

# ON RIEMANNIAN MANIFOLDS ENDOWED WITH A LOCALLY CONFORMAL COSYMPLECTIC STRUCTURE

ION MIHAI, RADU ROSCA, AND VALENTIN GHIȘOIU

*Received 18 September 2004 and in revised form 7 September 2005*

We deal with a locally conformal cosymplectic manifold  $M(\phi, \Omega, \xi, \eta, g)$  admitting a conformal contact quasi-torse-forming vector field  $T$ . The presymplectic 2-form  $\Omega$  is a locally conformal cosymplectic 2-form. It is shown that  $T$  is a 3-exterior concurrent vector field. Infinitesimal transformations of the Lie algebra of  $\wedge M$  are investigated. The Gauss map of the hypersurface  $M_\xi$  normal to  $\xi$  is conformal and  $M_\xi \times M_\xi$  is a Chen submanifold of  $M \times M$ .

## 1. Introduction

Locally conformal cosymplectic manifolds have been investigated by Olszak and Rosca [7] (see also [6]).

In the present paper, we consider a  $(2m + 1)$ -dimensional Riemannian manifold  $M(\phi, \Omega, \xi, \eta, g)$  endowed with a locally conformal cosymplectic structure. We assume that  $M$  admits a principal vector field (or a conformal contact quasi-torse-forming), that is,

$$\nabla T = sd p + T \wedge \xi = sd p + \eta \otimes T - T^b \otimes \xi, \quad (1.1)$$

with  $ds = s\eta$ .

First, we prove certain geometrical properties of the vector fields  $T$  and  $\phi T$ . The existence of  $T$  and  $\phi T$  is determined by an exterior differential system in involution (in the sense of Cartan [3]).

The principal vector field  $T$  is 3-exterior concurrent (see also [8]), it defines a Lie relative contact transformation of the co-Reeb form  $\eta$ , and the Lie differential of  $T^b$  with respect to  $T$  is conformal to  $T^b$ . The vector field  $\phi T$  is an infinitesimal transformation of generators  $T$  and  $\xi$ . The vector fields  $\xi$ ,  $T$ , and  $\phi T$  commute and the distribution  $D_T = \{T, \phi T, \xi\}$  is involutive. The divergence and the Ricci curvature of  $T$  are computed.

Next, we investigate infinitesimal transformations on the Lie algebra of  $\wedge M$ .

In the last section, we study the hypersurface  $M_\xi$  normal to  $\xi$ . We prove that  $M_\xi$  is Einsteinian, its Gauss map is conformal, and the product submanifold  $M_\xi \times M_\xi$  in  $M \times M$  is a  $\mathcal{U}$ -submanifold in the sense of Chen.

**2. Preliminaries**

Let  $(M, g)$  be an  $n$ -dimensional Riemannian manifold endowed with a metric tensor  $g$ . Let  $\Gamma TM$  and  $\flat : TM \rightarrow T^*M, Z \mapsto Z^\flat$  be the set of sections of the tangent bundle  $TM$  and the musical isomorphism defined by  $g$ , respectively. Following a standard notation, we set  $A^q(M, TM) = \text{Hom}(\Lambda^q TM, TM)$  and notice that the elements of  $A^q(M, TM)$  are the vector-valued  $q$ -forms ( $q \leq n$ ) (see also [9]). Denote by  $d^\nabla : A^q(M, TM) \rightarrow A^{q+1}(M, TM)$  the exterior covariant derivative operator with respect to the Levi-Civita connection  $\nabla$ . It should be noticed that generally  $d^{\nabla^2} = d^\nabla \circ d^\nabla \neq 0$ , unlike  $d^2 = d \circ d = 0$ . If  $dp \in A^1(M, TM)$  denotes the soldering form on  $M$ , one has  $d^\nabla(dp) = 0$ .

The cohomology operator  $d^\omega$  acting on  $\Lambda M$  is defined by  $d^\omega \gamma = d\gamma + \omega \wedge \gamma$ , where  $\omega$  is a closed 1-form. If  $d^\omega \gamma = 0$ ,  $\gamma$  is said to be  $d^\omega$ -closed.

Let  $R$  be the curvature operator on  $M$ . Then, for any vector field  $Z$  on  $M$ , the second covariant differential is defined as

$$\nabla^2 Z = d^\nabla(\nabla Z) \in A^2(M, TM) \tag{2.1}$$

and satisfies

$$\nabla^2 Z(V, W) = R(V, W)Z, \quad Z, V, W \in \Gamma TM. \tag{2.2}$$

Let  $O = \text{vect}\{e_A \mid A = 1, \dots, n\}$  be an adapted local field of orthonormal frames over  $M$  and let  $O^* = \text{covect}\{\omega^A\}$  be its associated coframe. With respect to  $O$  and  $O^*$ , É. Cartan’s structure equation can be written, in the indexless manner, as

$$\begin{aligned} \nabla e &= \theta \otimes e \in A^1(M, TM), \\ d\omega &= -\theta \wedge \omega, \\ d\theta &= -\theta \wedge \theta + \Theta. \end{aligned} \tag{2.3}$$

In the above equations,  $\theta$ , respectively,  $\Theta$  are the local connection forms in the bundle  $\mathcal{O}(M)$ , respectively, the curvature forms on  $M$ .

**3. Locally conformal cosymplectic structure**

Let  $M(\phi, \Omega, \xi, \eta, g)$  be a  $(2m + 1)$ -dimensional Riemannian manifold carrying a quintuple of structure tensor fields, where  $\phi$  is an automorphism of the tangent bundle  $TM$ ,  $\Omega$  a presymplectic form of rank  $2m$ ,  $\xi$  the Reeb vector field, and  $\eta = \xi^\flat$  the associated Reeb covector,  $g$  the metric tensor.

We assume in the present paper that  $\eta$  is closed and  $\lambda$  is a scalar ( $\lambda \in \Lambda^0 M$ ) such that  $d\lambda = \lambda' \eta$ , with  $\lambda' \in \Lambda^0 M$ .

We agree to denominate the manifold  $M$  a *locally conformal cosymplectic manifold* if it satisfies

$$\begin{aligned} \phi^2 &= -I + \eta \otimes \xi, & \phi\xi &= 0, & \eta \circ \phi &= 0, & \eta(\xi) &= 1, \\ \nabla\xi &= \lambda(dp - \eta \otimes \xi), \\ d\lambda &= \lambda' \eta, \\ \Omega(Z, Z') &= g(\phi Z, Z'), & \Omega^m \wedge \eta &\neq 0, \end{aligned} \tag{3.1}$$

where  $dp \in A^1(M, TM)$  denotes the canonical vector-valued 1-form (or the soldering form [5]) on  $M$ . Then  $\Omega$  is called the fundamental 2-form on  $M$  and is expressed by

$$\Omega = \sum_{i=1}^m \omega^i \wedge \omega^{i^*}, \quad i^* = i + m. \tag{3.2}$$

By the well-known relations

$$\theta_j^i = \theta_{j^*}^{i^*}, \quad \theta_j^{i^*} = \theta_i^{j^*}, \quad i^* = i + m, \tag{3.3}$$

one derives by differentiation of  $\Omega$

$$d^{-2\lambda\eta}\Omega = 0 \quad (d\Omega = 2\lambda\eta \wedge \Omega), \tag{3.4}$$

which shows that the presymplectic 2-form  $\Omega$  is a locally conformal cosymplectic form. Operating on  $\phi dp$  by  $d^\nabla$ , it follows that

$$d^\nabla(\phi dp) = 2\lambda\Omega \otimes \xi + 2\eta \wedge \phi dp. \tag{3.5}$$

On the other hand, we agree to call a vector field  $T$ , such that

$$\nabla T = s dp + T \wedge \xi = s dp + \eta \otimes T - T^b \otimes \xi, \tag{3.6}$$

a *principal vector field* on  $M$ , or a *conformal contact quasi-torse-forming* if

$$ds = s\eta. \tag{3.7}$$

In these conditions, since the  $q$ th covariant differential  $\nabla^q$  of a vector field  $Z \in \Gamma TM$  is defined inductively, that is,  $\nabla^q Z = d^\nabla(\nabla^{q-1} Z)$ , one derives from (3.6)

$$\nabla^4 T = -\lambda^3 \eta \wedge T^b \otimes dp. \tag{3.8}$$

As a natural concept of concurrent vector fields and by reference to [8], this proves that  $T$  is a 3-exterior concurrent vector field.

Since, as it is known, the divergence of a vector field  $Z$  is defined by

$$\operatorname{div} Z = \sum_A g(\nabla_{e_A} Z, e_A), \tag{3.9}$$

one derives from (3.2) and (3.6)

$$\begin{aligned} \operatorname{div} \xi &= 2m\lambda, \\ \operatorname{div} T &= T^0 + (2m+1)s, \end{aligned} \quad (3.10)$$

where  $T^0 = \eta(T)$ . On the other hand, from (3.6), we derive

$$\begin{aligned} dT^a + T^b \theta_b^a + \lambda T^0 \omega^a &= s\omega^a + T^a \eta, \quad a, b \in \{1, \dots, 2m\}, \\ dT^0 &= -(1+\lambda)T^b + [s + (1+\lambda)T^0] \eta. \end{aligned} \quad (3.11)$$

After some calculations, one gets

$$dT^b = \lambda dT^0 \wedge \eta + \lambda(1+\lambda)\eta \wedge T^b, \quad (3.12)$$

which proves that  $T^b$  is an exterior recurrent form [1].

Taking the Lie differential of  $\eta$  with respect of  $T$ , one gets

$$\mathcal{L}_T \eta = dT^0, \quad (3.13)$$

and so it turns out that

$$d(\mathcal{L}_T \eta) = 0. \quad (3.14)$$

Following a known terminology,  $T$  defines a relative contact transformation of the co-Reeb form  $\eta$ .

Next, we will point out some properties of the vector field  $\phi T$ .

By virtue of (3.11), one derives

$$\nabla \phi T = (s - \lambda T^0) \phi dp + \phi T \otimes \eta, \quad (3.15)$$

and so, by (3.6) and (3.2), one gets

$$\begin{aligned} [\phi T, T] &= -\lambda T^0 \phi T, \\ [\phi T, \xi] &= (1-\lambda) \phi T, \\ [T, \xi] &= 0. \end{aligned} \quad (3.16)$$

The above relations prove that  $\phi T$  admits an infinitesimal transformation of generators  $T$  and  $\xi$ . In addition, it is seen that  $\xi$  and the principal vector field  $T$  commute and that the distribution  $D_T = \{T, \phi T, \xi\}$  is involutive.

By Orsted lemma [1], if one takes

$$\mathcal{L}_T T^b = \rho T^b + [T, \xi]^b, \quad (3.17)$$

one gets at once by (3.16)

$$\mathcal{L}_T T^b = \rho T^b, \quad (3.18)$$

which shows that the Lie differential of  $T^b$  with respect to the principal vector field  $T$  is conformal to  $T^b$ .

Moreover, making use of the contact  $\phi$ -Lie derivative operator  $(\mathcal{L}_\xi\phi)Z = [\xi, \phi] - \phi[\xi, Z]$ , one gets in the case under discussion

$$(\mathcal{L}_\xi\phi)T = (\lambda - 1)\phi T. \tag{3.19}$$

Hence,  $\xi$  defines a  $\phi$ -Lie transformation of the principal vector field  $T$ .

It is worth to point out that the existence of  $T$  and  $\phi T$  is determined by an exterior differential system  $\Sigma$  whose characteristic numbers are  $r = 3, s_0 = 1, s_1 = 2$  ( $r = s_0 + s_1$ ). Consequently, the system  $\Sigma$  is in *involution* (in the sense of Cartan [3]) and so  $T$  and  $\phi T$  depend on 1 arbitrary function of 2 arguments (É. Cartan's test).

Recall Yano's formula for any vector field  $Z$ , that is,

$$\operatorname{div}(\nabla_Z Z) - \operatorname{div}(\operatorname{div} Z)Z = \mathcal{R}(Z, Z) - (\operatorname{div} Z)^2 + \sum_{A,B} (\nabla_{e_A} Z, e_B)(\nabla_{e_B} Z, e_A), \tag{3.20}$$

where  $\mathcal{R}$  denotes the Ricci tensor.

Then, since one has

$$\begin{aligned} \operatorname{div} T &= T^0 + (2m + 1)s, \\ \nabla_T T &= (s + T^0)T - \|T\|^2\xi, \end{aligned} \tag{3.21}$$

it follows by (3.20) that the Ricci tensor corresponding to  $T$  is expressed by

$$\mathcal{R}(T, T) = (s + T^0)(T^0 + (2m + 1)s) - 4m^2 - s^2. \tag{3.22}$$

Finally, in the same order of ideas, since one has  $i_{\phi T}T^b = 0$ , then, by the Lie differentiation, one derives  $\mathcal{L}_{\phi T}T^b = 0$ , which shows that  $\phi T$  defines a Lie Pfaffian transformation of the dual form of the vector field  $T$ .

Besides, by the Ricci identity involving the triple  $T, \phi T, \xi$ , that is,

$$(\mathcal{L}_\xi g)(T, \phi T) = g(\nabla_\xi T, \phi T) + g(T, \nabla_\xi \phi T), \tag{3.23}$$

one gets  $(\mathcal{L}_\xi g)(T, \phi T) = 0$ .

Hence, one may say that the Lie structure vanishes.

Thus, we have the following.

**THEOREM 3.1.** *Let  $M(\phi, \Omega, \xi, \eta, g)$  be a  $(2m + 1)$ -dimensional Riemannian manifold endowed with a locally conformal cosymplectic structure and a principal vector field  $T$  defined as a conformal contact quasi-torse-forming and structure scalar  $\lambda$ .*

*The following properties hold.*

- (i)  $\Omega$  is a locally conformal cosymplectic 2-form.
- (ii) The principal vector field  $T$  is 3-exterior concurrent, that is,

$$\nabla^4 T = -\lambda^3 \eta \wedge T^b \otimes dp. \tag{3.24}$$

- (iii)  $T$  defines a Lie relative contact transformation of the co-Reeb form  $\eta$ .

- (iv)  $\phi T$  is an infinitesimal transformation of generators  $T$  and  $\xi$ . The vector fields  $\xi$ ,  $T$ , and  $\phi T$  commute and the distribution  $D_T = \{T, \phi T, \xi\}$  is involutive.
- (v) The Lie differential of  $T^b$  with respect to  $T$  is conformal to  $T^b$ .
- (vi)  $\operatorname{div} T = T^0 + (2m + 1)s$ .
- (vii) The Ricci tensor corresponding to  $T$  is expressed by

$$\mathcal{R}(T, T) = (s + T^0)(T^0 + (2m + 1)s) - 4m^2 - s^2. \tag{3.25}$$

- (viii) The dual form  $T^b$  of  $T$  is an exterior recurrent form.

#### 4. Conformal symplectic form

We will point out some problems regarding the conformal symplectic form  $\Omega$ . Taking the Lie differential of  $\Omega$  with respect to the Reeb vector field  $\xi$ , we quickly get

$$d(\mathcal{L}_\xi \Omega) = 2\lambda \Omega. \tag{4.1}$$

Hence, we may say that  $\xi$  defines a conformal Lie derivative of  $\Omega$ .

Next, taking the Lie differential of  $\Omega$  with respect to the vector field  $\phi T$ , one gets in two steps

$$\mathcal{L}_{\phi T} \Omega = d(T^0 \eta - T^b), \tag{4.2}$$

and, by (3.12), one derives at once

$$d(\mathcal{L}_{\phi T} \Omega) = 0. \tag{4.3}$$

Consequently, from above, we may state that the vector field  $\phi T$  defines a relative almost-Pfaffian transformation of the form  $\Omega$  (see [6]).

In the same order of ideas, one derives after some longer calculations

$$d(\mathcal{L}_T \Omega) = 2\lambda \eta \wedge d(\phi T)^b - 2\lambda(1 + \lambda)T^b \wedge \Omega + [s + (1 + s)T^0 + 4\lambda^2 T^0] \eta \wedge \Omega, \tag{4.4}$$

and we may say that the principal vector field  $T$  defines a Lie almost-conformal transformation of  $\Omega$ .

Finally, we agree to define the 3-form

$$\psi = T^b \wedge \Omega, \tag{4.5}$$

the principal 3-form on the manifold  $M$  under consideration.

Making use of (3.4) and (3.12), one derives

$$d\psi = \lambda(1 + \lambda)\eta \wedge \psi. \tag{4.6}$$

This shows that  $\psi$  is a recurrent 3-form. Consequently, since one gets

$$i_{\phi T} T^b = 0, \quad i_{\phi T} \Omega = T^0 \eta - T^b, \tag{4.7}$$

one derives

$$i_{\phi T}\psi = T^0\eta \wedge T^b, \tag{4.8}$$

and so one obtains

$$\mathcal{L}_{\phi T}\psi = 0. \tag{4.9}$$

Hence, we may say that the Lie derivative defines  $\phi T$  as a Pfaffian transformation of  $\psi$ . Thus, we may state the following theorem.

**THEOREM 4.1.** *Let  $M(\phi, \Omega, \xi, \eta, g)$  be a locally conformal cosymplectic manifold. Then, the following hold.*

- (i) *The Reeb vector field  $\xi$  defines a conformal Lie derivative of  $\Omega$ .*
- (ii) *The vector field  $\phi T$  defines a relative almost-Pfaffian transformation of the 2-form  $\Omega$ .*
- (iii) *The principal vector field  $T$  defines a Lie almost-conformal transformation of  $\Omega$ .*
- (iv) *Let  $\psi = T^b \wedge \Omega$  be the principal 3-form on the manifold  $M$ . Then  $\psi$  is a recurrent 2-form and the Lie derivative defines  $\phi T$  as a Pfaffian transformation of  $\psi$ .*

**5. Hypersurface  $M_\xi$  normal to  $\xi$**

We denote by  $M_\xi$  the hypersurface of  $M$  normal to  $\xi$ . Since  $d\eta = 0$  ( $\eta = \xi^b$ ), one may consider the  $2m$ -dimensional manifold  $M_\xi$  and the 1-dimensional foliation in the direction of  $\xi$  is totally geodesic.

Recall that the Weingarten map

$$A : T_{\bar{p}}(M_\xi) \longrightarrow T_{\bar{p}}(M_\xi), \quad \forall \bar{p} \in M_\xi, \tag{5.1}$$

is a linear and selfadjoint application and  $\Omega_\eta$  is symplectic.

Then, if  $Z^T$  is any horizontal vector field, one gets by  $d\eta = 0$

$$AZ^T = \nabla_{Z^T}\xi = -Z^T, \tag{5.2}$$

and this shows that  $Z^T$  is a principal vector field of  $M_\xi$ .

Recall that  $II = \langle d\bar{p}, d\bar{p} \rangle$  and  $III = \langle \nabla\xi, \nabla\xi \rangle$  denote the second and the third fundamental forms associated with the immersion  $x : M_\xi \rightarrow M$ .

Then, by the expression of  $\nabla\xi$ , one finds that  $II = g^T$  and  $III = g^T$ , where  $g^T$  means the horizontal component of  $g$ . Hence, we may conclude that the immersion  $x : M_\xi \rightarrow M$  is horizontally umbilical and has  $2m$  principal curvatures equal to 1.

The expression of  $III$  proves that the Gauss map is conformal and it can also be seen that  $M_\xi$  is Einsteinian.

On the other hand, since obviously the mean curvature field  $\xi$  is nowhere zero, by reference to [4], it follows that the product submanifold  $M_\xi \times M_\xi$  in  $M \times M$  is a  $\mathcal{U}$ -submanifold (i.e., its allied mean curvature vanishes), or a *Chen* submanifold.

We may summarize the above by the following.

THEOREM 5.1. *Let  $M(\phi, \Omega, \xi, \eta, g)$  be a locally conformal cosymplectic manifold and  $x: M_\xi \rightarrow M$  the immersion of one hypersurface normal to  $\xi$ . Then, the following hold.*

- (i) *The Gauss map associated to the immersion  $x: M_\xi \rightarrow M$  is conformal.*
- (ii) *The product submanifold  $M_\xi \times M_\xi$  in  $M \times M$  is a  $\mathcal{U}$ -submanifold.*

### Acknowledgment

The third author was supported by the CEEEX-ET 2968/2005 Grant of the Romanian Ministry of Education and Research.

### References

- [1] T. P. Branson, *Conformally covariant equations on differential forms*, Comm. Partial Differential Equations **7** (1982), no. 4, 393–431.
- [2] A. Bucki, *Submanifolds of almost  $r$ -paracontact manifolds*, Tensor (N.S.) **40** (1984), 69–89.
- [3] É. Cartan, *Les Systèmes Différentiels Extérieurs et Leurs Applications Géométriques*, Actualités Sci. Ind., no. 994, Hermann, Paris, 1945.
- [4] B.-Y. Chen, *Geometry of Submanifolds*, Pure and Applied Mathematics, no. 22, Marcel Dekker, New York, 1973.
- [5] J. Dieudonné, *Treatise on Analysis. Vol. 4*, Pure and Applied Mathematics, vol. 10-IV, Academic Press, New York, 1974.
- [6] I. Mihai, R. Rosca, and L. Verstraelen, *Some Aspects of the Differential Geometry of Vector Fields*, Centre for Pure and Applied Differential Geometry (PADGE), vol. 2, Katholieke Universiteit Brussel Group of Exact Sciences, Brussels; Katholieke Universiteit Leuven, Department of Mathematics, Leuven, 1996.
- [7] Z. Olszak and R. Rosca, *Normal locally conformal almost cosymplectic manifolds*, Publ. Math. Debrecen **39** (1991), no. 3-4, 315–323.
- [8] M. Petrović, R. Rosca, and L. Verstraelen, *Exterior concurrent vector fields on Riemannian manifolds. I. Some general results*, Soochow J. Math. **15** (1989), no. 2, 179–187.
- [9] W. A. Poor, *Differential Geometric Structures*, McGraw-Hill, New York, 1981.
- [10] S.-I. Tachibana and W. N. Yu, *On a Riemannian space admitting more than one Sasakian structures*, Tôhoku Math. J. (2) **22** (1970), 536–540.
- [11] K. Yano, *Integral Formulas in Riemannian Geometry*, Pure and Applied Mathematics, no. 1, Marcel Dekker, New York, 1970.

Ion Mihai: Faculty of Mathematics and Computer Science, University of Bucharest, 14 Academiei street, 010014 Bucharest, Romania

*E-mail address:* imihai@math.math.unibuc.ro

Radu Rosca: 59 Avenue Emile Zola, 75015 Paris, France

Valentin Ghişoiu: Faculty of Mathematics and Computer Science, University of Bucharest, 14 Academiei street, 010014 Bucharest, Romania

*E-mail address:* ghisoiu@geometry.math.unibuc.ro