

L. Alkhazishvili and M. Iordanishvili

**LOCAL VARIATION FORMULAS
FOR SOLUTION OF DELAY CONTROLLED
DIFFERENTIAL EQUATION
WITH MIXED INITIAL CONDITION**

Abstract. In this work the variation formulas are proved for solution of non-linear controlled differential equation with variable delays and mixed initial condition.

2010 Mathematics Subject Classification. 34K07, 93C73.

Key words and phrases. Formula of variation, delay differential equations, mixed initial condition.

რეზიუმე. ნაშრომში მიღებულია ამონახსნის ვარიაციის ფორმულები არა-წრფივი სამართი დიფერენციალური განტოლებისთვის ცვლადი დაგვიანებებით და შერეული საწყისი პირობით.

INTRODUCTION

In the present paper the differential equation

$$\dot{x}(t) = f(t, y(\tau_1(t)), \dots, y(\tau_s(t)), z(\sigma_1(t)), \dots, z(\sigma_m(t)), u(t)) \quad (1)$$

with the mixed initial condition

$$x(t) = (y(t), z(t))^T = (\varphi(t), g(t))^T, \quad t \in [\tau, t_0], \quad x(t_0) = (y_0, g(t_0))^T \quad (2)$$

is considered.

The condition (2) is called the mixed initial condition. It consists of two parts: the first one is the discontinuous part, $y(t) = \varphi(t)$, $t \in [\tau, t_0)$, $y(t_0) = y_0$, because in general $\varphi(t_0) \neq y_0$; the second part is the continuous part $z(t) = g(t)$, $t \in [\tau, t_0]$ because, always $z(t_0) = g(t_0)$.

The local formula of variation of solution, that is, a linear representation of variation of the solution of the problem (1)–(2) in a neighborhood of the right end of the main interval with respect to initial data and perturbation of control $u(t)$ is proved by the scheme given in [1].

An analogous formula for the equation

$$\dot{x}(t) = f\left(t, y(\tau_1(t)), \dots, y(\tau_s(t)), z(\sigma_1(t)), \dots, z(\sigma_m(t))\right) \quad (3)$$

with the initial condition (2) when variation of initial data and right-hand side of equation occurs is proved in [1].

It is important to note that the formula of variation which is proved in the present work doesn't follow from the formula proved in [1].

Formulas of variation for differential equations with delays for concrete cases of continuous and discontinuous initial conditions are obtained in [2]–[6].

Formulas of variation for controlled differential equations with delays, with continuous and discontinuous initial conditions are proved in [7], [8].

Formulas of variation of solution play an important role in the proof of necessary conditions of optimality [6], [9]–[12].

1. FORMULATION OF MAIN RESULTS

Let R_x^n be the n -dimensional vector space of points $x = (x^1, \dots, x^n)^T$, T means transpose; $O_1 \subset R_y^k$, $O_2 \subset R_z^e$, $G \subset R_u^r$ be open sets, $x = (y, z)^T$, $n = k + e$; $\tau_i(t)$, $i = \overline{1, s}$, $\sigma_j(t)$, $j = \overline{1, m}$, $t \in R_t^1$ be absolutely continuous scalar-valued functions and satisfy the following conditions:

$$\tau_i(t) \leq t, \quad \dot{\tau}_i(t) > 0; \quad \sigma_j(t) \leq t, \quad \dot{\sigma}_j(t) > 0.$$

Let $f(t, y_1, \dots, y_s, z_1, \dots, z_m, u)$ be an n -dimensional function satisfying the following conditions: for almost all $t \in I = [a, b]$ the function $f(t, \cdot) : O_1^s \times O_2^m \times G \rightarrow R_x^n$ is continuously differentiable; for any

$$(y_1, \dots, y_s, z_1, \dots, z_m, u) \in O_1^s \times O_2^m \times G$$

the functions f , f_{y_i} , $i = \overline{1, s}$, f_{z_j} , $j = \overline{1, m}$, f_u , are measurable on I ; for any compacts $K \subset O_1^s \times O_2^m$ and $M \subset G$ there exists a function $m_{K, M}(\cdot) \in$

$L(I, R_+)$, $R_+ = [0, \infty)$, such that for any $(y_1, \dots, y_s, z_1, \dots, z_m, u) \in K \times M$ and for almost all $t \in I$ we have

$$|f(t, y_1, \dots, y_s, z_1, \dots, z_m, u)| + \sum_{i=1}^s |f_{y_i}(\cdot)| + \sum_{j=1}^m |f_{z_j}(\cdot)| + |f_u(\cdot)| \leq m_{K,M}(t).$$

Let $E_\varphi^{(k)} = E_\varphi(I_1, R_y^k)$ be the space of piecewise continuous functions $\varphi : I_1 = [\tau, b] \rightarrow R_y^k$ with a finite number of discontinuity points of the first kind, equipped with the norm $\|\varphi\| = \sup\{|\varphi(t)| : t \in I_1\}$, $\tau = \min\{\tau_1(a), \dots, \tau_s(a), \sigma_1(a), \dots, \sigma_m(a)\}$.

Next, $\Delta_1 = \{\varphi \in E_\varphi^{(k)} : \text{cl } \varphi(I_1) \subset O_1\}$, $\Delta_2 = \{g \in E_g^{(e)} = E_g^{(e)}(I_1; R_z^e) : \text{cl } g(I_1) \subset O_2\}$ are sets of initial functions, where $\varphi(I_1) = \{\varphi(t), t \in I_1\}$; let E_u be the space of measurable functions $u : I \rightarrow R_u^r$, satisfying the following condition: the set $\text{cl } u(I)$ is compact in R_u^r , $\|u\| = \sup\{|u(t)| : t \in I\}$, $\Omega = \{u \in E_u : \text{cl } u(I) \subset G\}$ is the set of controls.

To any element $\mu = (t_0, y_0, \varphi, g, u) \in A = I \times O_1 \times \Delta_1 \times \Delta_2 \times \Omega$ we put in correspondence the differential equation

$$\dot{x}(t) = f(t, y(\tau_1(t)), \dots, y(\tau_s(t)), z(\sigma_1(t)), \dots, z(\sigma_m(t)), u(t)) \quad (1.1)$$

with the mixed initial condition

$$x(t) = (y(t), z(t))^T = (\varphi(t), g(t))^T, \quad t \in [\tau, t_0], \quad x(t_0) = (y_0, g(t_0))^T. \quad (1.2)$$

Definition 1.1. Let $\mu = (t_0, y_0, \varphi, g, u) \in A$, $t_0 < b$. A function $x(t; \mu) = (y(t; \mu), z(t; \mu))^T$, $t \in [\tau, t_1]$, $t_1 \in (t_0, b]$, where $y(t, \mu) \in O_1$, $z(t, \mu) \in O_2$, is called a solution, corresponding to the element μ , and defined on the interval $[\tau, t_1]$, if it satisfies the condition (1.2) on the interval $[\tau, t_0]$, it is absolutely continuous on the interval $[t_0, t_1]$ and almost everywhere on $[t_0, t_1]$ satisfies the equation (1.1).

In the space $E_\mu = R \times R_y^k \times E_\varphi^{(k)} \times E_g^{(e)} \times E_u$ we introduce the set of variations

$$V = \left\{ \delta\mu = (\delta t_0, \delta y_0, \delta\varphi, \delta g, \delta u) \in E_\mu : |\delta t_0| \leq c, |\delta y_0| \leq c, \|\delta\varphi\| \leq c, \right. \\ \left. \delta g = \sum_{i=1}^l \lambda_i \delta g_i, |\lambda_i| \leq c, i = \overline{1, l}, \|\delta u\| \leq c \right\},$$

where $c > 0$ is a fixed number and $\delta g_i \in E_g^{(e)}$, $i = \overline{1, l}$ are fixed points.

Lemma 1.1. Let $x_0(t)$ be the solution corresponding to the element $\mu_0 = (t_{00}, y_{00}, \varphi_0, g_0, u_0) \in A$, and defined on the interval $[\tau, t_{10}]$, $t_{00}, t_{10} \in (a, b)$. There exist numbers $\varepsilon_1 > 0$ and $\delta_1 > 0$, such that for any $(\varepsilon, \delta\mu) \in [0, \varepsilon_1] \times V$ we have $\mu_0 + \varepsilon\delta\mu \in A$. In addition, to this element corresponds a solution $x(t; \mu_0 + \varepsilon\delta\mu)$, defined on the interval $[\tau, t_{10} + \delta_1] \subset I_1$.

This lemma follows from Theorem 1.3.2 (see [6, p. 17]).

Due to uniqueness, the solution $x(t; \mu_0)$, which is defined on $[\tau, t_{10} + \delta_1]$ is a continuation of the solution $x_0(t)$. Therefore we can assume that the solution $x_0(t)$ is defined on the whole interval $[\tau, t_{10} + \delta_1]$.

Lemma 1.1 allows us to introduce the increment of the solution $x_0(t) = x(t; \mu_0)$:

$$\begin{aligned} \Delta x(t) &= \Delta x(t; \varepsilon \delta \mu) = x(t; \mu_0 + \varepsilon \delta \mu) - x_0(t), \\ (t, \varepsilon, \delta \mu) &\in [\tau, t_{10} + \delta_1] \times [0, \varepsilon_1] \times V. \end{aligned}$$

In order to formulate main results, consider the following notation:

$$\begin{aligned} \omega_{0i}^- &= (t_{00}, \underbrace{y_{00}, \dots, y_{00}}_i, \underbrace{\varphi_0(t_{00-}), \dots, \varphi_0(t_{00-})}_{p-i}, \varphi_0(\tau_{p+1}(t_{00-})), \dots, \\ &\quad \varphi_0(\tau_s(t_{00-})), g_0(\sigma_1(t_{00-})), \dots, g_0(\sigma_m(t_{00-}))), \quad i = \overline{0, p}, \\ \omega_{0i}^- &= (\gamma_i, y_0(\tau_1(\gamma_i)), \dots, y_0(\tau_{i-1}(\gamma_i)), y_{00}, \varphi_0(\tau_{i+1}(\gamma_i-)), \dots, \varphi_0(\tau_s(\gamma_i-)), \\ &\quad z_0(\sigma_1(\gamma_i-)), \dots, z_0(\sigma_m(\gamma_i-))), \\ \omega_{1i}^- &= (\gamma_i, y_0(\tau_1(\gamma_i)), \dots, y_0(\tau_{i-1}(\gamma_i)), \varphi_0(t_{00-}), \varphi_0(\tau_{i+1}(\gamma_i-)), \dots, \\ &\quad \varphi_0(\tau_s(\gamma_i-)), z_0(\sigma_1(\gamma_i-)), \dots, z_0(\sigma_m(\gamma_i-))), \quad i = \overline{p+1, s}, \\ \gamma_i(t) &= \tau_i^{-1}(t), \quad \gamma_i = \gamma_i(t_{00}), \quad \rho_j(t) = \sigma_j^{-1}(t), \quad \dot{\gamma}_i^- = \dot{\gamma}_i(t_{00-}); \\ \omega &= (t, y_1, \dots, y_s, z_1, \dots, z_m), \\ f_0[t] &= f(t, y_0(\tau_1(t)), \dots, y_0(\tau_s(t)), z_0(\sigma_1(t)), \dots, z_0(\sigma_m(t))u_0(t)); \\ f_0(\omega) &= f(\omega, u_0(t)). \end{aligned}$$

$$\lim_{\omega \rightarrow \omega_{0i}^-} f_0(\omega) = f_i^-, \quad \omega \in (t_{00} - \delta, t_{00}] \times O_1^s \times O_2^m, \quad i = \overline{0, p}, \quad \delta > 0,$$

$$\begin{aligned} \lim_{(\omega_1, \omega_2) \rightarrow (\omega_{0i}^-, \omega_{1i}^-)} [f_0(\omega_1) - f_0(\omega_2)] &= f_i^-, \\ \omega_1, \omega_2 &\in (\gamma_i - \delta, \gamma_i] \times O_1^s \times O_2^m, \quad i = \overline{p+1, s}. \end{aligned}$$

Similarly we can define ω_{0i}^+ , ω_{1i}^+ , $\dot{\gamma}_i^+$, f_i^+ . In this case we have $t_{00}+$, γ_i+ , and the right semi-intervals of points t_{00} , γ_i .

Theorem 1.1. *Let the following conditions hold:*

- (1) $\gamma_i = t_{00}$, $i = \overline{1, p}$, $\gamma_{p+1} < \dots < \gamma_s < t_{10}$;
- (2) *there exists a number $\delta > 0$ such that $\gamma_1(t) \leq \dots \leq \gamma_p(t)$, $t \in (t_{00} - \delta, t_{00}]$;*
- (3) *the quantities $\dot{\gamma}_i^-$, f_i^- , $i = \overline{1, s}$ are finite;*
- (4) *the function $g_0(t)$ is absolutely continuous on the interval $(t_{00} - \delta, t_{00}]$ and there exists a finite limit \dot{g}_0^- .*

Then there exist numbers $\varepsilon_2 \in (0, \varepsilon_1)$, $\delta_2 \in (0, \delta_1)$ such that for any

$$(t, \varepsilon, \delta \mu) \in [t_{10} - \delta_2, t_{10} + \delta_2] \times [0, \varepsilon_2] \times V^-,$$

where $V^- = \{\delta\mu \in V : \delta t_0 \leq 0\}$, we have

$$\Delta x(t) = \varepsilon \delta x(t; \delta\mu) + o(t; \varepsilon \delta\mu), \quad (1.3)$$

where

$$\begin{aligned} \delta x(t; \delta\mu) &= Y(t_{00}; t) [Y_0 \delta y_0 + Y_1 \delta g(t_{00}^-)] + \\ &+ \left\{ Y(t_{00}; t) \left[Y_1 \dot{g}_0^- + \sum_{i=0}^p (\widehat{\gamma}_{i+1}^- - \widehat{\gamma}_i^-) f_i^- \right] - \right. \\ &\quad \left. - \sum_{i=p+1}^s Y(\gamma_i; t) f_i^- \dot{\gamma}_i^- \right\} \delta t_0 + \beta(t; \delta\mu), \end{aligned} \quad (1.4)$$

$$\begin{aligned} \beta(t; \delta\mu) &= \sum_{i=p+1}^s \int_{\tau_i(t_{00})}^{t_{00}} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \delta\varphi(\xi) d\xi + \\ &+ \sum_{j=1}^m \int_{\sigma_j(t_{00})}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi + \\ &+ \int_{t_{00}}^t Y(\xi; t) f_{0u}[\xi] \delta u(\xi) d\xi, \end{aligned} \quad (1.5)$$

$\widehat{\gamma}_0^- = 1$, $\widehat{\gamma}_i^- = \dot{\gamma}_i^-$, $i = \overline{1, p}$, $\widehat{\gamma}_{p+1}^- = 0$; next, $\lim_{\varepsilon \rightarrow 0} \frac{o(t; \varepsilon \delta\mu)}{\varepsilon} = 0$ uniformly with respect to $(t, \delta\mu) \in [t_{10} - \delta_2, t_{10} + \delta_2] \times V^-$;

$$f_{0y_i}[t] = f_{y_i}(t, y_0(\tau_1(t)), \dots, y_0(\tau_s(t)), z_0(\sigma_1(t)), \dots, z_0(\sigma_m(t)), u_0(t));$$

$Y(\xi; t)$ is an $n \times n$ matrix-valued function satisfying the equation

$$\begin{aligned} Y_\xi(\xi; t) &= - \sum_{i=1}^s Y(\gamma_i(\xi); t) F_{y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) - \\ &- \sum_{j=1}^m Y(\rho_j(\xi); t) F_{z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi), \quad \xi \in [t_{00}, t], \end{aligned} \quad (1.6)$$

and the condition

$$Y(\xi, t) = \begin{cases} I_{n \times n}, & \xi = t, \\ \Theta_{n \times n}, & \xi > t, \end{cases} \quad (1.7)$$

where $I_{n \times n}$ and $\Theta_{n \times n}$ are the identity and zero $n \times n$ matrices, $F_{y_i} = (f_{0y_i}, \Theta_{n \times e})$, $F_{z_j} = (\Theta_{n \times k}, f_{0z_j})$, $Y_0 = (I_{k \times k}, \Theta_{e \times k})^T$, $Y_1 = (\Theta_{k \times e}, I_{e \times e})^T$.

The function $\delta x(t; \delta\mu)$ is called the variation of the solution $x_0(t)$, $t \in [t_{10} - \delta_2, t_{10} + \delta_2]$ and the formula (1.4) is called the variation formula.

Theorem 1.2. Let the condition (1) and the following conditions hold:

- (5) there exists a number $\delta > 0$ such that $\gamma_1(t) \leq \dots \leq \gamma_p(t)$, $t \in [t_{00}, t_{00} + \delta)$;

- (6) the quantities $\dot{\gamma}_i^+$, f_i^+ , $i = \overline{1, s}$ are finite
 (7) the function $g_0(t)$ is absolutely continuous on the interval $[t_{00}, t_{00} + \delta)$ and there exists a finite limit \dot{g}_0^+ .

Then there exist numbers $\varepsilon_2 \in (0, \varepsilon_1)$ and $\delta_2 \in (0, \delta_1)$ such that for any $(t, \varepsilon, \delta\mu) \in [t_{10} - \delta_2, t_{10} + \delta_2] \times [0, \varepsilon_2] \times V^+$, where $V^+ = \{\delta\mu \in V : \delta t_0 \geq 0\}$, the formula (1.3) holds, where

$$\begin{aligned} \delta x(t; \delta\mu) = & Y(t_{00}; t) [Y_0 \delta y_0 + Y_1 \delta g(t_{00}+)] + \\ & + \left\{ Y(t_{00}; t) \left[Y_1 \dot{g}_0^+ + \sum_{i=0}^p (\hat{\gamma}_{i+1}^+ - \hat{\gamma}_i^+) f_i^+ \right] - \right. \\ & \left. - \sum_{i=p+1}^s Y(\gamma_i; t) f_i^+ \dot{\gamma}_i^+ \right\} \delta t_0 + \beta(t; \delta\mu), \quad (1.8) \\ \hat{\gamma}_0^+ = & 1, \quad \hat{\gamma}_i^+ = \dot{\gamma}_i^+, \quad i = \overline{1, p}, \quad \hat{\gamma}_{p+1}^+ = 0. \end{aligned}$$

Theorems 1.1 and 1.2 immediately imply the following assertion.

Theorem 1.3. *Let the conditions (1)–(7) and the following conditions hold:*

$$\begin{aligned} (8) \quad \sum_{i=0}^p (\hat{\gamma}_{i+1}^- - \hat{\gamma}_i^-) f_i^- + Y_1 \dot{g}_0^- = & \sum_{i=0}^p (\hat{\gamma}_{i+1}^+ - \hat{\gamma}_i^+) f_i^+ + Y_1 \dot{g}_0^+ =: f_0, \\ f_i^- \dot{\gamma}_i^- = & f_i^+ \dot{\gamma}_i^+ =: f_i, \quad i = \overline{p+1, s}; \end{aligned}$$

- (9) the functions $\delta g_i(t)$, $i = \overline{1, l}$ are continuous at the point t_{00} .

Then there exist numbers $\varepsilon_2 > 0$, $\delta_2 > 0$ such that for any $(t, \varepsilon, \delta\mu) \in [t_{10} - \delta_2, t_{10} + \delta_2] \times [0, \varepsilon_2] \times V$ the formula (1.3) holds, where

$$\begin{aligned} \delta x(t; \delta\mu) = & Y(t_{00}; t) [Y_0 \delta y_0 + Y_1 \delta g(t_{00})] + \\ & + \left\{ Y(t_{00}; t) f_0 - \sum_{i=p+1}^s Y(\gamma_i; t) f_i \right\} \delta t_0 + \beta(t; \delta\mu). \end{aligned}$$

Some comments: Theorems 1.1 and 1.2 correspond to the case where at the point t_{00} right-hand and left-hand variations, respectively, take place. Theorem 1.3 corresponds to the case where at the point t_{00} double-sided variation takes place.

In the formula of variation proved in [1], for the equation (3) instead of the expression

$$\int_{t_{00}}^t Y(\xi; t) f_{0u}[\xi] \delta u(\xi) d\xi$$

(see (1.5)), we have

$$\int_{t_{00}}^t Y(\xi; t) \delta f[\xi] d\xi.$$

The formula (1.4) follows from the formula of variation obtained in [1] if the function f additionally satisfies the condition: $f_u(t, y_1, \dots, y_s, z_1, \dots, z_m, u)$ is continuously differentiable with respect to the variables $y_i \in O_1$, $i = \overline{1, s}$ and $z_j \in O_2$, $j = \overline{1, m}$.

In the present work formulas of variation are proved without of these conditions.

2. AUXILIARY LEMMAS

To any element $\mu = (t_0, y_0, \varphi, g, u) \in A$, let us correspond the functional-differential equation

$$\begin{aligned} \dot{\omega}(t) = f\left(t, h(t_0, \varphi, q)(\tau_1(t)), \dots, h(t_0, \varphi, q)(\tau_s(t)), \right. \\ \left. h(t_0, g, v)(\sigma_1(t)), \dots, h(t_0, g, v)(\sigma_m(t)), u(t)\right) \end{aligned} \quad (2.1)$$

with the initial condition

$$\omega(t_0) = (q(t_0), v(t_0))^T = x_0 = (y_0, g(t_0))^T, \quad (2.2)$$

where the operator $h(\cdot)$ is defined by the formula

$$h(t_0, \varphi, q)(t) = \begin{cases} \varphi(t), & t \in [\tau, t_0], \\ q(t), & t \in [t_0, b]. \end{cases} \quad (2.3)$$

Definition 2.1. Let $\mu = (t_0, y_0, \varphi, g, u) \in A$. An absolutely continuous function $\omega(t) = \omega(t; \mu) = (q(t; \mu), v(t; \mu))^T \in (O_1, O_2)^T$, $t \in [r_1, r_2] \subset I$, where $(O_1, O_2)^T = \{x = (y, z)^T \in R_x^n : y \in O_1, z \in O_2\}$, is called a solution corresponding to the element $\mu \in A$, defined on the interval $[r_1, r_2]$, if $t_0 \in [r_1, r_2]$, the function $\omega(t)$ satisfies the condition (2.2) and the equation (2.1) almost everywhere on $[r_1, r_2]$.

Remark 2.1. Let $\omega(t; \mu)$, $t \in [r_1, r_2]$ be the solution corresponding to the element $\mu \in A$. Then the function

$$\begin{aligned} x(t; \mu) = (y(t; \mu), z(t; \mu))^T = \\ = (h(t_0, \varphi, q(\cdot; \mu))(t), h(t_0, g, v(\cdot; \mu))(t))^T, \quad t \in [\tau, r_2] \end{aligned} \quad (2.4)$$

is a solution of the equation (1.1) with the initial condition (1.2) (see (2.3)).

Lemma 2.1. Let $\omega_0(t)$, $t \in [r_1, r_2] \subset (a, b)$ be the solution corresponding to the element $\mu_0 \in A$; let $K \subset (O_1, O_2)^T$ be a compact set containing some neighborhood of the set $((\varphi_0(I_1) \cup q_0([r_1, r_2])), (g_0(I_1) \cup v_0([r_1, r_2])))^T$ and let $M \subset G$ be a compact set containing some neighborhood of the set $\text{cl } u_0(I)$. Then there exist numbers $\varepsilon_1 > 0$, $\delta_1 > 0$ such that for an arbitrary $(\varepsilon, \delta\mu) \in [0, \varepsilon_1] \times V$ to the element $\mu_0 + \varepsilon\delta\mu \in A$ there corresponds a solution

$\omega(t; \mu_0 + \varepsilon\delta\mu)$ defined on $[r_1 - \delta_1, r_2 + \delta_1] \subset I$. Moreover,

$$\begin{aligned} (\varphi(t), g(t)) &= (\varphi_0(t) + \varepsilon\delta\varphi(t), g_0(t) + \varepsilon g(t)) \in K, \quad t \in I_1, \\ u(t) &= u_0(t) + \varepsilon\delta u(t) \in M, \quad t \in I, \\ \omega(t; \mu_0 + \varepsilon\delta\mu) &\in K, \quad t \in [r_1 - \delta_1, r_2 + \delta_1], \\ \lim_{\varepsilon \rightarrow 0} \omega(t; \mu + \varepsilon\delta\mu) &= \omega(t, \mu_0) \\ &\text{uniformly for } (t, \delta\mu) \in [r_1 - \delta_1, r_2 + \delta_1] \times V. \end{aligned} \quad (2.5)$$

This lemma follows from Lemma 1.3.2 (see [6, p. 18]).

Due to uniqueness, the solution $\omega(t; \mu_0)$ on the interval $[r_1 - \delta_1, r_2 + \delta_1]$ is a continuation of the solution $\omega(t; \mu_0)$, therefore the solution $\omega_0(t)$ is assumed to be defined on the whole interval $[r_1 - \delta_1, r_2 + \delta_1]$.

Let us define the increment of the solution $\omega_0(t) = \omega(t; \mu_0)$,

$$\begin{aligned} \Delta\omega(t) &= (\Delta q(t), \Delta v(t))^T = \Delta\omega(t; \varepsilon\delta\mu) = \omega(t; \mu_0 + \varepsilon\delta\mu) - \omega_0(t), \\ (t, \varepsilon, \delta\mu) &\in [r_1 - \delta_1, r_2 + \delta_1] \times [0, \varepsilon_1] \times V. \end{aligned} \quad (2.6)$$

It is obvious that

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \Delta\omega(t; \varepsilon\delta\mu) &= 0 \\ &\text{uniformly with respect to } (t, \delta\mu) \in [r_1 - \delta_1, r_2 + \delta_1] \times V. \end{aligned} \quad (2.7)$$

Lemma 2.2. *Let $\gamma_i = t_{00}$, $i = \overline{1, p}$, $\gamma_{p+1} < \dots < \gamma_s \leq r_2$ and let the conditions 2)–4) of Theorem 1.1 hold. Then there exist numbers $\varepsilon_2 > 0$ and $\delta_2 > 0$ such that for any $(\varepsilon, \delta\mu) \in [0, \varepsilon_2] \times V^-$ we have*

$$\max_{t \in [t_{00}, r_2 + \delta_2]} |\Delta\omega(t)| = O(\varepsilon\delta\mu). \quad (2.8)$$

Moreover,

$$\begin{aligned} \Delta\omega(t_{00}) &= \varepsilon [Y_0 \delta y_0 + Y_1 \delta g(t_{00}^-)] + \\ &+ \varepsilon \left[Y_1 \dot{g}_0^- + \sum_{i=0}^p (\hat{\gamma}_{i+1}^- - \hat{\gamma}_i^-) f_i^- \right] \delta t_0 + o(\varepsilon\delta\mu). \end{aligned} \quad (2.9)$$

Lemma 2.3. *Let $\gamma_i = t_{00}$, $i = \overline{1, p}$; $\gamma_{p+1} < \dots < \gamma_s \leq r_2$, and let*

conditions (5)–(7) of Theorem 1.2 hold. Then there exist numbers $\varepsilon_2 > 0$ and $\delta_2 > 0$ such that for any $(\varepsilon, \delta\mu) \in [0, \varepsilon_2] \times V^+$ we have

$$\max_{t \in [t_0, r_2 + \delta_2]} |\Delta\omega(t)| = O(\varepsilon\delta\mu). \quad (2.10)$$

In addition,

$$\Delta\omega(t_0) = \varepsilon [Y_0 \delta y_0 + Y_1 \delta g(t_{00}^+) + (Y_1 \dot{g}_0^+ - f_p^+) \delta t_0] + o(\varepsilon\delta\mu). \quad (2.11)$$

Lemmas 2.2 and 2.3 are proved in analogue way as Lemmas 2.2 and 3.1, respectively (see [1]).

3. PROOF OF THEOREM 1.1

Let $r_1 = t_{00}$, $r_2 = t_{10}$. Then for an arbitrary element $(\varepsilon, \delta\mu) \in [0, \varepsilon_1] \times V^-$ the corresponding solution $\omega(t; \mu_0 + \varepsilon\delta\mu)$ is defined on the interval $[t_{00} - \delta_1, t_{10} + \delta_1]$ and the solution $x(t; \mu_0 + \varepsilon\delta\mu)$ is defined on the interval $[\tau, t_{10} + \delta_1]$. Moreover,

$$\omega(t; \mu_0 + \varepsilon\delta\mu) = x(t, \mu_0 + \varepsilon\delta\mu), \quad t \in [t_{00}, t_{10} + \delta_1]$$

(see Lemma 1.1, 2.1 and Remark 2.1).

Therefore

$$\Delta y(t) = \begin{cases} \varepsilon\delta\varphi(t), & t \in [\tau, t_0), \\ q(t; \mu_0 + \varepsilon\delta\mu) - \varphi_0(t), & t \in [t_0, t_{00}), \\ \Delta q(t), & t \in [t_{00}, t_{00} + \delta_1], \end{cases} \quad (3.1)$$

$$\Delta z(t) = \begin{cases} \varepsilon\delta g(t), & t \in [\tau, t_0), \\ v(t; \mu_0 + \varepsilon\delta\mu) - g_0(t), & t \in [t_0, t_{00}), \\ \Delta v(t), & t \in [t_{00}, t_{00} + \delta_1] \end{cases} \quad (3.2)$$

(see(2.6)).

By Lemma 2.2, there exist numbers

$$\varepsilon_2 \in (0, \varepsilon_1), \quad \delta_2 \in (0, \min(\delta_1, t_{10} - \gamma_s)) \quad (3.3)$$

such that the following inequalities hold

$$|\Delta y(t)| \leq O(\varepsilon\delta\mu), \quad \forall (t, \varepsilon, \delta\mu) \in [t_{00}, t_{10} + \delta_2] \times [0, \varepsilon_2] \times V^-, \quad (3.4)$$

$$|\Delta z(t)| \leq O(\varepsilon\delta\mu), \quad \forall (t, \varepsilon, \delta\mu) \in [\tau, t_{10} + \delta_2] \times [0, \varepsilon_2] \times V^- \quad (3.5)$$

(see (2.8), (3.1), (3.2)),

$$\begin{aligned} \Delta x(t_{00}) = \Delta\omega(t_{00}) = & \varepsilon \left(Y_0\delta y_0 + Y_1\delta g(t_{00}^-) + \right. \\ & \left. + \left[Y_1 \dot{g}_0^- + \sum_{i=0}^p (\hat{\gamma}_{i+1}^- - \hat{\gamma}_i^-) f_i^- \right] \delta t_0 \right) + o(\varepsilon\delta\mu) \end{aligned} \quad (3.6)$$

(see (2.9)).

The function $\Delta x(t)$ on the interval $[t_{00}, t_{10} + \delta_2]$ satisfies the equation

$$\begin{aligned} \frac{d}{dt} \Delta x(t) = & \sum_{i=1}^s f_{0y_i}[t] \Delta y(\tau_i(t)) + \\ & \sum_{j=1}^m f_{0z_j}[t] \Delta z(\sigma_j(t)) + \varepsilon f_{0u}[t] \delta u(t) + R(t; \varepsilon\delta\mu), \end{aligned} \quad (3.7)$$

where

$$\begin{aligned} R(t; \varepsilon\delta\mu) = & f \left(t, y_0(\tau_1(t)) + \Delta y(\tau_1(t)), \dots, y_0(\tau_s(t)) + \Delta y(\tau_s(t)), \right. \\ & \left. z_0(\sigma_1(t)) + \Delta z(\sigma_1(t)), \dots, z_0(\sigma_m(t)) + \Delta z(\sigma_m(t)), u_0(t) \right) - \end{aligned}$$

$$f_0[t] - \sum_{i=1}^s f_{0y_i}[t] \Delta y(\tau_i(t)) - \sum_{j=1}^m f_{0z_j}[t] \Delta z(\sigma_j(t)) - \varepsilon f_{0u}[t] \delta u(t). \quad (3.8)$$

We can represent the solution of (3.7) by the Cauchy formula in the following form:

$$\begin{aligned} \Delta x(t) &= Y(t_{00}; t) \Delta x(t_{00}) + \varepsilon \int_{t_{00}}^t Y(\xi; t) f_{0u}[t] \delta u(\xi) d\xi + \\ &+ \sum_{i=0}^2 h_i(t; t_0, \varepsilon \delta \mu), \quad t \in [t_{00}, t_{10} + \delta_2], \end{aligned} \quad (3.9)$$

where

$$\begin{cases} h_0 = \sum_{i=p+1}^s \int_{\tau_i(t_{00})}^{t_{00}} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \Delta y(\xi) d\xi, \\ h_1 = \sum_{j=1}^m \int_{\tau_i(t_{00})}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \Delta z(\xi) d\xi, \\ h_2 = \int_{t_{00}}^t Y(\xi; t) R(\xi; \varepsilon \delta \mu) d\xi. \end{cases} \quad (3.10)$$

$Y(\xi, t)$ is a matrix-valued function satisfying (1.6) and the condition (1.7).

The function $Y(\xi, t)$ is continuous on the set $\Pi = \{(\xi, t) : a \leq \xi \leq t \leq b\}$. Therefore

$$\begin{aligned} Y(t_{00}, t) \Delta x(t_{00}) &= \varepsilon Y(t_{00}; t) \left\{ Y_0 \delta y_0 + Y_1 \delta g(t_{00}^-) + \right. \\ &\left. + [Y_1 g_0^- + \sum_{i=0}^p (\hat{\gamma}_{i+1}^- - \hat{\gamma}_i^-) f_i^-] \delta t_0 \right\} + o(t; \varepsilon \delta \mu) \end{aligned} \quad (3.11)$$

(see (3.6)).

For $h_0(t; t_0, \varepsilon \delta \mu)$ we have

$$\begin{aligned} h_0(t; t_0, \varepsilon \delta \mu) &= \sum_{i=p+1}^s \left[\varepsilon \int_{\tau_i(t_{00})}^{t_0} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \delta \varphi(\xi) d\xi + \right. \\ &\quad \left. + \int_{t_0}^{t_{00}} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \Delta y(\xi) d\xi \right] = \\ &= \varepsilon \sum_{i=p+1}^s \int_{\tau_i(t_{00})}^{t_{00}} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \delta \varphi(\xi) d\xi + \end{aligned}$$

$$+ \sum_{i=p+1}^s \int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi + o(t; \varepsilon \delta \mu), \quad (3.12)$$

where

$$o(t; \varepsilon \delta \mu) = -\varepsilon \sum_{i=p+1}^s \int_{t_0}^{t_{00}} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \delta \varphi(\xi) d\xi.$$

Further, for $h_1(t; t_0, \varepsilon \delta \mu)$ we have

$$\begin{aligned} h_1(t; t_0, \varepsilon \delta \mu) &= \sum_{j \in I_1 \cup I_2} \int_{\tau_j(t_{00})}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \Delta z(\xi) d\xi = \\ &= \sum_{j \in I_1 \cup I_2} \left[\varepsilon \int_{\tau_j(t_{00})}^{t_0} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi + \right. \\ &\quad \left. + \int_{t_0}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \Delta z(\xi) d\xi \right] = \\ &= \sum_{j \in I_1 \cup I_2} [\varepsilon \alpha_j(t) + \beta_j(t)], \end{aligned}$$

where

$$\begin{aligned} \alpha_j(t) &= \int_{\sigma_j(t_{00})}^{t_0} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi, \\ \beta_j(t) &= \int_{t_0}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \Delta z(\xi) d\xi. \end{aligned}$$

It is easy to see that

$$\begin{aligned} \alpha_j(t) &= \int_{\sigma_j(t_{00})}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi - \\ &\quad - \int_{t_0}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi, \\ \beta_j(t) &= o(t; \varepsilon \delta \mu) \end{aligned}$$

(see (3.5)). Therefore

$$\begin{aligned} h_1(t; t_0, \varepsilon\delta\mu) &= \varepsilon \sum_{i=1}^m \int_{\sigma_j(t_0)}^{t_0} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi + \\ &\quad + o(t; \varepsilon\delta\mu). \end{aligned} \quad (3.13)$$

For $t \in [t_{10} - \delta_2, t_{10} + \delta_2]$ we have

$$h_2(t; t_0, \varepsilon\delta\mu) = \sum_{k=1}^4 \alpha_k(t; \varepsilon\delta\mu), \quad (3.14)$$

where

$$\begin{aligned} \alpha_1(t; \varepsilon\delta\mu) &= \int_{t_0}^{\gamma_{p+1}(t_0)} \bar{\omega}(\xi; t, \varepsilon\delta\mu) d\xi, \quad \alpha_2(t; \varepsilon\delta\mu) = \sum_{i=p+1}^s \int_{\gamma_i(t_0)}^{\gamma_i} \bar{\omega}(\xi; t, \varepsilon\delta\mu) d\xi, \\ \alpha_3(t; \varepsilon\delta\mu) &= \sum_{i=p+1}^{s-1} \int_{\gamma_i(t_0)}^{\gamma_{i+1}(t_0)} \bar{\omega}(\xi; t, \varepsilon\delta\mu) d\xi, \quad \alpha_4(t; \varepsilon\delta\mu) = \int_{\gamma_s}^t \bar{\omega}(\xi; t, \varepsilon\delta\mu) d\xi \end{aligned}$$

(see (3.10)),

$$\bar{\omega}(\xi; t, \varepsilon\delta\mu) = Y(\xi; t) R(\xi; \varepsilon\delta\mu).$$

Let us estimate $\alpha_1(t; \varepsilon\delta\mu)$

$$\begin{aligned} |\alpha_1(t; \varepsilon\delta\mu)| &\leq \|Y\| \int_{t_0}^{\gamma_{p+1}(t_0)} \left[\left| f\left(t, y_0(\tau_1(t)) + \Delta y(\tau_1(t)), \dots, \right. \right. \right. \\ &\quad \left. \left. \left. y_0(\tau_p(t)) + \Delta y(\tau_p(t)), \varphi(\tau_{p+1}(t)), \dots, \varphi(\tau_s(t)), \right. \right. \right. \\ &\quad \left. \left. \left. z_0(\sigma_1(t)) + \Delta z(\sigma_1(t)), \dots, z_0(\sigma_m(t)) + \Delta z(\sigma_m(t)), u_0(t) + \varepsilon\delta u(t) \right) - \right. \right. \\ &\quad \left. \left. \left. - f\left(t, y_0(\tau_1(t)), \dots, y_0(\tau_p(t)), \varphi_0(\tau_{p+1}(t)), \dots, \varphi_0(\tau_s(t)), \right. \right. \right. \right. \\ &\quad \left. \left. \left. z_0(\sigma_1(t)), \dots, z_0(\sigma_m(t)), u_0(t) \right) - \right. \right. \\ &\quad \left. \left. \left. - \sum_{i=1}^p f_{0y_i}[t] \Delta y(\tau_i(t)) - \varepsilon \sum_{i=p+1}^s f_{0y_i}[t] \delta \varphi(\tau_i(t)) - \right. \right. \\ &\quad \left. \left. \left. - \sum_{j=1}^m f_{0z_j}[t] \Delta z(\sigma_j(t)) - \varepsilon f_{0u}[t] \right| \right] dt \leq \\ &\leq \|Y\| \int_{t_0}^{t_{10}+\delta_2} \left\{ \int_0^1 \left| \frac{d}{d\xi} f\left(t, y_0(\tau_1(t)) + \xi \Delta y(\tau_1(t)), \dots, y_0(\tau_p(t)) + \xi \Delta y(\tau_p(t)), \right. \right. \right. \\ &\quad \left. \left. \left. \varphi(\tau_{p+1}(t)) + \xi \varepsilon \delta \varphi_0(\tau_{p+1}(t)), \dots, \varphi_0(\tau_s(t)) + \xi \varepsilon \delta \varphi(\tau_s(t)), \right. \right. \right. \end{aligned}$$

$$\begin{aligned}
& \left. z_0(\sigma_1(t)) + \xi \Delta z(\sigma_1(t)), \dots, z_0(\sigma_s(t)) + \xi \Delta z(\sigma_s(\xi)), u_0(t) + \xi \varepsilon \delta u(t) \right) \Big| - \\
& \quad - \sum_{i=1}^p f_{0y_i}[t] \Delta y(\tau_i(t)) - \varepsilon \sum_{i=p+1}^s f_{0y_i}[t] \delta \varphi(\tau_i(t)) - \\
& \quad - \sum_{j=1}^m f_{0z_j}[t] \Delta z(\sigma_j(t)) - \varepsilon f_{0u}[t] \delta u(t) \Big| \Big] d\xi \Big\} dt \leq \\
\leq & \|Y\| \int_{t_0}^{t_0+\delta_2} \left\{ \int_0^1 \left[\sum_{i=1}^p \left| f_{y_i}(t, y_0(\tau_1(t)) + \xi \Delta y(\tau_1(t)), \dots) - f_{0y_i}[t] \right| |\Delta y(\tau_i(t))| + \right. \right. \\
& + \varepsilon \sum_{i=p+1}^s \left| f_{y_i}(t, y_0(\tau_1(t)) + \xi \Delta y(\tau_1(t)), \dots) - f_{0y_i}[t] \right| |\delta \varphi(\tau_i(t))| + \\
& + \sum_{j=1}^m \left| f_{z_j}(t, y_0(\tau_1(t)) + \xi \Delta y(\tau_1(t)), \dots) - f_{0z_j}[t] \right| |\delta z(\sigma_j(t))| + \\
& \left. \left. + \varepsilon \left| f_u(t, y_0(\tau_1(t)) + \xi \Delta y(\tau_1(t)), \dots) - f_{0u}[t] \right| |\delta u(t)| \right] d\xi \right\} dt \leq \\
& \leq \|Y\| \left[O(\varepsilon \delta \mu) \sum_{i=1}^p \vartheta_i(t_{00}; \varepsilon \delta \mu) + \varepsilon c \sum_{i=p+1}^s \vartheta_i(t_{00}; \varepsilon \delta \mu) + \right. \\
& \quad \left. + O(\varepsilon \delta \mu) \sum_{j=1}^m \eta_j(t_{00}; \varepsilon \delta \mu) + \varepsilon c \delta(t_{00}; \varepsilon \delta \mu) \right], \quad (3.15)
\end{aligned}$$

where

$$\begin{aligned}
\|Y\| &= \sup_{(\xi, t) \in \Pi} |Y(\xi, t)|, \\
\vartheta_i(t_{00}; \varepsilon \delta \mu) &= \int_{t_0}^{t_0+\delta_2} \left[\int_0^1 \left| f_{y_i}(t, y_0(\tau_1(t)) + \xi \Delta y(\tau_1(t)), \dots) - f_{0y_i}[t] \right| d\xi \right] dt, \\
& \quad i = \overline{1, s}, \\
\eta_j(t_{00}; \varepsilon \delta \mu) &= \int_{t_0}^{t_0+\delta_2} \left[\int_0^1 \left| f_{z_j}(t, y_0(\tau_1(t)) + \xi \delta y(\tau_1(t)), \dots) - f_{0z_j}[t] \right| d\xi \right] dt, \\
& \quad j = 1, \dots, m, \\
\delta(t_{00}; \varepsilon \delta \mu) &= \int_{t_0}^{t_0+\delta_2} \left[\int_0^1 \left| f_u(t, y_0(\tau_1(t)) + \xi \Delta y(\tau_1(t)), \dots) - f_{0u}[t] \right| d\xi \right] dt.
\end{aligned}$$

We have

$$\begin{aligned}
\varphi(t) &= \varphi_0(t) + \varepsilon \delta \varphi(t) \rightarrow \varphi_0(t); \quad \Delta y(\tau_i(t)) \rightarrow 0, \quad i = \overline{1, p}, \\
\Delta z(\sigma_j(t)) &\rightarrow 0, \quad j = \overline{1, m};
\end{aligned}$$

$$u_0(t) + \xi \varepsilon \delta u(t) \rightarrow u_0(t)$$

as $\varepsilon \rightarrow 0$ uniformly with respect to

$$(\xi, t, \delta\mu) \in [0, 1] \times [t_{00}, t_{10} + \delta_2] \times V^-.$$

By the Lebesgue theorem we obtain that

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \vartheta_i(t_{00}; \varepsilon \delta\mu) &= 0, \quad i = \overline{1, s}, \quad \lim_{\varepsilon \rightarrow 0} \eta_j(t_{00}; \varepsilon \delta\mu) = 0, \quad j = \overline{1, m}, \\ \lim_{\varepsilon \rightarrow 0} \delta(t_{00}; \varepsilon \delta\mu) &= 0 \end{aligned}$$

uniformly with respect to $\delta\mu \in V^-$.

Therefore

$$\alpha_1(t; \varepsilon \delta\mu) = o(t; \varepsilon \delta\mu).$$

Consider $\alpha_2(t; \varepsilon \delta\mu)$. It is easy to see that for $i \in p+1, \dots, s$ and $t \in [\gamma_i(t_0), \gamma_i]$ we have

$$\begin{aligned} |\Delta y(\tau_j(t))| &\leq O(\varepsilon \delta\mu), \quad j = \overline{1, i-1}; \\ \Delta y(\tau_j(t)) &= \varepsilon \delta\varphi(\tau_j(t)), \quad j = \overline{i+1, s} \end{aligned} \quad (3.16)$$

(see (3.1), (3.4)). Therefore

$$\begin{aligned} \int_{\gamma_i(t_0)}^{\gamma_i} \bar{\omega}(\xi; t, \varepsilon \delta\mu) d\xi &= \int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) \beta_i(\xi) d\xi - \\ &\quad - \int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi + o(t; \varepsilon \delta\mu), \end{aligned}$$

where

$$\begin{aligned} \beta_i(\xi) &= f\left(\xi, y_0(\tau_1(\xi)) + \Delta y(\tau_1(\xi)), \dots, y_0(\tau_i(\xi)) + \Delta y(\tau_i(\xi)), \right. \\ &\quad \left. \varphi(\tau_{i+1}(\xi)), \dots, \varphi(\tau_s(\xi)), z_0(\sigma_1(\xi)) + \Delta z(\sigma_1(\xi)), \dots, \right. \\ &\quad \left. z_0(\sigma_m(\xi)) + \Delta z(\sigma_m(\xi)), u_0(\xi) + \delta u(\xi)\right) - f_0[\xi], \end{aligned}$$

$$\begin{aligned} o(t; \varepsilon \delta\mu) &= - \sum_{j=1}^{i-1} \int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) f_{0y_j}[\xi] \Delta y(\tau_j(\xi)) d\xi - \\ &\quad - \varepsilon \sum_{j=i+1}^s \int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) f_{0y_j}[\xi] \delta\varphi(\tau_j(\xi)) d\xi - \\ &\quad - \sum_{j=1}^m \int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) f_{0z_j}[\xi] \Delta z(\sigma_j(\xi)) d\xi - \varepsilon \int_{\gamma_i(t_0)}^{\gamma_i} f_{0u}[\xi] \delta u(\xi) d\xi \end{aligned}$$

(see (3.5), (3.16)). Clearly,

$$\int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) \beta_i(\xi) d\xi = \alpha_5(t; \varepsilon \delta \mu) + \alpha_6(t; \varepsilon \delta \mu),$$

where

$$\alpha_5(t; \varepsilon \delta \mu) = \int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) [\beta_i(\xi) - f_i^-] d\xi, \quad \alpha_6(t; \varepsilon \delta \mu) = \int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) f_i^- d\xi.$$

Further, if $i \in \{p+1, \dots, s\}$ and $\xi \in [\gamma_i(t_0), \gamma_i]$, then $\tau_j(\xi) \geq t_{00}$, $j = \overline{1, i-1}$. Hence

$$\lim_{\varepsilon \rightarrow 0} (y_0(\tau_j(\xi)) + \Delta y(\tau_j(\xi))) = \lim_{\xi \in \gamma_i^-} y_0(\tau_j(\xi)) = y_0(\tau_j(\gamma_i)), \quad j = \overline{1, i-1}.$$

We have $\tau_i(\xi) \in [t_0, t_{00}]$ for $\xi \in [\gamma_i(t_0), \gamma_i]$. Therefore

$$y_0(\tau_i(\xi)) + \Delta y(\tau_i(\xi)) = y(\tau_i(\xi), \mu_0 + \varepsilon \delta \mu) = q_0(\tau_i(\xi)) + \Delta q(\tau_i(\xi))$$

(see (2.4), (2.5)).

Therefore, taking into account the continuity of the function $q_0(t)$, $t \in [t_{00} - \delta_2, t_{10} + \delta_2]$, (2.6), and the condition $q_0(t_{00}) = y_{00}$, we have

$$\lim_{\varepsilon \rightarrow 0} (y_0(\tau_i(\xi)) + \Delta y(\tau_i(\xi))) = \lim_{\xi \in \gamma_i^-} q_0(\tau_i(\xi)) = y_{00}.$$

Hence, we see that for $\varepsilon \rightarrow 0$, $i \in \{p+1, \dots, s\}$ and $\xi \in [\gamma_i(t_0), \gamma_i]$, we have

$$\lim_{\varepsilon \rightarrow 0} \left(\xi, y_0(\tau_1(\xi)) + \Delta y(\tau_1(\xi)), \dots, y_0(\tau_i(\xi)) + \Delta y(\tau_i(\xi)), \varphi(\tau_{i+1}(\xi)), \dots, \varphi(\tau_s(\xi)), z_0(\sigma_1(\xi)) + \Delta z(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)) + \Delta z(\sigma_m(\xi)) \right) = \omega_{0i}^-.$$

On the other hand,

$$\lim_{\varepsilon \rightarrow 0} \left(\xi, y_0(\tau_1(\xi)), \dots, y_0(\tau_{i-1}(\xi)), \varphi(\tau_i(\xi)), \dots, \varphi(\tau_s(\xi)), z_0(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)) \right) = \omega_{1i}^-.$$

Therefore,

$$\lim_{\varepsilon \rightarrow 0} \sup_{\xi \in [\gamma_i(t_0), \gamma_i]} |\beta_i(\xi) - f_i^-| = 0$$

uniformly with respect to $\delta \mu \in V^-$.

The function $Y(\xi; t)$ is continuous on the set

$$[\gamma_i(t_0), \gamma_i] \times [t_{10} - \delta_2, t_{10} + \delta_2] \subset \Pi$$

and, moreover

$$\gamma_i - \gamma_i(t_0) = -\varepsilon \dot{\gamma}_i^- \delta t_0 + o(\varepsilon \delta \mu).$$

Therefore $\alpha_5(t; \varepsilon \delta \mu) = o(t; \delta \mu)$ and

$$\alpha_6(t; \varepsilon \delta \mu) = -\varepsilon \sum_{i=p+1}^s Y(\gamma_i; t) f_i^- \dot{\gamma}_i^- \delta t_0 + o(t; \varepsilon \delta \mu).$$

Finally,

$$\begin{aligned} \alpha_2(t; \varepsilon \delta \mu) = & -\varepsilon \sum_{i=p+1}^s Y(\gamma_i; t) f_i^- \dot{\gamma}_i^- \delta t_0 - \\ & - \sum_{i=p+1}^s \int_{\gamma_i(t_0)}^{\gamma_i} Y(\gamma_i; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi + o(t; \varepsilon \delta \mu). \end{aligned}$$

Similarly, we can prove the relations

$$\alpha_i(t; \varepsilon \delta \mu) = o(t; \varepsilon \delta \mu), \quad i = 3, 4$$

(see (3.15)).

For $h_2(t; t_{00}, \varepsilon \delta \mu)$ we have the final formula

$$\begin{aligned} h_2(t; t_{00}, \varepsilon \delta \mu) = & -\varepsilon \sum_{i=p+1}^s Y(\gamma_i; t) f_i^- \dot{\gamma}_i^- \delta t_0 - \\ & - \sum_{i=p+1}^s \int_{\gamma_i(t_0)}^{\gamma_i} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi + o(t; \varepsilon \delta \mu) \quad (3.17) \end{aligned}$$

(see (3.14)).

Taking into account (3.9)–(3.13) and (3.17), we obtain (1.3), where $\delta x(t; \varepsilon \delta \mu)$ has the form (1.4).

4. PROOF OF THEOREM 1.2

Assume that in Lemma 2.3 $r_1 = t_{00}$ and $r_2 = t_{10}$. Then for any element $(\varepsilon, \delta \mu) \in [0, \varepsilon_1] \times V^+$, the corresponding solution $\omega(t; \mu_0 + \varepsilon \delta \mu)$ is defined on $[t_{10} - \delta_1, t_{10} + \delta_1]$. The solution $x(t; \mu_0 + \varepsilon \delta \mu)$ is defined on $[\tau, t_{10} + \delta_1]$ and

$$\omega(t; \mu_0 + \varepsilon \delta \mu) = x(t; \mu_0 + \varepsilon \delta \mu), \quad t \in [t_0, t_{10} + \delta_1]$$

(see Lemma 1.1 and 2.1). It is easy to see that

$$\Delta y(t) = \begin{cases} \varepsilon \delta \varphi(t), & t \in [\tau, t_{00}], \\ \varphi(t) - y_0(t), & t \in [t_{00}, t_0), \\ \Delta q(t), & t \in [t_0, t_{10} + \delta_1], \end{cases} \quad (4.1)$$

$$\Delta z(t) = \begin{cases} \varepsilon \delta g(t), & t \in [\tau, t_{00}], \\ g(t) - v_0(t), & t \in [t_{00}, t_0), \\ \Delta v(t), & t \in [t_0, t_{10} + \delta_1]. \end{cases} \quad (4.2)$$

Let numbers $\delta_2 \in (0, \delta_1)$ and $\varepsilon_2 \in (0, \varepsilon_1)$ be sufficiently small so that for an arbitrary $(\varepsilon, \delta \mu) \in [0, \varepsilon_2] \times V^+$ the inequality $\gamma_s(t_0) < t_{10} - \delta_2$ holds. By Lemma 3.1 we have

$$|\Delta y(t)| \leq O(\varepsilon \delta \mu), \quad \forall (t, \varepsilon, \delta \mu) \in [t_0, t_{10} + \delta_1] \times [0, \varepsilon_2] \times V^+, \quad (4.3)$$

$$|\Delta z(t)| \leq O(\varepsilon \delta \mu), \quad \forall (t, \varepsilon, \delta \mu) \in [\tau, t_{10} + \delta_1] \times [0, \varepsilon_2] \times V^+ \quad (4.4)$$

(see (4.1), (4.2), (2.10)). Moreover,

$$\Delta x(t_0) = \Delta \omega(t_0) = \varepsilon [Y_0 \delta y_0 + Y_1 \delta g(t_{00}+) + (Y_1 g_0^+ - f_p^+) \delta t_0] + o(\varepsilon \delta \mu) \quad (4.5)$$

(see (2.11)).

The function $\Delta x(t)$ on the interval $[t_0, t_{10} + \delta_2]$ satisfies (3.7) and hence it can be represented by the Cauchy formula

$$\Delta x(t) = Y(t_{00}, t) \Delta x(t_0) + \varepsilon \int_{t_0}^t Y(\xi; t) f_{0u}[t] \delta u(\xi) d\xi + \sum_{i=0}^2 h_i(t; t_0, \varepsilon \delta \mu), \quad (4.6)$$

where

$$h_0(t; t_0, \varepsilon \delta \mu) = \sum_{i=1}^s \int_{\tau_i(t_0)}^{t_0} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \Delta y(\xi) d\xi$$

and the functions $h_i(t; t_0, \varepsilon \delta \mu)$, $i = 1, 2$ are defined by the formulas (3.10).

The function $Y(\xi; t)$ is continuous on the set $[t_{00}, \tau_s(t_{10} - \delta_2)] \times [t_{10} - \delta_2, t_{10} + \delta_2]$. Since $t_0 \in [t_{00}, \tau_s(t_{10} - \delta_2)]$, we have

$$Y(t_{00}; t) \Delta x(t_0) = \varepsilon Y(t_{00}; t) [Y_0 \delta y_0 + Y_1 \delta g(t_{00}+) + (Y_1 g_0^+ - f_p^+) \delta t_0] + o(t; \varepsilon \delta \mu). \quad (4.7)$$

(see(4.5)).

Consider $h_0(t; t_0, \varepsilon \delta \mu)$. We have

$$\begin{aligned} h_0(t; t_0, \varepsilon \delta \mu) &= \sum_{i=1}^p \int_{\tau_i(t_0)}^{t_0} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \Delta y(\xi) d\xi + \\ &+ \sum_{i=p+1}^s \left[\varepsilon \int_{\tau_i(t_0)}^{t_{00}} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \delta \varphi(\xi) d\xi + \right. \\ &+ \left. \int_{t_{00}}^{t_0} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \Delta y(\xi) d\xi \right] = \\ &= \sum_{i=1}^p \int_{t_0}^{\gamma_i(t_0)} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi + \\ &+ \varepsilon \sum_{i=p+1}^s \int_{\tau_i(t_{00})}^{t_{00}} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \delta \varphi(\xi) d\xi + \\ &+ \sum_{i=p+1}^s \int_{\gamma_i}^{\gamma_i(t_0)} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi + o(t; \varepsilon \delta \mu), \quad (4.8) \end{aligned}$$

where

$$o(t; \varepsilon \delta \mu) = -\varepsilon \sum_{i=1}^s \int_{\tau_i(t_{00})}^{\tau_i(t_0)} Y(\gamma_i(\xi); t) f_{0y_i}[\gamma_i(\xi)] \dot{\gamma}_i(\xi) \delta \varphi(\xi) d\xi.$$

This implies

$$\begin{aligned} \sum_{i=1}^p \int_{t_0}^{\gamma_i(t_0)} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi &= \\ &= \sum_{i=1}^p \sum_{j=0}^{i-1} \int_{\gamma_j(t_0)}^{\gamma_{j+1}(t_0)} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi = \\ &= \sum_{i=0}^{p-1} \sum_{j=i+1}^p \int_{\gamma_i(t_0)}^{\gamma_{i-1}(t_0)} Y(\xi; t) f_{0y_j}[\xi] \Delta y(\tau_j(\xi)) d\xi, \quad \gamma_0(t_0) = t_0. \end{aligned} \quad (4.9)$$

Further,

$$\begin{aligned} h_1(t; t_0, \varepsilon \delta \mu) &= \sum_{j \in I_1 \cup I_2} \left[\varepsilon \int_{\sigma_j(t_0)}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi + \right. \\ &\quad \left. + \int_{t_{00}}^{t_0} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \Delta z(\xi) d\xi \right] + \\ &\quad + \sum_{j \in I_3} \int_{\sigma_j(t_0)}^{t_0} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \Delta z(\xi) d\xi = \\ &= \sum_{j \in I_1 \cup I_2} (\varepsilon \alpha_j(t) + \beta_j(t)) + \sum_{j \in I_3} \eta_j(t), \end{aligned}$$

where

$$\begin{aligned} \alpha_j(t) &= \int_{\sigma_j(t_0)}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi, \\ \beta_j(t) &= \int_{t_{00}}^{t_0} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \Delta z(\xi) d\xi, \\ \eta_j(t) &= \int_{\sigma_j(t_0)}^{t_0} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \Delta z(\xi) d\xi. \end{aligned}$$

Obviously $\beta_j(t) = o(t; \varepsilon\delta\mu)$, $\eta_j(t) = o(t; \varepsilon\delta\mu)$, so we have

$$\begin{aligned} \alpha_j(t) &= \int_{\sigma_j(t_{00})}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi - \\ &- \int_{\sigma_j(t_{00})}^{\sigma_j(t_0)} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi. \end{aligned}$$

Therefore

$$\begin{aligned} h_1(t; t_0, \varepsilon\delta\mu) &= \varepsilon \sum_{j=1}^s \int_{\sigma_j(t_{00})}^{t_{00}} Y(\rho_j(\xi); t) f_{0z_j}[\rho_j(\xi)] \dot{\rho}_j(\xi) \delta g(\xi) d\xi + \\ &+ o(t; \varepsilon\delta\mu). \end{aligned} \quad (4.10)$$

$h_2(t; t_0, \varepsilon\delta\mu)$ for $t \in [t_{10} - \delta_2, t_{10} + \delta_2]$ can be represented by the form

$$h_2(t; t_0, \varepsilon\delta\mu) = \sum_{i=1}^5 \beta_i(t; \varepsilon\delta\mu), \quad (4.11)$$

where

$$\begin{aligned} \beta_1(t; \varepsilon\delta\mu) &= \sum_{i=1}^{p-1} \int_{\gamma_i(t_0)}^{\gamma_{i+1}(t_0)} \bar{\omega}(\xi; t, \varepsilon\delta\mu) d\xi, \\ \beta_2(t; \varepsilon\delta\mu) &= \int_{\gamma_p(t_0)}^{\gamma_{p+1}} \bar{\omega}(\xi; t, \varepsilon\delta\mu) d\xi, \\ \beta_3(t; \varepsilon\delta\mu) &= \sum_{i=p+1}^s \int_{\gamma_i}^{\gamma_i(t_0)} \bar{\omega}(\xi; t, \varepsilon\delta\mu) d\xi, \\ \beta_4(t; \varepsilon\delta\mu) &= \sum_{i=p+1}^s \int_{\gamma_i(t_0)}^{\gamma_{i+1}} \bar{\omega}(\xi; t, \varepsilon\delta\mu) d\xi, \\ \beta_5(t; \varepsilon\delta\mu) &= \int_{\gamma_s(t_0)}^t \bar{\omega}(\xi; t, \varepsilon\delta\mu) d\xi. \end{aligned}$$

For $\beta_1(t; \varepsilon\delta\mu)$ we have

$$\beta_1(t; \varepsilon\delta\mu) = \beta_{11}(t; \varepsilon\delta\mu) - \beta_{12}(t; \varepsilon\delta\mu), \quad (4.12)$$

where

$$\begin{aligned} \beta_{11}(t; \varepsilon \delta \mu) &= \sum_{i=0}^{p-1} \int_{\gamma_i(t_0)}^{\gamma_{i+1}(t_0)} Y(\xi; t) \left[f\left(\xi, y_0(\tau_1(\xi)) + \Delta y(\tau_1(\xi)), \dots, \right. \right. \\ &\quad \left. \left. y_0(\tau_i(\xi)) + \Delta y(\tau_i(\xi)), \varphi(\tau_{i+1}(\xi)), \dots, \varphi(\tau_s(\xi)), \right. \right. \\ &\quad \left. \left. z_0(\sigma_1(\xi)) + \Delta z(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)) + \Delta z(\sigma_m(\xi)), \right. \right. \\ &\quad \left. \left. u_0(\xi) + \varepsilon \delta u(\xi)\right) - \right. \\ &\quad \left. - f\left(\xi, y_0(\tau_1(\xi)), \dots, y_0(\tau_p(\xi)), \varphi_0(\tau_{p+1}(\xi)), \dots, \varphi_0(\tau_s(\xi)), \right. \right. \\ &\quad \left. \left. z_0(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)), u_0(\xi)\right) \right] d\xi, \\ \beta_{12}(t; \varepsilon \delta \mu) &= \sum_{i=0}^{p-1} \int_{\gamma_i(t_0)}^{\gamma_{i+1}(t_0)} Y(\xi; t) \left[\sum_{j=1}^s f_{0y_j}[\xi] \Delta y(\tau_j(\xi)) + \right. \\ &\quad \left. + \sum_{j=1}^m f_{0z_j}[\xi] \Delta z(\tau_j(\xi)) \right] d\xi. \end{aligned}$$

Let $\xi \in [\gamma_i(t_0), \gamma_{i+1}(t_0)]$. Then

$$\tau_j(\xi) \geq t_0, \quad j = \overline{1, i}, \quad \tau_j(\xi) \leq t_0, \quad j = \overline{i+1, p}, \quad \tau_j(\xi) < t_{00}, \quad j = \overline{p+1, s},$$

and hence

$$\begin{aligned} |\Delta y(\tau_j(\xi))| &\leq O(\varepsilon \delta \mu), \quad j = \overline{1, i}, \\ \Delta y(\tau_j(\xi)) &= \varepsilon \delta \varphi(\tau_j(\xi)), \quad j = \overline{p+1, s}, \end{aligned} \quad (4.13)$$

(see (4.1), (4.3)).

For any $i \in \{0, \dots, p-1\}$, the function $\gamma_{i+1}(t_0) - \gamma_i(t_0)$ tends to zero as $\varepsilon \rightarrow 0$. Therefore, taking into account (4.13) and (4.4) we have

$$\beta_{12}(t; \varepsilon \delta \mu) = \sum_{i=0}^{p-1} \sum_{j=i+1}^p \int_{\gamma_i(t_0)}^{\gamma_{i+1}(t_0)} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_j(\xi)) d\xi + o(t; \varepsilon \delta \mu). \quad (4.14)$$

Further

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \sup_{\xi \in [\gamma_i(t_0), \gamma_{i+1}(t_0)]} &\left| f\left(\xi, y_0(\tau_1(\xi)) + \Delta y(\tau_1(\xi)), \dots, y_0(\tau_i(\xi)) + \Delta y(\tau_i(\xi)), \right. \right. \\ &\quad \left. \left. \varphi(\tau_{i+1}(\xi)), \dots, \varphi(\tau_s(\xi)), \right. \right. \\ &\quad \left. \left. z_0(\sigma_1(\xi)) + \Delta z(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)) + \Delta z(\sigma_m(\xi)), u_0(\xi) + \varepsilon \delta u(\xi)\right) \right. \\ &\quad \left. - f_i^+ + f_p^+ - f\left(\xi, y_0(\tau_1(\xi)), \dots, y_0(\tau_p(\xi)), \varphi_0(\tau_{p+1}(\xi)), \dots, \varphi_0(\tau_s(\xi)), \right. \right. \\ &\quad \left. \left. z_0(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)), u_0(\xi)\right) \right| = 0, \quad i = \overline{0, p-1}, \quad (4.15) \end{aligned}$$

uniformly with respect of to $\delta \mu \in V^+$.

The properties of the functions $Y(\xi; t)$ and $\gamma_i(t)$, $i = \overline{1, p}$ imply that

$$\lim_{\varepsilon \rightarrow 0} \sup_{\xi \in [\gamma_i(t_0), \gamma_{i+1}(t_0)]} |Y(\xi; t) - Y(t_{00}; t)| = 0, \quad i = \overline{0, p-1} \quad (4.16)$$

uniformly with respect to $t \in [t_{10} - \delta_2, t_{10} + \delta_2]$ and

$$\gamma_{i+1}(t_0) - \gamma_i(t_0) = \varepsilon(\dot{\gamma}_{i+1}^+ - \dot{\gamma}_i^+) \delta t_0 + o(\varepsilon \delta \mu), \quad i = \overline{0, p-1}, \quad \dot{\gamma}_0 = 1. \quad (4.17)$$

From (4.13)–(4.15) we have

$$\beta_{11}(t; \varepsilon \delta \mu) = \varepsilon Y(t_{00}, t) \sum_{i=0}^p (f_i^+ - f_p^+) (\dot{\gamma}_{i+1}^+ - \dot{\gamma}_i^+) \delta t_0 + o(t; \varepsilon \delta \mu). \quad (4.18)$$

From (4.12), (4.14) and (4.18) we have

$$\begin{aligned} \beta_1(t; \varepsilon \delta \mu) &= \varepsilon Y(t_{00}, t) \left[\sum_{i=0}^p (\dot{\gamma}_{i+1}^+ - \dot{\gamma}_i^+) f_i^+ + f_p^+ \right] \delta t_0 - \\ &\quad - \sum_{i=0}^{p-1} \sum_{j=i+1}^p \int_{\gamma_i(t_0)}^{\gamma_{i+1}(t_0)} Y(\xi; t) f_{0y_j}[\xi] \Delta y(\tau_j(\xi)) d\xi + o(t; \varepsilon \delta \mu). \end{aligned} \quad (4.19)$$

It is easy to see that

$$\begin{aligned} \beta_2(t; \varepsilon \delta \mu) &= \int_{\gamma_p(t_0)}^{\gamma_{p+1}} Y(\xi; t) \left[f(\xi, y_0(\tau_1(\xi)) + \Delta y(\tau_1(\xi)), \dots, y_0(\tau_p(\xi)) + \Delta y(\tau_p(\xi)), \right. \\ &\quad \left. \varphi(\tau_{p+1}(\xi)), \dots, \varphi(\tau_s(\xi)), z_0(\sigma_1(\xi)) + \Delta z(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)) + \Delta z(\sigma_m(\xi)), \right. \\ &\quad \left. u_0(\xi) + \varepsilon \delta u(\xi) \right) - \\ &\quad - f(\xi, y_0(\tau_1(\xi)), \dots, y_0(\tau_p(\xi)), \varphi_0(\tau_{p+1}(\xi)), \dots, \varphi_0(\tau_s(\xi)), \\ &\quad \left. z_0(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)), u_0(\xi) \right) - \\ &\quad - \sum_{j=1}^p f_{0y_j}[\xi] \Delta y(\tau_j(\xi)) - \varepsilon \sum_{j=p+1}^s f_{0y_j}[\xi] \delta \varphi(\tau_j(\xi)) - \\ &\quad \left. - \sum_{j=1}^m f_{0z_j}[\xi] \Delta z(\sigma_j(\xi)) - \varepsilon f_{0u}[\xi] \delta u(\xi) \right] d\xi. \end{aligned}$$

It is easy to prove that

$$\beta_2(t; \varepsilon \delta \mu) = o(t; \varepsilon \delta \mu) \quad (4.20)$$

(see (4.3) and (4.4)).

Consider the other terms of (4.11). We have

$$\beta_3(t; \varepsilon \delta \mu) = \sum_{i=p+1}^s \int_{\gamma_i}^{\gamma_i(t_0)} Y(\xi; t) \left[f(\xi, y_0(\tau_1(\xi)) + \Delta y(\tau_1(\xi)), \dots, \right.$$

$$\begin{aligned}
& y_0(\tau_{i-1}(\xi)) + \Delta y(\tau_{i-1}(\xi)), \varphi(\tau_i(\xi)), \dots, \varphi(\tau_s(\xi)), \\
& z_0(\sigma_1(\xi)) + \Delta z(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)) + \Delta z(\sigma_m(\xi)), u_0(\xi) + \varepsilon \delta u(\xi) \Big) - \\
& - f\left(\xi, y_0(\tau_1(\xi)), \dots, y_0(\tau_i(\xi)), \varphi(\tau_{i+1}(\xi)), \dots, \varphi(\tau_s(\xi)), \right. \\
& \quad \left. z_0(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)), u_0(\xi)\right) \Big] d\xi - \\
& - \sum_{i=p+1}^s \left[\sum_{j=1}^{i-1} \int_{\gamma_i}^{\gamma_i(t_0)} Y(\xi; t) f_{0y_j}[\xi] \Delta y(\tau_j(\xi)) d\xi + \right. \\
& + \int_{\gamma_i}^{\gamma_i(t_0)} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi + \varepsilon \sum_{j=i+1}^s \int_{\gamma_i}^{\gamma_i(t_0)} Y(\xi; t) f_{0y_j}[\xi] \delta \varphi(\tau_j(\xi)) d\xi \Big] - \\
& \quad - \sum_{i=p+1}^s \int_{\gamma_i}^{\gamma_i(t_0)} Y(\xi; t) \sum_{j=1}^m f_{0z_j}[\xi] \Delta z(\sigma_j(\xi)) d\xi.
\end{aligned}$$

By the condition (6) we have

$$\begin{aligned}
\lim_{\varepsilon \rightarrow 0} \sup_{\xi \in [\gamma_i, \gamma_i(t_0)]} & \left| f\left(\xi, y_0(\tau_1(\xi)) + \Delta y(\tau_1(\xi)), \dots, y_0(\tau_{i-1}(\xi)) + \Delta y(\tau_{i-1}(\xi)), \right. \right. \\
& \varphi(\tau_i(\xi)), \dots, \varphi(\tau_s(\xi)), z_0(\sigma_1(\xi)) + \Delta z(\sigma_1(\xi)), \dots, \\
& \quad \left. z_0(\sigma_m(\xi)) + \Delta z(\sigma_m(\xi)), u_0(\xi) + \varepsilon \delta u(\xi) \Big) - \right. \\
& - f\left(\xi, y_0(\tau_1(\xi)), \dots, y_0(\tau_i(\xi)), \varphi(\tau_{i+1}(\xi)), \dots, \varphi(\tau_s(\xi)), \right. \\
& \quad \left. z_0(\sigma_1(\xi)), \dots, z_0(\sigma_m(\xi)), u_0(\xi) \Big) + f_i^+ \Big| = 0, \quad i = \overline{p+1, s}
\end{aligned}$$

uniformly with respect to $\delta \mu \in V^+$.

Further,

$$\begin{aligned}
|\Delta y(\tau_j(\xi))| & \leq O(\varepsilon \delta \mu), \quad j = \overline{1, i-1}, \quad \xi \in [\gamma_i, \gamma_i(t_0)], \\
\lim_{\varepsilon \rightarrow 0} \sup_{\xi \in [\gamma_i, \gamma_i(t_0)]} & |Y(\xi; t) - Y(\gamma_i; t)| = 0, \quad i = \overline{p+1, s}
\end{aligned}$$

uniformly with respect to $t \in [t_{10} - \delta_2, t_{10} + \delta_2]$.

Now, we obtain for the function $\beta_3(t; \varepsilon \delta \mu)$ the representation

$$\begin{aligned}
\beta_3(t; \varepsilon \delta \mu) & = -\varepsilon \sum_{i=p+1}^s Y(\gamma_i; t) f_i^+ \delta t_0 - \\
& - \sum_{i=p+1}^s \int_{\gamma_i}^{\gamma_i(t_0)} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_j(\xi)) d\xi + o(t; \varepsilon \delta \mu). \quad (4.21)
\end{aligned}$$

Similarly we can prove (see (3.16)) that

$$\beta_i(t; \varepsilon\delta\mu) = o(\varepsilon\delta\mu), \quad i = 4, 5. \quad (4.22)$$

Taking into account (4.19)–(4.22), we obtain

$$\begin{aligned} h_1(t; t_0, \varepsilon\delta\mu) = & \varepsilon \left\{ Y(t_{00}, t) \sum_{i=0}^p (\dot{\gamma}_{i+1}^+ - \dot{\gamma}_i^+) - \sum_{i=p+1}^s Y(\gamma_i; t) f_i^+ \right\} \delta t_0 - \\ & - \sum_{i=0}^{p-1} \sum_{j=i+1}^p \int_{\gamma_i(t_0)}^{\gamma_{i+1}(t_0)} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_j(\xi)) d\xi - \\ & - \sum_{i=p+1}^s \int_{\gamma_i}^{\gamma_i(t_0)} Y(\xi; t) f_{0y_i}[\xi] \Delta y(\tau_i(\xi)) d\xi + o(t; \varepsilon\delta\mu) \quad (4.23) \end{aligned}$$

(see (4.11)).

From (4.6), taking into account (4.7)–(4.10) and (4.23), we obtain (1.3), where $\delta x(t; \delta\mu)$ has the form (1.8).

ACKNOWLEDGEMENT

The work was supported by Georgian National Scientific Foundation, grant GNSF/ST06/3-046.

REFERENCES

1. G. L. KHARATISHVILI AND T. A. TADUMADZE, Formulas for the variation of a solution of a nonlinear differential equation with delays and a mixed initial condition. (Russian) *Sovrem. Mat. Prilozh.* No. 42, Optim. Upr. (2006), 12–38; English transl.: *J. Math. Sci. (N. Y.)* **148** (2008), No. 3, 302–330.
2. G. KHARATISHVILI, T. TADUMADZE, AND N. GORGODZE, Continuous dependence and differentiability of solution with respect to initial data and right-hand side for differential equations with deviating argument. *Mem. Differential Equations Math. Phys.* **19** (2000), 3–105.
3. T. TADUMADZE, Local representations for the variation of solutions of delay differential equations. *Mem. Differential Equations Math. Phys.* **21** (2000), 138–141.
4. G. L. KHARATISHVILI AND T. A. TADUMADZE, Formulas for the variation of the solution of a differential equation with retarded arguments and a continuous initial condition. (Russian) *Differ. Uravn.* **40** (2004), No. 4, 500–508, 575; English transl.: *Differ. Equ.* **40** (2004), No. 4, 542–551.
5. G. L. KHARATISHVILI AND T. A. TADUMADZE, Formulas for variations of solutions to a differential equation with retarded arguments and a discontinuous initial condition. (Russian) *Mat. Sb.* **196** (2005), No. 8, 49–74; English transl.: *Sb. Math.* **196** (2005), No. 7-8, 1137–1163.
6. G. L. KHARATISHVILI AND T. A. TADUMADZE, Formulas for the variation of a solution and optimal control problems for differential equations with retarded arguments. (Russian) *Sovrem. Mat. Prilozh.* No. 25, Optimal. Upr. (2005), 3–166; English transl.: *J. Math. Sci. (N. Y.)* **140** (2007), No. 1, 1–175.

7. T. TADUMADZE AND L. ALKHAZISHVILI, Formulas of variation of solution for non-linear controlled delay differential equations with discontinuous initial condition. *Mem. Differential Equations Math. Phys.* **29** (2003), 125–150.
8. T. TADUMADZE AND L. ALKHAZISHVILI, Formulas of variation of solution for non-linear controlled delay differential equations with continuous initial condition. *Mem. Differential Equations Math. Phys.* **31** (2004), 83–97.
9. R. V. GAMKRELIDZE, Foundations of optimal control. (Russian) *Izdat. Tbilis. Univ., Tbilisi*, 1977.
10. L. W. NEUSTADT, Optimization. A theory of necessary conditions. With a chapter by H. T. Banks. *Princeton University Press, Princeton, N. J.*, 1976.
11. N. M. OGUSTORELI, Time-delay control systems. *Academic Press, New York–London*, 1966.
12. G. L. KHARATISHVILI AND T. A. TADUMADZE, A nonlinear optimal control problem with variable delay, nonfixed initial moment, and piecewise-continuous prehistory. (Russian) *Tr. Mat. Inst. Steklova* **220** (1998), Optim. Upr., Differ. Uravn. i Gladk. Optim., 236–255; English transl.: *Proc. Steklov Inst. Math.* **1998**, No. 1 (220), 233–252.

(Received 24.06.2009)

Authors' address:

Faculty of Exact and Natural Sciences
Iv. Javakhishvili Tbilisi State University
2, University St., Tbilisi 0186
Georgia
E-mail: lelahaz@yahoo.com
 imedea@yahoo.com