_-} \quad (34)$$

is valid for some  $c = \text{const} > 0$  not depending on  $v \in W_+^*$ .

*Proof.* As in Lemma 4, by Remark 2 it suffices to prove the validity of inequality (34) for  $v \in E^*$ . Let  $v \in E^*$  and introduce into consideration the function

$$u(x_1, x_2, t) = \int_{\varphi_1(x_1, x_2)}^t e^{\lambda\tau} v(x_1, x_2, \tau) d\tau, \quad \lambda = \text{const} > 0,$$

where  $t = \varphi_1(x_1, x_2)$  is the equation of the characteristic surface  $S_1$ . It is easily seen that the function  $u(x_1, x_2, t)$  belongs to the class  $E$ , and we have the equalities

$$u_t(x_1, x_2, t) = e^{\lambda t} v(x_1, x_2, t), \quad v(x_1, x_2, t) = e^{-\lambda t} u_t(x_1, x_2, t). \quad (35)$$

Because of (10), (15), and (35) we have

$$\begin{aligned} (L^*v, u)_{L_2(D)} &= \int_{\partial D} \left[ u \frac{\partial v}{\partial N} - (a_1\nu_1 + a_2\nu_2 + a_3\nu_0)uv \right] ds + \\ &+ \int_D [-v_t u_t + x_2^m v_{x_1} u_{x_1} + v_{x_2} u_{x_2} + a_1 v u_{x_1} + a_2 v u_{x_2} + a_3 v u_t + a_4 uv] dD = \\ &= - \int_D e^{\lambda t} v_t v dD + \int_D e^{-\lambda t} [x_2^m u_{x_1 t} u_{x_1} + u_{x_2 t} u_{x_2}] dD + \\ &+ \int_D e^{-\lambda t} [a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u] u_t dD. \end{aligned} \quad (36)$$

Similarly to (26)–(29) we can prove the equalities

$$- \int_D e^{\lambda t} v_t v dD = - \frac{1}{2} \int_{\partial D} e^{\lambda t} v^2 \nu_0 ds + \frac{1}{2} \int_D e^{\lambda t} \lambda v^2 dD =$$

$$= -\frac{1}{2} \int_{S_1} e^{-\lambda t} u_t^2 \nu_0 \, ds + \frac{1}{2} \int_D e^{-\lambda t} \lambda u_t^2 \, dD, \tag{37}$$

$$\int_D e^{-\lambda t} [x_2^m u_{x_1 t} u_{x_1} + u_{x_2 t} u_{x_2}] \, dD = \frac{1}{2} \int_{\partial D} e^{-\lambda t} [x_2^m u_{x_1}^2 + u_{x_2}^2] \nu_0 \, ds + \frac{1}{2} \int_D e^{-\lambda t} \lambda [x_2^m u_{x_1}^2 + u_{x_2}^2] \, dD, \tag{38}$$

$$\begin{aligned} (u_t^2 - x_2^m u_{x_1}^2 - u_{x_2}^2)|_{S_1} &= 0, \tag{39} \\ -\frac{1}{2} \int_{S_1} e^{-\lambda t} u_t^2 \nu_0 \, ds + \frac{1}{2} \int_{\partial D} e^{-\lambda t} [x_2^m u_{x_1}^2 + u_{x_2}^2] \nu_0 \, ds &= \\ = -\frac{1}{2} \int_{S_1} e^{-\lambda t} u_t^2 \nu_0 \, ds + \frac{1}{2} \int_{S_1} e^{-\lambda t} [x_2^m u_{x_1}^2 + u_{x_2}^2] \nu_0 \, ds + \\ &+ \frac{1}{2} \int_{S_2} e^{-\lambda t} [x_2^m u_{x_1}^2 + u_{x_2}^2] \nu_0 \, ds \geq \\ &\geq -\frac{1}{2} \int_{S_1} e^{-\lambda t} [u_t^2 - x_2^m u_{x_1}^2 - u_{x_2}^2] \nu_0 \, ds = 0. \tag{40} \end{aligned}$$

To obtain inequality (40) we have used the fact that  $\nu_0|_{S_2} > 0$ .

Owing to (37)–(40), from (36) we get

$$\begin{aligned} (L^* v, u)_{L_2(D)} &\geq \frac{1}{2} \int_D e^{-\lambda t} \lambda [u_t^2 + x_2^m u_{x_1}^2 + u_{x_2}^2] \, dD + \\ &+ \int_D e^{-\lambda t} [a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u] u_t \, dD \geq \frac{\lambda}{2} \int_D e^{-\lambda t} [u_t^2 + x_2^m u_{x_1}^2 + \\ &+ u_{x_2}^2] \, dD - \left| \int_D e^{-\lambda t} [a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u] u_t \, dD \right|. \end{aligned}$$

whence, as in obtaining inequality (33) from (30), we have

$$\begin{aligned} (L^* v, u)_{L_2(D)} &\geq \left[ \frac{\lambda}{2(1+c_0)} - \left( \frac{1}{2} M + \max_{i=2,3,4} \sup_D |a_i| \right) \right] \times \\ &\times \inf_D e^{-\lambda t} \|v\|_{L_2(D)} \|u\|_{W_+}. \end{aligned}$$

Inequality (34) follows directly from the above inequality for sufficiently large  $\lambda$ .  $\square$

**Definition 1.** If  $F \in L_2(D)$ , then the function  $u$  will be called a strong generalized solution of problem (1), (2) of the class  $W_+$  if  $u \in W_+$ , and

there exists a sequence of functions  $u_n \in E$  such that  $u_n \rightarrow u$  and  $Lu_n \rightarrow F$  respectively in the spaces  $W_+$  and  $W_-^*$  as  $n \rightarrow \infty$ , i.e.,

$$\lim_{n \rightarrow \infty} \|u_n - u\|_{W_+} = 0. \quad \lim_{n \rightarrow \infty} \|Lu_n - F\|_{W_-^*} = 0.$$

**Definition 2.** If  $F \in W_-^*$ , then the function  $u$  will be called a strong generalized solution of problem (1), (2) of the class  $L_2$  if  $u \in L_2(D)$ , and there exists a sequence of functions  $u_n \in E$  such that  $u_n \rightarrow u$  and  $Lu_n \rightarrow F$  respectively in the spaces  $L_2(D)$  and  $W_-^*$  as  $n \rightarrow \infty$ , i.e.,

$$\lim_{n \rightarrow \infty} \|u_n - u\|_{L_2(D)} = 0. \quad \lim_{n \rightarrow \infty} \|Lu_n - F\|_{W_-^*} = 0.$$

According to the results of [11], the theorems below are consequences of Lemmas 2–5.

**Theorem 1.** *Let condition (5) be fulfilled. Then for every  $F \in W_-^*$  there exists a unique strong generalized solution  $u$  of problem (1), (2) of the class  $L_2$  for which the estimate*

$$\|u\|_{L_2(D)} \leq c \|F\|_{W_-^*}, \quad (41)$$

with a positive constant  $c$  not depending on  $F$ , is valid.

**Theorem 2.** *Let condition (5) be fulfilled. Then for every  $F \in L_2(D)$  there exists a unique strong generalized solution  $u$  of problem (1), (2) of the class  $W_+$  for which estimate (41) is valid.*

*Proof.* The existence of a solution of problem (1), (2) in Theorem 2 follows, for example, from the arguments as follows. By virtue of inequality (34), the functional  $(F, v)_{L_2(D)}$  can be regarded as a linear continuous functional of  $L^*v$ , where  $v \in E^*$ ,  $F \in L_2(D)$ . Indeed, using this inequality, we have

$$|(F, v)_{L_2(D)}| \leq \|F\|_{L_2(D)} \|v\|_{L_2(D)} \leq c^* \|L^*v\|_{W_-}, \quad c^* = \text{const} > 0.$$

By the Khan–Banach theorem, this functional can be linearly and continuously extended into the whole space  $W_-$ . Following the theorem on a general type of a linear continuous functional over  $W_-$ , there exists a function  $u \in W_+$  such that

$$(u, L^*)_{L_2(D)} = (F, v)_{L_2(D)}, \quad v \in E^*. \quad (42)$$

Equality (42) means that  $u$  is a weak generalized solution of the problem (1), (2). Let us now show that this solution is also a strong generalized solution of problem (1), (2) of the class  $W_+$ .

Since the space  $E$  is dense in  $W_+$ , there exists a sequence  $u_n \in E$  of functions such that

$$\lim_{n \rightarrow \infty} \|u_n - u\|_{W_+} = 0. \quad (43)$$

Using equalities (21) and (42), we have

$$(u_n - u, L^*v)_{L_2(D)} = (Lu_n - F, v)_{L_2(D)}. \quad (44)$$

Now, according to the generalized Schwartz inequality,

$$|(u_n - u, L^*v)_{L_2(D)}| \leq \|u_n - u\|_{W_+} \|L^*v\|_{W_-}. \quad (45)$$

It follows from (43)–(45) that in the space  $W^*$  the sequence  $Lu_n$  of functions converges weakly to the function  $F$ . But since this sequence, because of (16) and (43), converges in the norm of the space  $W_-^*$ , we obtain

$$\lim_{n \rightarrow \infty} \|Lu_n - F\|_{W_-^*} = 0.$$

Consequently, the function  $u$  is a strong generalized solution of problem (1), (2) of the class  $W_+$ .

This fact can be proved in a different way. Indeed, using equalities (21) and (42) and inequality (17), we have

$$\begin{aligned} \|Lu_n - F\|_{W_-^*} &= \sup_{v \in W_+^*} \|v\|_{W_+^*}^{-1} (Lu_n - F, v)_{L_2(D)} = \\ &= \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} [(Lu_n, v)_{L_2(D)} - (F, v)_{L_2(D)}] = \\ &= \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} [(u_n, L^*v)_{L_2(D)} - (u, L^*v)_{L_2(D)}] = \\ &= \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} (u_n - u, L^*v)_{L_2(D)} \leq \\ &\leq \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} \|u_n - u\|_{W_+} \|L^*v\|_{W_-} \leq \\ &\leq \sup_{v \in E^*} \|v\|_{W_+^*}^{-1} \|u_n - u\|_{W_+} c_2 \|v\|_{W_+^*} = c_2 \|u_n - u\|_{W_+}, \end{aligned}$$

whence  $\lim_{n \rightarrow \infty} \|Lu_n - F\|_{W_-^*} = 0$ .

The uniqueness of a strong generalized solution of problem (1), (2) of the class  $W_+$  in Theorem 2 as well as estimate (41) follow from inequality (23).

As for Theorem 1, it can be proved as follows. Since the space  $L_2(D)$  is dense in the space  $W_-^*$ , for every element  $F \in W_-^*$  there exists a sequence  $F_n \in L_2(D)$  of functions such that  $\lim_{n \rightarrow \infty} \|F_n - F\|_{W_-^*} = 0$ . According to Theorem 2, for every function  $F_n \in L_2(D)$  there exists a unique strong generalized solution  $u_n$  of problem (1), (2) of the class  $W_+$ . Furthermore, using inequality (23) and passing to the limit, we obtain the existence and the uniqueness of a strong generalized solution of problem (1), (2) of the class  $L_2$  as well as estimate (41).  $\square$

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