

Quarter-Symmetric Non-Metric Connection on Pseudosymmetric Kenmotsu Manifolds

C. Patra^a and A. Bhattacharyya^b

^aAssistant Professor in Mathematics,
Govt. Degree College, Kamalpur, Dhalai, Tripura, India.
patrachinmoy@yahoo.co.in

^bReader, Department of Mathematics,
Jadavpur University, Kolkata-700032, W.B., India.
aribh22@hotmail.com

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In this paper we shall introduce a quarter-symmetric non-metric connection in a pseudosymmetric Kenmotsu manifold and find out some of its properties. We shall show the existence of quarter-symmetric non-metric connection on Kenmotsu manifold. Also we state the definitions of Weyl-pseudosymmetric Kenmotsu manifold and Ricci pseudosymmetric Kenmotsu manifold with respect to quarter-symmetric non-metric connection. Next we show some results on Weyl-pseudosymmetric Kenmotsu manifold and partially Ricci pseudosymmetric Kenmotsu manifold with respect to quarter-symmetric non-metric connection and η -Einstein manifold. At the end we show an example of pseudosymmetric Kenmotsu manifold with respect to quarter-symmetric non-metric connection.

Keywords: Kenmotsu manifold, Quarter-Symmetric Non-Metric connection, Pseudosymmetric Kenmotsu Manifolds, Weyl-pseudosymmetric, Ricci pseudosymmetric.

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1. Introduction

In 1987, M.C. Chaki and B. Chaki [11] studied pseudosymmetric manifolds with semisymmetric connection and many authors studied properties on this manifold. Also R. Deszcz et. al. studied Ricci-pseudosymmetric manifolds and pseudosymmetric manifolds [2], [3], [6], [7]. The conceptions of pseudosymmetric manifold are different with the above authors. In 2008, C. S. Bagewadi and et. al. studied pseudosymmetric Lorentzian α -Sasakian manifolds in the Deszcz sense [10]. We shall study the properties of pseudosymmetric Kenmotsu manifolds and Ricci-pseudosymmetric Kenmotsu manifolds with respect to quarter-symmetric non-metric connection in the Deszcz sense.

A Riemannian manifold (M, g) of dimension n is called pseudosymmetric if the Riemannian curvature tensor R satisfies the conditions [1], [4], [7]

$$1. \quad (R(X, Y) \cdot R)(U, V, W) = L_R[((X \wedge Y) \circ R)(U, V, W)] \quad (1)$$

^aCorresponding author. Email: patrachinmoy@yahoo.co.in

for all vector fields X, Y, U, V, W on M , where $L_R \in C^\infty(M)$, $R(X, Y)Z = \nabla_{[X, Y]}Z - [\nabla_X, \nabla_Y]Z$ and $X \wedge Y$ is an endomorphism defined by

$$(X \wedge Y)Z = g(Y, Z)X - g(X, Z)Y \quad (2)$$

$$\begin{aligned} 2. \quad (R(X, Y).R)(U, V, W) &= R(X, Y)(R(U, V)W) \\ &\quad - R(R(X, Y)U, V)W - R(U, R(X, Y)V)W - R(U, V)(R(X, Y)W), \end{aligned} \quad (3)$$

$$\begin{aligned} 3. \quad ((X \wedge Y).R)(U, V, W) &= (X \wedge Y)(R(U, V)W) \\ &\quad - R((X \wedge Y)U, V)W - R(U, (X \wedge Y)V)W - R(U, V)((X \wedge Y)W). \end{aligned} \quad (4)$$

M is said to be pseudosymmetric of constant type if L is constant. A Riemannian manifold (M, g) is called quarter-symmetric if $R.R = 0$, where $R.R$ is the derivative of R by R .

Remark 1: From [4], [5] we know that the $(0, k+2)$ tensor fields $R.T$ and $Q(g, T)$ are defined by

$$\begin{aligned} (R.T)(X_1, \dots, X_k; X, Y) &= (R(X, Y).T)(X_1, \dots, X_k) \\ &= -T(R(X, Y)X_1, \dots, X_k) - \dots - T(X_1, \dots, R(X, Y)X_k) \\ Q(g, T)(X_1, \dots, X_k; X, Y) &= -((X \wedge Y).T)(X_1, \dots, X_k) \\ &= T((X \wedge Y)X_1, \dots, X_k) + \dots + T(X_1, \dots, (X \wedge Y)X_k), \end{aligned}$$

where T is a $(0, k)$ tensor field.

Let S and r denote the Ricci tensor and the scalar curvature tensor of M respectively. The operator Q and the $(0, 2)$ -tensor S^2 are defined by

$$S(X, Y) = g(QX, Y) \quad (5)$$

and

$$S^2(X, Y) = S(QX, Y) \quad (6)$$

The Weyl conformal curvature operator C is defined by

$$C(X, Y) = R(X, Y) - \frac{1}{n-2}[X \wedge QY + QX \wedge Y - \frac{r}{n-1}X \wedge Y]. \quad (7)$$

If $C = 0$, $n \geq 4$ then M is called conformally flat. If the tensor $R.C$ and $Q(g, C)$ are linearly dependent then M is called Weyl-pseudosymmetric. This is equivalent to

$$R.C(U, V, W; X, Y) = L_C[(X \wedge Y).C](U, V)W, \quad (8)$$

holds on the set $U_C = \{x \in M : C \neq 0 \text{ at } x\}$, where L_C is defined on U_C . If $R.C = 0$, then M is called Weyl-semi-symmetric. If $\nabla C = 0$, then M is called conformally symmetric [10].

2. Preliminaries:

Let M be an almost contact metric manifold of dimension $2n + 1$ with an almost contact metric structure (ϕ, ξ, η, g) where ϕ is $(1, 1)$ tensor field, ξ is a contravariant vector field, η is a 1-form and g is an associated Riemannian metric such that,

$$\phi^2 = -I + \eta \otimes \xi, \quad (9)$$

$$\eta(\xi) = 1, \quad \phi\xi = 0, \quad \eta \circ \phi = 0, \quad (10)$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y) \quad (11)$$

and

$$g(X, \xi) = \eta(X), \quad (12)$$

$\forall X, Y \in \chi(M)$, then M is called a *Kenmotsu manifold* provided,

$$(\nabla_X \phi)(Y) = -g(X, \phi Y)\xi - \eta(Y)\phi X \quad (13)$$

and

$$\nabla_X \xi = X - \eta(X)\xi \quad (14)$$

holds, where ∇ is affine connection on M [8], [9].

On a Kenmotsu manifold, it can be shown that

$$(\nabla_X \eta)Y = g(\phi X, \phi Y), \quad (15)$$

$$F(X, Y) = -F(Y, X), \quad (16)$$

where $F(X, Y) = g(\phi X, Y)$, is a fundamental 2-form.

Further on a Kenmotsu manifold the following relations hold, [8]

$$\eta(R(X, Y)Z) = g(X, Z)\eta(Y) - g(Y, Z)\eta(X), \quad (17)$$

$$R(\xi, X)Y = \eta(Y)X - g(X, Y)\xi, \quad (18)$$

$$R(X, Y)\xi = \eta(X)Y - \eta(Y)X, \quad (19)$$

$$S(\xi, X) = S(X, \xi) = -2n\eta(X), \quad (20)$$

$$Q\xi = -2n\xi. \quad (21)$$

3. Quarter-symmetric non-metric connection on Kenmotsu manifold:

Let M be a Kenmotsu manifold with Levi-Civita connection ∇ and $X, Y \in \chi(M)$. We define a linear connection D on M by

$$D_X Y = \nabla_X Y + \eta(Y)\phi(X), \quad (22)$$

where η is a 1-form and ϕ is a tensor field of type $(1, 1)$. D is said to be quarter symmetric connection if \bar{T} , the torsion tensor with respect to the connection D , satisfies

$$\bar{T}(X, Y) = \eta(Y)\phi X - \eta(X)\phi Y. \quad (23)$$

D is said to be non-metric connection if $(Dg) \neq 0$. Using (16) we have

$$(D_X g)(Y, Z) = -\{\eta(Y)g(\phi X, Z) + \eta(Z)g(\phi X, Y)\}. \quad (24)$$

A linear connection D is said to be a quarter-symmetric non-metric connection if it satisfies (22), (23) and (24).

Now we shall show the existence of the quarter-symmetric non-metric connection D on a Kenmotsu manifold M .

Theorem 3.1: *Let X, Y, Z be any vectors fields on a Kenmotsu manifold M with an almost structure (ϕ, ξ, η, g) . Let us define a connection D by*

$$\begin{aligned} 2g(D_X Y, Z) = & Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) \\ & + g([X, Y], Z) - g([Y, Z], X) + g([Z, X], Y) \\ & + g(\eta(Y)\phi X - \eta(X)\phi Y, Z) + g(\eta(X)\phi Z \\ & - \eta(Z)\phi X, Y) + g(\eta(Y)\phi Z + \eta(Z)\phi Y, X). \end{aligned} \quad (25)$$

Then D is a quarter-symmetric non-metric connection on M .

Proof: It can be verified that $D : (X, Y) \rightarrow D_X Y$ satisfies the following equations:

$$D_X(Y + Z) = D_X Y + D_X Z \quad (26)$$

$$D_{X+Y} Z = D_X Z + D_Y Z \quad (27)$$

$$D_{fX} Y = fD_X Y \quad (28)$$

$$D_X(fY) = f(D_X Y) + (Xf)Y \quad (29)$$

for all $X, Y, Z \in \chi(M)$ and for all f , all differentiable functions on M .
 From (26), (27), (28) and (29) we can conclude that D is a linear connection on M . From (25) we have,
 $D_X Y - D_Y X - [X, Y] = \eta(Y)\phi X - \eta(X)\phi Y$
 or,

$$\bar{T}(X, Y) = \eta(Y)\phi X - \eta(X)\phi Y. \quad (30)$$

Again from (25) we get,
 $2g(D_X Y, Z) + 2g(D_X Z, Y)$

$$= 2Xg(Y, Z) + 2\eta(Y)g(\phi X, Z) + 2\eta(Z)g(\phi X, Y)$$

$$(D_X g)(Y, Z) = -\{\eta(Y)g(\phi X, Z) + \eta(Z)g(\phi X, Y)\}. \quad (31)$$

This shows that D is a quarter-symmetric non-metric connection on M .
 \diamond

Theorem 3.2: Let D be a linear connection on a Kenmotsu manifold M , given by

$$D_X Y = \nabla_X Y + H(X, Y), \quad (32)$$

where $H(X, Y)$ is a $(1, 2)$ tensor field and ∇ is Levi-Civita connection, satisfying (24). Then $H(X, Y) = \eta(Y)\phi(X)$.

Proof: Using (32) in the definition of torsion tensor, we get

$$\bar{T}(X, Y) = H(X, Y) - H(Y, X). \quad (33)$$

From (32), we have

$$g(H(X, Y), Z) + g(H(X, Z), Y) = -(D_X g)(Y, Z). \quad (34)$$

From (24), (32), (33) and (34) we have

$$g(\bar{T}(X, Y), Z) + g(\bar{T}(Z, Y), X) + g(\bar{T}(Z, X), Y)$$

$$= 2g(H(X, Y), Z) - (D_Z g)(X, Y) + (D_Y g)(X, Z) + (D_X g)(Y, Z).$$

We get from the above equation,

$$g(H(X, Y), Z) = \frac{1}{2}[g(\bar{T}(X, Y), Z) + g(\bar{T}(Z, Y), X)$$

$$+ g(\bar{T}(Z, X), Y)] + [\eta(Y)g(\phi X, Z) + \eta(X)g(\phi Y, Z)].$$

Thus, we get

$$H(X, Y) = \frac{1}{2}[\bar{T}(X, Y) + \tilde{T}(X, Y) + \tilde{T}(Y, X)] + [\eta(Y)\phi X + \eta(X)\phi Y],$$

where \tilde{T} is a tensor field of type $(1, 2)$ defined by

$$g(\tilde{T}(X, Y), Z) = g(\bar{T}(Z, X), Y).$$

Thus $H(X, Y) = \eta(Y)\phi X$.

Hence $D_X Y = \nabla_X Y + \eta(Y)\phi X$. \diamond

4. Curvature tensor and Ricci tensor with respect to quarter-symmetric non-metric connection D in a Kenmotsu manifold

Let $\bar{R}(X, Y)Z$ and $R(X, Y)Z$ be the curvature tensors on a Kenmotsu manifold M with respect to the quarter-symmetric non-metric connection D and with respect to the Riemannian connection ∇ respectively. A relation between the curvature tensors of M with respect to the quarter-symmetric non-metric connection D and the Riemannian connection ∇ is given by

$$\begin{aligned} \bar{R}(X, Y)Z &= R(X, Y)Z + 2\eta(Z)g(\phi X, Y)\xi \\ &\quad + g(X, Z)\phi Y - g(Y, Z)\phi X. \end{aligned} \quad (35)$$

Also from (35) we obtain

$$\bar{S}(X, Y) = S(X, Y) + g(\phi X, Y), \quad (36)$$

where \bar{S} and S are the Ricci tensors of the connections D and ∇ respectively. Contracting (36), we get

$$\bar{r} = r, \quad (37)$$

where \bar{r} and r are the scalar curvature with respect to the connection D and ∇ respectively.

Let \bar{C} be the conformal curvature tensors on Kenmotsu manifolds with respect to the connections D . Then

$$\begin{aligned} \bar{C}(X, Y)Z &= \bar{R}(X, Y)Z - \frac{1}{n-2}[\bar{S}(Y, Z)X - g(X, Z)\bar{Q}Y + g(Y, Z)\bar{Q}X \\ &\quad - \bar{S}(X, Z)Y] + \frac{\bar{r}}{(n-1)(n-2)}[g(Y, Z)X - g(X, Z)Y], \end{aligned} \quad (38)$$

where \bar{Q} is the Ricci operator with the connection D on M and

$$\bar{S}(X, Y) = g(\bar{Q}X, Y), \quad (39)$$

$$\bar{S}^2(X, Y) = \bar{S}(\bar{Q}X, Y). \quad (40)$$

Now we shall prove the following theorem.

Theorem 4.1: *Let M be a Kenmotsu manifold with respect to the quarter-symmetric non-metric connection D , then the following relations hold:*

$$\bar{R}(\xi, X)Y = \eta(Y)X - g(X, Y)\xi + \eta(Y)\phi X, \quad (41)$$

$$\eta(\bar{R}(X, Y)Z) = g(X, Z)\eta(Y) - g(Y, Z)\eta(X) + 2g(\phi X, Y)\eta(Z), \quad (42)$$

$$\bar{R}(X, Y)\xi = \eta(X)Y - \eta(Y)X - \eta(Y)\phi X + \eta(X)\phi Y + 2g(\phi X, Y)\xi, \quad (43)$$

$$\bar{S}(X, \xi) = \bar{S}(\xi, X) = -2n\eta(X), \quad (44)$$

$$\bar{Q}X = QX + \phi X, \quad (45)$$

$$\bar{S}^2(X, \xi) = \bar{S}^2(\xi, X) = 4n^2\eta(X), \quad (46)$$

$$\bar{Q}\xi = -2n\xi. \quad (47)$$

Proof: Since M is a Kenmotsu with respect to the quarter-symmetric non-metric connection D , then replacing $X = \xi$ in (35) and using (10) and (18) we get (41). Using (10) and (17), from (35) we get (42). To prove (43), we put $Z = \xi$ in (35) and then we use (19). Replacing $Y = \xi$ in (36) and using (20) we get (44). Using (36) and (39) we get (45). Using (40), (44) and (45) we get (46). Putting $X = \xi$ in (45) we obtain (47). ◇

5. Kenmotsu manifold with respect to the quarter-symmetric non-metric connection D satisfying the condition $\bar{C}.\bar{S} = 0$.

In this section we shall find out the characterization of Kenmotsu manifold with respect to the quarter-symmetric non-metric connection D satisfying the condition $\bar{C}.\bar{S} = 0$.

We define $\bar{C}.\bar{S} = 0$ on M by

$$(\bar{C}(X, Y).\bar{S})(Z, W) = -\bar{S}(\bar{C}(X, Y)Z, W) - \bar{S}(Z, \bar{C}(X, Y)W), \quad (48)$$

where $X, Y, Z, W \in \chi(M)$.

Theorem 5.1: *Let M be a Kenmotsu manifold with respect to the quarter-symmetric non-metric connection D . If $\bar{C}.\bar{S} = 0$, then*

$$\begin{aligned} \bar{S}^2(X, Y) = -\left\{\frac{r}{(n-1)} + n - 2\right\}\bar{S}(X, Y) + 2n\left\{\frac{r}{n-1} + n + 2\right\}g(X, Y) \\ - 2n(2n - 1)\eta(X)\eta(Y) - (n - 2)\bar{S}(\phi X, Y) \end{aligned} \quad (49)$$

Proof: Let us consider M to be a Kenmotsu manifold with respect the quarter-symmetric non-metric connection D satisfying the condition $\bar{C}.\bar{S} = 0$. Then from (48), we get

$$\bar{S}(\bar{C}(X, Y)Z, W) + \bar{S}(Z, \bar{C}(X, Y)W) = 0, \quad (50)$$

where $X, Y, Z, W \in \chi(M)$. Now putting $X = \xi$ in (50), we get

$$\bar{S}(\bar{C}(\xi, X)Y, Z) + \bar{S}(Y, \bar{C}(\xi, X)Z) = 0. \quad (51)$$

Using (41) and (44) we have

$$\begin{aligned} \bar{S}(\bar{C}(\xi, X)Y, Z) &= \left[\frac{\bar{r}}{(n-1)(n-2)} - \frac{(n+2)}{n-2} \right] [2n\eta(Z)g(X, Y) + \eta(Y)\bar{S}(X, Z)] \\ &+ \eta(Y)\bar{S}(\phi X, Z) + \frac{1}{n-2} [2n\eta(Z)\bar{S}(X, Y) + \bar{S}^2(X, Z)\eta(Y)] \end{aligned} \quad (52)$$

and

$$\begin{aligned} \bar{S}(\bar{C}(\xi, X)Y, Z) &= \left[\frac{\bar{r}}{(n-1)(n-2)} - \frac{(n+2)}{n-2} \right] [2n\eta(Y)g(X, Z) + \eta(Z)\bar{S}(X, Y)] \\ &+ \eta(Z)\bar{S}(\phi X, Y) + \frac{1}{n-2} [2n\eta(Y)\bar{S}(X, Z) + \bar{S}^2(X, Y)\eta(Z)]. \end{aligned} \quad (53)$$

Using (52) and (53) in (51) we get

$$\begin{aligned} 2n \left[\frac{\bar{r}}{(n-1)(n-2)} - \frac{(n+2)}{n-2} \right] \{ \eta(Z)g(X, Y) + \eta(Y)g(X, Z) \} + \eta(Z)\bar{S}(\phi X, Y) \\ + \left[\frac{\bar{r}}{(n-1)(n-2)} + 1 \right] \{ \eta(Z)\bar{S}(X, Y) + \eta(Y)\bar{S}(X, Z) \} + \eta(Y)\bar{S}(\phi X, Z) \\ + \frac{1}{n-2} [\eta(Z)\bar{S}^2(X, Y) + \bar{S}^2(X, Z)\eta(Y)], \end{aligned} \quad (54)$$

Replacing $Z = \xi$ in (54) and using (44) and (46) we get

$$\begin{aligned} \bar{S}^2(X, Y) &= - \left\{ \frac{\bar{r}}{(n-1)} + n - 2 \right\} \bar{S}(X, Y) + 2n \left\{ \frac{\bar{r}}{n-1} + n + 2 \right\} g(X, Y) \\ &- 2n(2n-1)\eta(X)\eta(Y) - (n-2)\bar{S}(\phi X, Y). \quad \diamond \end{aligned}$$

A Kenmotsu manifold M with the quarter-symmetric non-metric connection D is said to be η -Einstein if its Ricci tensor \bar{S} is of the form

$$\bar{S}(X, Y) = Ag(X, Y) + B\eta(X)\eta(Y), \quad (55)$$

where A and B are smooth functions on M .

Now putting $X = Y = e_i$, $i = 1, 2, \dots, 2n+1$ in (55) and taking summation for $1 \leq i \leq n$ we get,

$$A(2n+1) + B = r. \quad (56)$$

Again replacing $X = Y = \xi$ in (55) we have

$$A + B = -2n. \quad (57)$$

Solving (56) and (57) we obtain

$$A = \frac{r}{2n} + 1 \text{ and } B = - \left[\frac{r}{2n} + 2n + 1 \right].$$

Thus the Ricci tensor of an η -Einstein manifold with the quarter-symmetric non-metric connection D is given by

$$\bar{S}(X, Y) = \left[\frac{r}{2n} + 1\right]g(X, Y) - \left[\frac{r}{2n} + 2n + 1\right]\eta(X)\eta(Y). \quad (58)$$

6. η -Einstein Kenmotsu manifold with respect to the quarter-symmetric non-metric connection D satisfying the condition $\bar{C}.\bar{S} = 0$.

Theorem 6.1: *Let M be an η -Einstein Kenmotsu manifold with the restriction $U = Y = \xi$ in $\chi(M)$. Then $\bar{C}.\bar{S} = 0$ iff*

$$g(X, Z) = \eta(X)\eta(Z), \text{ where } X, Z \in \chi(M).$$

Proof: Let M be an η -Einstein Kenmotsu manifold with respect to the quarter-symmetric non-metric connection D satisfying $\bar{C}.\bar{S} = 0$. Using (48) in (58), we get

$$\eta(\bar{C}(X, Y)Z)\eta(W) + \eta(\bar{C}(X, Y)W)\eta(Z) = 0.$$

Using (38), (42), (44) and (58) in the above equation we obtain

$$4g(\phi U, X)\eta(Y)\eta(Z) = \frac{n+1}{n-2} \left\{ \frac{r}{2n(n-1)+1} \right\} [g(U, Y)\eta(X)\eta(Z) + g(U, Z)\eta(X)\eta(Y) - g(X, Y)\eta(U)\eta(Z) - g(X, Z)\eta(Y)\eta(U)]. \quad (59)$$

Putting $U = Y = \xi$ in (59) we get

$$g(X, Z) = \eta(X)\eta(Z).$$

Conversely,

$$\bar{C}.\bar{S} = 4g(\phi U, X)\eta(Y)\eta(Z) - \frac{n+1}{n-2} \left\{ \frac{r}{2n(n-1)+1} \right\} [g(U, Y)\eta(X)\eta(Z) + g(U, Z)\eta(X)\eta(Y) - g(X, Y)\eta(U)\eta(Z) - g(X, Z)\eta(Y)\eta(U)].$$

Putting $U = Y = \xi$ in the above equation we get

$$\bar{C}.\bar{S} = -g(X, Z) + \eta(X)\eta(Z).$$

Thus $\bar{C}.\bar{S} = 0$. ◇

7. Ricci pseudosymmetric Kenmotsu manifolds with quarter-symmetric non-metric connection D

Theorem 7.1: *A Ricci pseudosymmetric Kenmotsu manifold M with quarter-symmetric non-metric connection D with restriction $Y = W = \xi \in \chi(M)$ and $L_{\bar{S}} = -1$ is an η -Einstein manifold.*

Proof: Kenmotsu manifold M with quarter-symmetric non-metric connection D is called a Ricci pseudosymmetric Kenmotsu manifold if

$$(\bar{R}(X, Y).\bar{S})(Z, W) = L_{\bar{S}}[(X \wedge Y).\bar{S})(Z, W)], \quad (60)$$

or,

$$\begin{aligned} \bar{S}(\bar{R}(X, Y)Z, W) + \bar{S}(Z, \bar{R}(X, Y)W) \\ = L_{\bar{S}}[\bar{S}((X \wedge Y)Z, W) + \bar{S}(Z, (X \wedge Y)W)]. \end{aligned} \quad (61)$$

Putting $Y = W = \xi$, in (61) and using (2), (41) and (44), we have

$$[L_{\bar{S}} + 1][\bar{S}(Z, X) + 2ng(Z, X)] = -\bar{S}(Z, \phi X). \quad (62)$$

Then for $L_{\bar{S}} = -1$, (62) becomes

$$\bar{S}(Z, \phi X) = 0.$$

Then (36) implies that M is an η -Einstein manifold. \diamond

Corollary 7.1: If M is a Ricci semi-symmetric α -Sasakian manifold with quarter-symmetric non-metric connection D with restriction $Y = W = \xi$, then $\bar{S}(Z, X) + 2ng(Z, X) + \bar{S}(Z, \phi X) = 0$.

Proof: Since M is a Ricci semi-symmetric Kenmotsu manifold with quarter-symmetric non-metric connection D , then $L_{\bar{C}} = 0$. Putting $L_{\bar{C}} = 0$ in (62) we get $\bar{S}(Z, X) + 2ng(Z, X) + \bar{S}(Z, \phi X) = 0$. \diamond

8. Pseudosymmetric Kenmotsu manifold and Weyl- pseudosymmetric Kenmotsu manifold with quarter-symmetric non-metric connection

In the present section we shall give the definition of pseudosymmetric Kenmotsu manifold and Weyl-pseudosymmetric Kenmotsu manifold with quarter-symmetric non-metric connection and discuss some of there properties.

Definition 8.1: A Kenmotsu manifold M with quarter-symmetric non-metric connection D is said to be pseudosymmetric Kenmotsu manifold with quarter-symmetric non-metric connection if the curvature tensor \bar{R} of M with respect to D satisfies the conditions

$$(\bar{R}(X, Y) \circ \bar{R})(U, V, W) = L_{\bar{R}}[(X \wedge Y) \circ \bar{R})(U, V, W)], \quad (63)$$

where $(\bar{R}(X, Y) \circ \bar{R})(U, V, W) = \bar{R}(X, Y)(\bar{R}(U, V)W)$

$$-\bar{R}(\bar{R}(X, Y)U, V)W - \bar{R}(U, \bar{R}(X, Y)V)W - \bar{R}(U, V)(R(X, Y)W), \quad (64)$$

and $((X \wedge Y) \circ \bar{R})(U, V, W) = (X \wedge Y)(\bar{R}(U, V)W)$

$$-\bar{R}((X \wedge Y)U, V)W - \bar{R}(U, (X \wedge Y)V)W - \bar{R}(U, V)((X \wedge Y)W). \quad (65)$$

Definition 8.2: A Kenmotsu manifold M with quarter-symmetric non-metric connection D is said to be Weyl-pseudosymmetric Kenmotsu manifold with quarter-symmetric non-metric connection if the curvature tensor \bar{R} of M with respect to D satisfies the conditions

$$(\bar{R}(X, Y) \circ \bar{C})(U, V, W) = L_{\bar{C}}[(X \wedge Y) \circ \bar{C})(U, V, W)], \quad (66)$$

where $(\bar{R}(X, Y) \circ \bar{C})(U, V, W) = \bar{R}(X, Y)(\bar{C}(U, V)W)$

$$-\bar{C}(\bar{R}(X, Y)U, V)W - \bar{C}(U, \bar{R}(X, Y)V)W - \bar{C}(U, V)(R(X, Y)W), \quad (67)$$

and $((X \wedge Y) \circ \bar{C})(U, V, W) = (X \wedge Y)(\bar{C}(U, V)W)$

$$-\bar{C}((X \wedge Y)U, V)W - \bar{C}(U, (X \wedge Y)V)W - \bar{C}(U, V)((X \wedge Y)W). \quad (68)$$

Theorem 8.1: *Let M be a Kenmotsu manifold. If M is Weyl-pseudosymmetric with the connection D then M is either conformally flat and η -Einstein manifold or $L_{\bar{C}} = -1$.*

Proof: Let M be a Weyl-pseudosymmetric Kenmotsu manifold and $X, Y, U, V, W \in \chi(M)$. Then using (67) and (68) in (66), we have

$$\begin{aligned} & \bar{R}(X, Y)(\bar{C}(U, V)W) - \bar{C}(\bar{R}(X, Y)U, V)W \\ & - \bar{C}(U, \bar{R}(X, Y)V)W - \bar{C}(U, V)(R(X, Y)W) \\ & = L_{\bar{C}}[(X \wedge Y)(\bar{C}(U, V)W) - \bar{C}((X \wedge Y)U, V)W \\ & \quad - \bar{C}(U, (X \wedge Y)V)W - \bar{C}(U, V)((X \wedge Y)W)]. \end{aligned} \quad (69)$$

Replacing X with ξ in (69) we obtain

$$\begin{aligned} & \bar{R}(\xi, Y)(\bar{C}(U, V)W) - \bar{C}(\bar{R}(\xi, Y)U, V)W \\ & - \bar{C}(U, \bar{R}(\xi, Y)V)W - \bar{C}(U, V)(R(\xi, Y)W) \\ & = L_{\bar{C}}[(\xi \wedge Y)(\bar{C}(U, V)W) - \bar{C}((\xi \wedge Y)U, V)W \\ & \quad - \bar{C}(U, (\xi \wedge Y)V)W - \bar{C}(U, V)((\xi \wedge Y)W)]. \end{aligned} \quad (70)$$

Using (2), (41) in (70) and taking the inner product of (70) with ξ , we get

$$\begin{aligned} & -\bar{C}(U, V, W, Y) + \eta(\bar{C}(U, V)W)\eta(Y) - g(Y, U)\eta(\bar{C}(\xi, V)W) \\ & + \eta(U)\eta(\bar{C}(Y, V)W) - g(Y, V)\eta(\bar{C}(U, \xi)W) + \eta(V)\eta(\bar{C}(U, Y)W) \\ & + \eta(W)\eta(\bar{C}(U, V)Y) + \eta(U)\eta(\bar{C}(\phi Y, V)W) + \eta(V)\eta(\bar{C}(U, \phi Y)W) \\ & + \eta(W)\eta(\bar{C}(U, V)\phi Y) - g(Y, W)\eta(\bar{C}(U, V)\xi) \\ & = L_{\bar{C}}[\bar{C}(U, V, W, Y) - \eta(Y)\eta(\bar{C}(U, V)W) + g(Y, U)\eta(\bar{C}(\xi, V)W) - \\ & \eta(U)\eta(\bar{C}(Y, V)W) + g(Y, V)\eta(\bar{C}(U, \xi)W) - \eta(V)\eta(\bar{C}(U, Y)W) - \eta(W)\eta(\bar{C}(U, V)Y) + \\ & g(Y, W)\eta(\bar{C}(U, V)\xi)]. \end{aligned}$$

Then putting $Y = U = \xi$, we get

$$[L_{\bar{C}} + 1]\eta(\bar{C}(\xi, V)W) = 0. \quad (71)$$

Now (71) gives either $\eta(\bar{C}(\xi, V)W) = 0$ or $L_{\bar{C}} = -1$.

Now $L_{\bar{C}} \neq -1$, then $\eta(\bar{C}(\xi, V)W) = 0$, and we have that M is conformally flat which gives

$$\bar{S}(V, W) = Ag(V, W) + B\eta(V)\eta(W),$$

where $A = n + 2 + \frac{\bar{r}}{n-1}$

and $B = -[3n + 2 + \frac{\bar{r}}{n-1}]$.

This shows that M is an η -Einstein manifold.

If $\eta(\bar{C}(\xi, V)W) \neq 0$, then we have $L_{\bar{C}} = -1$. ◇

Theorem 8.2: *Let M be a Kenmotsu manifold. If M is pseudosymmetric then either M is a space of constant curvature and $g(X, Y) = \eta(X)\eta(Y)$ or*

$L_{\bar{R}} = -1$, for $X, Y \in \chi(M)$.

Proof: Let M be a pseudosymmetric Kenmotsu manifold and $X, Y, U, V, W \in \chi(M)$. Then using (64) and (65) in (63), we have

$$\begin{aligned} & \bar{R}(X, Y)(\bar{R}(U, V)W) - \bar{R}(\bar{R}(X, Y)U, V)W \\ & - \bar{R}(U, \bar{R}(X, Y)V)W - \bar{R}(U, V)(\bar{R}(X, Y)W) \\ & = L_{\bar{R}}[(X \wedge Y)(\bar{R}(U, V)W) - \bar{R}((X \wedge Y)U, V)W \\ & \quad - \bar{R}(U, (X \wedge Y)V)W - \bar{R}(U, V)((X \wedge Y)W)]. \end{aligned} \quad (72)$$

Replacing X with ξ in (72) we obtain

$$\begin{aligned} & \bar{R}(\xi, Y)(\bar{R}(U, V)W) - \bar{R}(\bar{R}(\xi, Y)U, V)W \\ & - \bar{R}(U, \bar{R}(\xi, Y)V)W - \bar{R}(U, V)(\bar{R}(\xi, Y)W) \\ & = L_{\bar{R}}[(\xi \wedge Y)(\bar{R}(U, V)W) - \bar{R}((\xi \wedge Y)U, V)W \\ & \quad - \bar{R}(U, (\xi \wedge Y)V)W - \bar{R}(U, V)((\xi \wedge Y)W)]. \end{aligned} \quad (73)$$

Using (2), (41) in (70) and taking the inner product of (73) with ξ , we get

$$\begin{aligned} & -\bar{R}(U, V, W, Y) + \eta(\bar{R}(U, V)W)\eta(Y) - g(Y, U)\eta(\bar{R}(\xi, V)W) \\ & + \eta(U)\eta(\bar{R}(Y, V)W) - g(Y, V)\eta(\bar{R}(U, \xi)W) + \eta(V)\eta(\bar{R}(U, Y)W) \\ & + \eta(W)\eta(\bar{R}(U, V)Y) + \eta(U)\eta(\bar{R}(\phi Y, V)W) + \eta(V)\eta(\bar{R}(U, \phi Y)W) \\ & + \eta(W)\eta(\bar{R}(U, V)\phi Y) - g(Y, W)\eta(\bar{R}(U, V)\xi) \\ & = L_{\bar{R}}[\bar{R}(U, V, W, Y) - \eta(Y)\eta(\bar{R}(U, V)W) + g(Y, U)\eta(\bar{R}(\xi, V)W) \\ & - \eta(U)\eta(\bar{R}(Y, V)W) + g(Y, V)\eta(\bar{R}(U, \xi)W) - \eta(V)\eta(\bar{R}(U, Y)W) \\ & - \eta(W)\eta(\bar{R}(U, V)Y) + g(Y, W)\eta(\bar{R}(U, V)\xi)]. \end{aligned}$$

Then putting $Y = U = \xi$, we get

$$[L_{\bar{C}} + 1]\eta(\bar{R}(\xi, V)W) = 0. \quad (74)$$

Now (71) gives either $\eta(\bar{R}(\xi, V)W) = 0$ or $L_{\bar{R}} = -1$.

Now $L_{\bar{R}} \neq -1$, then $\eta(\bar{R}(\xi, V)W) = 0$, and we have that M is a space of constant curvature and $\eta(\bar{R}(\xi, V)W) = 0$ gives

$$g(V, W) = \eta(V)\eta(W).$$

If $\eta(\bar{R}(\xi, V)W) \neq 0$, then we have $L_{\bar{R}} = -1$. \diamond

9. Example of pseudosymmetric Kenmotsu manifold with quarter-symmetric non-metric connection D

Let us consider the three dimensional manifold $M = \{(x_1, x_2, x_3) \in R^3 : x_1, x_2, x_3 \in R\}$, where (x_1, x_2, x_3) are the standard coordinates of R^3 . We consider the vector fields

$$e_1 = x_1 \frac{\partial}{\partial x_3}, e_2 = x_1 \frac{\partial}{\partial x_2} \text{ and } e_3 = -x_1 \frac{\partial}{\partial x_1}.$$

Clearly, $\{e_1, e_2, e_3\}$ is a set of linearly independent vectors for each point of M and hence a basis of M . The non-metric g is defined by

$$g(e_1, e_2) = g(e_2, e_3) = g(e_1, e_3) = 0,$$

$$g(e_1, e_1) = g(e_2, e_2) = g(e_3, e_3) = 1.$$

Let η be the 1-form defined by $\eta(Z) = g(Z, e_3)$, for any $Z \in \chi(M)$ and the $(1, 1)$ - tensor field ϕ is defined by

$$\phi e_1 = e_2, \phi e_2 = -e_1, \phi e_3 = 0.$$

From the linearity of ϕ and g , we have

$$\eta(e_3) = 1,$$

$$\phi^2(X) = -X + \eta(X)e_3 \text{ and}$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \text{ for any } X \in \chi(M).$$

Then for $e_3 = \xi$, the structure (ϕ, ξ, η, g) defines an almost contact metric structure on M .

Let ∇ be the Levi-Civita connection with respect to the metric g . Then we have

$$[e_1, e_2] = 0, [e_1, e_3] = e_1, [e_2, e_3] = e_2.$$

Koszul's formula is defined by

$$2g(\nabla_X Y, Z) = Xg(Y, Z) + Yg(Z, X) - Zg(X, Y)$$

$$-g(X, [Y, Z]) - g(Y, [X, Z]) + g(Z, [X, Y]).$$

Then from the above formula we can calculate the following,

$$\begin{aligned} \nabla_{e_1} e_1 &= -e_3, & \nabla_{e_1} e_2 &= 0, & \nabla_{e_1} e_3 &= e_1, \\ \nabla_{e_2} e_1 &= 0, & \nabla_{e_2} e_2 &= -e_3, & \nabla_{e_2} e_3 &= e_2, \\ \nabla_{e_3} e_1 &= 0, & \nabla_{e_3} e_2 &= 0, & \nabla_{e_3} e_3 &= 0. \end{aligned}$$

Hence the structure (ϕ, ξ, η, g) is a Kenmotsu manifold. [8]

Using (22), we find D , the quarter-symmetric non-metric connection on M

$$\begin{aligned} D_{e_1} e_1 &= -e_3, & D_{e_1} e_2 &= 0, & D_{e_1} e_3 &= e_1 + e_2, \\ D_{e_2} e_1 &= 0, & D_{e_2} e_2 &= -e_3, & D_{e_2} e_3 &= e_2 - e_1, \\ D_{e_3} e_1 &= 0, & D_{e_3} e_2 &= 0, & D_{e_3} e_3 &= 0. \end{aligned}$$

Using (23), the torsion tensor \bar{T} , with respect to quarter-symmetric non-metric connection D as follows:

$$\bar{T}(e_i, e_i) = 0, \forall i = 1, 2, 3$$

$$\bar{T}(e_1, e_2) = 0, \bar{T}(e_1, e_3) = e_2, \bar{T}(e_2, e_3) = -e_1.$$

Also $(D_{e_1} g)(e_2, e_3) = -1, (D_{e_2} g)(e_3, e_1) = 1$
and $(D_{e_3} g)(e_1, e_2) = 0$.

Thus M is a 3-dimensional Kenmotsu manifold with quarter-symmetric non-metric connection D .

Now we calculate curvature tensor \bar{R} and Ricci tensors \bar{S} as follows:

$$\begin{aligned} \bar{R}(e_1, e_2)e_3 &= 0, & \bar{R}(e_1, e_3)e_3 &= -(e_1 + e_2), \\ \bar{R}(e_3, e_2)e_2 &= -e_3, & \bar{R}(e_3, e_1)e_1 &= -e_3, \\ \bar{R}(e_2, e_1)e_1 &= e_1 - e_2, & \bar{R}(e_2, e_3)e_3 &= e_1 - e_2, \\ \bar{R}(e_1, e_2)e_2 &= -(e_1 + e_2). \end{aligned}$$

From the definition of \bar{S} , $\bar{S}(X, Y) = \sum_i g(\bar{R}(e_i, X)Y, e_i)$, $i = 1, 2, 3$, we get
 $\bar{S}(e_1, e_1) = \bar{S}(e_2, e_2) = \bar{S}(e_3, e_3) = -2, \bar{S}(e_1, e_2) = 1,$

$$\bar{S}(e_1, e_3) = \bar{S}(e_2, e_3) = 0.$$

Again using (2) we get

$$\begin{aligned} (e_1, e_2)e_3 = 0, \quad (e_i \wedge e_i)e_j = 0, \quad \forall i, j = 1, 2, 3, \\ (e_1 \wedge e_2)e_2 = (e_1 \wedge e_3)e_3 = e_1, \quad (e_2 \wedge e_1)e_1 = (e_2 \wedge e_3)e_3 = e_2, \\ (e_3 \wedge e_2)e_2 = (e_3 \wedge e_1)e_1 = e_3. \end{aligned}$$

$$\begin{aligned} \text{Now } \bar{R}(e_1, e_2)(\bar{R}(e_3, e_1)e_2) = 0, \quad \bar{R}(\bar{R}(e_1, e_2)e_3, e_1)e_2 = 0, \\ \bar{R}(e_3, \bar{R}(e_1, e_2)e_1)e_2 = -e_3, \\ (\bar{R}(e_3, e_1)(\bar{R}(e_1, e_2)e_2) = e_3. \\ \text{Then } (\bar{R}(e_1, e_2).\bar{R})(e_3, e_1, e_2) = 0. \end{aligned}$$

$$\begin{aligned} \text{Again } (e_1 \wedge e_2)(\bar{R}(e_3, e_1)e_2) = 0, \quad \bar{R}((e_1 \wedge e_2)e_3, e_1)e_2 = 0, \\ \bar{R}(e_3, (e_1 \wedge e_2)e_1)e_2 = e_3, \\ \bar{R}(e_3, e_1)((e_1 \wedge e_2)e_2) = -e_3. \\ \text{Then } ((e_1, e_2).\bar{R})(e_3, e_1, e_2) = 0. \end{aligned}$$

Thus

$$(\bar{R}(e_1, e_2).\bar{R})(e_3, e_1, e_2) = L_{\bar{R}}[(e_1, e_2).\bar{R})(e_3, e_1, e_2)],$$

for any function $L_{\bar{R}} \in C^\infty(M)$.

Similarly, we can show any combination of e_1, e_2 and e_3 (60).

Hence M is a pseudosymmetric Kenmotsu manifold with quarter-symmetric non-metric connection.

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