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**ON THE EXISTENCE OF NONNEGATIVE SOLUTIONS OF THE PERIODIC BOUNDARY VALUE PROBLEM FOR A SYSTEM OF LINEAR GENERALIZED ORDINARY DIFFERENTIAL EQUATIONS**

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Consider the  $\omega$ -periodic boundary value problem

$$dx(t) = dA(t) \cdot \mathcal{P}(t)x(t) + dq(t), \tag{1}$$

$$x(0) = x(\omega), \tag{2}$$

where  $\omega$  is a positive number,  $A = (a_{ik}(t))_{i,k=1}^n$ ,  $a_{ik}(t) \equiv a_{ik}^{(1)}(t) - a_{ik}^{(2)}(t)$ ,  $a_{ik}^{(\sigma)} : R \rightarrow R$  ( $\sigma = 1, 2$ ) are functions nondecreasing on  $[0, \omega]$ ,  $A^{(\sigma)} = (a_{ik}^{(\sigma)})_{i,k=1}^n \in \text{BV}_{\omega}^{n \times n}$  ( $\sigma = 1, 2$ ),  $q = (q_k)_{k=1}^n \in \text{BV}_{\omega}^n$  and  $\mathcal{P} = (p_{ik})_{i,k=1}^n \in \bigcap_{\sigma=1}^2 L([0, \omega], R^{n \times n}; A^{(\sigma)})$  is such that  $\int_0^t dA(\tau) \cdot \mathcal{P}(\tau) \in \text{BV}_{\omega}^{n \times n}$ .

In this note, sufficient conditions are given guaranteeing both the unique solvability of the problem (1),(2) and the nonnegativeness of the solution.

The following notation and definitions will be used:  $R = ]-\infty, +\infty[$ ,  $R_+ = [0, +\infty[$ ,  $[a, b]$  ( $a, b \in R$ ) is a closed segment,  $R^{n \times m}$  is the space of all real  $n \times m$ -matrices  $X = (x_{ik})_{i,k=1}^{n,m}$  with the norm  $\|X\| = \max_{k=1, \dots, m} \sum_{i=1}^n |x_{ik}|$ ; if  $X \in R^{n \times n}$ , then  $\det(X)$  is the determinant of  $X$ ,  $I_n$  is the identity  $n \times n$ -matrix;  $\delta_{ij}$  is the Kroneker symbol, i.e.,  $\delta_{ij} = 1$  if  $i = j$ ,  $\delta_{ij} = 0$  if  $i \neq j$ ;  $R^n = R^{n \times 1}$  is the space of all real column  $n$ -vectors  $x = (x_i)_{i=1}^n$ .

$\text{BV}([a, b], R^{n \times m})$  is the set of all matrix-functions  $X = (x_{ik})_{i,k=1}^{n,m} : [a, b] \rightarrow R^{n \times m}$  such that every its component  $x_{ik}$  has bounded total variation on  $[a, b]$ .

$s_k : \text{BV}([a, b], R) \rightarrow \text{BV}([a, b], R)$  ( $k = 0, 1, 2$ ) are the operators defined by  $s_1(x)(a) = s_2(x)(a) = 0$ ,

$$s_1(x)(t) = \sum_{a < \tau \leq t} d_1 x(\tau) \quad \text{and} \quad s_2(x)(t) = \sum_{a \leq \tau < t} d_2 x(\tau) \quad \text{for } t \in ]a, b],$$

$$s_0(x)(t) \equiv x(t) - s_1(x)(t) - s_2(x)(t).$$

$\text{BV}_{\omega}^{n \times m}$  is the set of all matrix-functions  $X : R \rightarrow R^{n \times m}$  such that  $X(t+\omega) = X(t) + X(\omega)$  for  $t \in R$ , and its restriction on  $[0, \omega]$  belongs to  $\text{BV}([0, \omega], R^{n \times m})$ ;  $X(t-)$  and  $X(t+)$  are the left and the right limits of  $X$  at the point  $t \in R$ ;  $d_1 X(t) = X(t) - X(t-)$ ,  $d_2 X(t) = X(t+) - X(t)$ .

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If  $x \in \text{BV}([0, \omega], R)$ ,  $x(0) = 0$ ,  $1 + (-1)^j d_j x(t) \neq 0$  for  $t \in [0, \omega]$  ( $j = 1, 2$ ) and  $\lambda(x)(\omega) \neq 1$ , where

$$\lambda(x)(t) = \exp\left(s_0(x)(t)\right) \prod_{0 \leq \tau < t} (1 + d_2 x(\tau)) / \prod_{0 < \tau \leq t} (1 - d_1 x(\tau)),$$

then  $g_0(x)(t, \tau) = (1 - \lambda(x)(\omega))^{-1} \lambda(x)(\omega) \lambda(x)(t) \lambda^{-1}(x)(\tau)$  for  $0 \leq t \leq \tau \leq \omega$  and  $g_0(x)(t, \tau) = (1 - \lambda(x)(t) \lambda^{-1}(x)(\tau))$  for  $0 \leq \tau < t \leq \omega$ ;  $g_k(x)(t, \tau) = (1 + (-1)^k d_k x(\tau))^{-1} g_0(x)(t, \tau)$  for  $t \neq \tau$  ( $k = 1, 2$ ),  $g_1(x)(t, t) = (1 - \lambda(x)(\omega))^{-1} (1 - d_1 x(t))^{-1}$  and  $g_2(x)(t, t) = (1 - \lambda(x)(\omega))^{-1} (1 + d_2 x(t))^{-1} \lambda(x)(\omega)$ .

If  $g : R \rightarrow R$  is nondecreasing on the interval  $I \subset R$ ,  $x : R \rightarrow R$  and  $s < t$  ( $s, t \in I$ ), then

$$\int_s^t x(\tau) dg(\tau) = \int_{]s, t[} x(\tau) dg(\tau) + x(t) d_1 g(t) + x(s) d_2 g(s),$$

where  $\int_{]s, t[} x(\tau) dg(\tau)$  is the Lebesgue-Stieltjes integral over the open interval  $]s, t[$  with

respect to the measure  $\mu_g$  corresponding to the function  $g$  (if  $s = t$ , then  $\int_s^t x(\tau) dg(\tau) = 0$ );  $L([a, b], R; g)$  is the set of all  $\mu_g$ -measurable functions  $x : [0, \omega] \rightarrow R$  such that  $\int_a^b |x(t)| dg(t) < +\infty$ .

A matrix-function is said to be nondecreasing if every of its components are such.

If  $G = (g_{ik})_{i,k=1}^{l,n} : R \rightarrow R^{l \times n}$  is a matrix-function nondecreasing on the interval  $I \subset R$  and  $X = (x_{kj})_{k,j=1}^{n,m} : R \rightarrow R^{n \times m}$ , then

$$\int_s^t dG(\tau) \cdot X(\tau) = \left( \sum_{k=1}^n \int_s^t x_{kj}(\tau) dg_{ik}(\tau) \right)_{i,j=1}^{l,m} \quad \text{for } s \leq t \text{ } (s, t \in I);$$

$L([a, b], R^{n \times m}; G)$  is the set of all matrix-functions  $X = (x_{kj})_{k,j=1}^{n,m} : [a, b] \rightarrow R^{n \times m}$  such that  $x_{kj} \in L([a, b], R; g_{ik})$  ( $i = 1, \dots, l$ ;  $k = 1, \dots, n$ ;  $j = 1, \dots, m$ ).

If  $G^{(\sigma)} : R \rightarrow R^{l \times n}$  ( $\sigma = 1, 2$ ) are matrix-functions nondecreasing on the interval  $I \subset R$ ,  $G = G^{(1)} - G^{(2)}$  and  $X : R \rightarrow R^{n \times m}$ , then

$$\int_s^t dG(\tau) \cdot X(\tau) = \int_s^t dG^{(1)}(\tau) \cdot X(\tau) - \int_s^t dG^{(2)}(\tau) \cdot X(\tau) \quad \text{for } s \leq t \text{ } (s, t \in I).$$

A vector-function  $x : R \rightarrow R^n$  is said to be a solution of the system (1) (of the system  $dA(t) \leq dA(t) \cdot \mathcal{P}(t)x(t) + dq(t)$ ) if its restriction on  $[s, t]$  belongs to  $\text{BV}([s, t], R^n)$  and

$$x(t) - x(s) - \int_s^t dA(\tau) \cdot \mathcal{P}(\tau)x(\tau) - q(t) + q(s) = 0 \quad (< 0) \quad \text{for } s < t \text{ } (s, t \in R).$$

**Definition.** Let  $\sigma_i \in \{-1, 1\}$  ( $i = 1, \dots, n$ ). We say that the matrix-function  $C = (c_{il})_{i,l=1}^n : R \rightarrow R^{n \times n}$  belongs to the set  $U_\omega^{\sigma_1, \dots, \sigma_n}$  if  $c_{il} \in \text{BV}_\omega$  ( $i, l = 1, \dots, n$ ), the

functions  $c_{il}$  ( $i \neq l$ ;  $i, l = 1, \dots, n$ ) are nondecreasing on  $[0, \omega]$  and continuous at the point  $t_i = \frac{1-\sigma_i}{2}\omega$ ,

$$d_j c_{ii}(t_i) \geq 0 \quad (j = 1, 2; \quad i = 1, \dots, n), \tag{3}$$

$$\|d_j C(t)\| < 1 \quad \text{for } t \in [0, \omega] \quad (j = 1, 2) \tag{4}$$

and the system of differential inequalities

$$\sigma_i dy_i(t) \leq \sum_{l=1}^n y_l(t) dc_{il}(t) \quad (i = 1, \dots, n)$$

has no nontrivial nonnegative  $\omega$ -periodic solution.

Let  $I_\omega^{\sigma_i} = ]0, \omega[ \cup \{ \frac{1+\sigma_i}{2}\omega \}$  and  $j_i = \frac{3+\sigma_i}{2}$  for  $i \in \{1, \dots, n\}$ .

**Theorem 1.** *Let*

$$\begin{aligned} &(-1)^{\sigma+1} \sigma_i p_{ki}(t) \leq p_{iki}^{(\sigma)}(t) \quad \text{and} \quad 0 \leq (-1)^{\sigma+1} \sigma_i p_{kl}(t) \leq p_{ikl}^{(\sigma)}(t) \\ &\text{for } \mu_{\alpha_{ik}^{(\sigma)}} - \text{almost everywhere } t \in I_\omega^{\sigma_i} \quad (i \neq l; \quad i, k, l = 1, \dots, n), \end{aligned} \tag{5}$$

$$0 \leq (-1)^{\sigma+1} \sigma_i p_{kl}(t_i) d_{j_i} \alpha_{ik}^{(\sigma)}(t_i) \leq \alpha_{ikl}^{(\sigma)} d_{j_i} \alpha_{ik}^{(\sigma)}(t_i) \quad (i, k, l = 1, \dots, n) \tag{6}$$

and

$$\left| \sum_{k=1}^n p_{ki}(t) d_{j_i} \alpha_{ik}^{(\sigma)}(t) \right| \leq |d_j c_{ii}(t)| \quad \text{for } t \in I_\omega^{\sigma_i} \quad (j = 1, 2; \quad i = 1, \dots, n) \tag{7}$$

for every  $\sigma \in \{1, 2\}$ , where  $\sigma_i \in \{-1, 1\}$ ,  $\alpha_{ikl}^{(\sigma)} \in R_+$ ,  $\mathcal{P}_i^{(\sigma)} = (p_{ikl}^{(\sigma)})_{k,l=1}^n \in L([0, \omega], R^{n \times n}; A^{(\sigma)})$ . Let, moreover, the functions  $\sigma_i q_i$  ( $i = 1, \dots, n$ ) be nondecreasing on  $R$ ,

$$\sum_{\sigma=1}^2 \sum_{k=1}^n \int_s^t p_{ikl}^{(\sigma)}(\tau) d\alpha_{ik}^{(\sigma)}(\tau) \leq c_{il}(t) - c_{il}(s) \quad \text{for } s < t; \quad s, t \in I_\omega^{\sigma_i} \quad (i, l = 1, \dots, n) \tag{8}$$

and

$$\sum_{\sigma=1}^2 \sum_{k=1}^n \alpha_{ikl}^{(\sigma)} d_{j_i} \alpha_{ik}^{(\sigma)}(t_i) \leq \delta_{il} d_{j_i} c_{il}(t_i) \quad (i, l = 1, \dots, n), \tag{9}$$

where

$$C = (c_{il})_{i,l=1}^n \in U_\omega^{\sigma_1, \dots, \sigma_n}.$$

Then the problem (1),(2) has a unique solution which is nonnegative.

**Corollary 1.** *Let the conditions (3)-(9) and*

$$\begin{aligned} &c_{ii}(\omega) - \sigma_i \sum_{0 < \tau \leq \omega} [\ln(1 - \sigma_i d_1 c_{ii}(\tau)) + \sigma_i d_1 c_{ii}(\tau)] + \\ &+ \sigma_i \sum_{0 \leq \tau < \omega} [\ln(1 + \sigma_i d_2 c_{ii}(\tau)) - \sigma_i d_2 c_{ii}(\tau)] < 0 \quad (i = 1, \dots, n) \end{aligned}$$

hold for every  $\sigma \in \{1, 2\}$ , where  $\sigma_i \in \{1, 2\}$ ,  $\alpha_{ikl}^{(\sigma)} \in R_+$ ,  $\mathcal{P}_i^{(\sigma)} = (p_{ikl}^{(\sigma)})_{k,l=1}^n \in L([0, \omega], R^{n \times n}; A^{(\sigma)})$ ,  $c_{il} \in BV_\omega$ ,  $c_{il}$  ( $i \neq l$ ) be nondecreasing on  $[0, \omega]$  and continuous at the point  $t_i$ . Let, moreover, the functions  $\sigma_i q_i$  ( $i = 1, \dots, n$ ) be nondecreasing on

$R$  and the modulus of every characteristic value of the matrix  $(s_{il})_{i,l=1}^n$ ,

$$s_{ii} = 0, \quad s_{il} = \sup \left\{ \sum_{j=0}^2 \int_0^\omega \sigma_i g_j(\sigma_i c_{ii})(t, \tau) ds_j(c_{il})(\tau) : t \in [0, \omega] \right\} \quad (i \neq l),$$

be less than 1. Then the conclusion of Theorem 1 is true.

**Corollary 2.** Let the conditions (5)–(9),

$$c_{il}(t) = \eta_{il} \alpha_i(t) \quad \text{for } t \in R \quad (i, l = 1, \dots, n)$$

and

$$d_j \alpha_i(t) < \left( |\eta_{ii}| + \sum_{l \neq i; l=1}^n \eta_{il} \right) d_j \alpha_i(t) < 1 \quad \text{for } t \in [0, \omega] \quad (j = 1, 2; \quad i = 1, \dots, n)$$

hold for every  $\sigma \in \{-1, 1\}$ , where  $\sigma_i \in \{1, 2\}$ ,  $\alpha_{ikl}^{(\sigma)} \in R_+$ ,  $\eta_{ii} \in R$ ,  $\eta_{il} \in R_+$  ( $i \neq l$ ),  $\mathcal{P}_i^{(\sigma)} = (p_{ikl}^{(\sigma)})_{k,l=1}^n \in L([0, \omega], R^{n \times n}; A^{(\sigma)})$ ,  $\alpha_i \in BV_\omega$  be nondecreasing on  $[0, \omega]$  and continuous at the point  $t_i$ ,  $\alpha_i(\omega) \neq 0$ . Let, moreover, the functions  $\sigma_i q_i$  ( $i = 1, \dots, n$ ) be nondecreasing on  $R$  and the real part of every characteristic value of the matrix  $(\eta_{il})_{i,l=1}^n$  be nonnegative. Then the conclusion of Theorem 1 is true.

**Corollary 3.** Let the conditions (3)–(9) hold for every  $\sigma \in \{-1, 1\}$ , where  $\sigma_1 = \sigma_2 = \dots = \sigma_n = \sigma_0 \in \{1, 2\}$ ,  $\alpha_{ikl}^{(\sigma)} \in R$ ,  $\mathcal{P}_i^{(\sigma)} = (p_{ikl}^{(\sigma)})_{k,l=1}^n \in L([0, \omega], R^{n \times n}; A^{(\sigma)})$ ,  $c_{il} \in BV_\omega$ ,  $c_{il}$  ( $i \neq l$ ) be nondecreasing on  $[0, \omega]$  and continuous at the point  $t_i$ . Let, moreover, the functions  $\sigma_i q_i$  ( $i = 1, \dots, n$ ) be nondecreasing on  $R$  and the modulus of every multiplier of the system

$$dy(t) = dC_{\sigma_0}(t) \cdot y(t)$$

be less than 1, where  $C_{\sigma_0}(t) = \sigma_0 C(\sigma_0 t + \frac{1-\sigma_0}{2} \omega)$ . Then the conclusion of Theorem 1 is true.

The analogous question has been considered in [1] for a system of linear ordinary differential equations.

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