

TQFT's and gerbes

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Abstract We generalize the notion of parallel transport along paths for abelian bundles to parallel transport along surfaces for abelian gerbes using an embedded Topological Quantum Field Theory (TQFT) approach. We show both for bundles and gerbes with connection that there is a one-to-one correspondence between their local description in terms of locally-defined functions and forms and their non-local description in terms of a suitable class of embedded TQFT's.

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1 Introduction

Gerbes can be regarded as a higher-order version of the geometry of bundles. They originally appeared in the context of algebraic geometry in a paper by Giraud [14], and the concept was further developed in Brylinski's book [9]. Interest in gerbes has been revived recently following a concrete approach due to Hitchin and Chatterjee [15]. Gerbes can be understood both in terms of local geometry, local functions and forms, and in terms of non-local geometry, holonomies and parallel transports, and these two viewpoints are equivalent, in a sense made precise by Mackaay and the author in [16], following on from work by Barrett [5] and Caetano and the author [11]. In [16] holonomies around spheres and parallel transports along cylinders were considered. The aim of the present article is to describe the generalization to parallel transports along general surfaces with boundary.

The conceptual framework for this generalization is Topological Quantum Field Theory (TQFT), a notion introduced by Witten [26], which was subsequently axiomatized by Atiyah [1], in a very similar manner to Segal's axiomatic approach to Conformal Field Theory [21]. The manifolds involved in the TQFT now come equipped with maps to a target manifold on which the bundle or

gerbe lives. This brings us into the realm of Segal's category \mathcal{C} [23] and string connection [22], as well as Turaev's Homotopy Quantum Field Theory (HQFT) [24] and a related construction by Brightwell and Turner [8], as well as subsequent developments by Rodrigues [19], Bunke, Turner and Willerton [10] and Turner [25]. Here we will base our approach on a general framework for TQFT and related constructions by Semiao and the author [18], which defines a TQFT to be a certain type of monoidal functor, without using the cobordism approach.

There are a number of interesting connections between the present work and an early approach by Gawedzki [12], further developed by Gawedzki and Reis in [13]. In particular equivalent formulae to equations (3) and (9) for the bundle and gerbe parallel transport appear.

The article is organized as follows. In section 2 we describe some general preliminaries. In section 3 we define rank-1, embedded, 1-dimensional TQFT's, show how they can arise from bundles with connection and prove the equivalence of bundles with connection and a class of these TQFT's. In section 4 we outline the corresponding procedure for gerbes and rank-1, embedded, 2-dimensional TQFT's. Section 5 contains some comments.

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2 Preliminaries

Let us consider smooth, oriented manifolds B of dimension $d \geq 3$, with or without boundary, partitioned into d -dimensional regions by a finite, embedded

$(d+1)$ -valent $(d-1)$ -graph. Here a 0-graph is a collection of points, a 1-graph is a graph, and a 2-graph has smoothly embedded surfaces incident at each vertex. The valency is the number of d -dimensional regions in the neighbourhood of each vertex. Such partitions can be obtained from triangulations of the manifold by dualizing. When the manifold has a boundary, the partition of the manifold should restrict to a partition of the boundary.

Let M be a fixed smooth real manifold of finite dimension, called the target manifold, with an open cover $U = \cup_{j \in J} U_j$ such that every non-empty p -fold intersection $U_{i_1, \dots, i_p} = U_{i_1} \cap \dots \cap U_{i_p}$, for any p , is contractible. The objects we will be working with are of the form

$$(Y; T);$$

where Y is a smooth map from B to M , satisfying a "constant at the boundary" condition, to be described later, and T is a labelled partition of B , such that each region of the partition is labelled by an open set of M containing its image under Y . Morphisms between two such objects $(Y; T)$ and $(Y^\theta; T^\theta)$ are smooth, orientation-preserving maps $f: B \rightarrow B^\theta$, such that $Y = Y^\theta \circ f$, with no requirements on T or T^θ . There is a natural monoidal structure in this category, which, on objects, is given by:

$$(Y; T) \times (Y^\theta; T^\theta) = (Y \times Y^\theta; T \times T^\theta);$$

where $Y \times Y^\theta$ is the disjoint union of Y and Y^θ from $B \times B^\theta$ to M , and $T \times T^\theta$ is the obvious labelled partition of $B \times B^\theta$ obtained from T and T^θ .

Our approach in this article is based on a general framework for TQFT and related constructions, which is the subject of [18]. Since we are working in a very specific context here, and a number of features simplify, it is unnecessary to develop the full formalism, so we will just sketch the general approach to provide some background. The topological category has as its objects essentially pairs consisting of e.g. an oriented manifold and its boundary. The boundaries, called subobjects, together with isomorphisms between them, form a category themselves. The morphisms of the topological category are of two types only, namely isomorphisms and gluing morphisms, where the latter are, roughly speaking, morphisms from an object before gluing along one or more boundary components to the object which results after gluing. The topological category is endowed with a monoidal structure (disjoint union) and an endofunctor (change of orientation). Note that the topological category is not set up in the cobordism framework - we refer to the introduction of [18] for the reasons for preferring an approach closer to Atiyah's original paper [1]. A TQFT is a functor from the topological category to an algebraic category whose objects are

e.g. pairs consisting of a finite-dimensional vector space over \mathbb{C} and an element of that space. The topological subobject determines the vector space, and the manifold of which it is the boundary determines the element. The algebraic category is endowed with a manifold structure (tensor product) and an endofunctor (passing to the vector space with conjugate scalar multiplication), and the TQFT functor respects these structures in a suitable sense. At the level of morphisms the TQFT sends the isomorphisms between subobjects to certain "unitary" algebraic morphisms, namely linear transformations preserving so-called evaluations (resembling inner products). When an isomorphism extends to an isomorphism of topological objects the corresponding linear transformation preserves the elements of the vector spaces involved. Likewise the TQFT functor sends topological gluing morphisms to specific algebraic morphisms involving the evaluations, which again preserve the elements. The requirement that these algebraic morphisms preserve elements implies a set of equations for the elements, which have to be solved for the TQFT functor to exist. In the next sections we will be describing bundle and gerbe parallel transport via operational definitions based on this general TQFT framework.

3 Embedded TQFT's and bundles

We will concentrate, for the time being, on 0 and 1-dimensional objects, as described in the previous section. We will call the 0-dimensional objects subobjects, and write irreducible subobjects as

$$(y; I);$$

where y denotes the map from the positively or negatively oriented point to M , whose image is $y \in M$, and I labels an open set of M containing y . General subobjects are finite disjoint unions of irreducible subobjects. An irreducible 1-dimensional object is of the form

$$(p; T);$$

where $p: [a; b] \rightarrow M$ is a smooth path, constant in $[a; a + \epsilon]$ and $[b - \epsilon; b]$, for some $\epsilon > 0$, and T is given by a set of points $a = x_0 < x_1 < \dots < x_N = b$, with a labelling of $e = [x_{i-1}; x_i]$ by $i \in J$, such that $p(e) \subset U_i$ (see Figure 1). The interval $[a; b]$ is taken to be oriented in the direction from a to b and the boundary subobject of $(p; T)$ is $(p(a)^-; i_1) \# (p(b)^+; i_N)$.

As discussed at the end of the previous section there are three types of morphism which enter the description of the topological category: isomorphisms

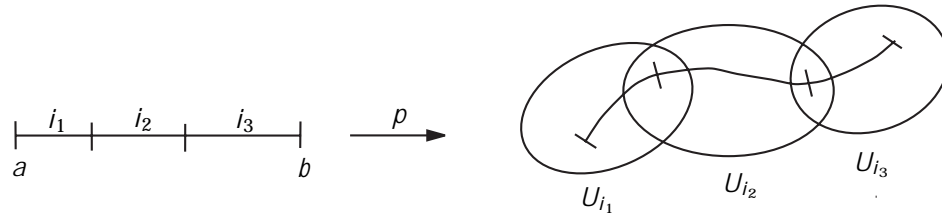


Figure 1: A path $(p; T)$

between subobjects, isomorphisms between objects and gluing morphisms between objects. For the present situation, isomorphisms between (irreducible) subobjects are described by

$$(y; i) \stackrel{j}{\sim} (y; j)$$

which will be denoted

$$(y; i; j):$$

Isomorphisms and gluing morphisms between objects are generated (via composition and disjoint union) by basic isomorphisms

$$(p; T) \stackrel{f}{\sim} (p^\theta; T^\theta);$$

where $f: [a; b] \xrightarrow{\sim} [a^\theta; b^\theta]$ is an orientation-preserving diffeomorphism, and basic gluing morphisms

$$(p; T) \stackrel{t}{\sim} (p^\theta; T^\theta) \stackrel{f}{\sim} (p; p^\theta; T; T^\theta)$$

where $f: [a; b] \xrightarrow{\sim} [a^\theta; b^\theta]$ is defined by $f(x) = x$ on both $[a; b]$ and $[b; c]$, $p; p^\theta$ is given by $(p; p^\theta)(x) = p(x)$ for $x \in [a; b]$ and $(p; p^\theta)(x) = p^\theta(x)$ for $x \in [b; c]$, and $T; T^\theta$ is the natural labelled partition of $[a; c]$ obtained from T and T^θ . Note that, for this morphism to exist, we must have $p(b) = p^\theta(b)$, since $f(b) = b$ for b in either interval. Also note that $p; p^\theta$ is smooth because of the constant condition at the endpoints of the paths. This method of handling products of smooth loops and paths was introduced in [11].

Remark 3.1 The subobjects $f(y; i)g_{y2M; i2J}$ and the isomorphisms between them form a category, which we will call M_U^0 , where U denotes the cover $fU_i g_{i2J}$ and the superscript indicates the dimension of the subobjects. This category is similar to the category X_U introduced by Segal in [20] for a cover $U = fU_i g_{i2J}$ of a space X by subsets of X . In X_U the objects are of the form $(y; U)$ where y is a finite subset of J , U denotes $\bigcap_{i \in y} U_i$ and $y \in U$.

The orientation of points is disregarded in X_U . The morphisms of X_U may be characterized as follows: for every inclusion $y \subset U$ and for every $y \subset U$, there is a unique morphism, which we will denote $(y; \cdot)$, from $(y; U)$ to $(y; U)$. Shortly we will return to a comparison of M_U^0 and X_U in the context of bundles.

The full definition of a TQFT functor in [18] can be replaced here by a considerably reduced operational definition, since in the present situation we are able to make a number of simplifying choices. We take all vector spaces in the algebraic category to be of dimension 1, which allows the "unitary" algebraic morphisms corresponding to topological isomorphisms of subobjects to be replaced by complex numbers of norm 1. Likewise we need only write down the equations which arise from applying the TQFT functor to basic isomorphisms and gluing morphisms, omitting equations relating to the monoidal structure (disjoint union, empty set), which are understood. The elements of the 1-dimensional vector spaces corresponding to topological objects $(p; T)$ may again be identified with complex numbers of norm 1. Thus we are led to the following definition.

Definition 3.2 A rank-1, embedded, 1-dimensional TQFT is a pair of assignments $(Z^0; Z)$

$$\begin{aligned} (y; i; j) &\mapsto Z^0(y; i; j) \in U(1) \\ (p; T) &\mapsto Z(p; T) \in U(1) \end{aligned}$$

such that

- i) for isomorphisms between subobjects

$$Z^0(y; i; j)Z^0(y; j; k) = Z^0(y; i; k);$$

- ii) for basic isomorphisms $(p; T) \xrightarrow{f} (p^0; T^0)$

$$Z(p^0; T^0) = Z^0(p(a)^-; i_1; i_1^0)Z(p; T)Z^0(p(b)^+; i_N; i_N^0);$$

- iii) for basic gluing morphisms $(p; T) \xrightarrow{t} (p \cup p^0; T \cup T^0)$

$$Z(p \cup p^0; T \cup T^0) = Z(p; T)Z^0(p(b)^+; i_N; i_1^0)Z(p^0; T^0);$$

The terminology rank-1 is the same as that used for Homotopy Quantum Field Theories in [10]. We remark that an analogous definition can be given of rank- n embedded TQFT's by replacing $U(1)$ by $U(n)$. We will comment on this in section 5. Next we state some simple properties of TQFT's which will be needed later on.

Proposition 3.3 For a rank-1, embedded, 1-dimensional TQFT $(Z^0; Z)$ the following properties hold:

- a) $Z^0(y; i; \emptyset) = 1$,
- b) for any interval $[a; b]$,

$$Z(t_{y[a;b]}; i) = 1$$

where $t_{y[a;b]}$ denotes the constant map from $[a; b]$ to y , and i denotes the labelled partition which assigns i to the whole interval $[a; b]$,

- c) $Z(t_y; ij) = Z^0(y^+; i; j)$, where t_y denotes the constant map from the standard interval $[0; 1]$ to y , and ij is the labelled partition which labels $[0; 1-2]$ with i and $[1-2; 1]$ with j ,
- d) $Z^0(y^-; i; j) = Z^0(y^+; i; j)^{-1}$.

Proof a) is obvious, from i) of Definition 3.2. To show b) we first use ii) applied to an obvious isomorphism to obtain

$$Z(t_{y[a;b]}; i) = Z(t_{y[c;d]}; i)$$

for any intervals $[a; b]$ and $[c; d]$, and then derive

$$Z(t_{y[a;b]}; i) \stackrel{ii)}{=} Z(t_{y[a;d]} \cup t_{y[c;b]}; i \cup i) \stackrel{iii) a)}{=} Z(t_{y[a;d]}; i) Z(t_{y[c;b]}; i):$$

c) follows from applying iii) to the obvious gluing morphism from $(t_{y[0;1-2]}; i) \cup (t_{y[1-2;1]}; j)$ to $(t_y; ij)$ and using b). To show d), we apply ii) to any trivial path as follows:

$$Z(t_y; j) = Z^0(y^-; i; j) Z(t_y; i) Z^0(y^+; i; j)$$

and use b). □

Suppose we are given a $U(1)$ -bundle with connection on the target manifold M , i.e. a collection of (smooth) transition functions

$$g_{ij} : U_{ij} \rightarrow U(1)$$

and (smooth) local connection 1-forms

$$A_j \in \Omega^1(U_j);$$

satisfying

- B1) $g_{ij} g_{jk} = g_{ik}$ on U_{ijk} ,
- B2) $i(A_k - A_j) = d \log g_{jk}$ on U_{jk} .

B1) is called the cocycle condition. It implies also the equation $g_{ji} = g_{ij}^{-1}$ on U_{ij} . The curvature of this connection is the globally-defined 2-form $F \in \Omega^2(M)$, given locally by

$$F = dA_i; \tag{1}$$

Theorem 3.4 *A $U(1)$ -bundle with connection on M gives rise to a rank-1, embedded, 1-dimensional TQFT with target M via*

$$Z^0(y^+; i; j) = g_{ij}(y); \quad Z^0(y^-; i; j) = g_{ij}(y) \tag{2}$$

$$\begin{aligned} Z(\rho; T) = & \exp i \int_{x_0}^{x_1} \rho(A_{i_1}) : g_{i_1 i_2}(\rho(x_1)) : \exp i \int_{x_1}^{x_2} \rho(A_{i_2}) : g_{i_2 i_3}(\rho(x_2)) : \dots \\ & \exp i \int_{x_{N-1}}^{x_N} \rho(A_{i_N}) : \end{aligned} \tag{3}$$

Proof i) of Definition 3.2 follows immediately from the cocycle condition B1). The proof of ii) is deferred until after Lemma 3.5. iii) is immediate.

Let us now introduce the following shorthand notation for the right-hand-side of equation (3):

$$\int \exp i \int_{(\rho; T)} (g; A)$$

and an analogous notation for $(\gamma; T)$, where $\gamma : S^1 \rightarrow M$ is a closed curve, and T is a labelled partition of S^1 . We will also now introduce 2-dimensional objects $(H; T)$, where H is a smooth map from an oriented surface S with or without boundary, and T is a labelled partition of S , by means of an embedded 3-valent graph, into faces f , such that $H(f) \subset U_j$. When S has a boundary, we will denote by $(@H; @T)$ the 1-dimensional object obtained by restricting H and the labelled partition T to the oriented boundary $@S$ of S .

We now have the following useful Lemma:

Lemma 3.5 *For a 2-dimensional object $(H; T)$,*

$$\int \exp i \int_{(@H; @T)} (g; A) = \int_S \exp i \int H(F);$$

Proof We have

$$\exp i \int_{(\mathcal{H}; \mathcal{T})} (g; A) = \prod \exp i \int_{\mathcal{F}} H(A_i);$$

since the transition function contributions around the boundary may be replaced by the factors on the right-hand-side of the above equation corresponding to the internal edges of the partition, using the relation for an edge e of the partitioning graph from x to y in S , between faces labelled j and k :

$$\exp i \int_e H(A_k - A_j) = \exp \int_{\mathcal{H}} H(\log g_{jk}) = g_{jk}^{-1}(H(x))g_{jk}(H(y));$$

and the fact that the contributions of the transition functions cancel at each internal vertex because of the cocycle condition. Using equation (1) and Stokes' theorem the result follows. \square

We now complete the proof of Theorem 3.4.

Proof To show ii) of Definition 3.2, we introduce a homotopy $(H; \mathcal{F})$ from ρ to ρ^θ , whose image is contained in the shared image of ρ and ρ^θ , and such that \mathcal{F} coincides with \mathcal{T} and \mathcal{T}^θ on the top and bottom edges, and changes from i_1 to i_1^θ and from i_N to i_N^θ on the two sides (see Figure 2). It is easy to see that such a partition \mathcal{F} exists, by constructing partitions for the elementary moves of splitting an interval labelled with i into two regions labelled with i (and the inverse move), and relabelling a single interval. Applying the Lemma and using $H(F) = 0$, we get

$$g_{i_1 i_1^\theta}(\rho(a))Z(\rho; \mathcal{T})g_{i_N i_N^\theta}(\rho(b))Z^{-1}(\rho^\theta; \mathcal{T}^\theta) = 1;$$

which implies ii). Here we have used the equation

$$Z(\rho; \mathcal{T})Z(\rho^{-1}; \mathcal{T}^{-1}) = 1;$$

where $\rho^{-1} : [a; b] \rightarrow M$ is given by $\rho^{-1}(x) = \rho(a + b - x)$ and \mathcal{T}^{-1} is the corresponding inverse labelled partition, which follows from applying the Lemma to the identity homotopy from $(\rho; \mathcal{T})$ to $(\rho; \mathcal{T})$. \square

Remark 3.6 The assignment Z^θ of Theorem 3.4 defines a functor from the category M_U^0 , introduced in Remark 3.1, to $U(1)$, regarded as a 1-object category, because of equation i) of Definition 3.2. Conversely it is clear that, subject to a smoothness restriction, any such functor defines transition functions, so that we have a correspondence between smooth functors from M_U^0 to $U(1)$ and smooth bundles on M defined by transition functions g_{ij} on U_{ij} . In

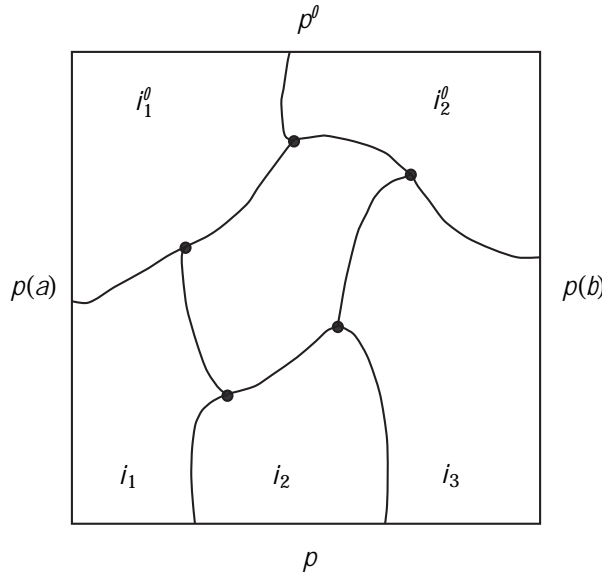


Figure 2: Proof of Theorem 3.4, part ii)

what follows we will be extending this correspondence to one between a suitable class of TQFT's as in Definition 3.2 and smooth bundles with connection. It is interesting to contrast this with Segal's functorial approach to principal bundles in [20]. A functor from the category \mathcal{X}_U (discussed in Remark 3.1) to a topological group G implies choosing transition functions on the cover U^θ of X , whose elements are all finite intersections of elements of the cover U , via $(y; \cdot) \nabla g(y) \in G$. Transition functions on the cover U are obtained by

$$g_{ij}(y) = g_{f_i g f_i; j g}(y) (g_{f_j g f_j; i g}(y))^{-1};$$

Then the statement is that (smooth) principal G -bundles over X defined with respect to the cover U correspond to equivalence classes of (smooth) functors from \mathcal{X}_U to G .

The TQFT's obtained in this way from bundles with connection satisfy two special properties.

Theorem 3.7 *The rank-1, embedded, 1-dimensional TQFT's of Theorem 3.4 satisfy*

- 1) *thin invariance: if $(p; T)$ and $(p^\theta; T^\theta)$ are such that $i_1 = i_1^\theta$, $i_N = i_N^\theta$ and there is a relative homotopy $(H; \bar{F})$ from $(p; T)$ to $(p^\theta; T^\theta)$ satisfying*

rank $DH = 1$ (a so-called *thin homotopy* - see [11, 16]), then

$$Z(p; T) = Z(p^\theta; T^\theta);$$

- 2) *smoothness*: for any smooth k -dimensional family of objects $(p(u); T(u))$, $u \in U \subset \mathbb{R}^k$, $Z(p(u); T(u))$ depends smoothly on u .

Proof 1) follows directly from the Lemma, noting that $H(F) = 0$, since rank $DH = 1$. 2) follows from the fact that the formula for $Z(p; T)$ is smooth, since it involves smooth functions and integrals. \square

We remark that, as pointed out by Bunke et al [10], the thin invariance also holds if one replaces the homotopy H by a cobordism which is thin in the same sense as above.

The properties of the previous theorem in fact characterize the TQFT's obtained from bundles with connection, because of the following theorem.

Theorem 3.8 *There is a one-to-one correspondence between bundles with connection on M and smooth, thin invariant, rank-1, embedded, 1-dimensional TQFT's with target M .*

Proof We have already seen the correspondence in one direction (Theorem 3.4 and Theorem 3.7). Suppose we are given an embedded TQFT with the stated properties. We may reconstruct a bundle with connection on M as follows.

$$g_{ij}(y) = Z(t_y; ij) \tag{4}$$

where t_y is the trivial, constant path from $[0; 1]$ to $y \in M$, and ij is the labelled partition which labels $[0; 1=2]$ with i and $[1=2; 1]$ with j .

$$i(A_j)_y(v) = \frac{d}{dt} \log Z(q_t; j) \Big|_{t=0} \tag{5}$$

where we take a path $q : (-;) \rightarrow U_i$ such that $q(0) = y; q(1) = v$, and set q_t to be a path from y to $q(t)$ along q , reparametrized to be constant at the endpoints. Furthermore j denotes the labelled partition assigning j to the whole domain of q_t .

To show that A_j is well-defined, we note first that, given a choice of q , the definition does not depend on the choice of q_t , because of the fact that the different choices are all thin equivalent, and using the thin invariance of Z . Thus it remains to show that the definition does not depend on the choice of q . We use the fact that M is a manifold, i.e. locally diffeomorphic to an

open neighbourhood of the origin in \mathbb{R}^d , to fix a smooth family of radial paths, denoted r_x , from any point x in a sufficiently small neighbourhood of y to y (reparametrized to be constant at the endpoints). Now

$$\frac{d}{dt} \log Z(q_t; j)_{j_{t=0}} = -\frac{d}{dt} \log Z(r_{q(t)}; j)_{j_{t=0}} \tag{6}$$

since

$$\frac{d}{dt} \log Z(q_t - r_{q(t)}; j)_{j_{t=0}} = 0;$$

where we use Barrett’s lemma [5] (see also [11, 16]) stating that the trivial loop is a critical point for any holonomy. Note that $Z(\cdot; j)$ restricted to loops based at y contained in U_j satisfies the conditions to be a holonomy in the sense of Barrett’s lemma, because of the thin invariance and smoothness of Z (Theorem 3.7). Now the right-hand-side of equation (6) is equal to $(dh)_y(v)$, where h is a smooth function defined in a neighbourhood of y by $h(x) = \log Z(r_x; j)$, and thus is independent of the choice of q with $q(0) = v$.

Now property B1) for the transition functions (4) is immediate, using Proposition 3.3 c) and i) of Definition 3.2. To show B2) consider $\gamma : (-\epsilon; \epsilon) \rightarrow \mathbb{R}$ defined by

$$\gamma(t) = \log Z(q_t - q_t^{-1}; j - k);$$

By the thin invariance of Z , γ is constant, since there are natural thin homotopies between the arguments of Z for different values of t . Thus

$$\begin{aligned} 0 &\stackrel{ii)}{=} \frac{d}{dt} \log Z(q_t; j) + \log Z^0(q(t); j - k) + \log Z(q_t^{-1}; k) \Big|_{j_{t=0}} \\ &= i(A_j)_y(v) + (d \log g_{j-k})_y(v) - i(A_k)_y(v); \end{aligned}$$

which proves B2).

Finally we show the correspondence is one-to-one. Let $(g_{ij}; A_j)_{i,j \in 2J}$ be a bundle with connection, and let $(Z^0; Z)$ be the TQFT which arises from it (Theorem 3.4). Now take $(\tilde{g}_{ij}; \tilde{A}_j)_{i,j \in 2J}$ to be the bundle and connection reconstructed from $(Z^0; Z)$ via equations (4) and (5). We have

$$g_{ij}(y) = Z(t_y; ij) = Z^0(y^+; i; j) = \tilde{g}_{ij}(y)$$

using Proposition 3.3 c) in the second equality, and

$$\begin{aligned} i(A_j)_y(v) &= \frac{d}{dt} \log Z(q_t; j)_{j_{t=0}} = i \frac{d}{dt} \Big|_0^{Z^{-1}} q_t(A_j)_{j_{t=0}} \\ &= i \frac{d}{dt} \Big|_0^{Z^{-1}} q(A_j)_{j_{t=0}} = i(A_j)_y(v) \end{aligned}$$

where, in the first equality, we choose $q_t : [0; 1] \rightarrow M$ defined by $q_t(s) = q(st)$, reparametrized to be constant at the endpoints, in the second equality we use

equation (3), and, in the third equality, we use the reparametrization invariance of the integral and make a substitution.

Conversely, let $(Z^0; Z)$ be a TQFT, as specified, and let $(g_{ij}; A_j)_{i,j \in 2J}$ be the bundle with connection reconstructed from it. Now take $(Z^0; Z)$ to be the TQFT that this bundle with connection gives rise to (Theorem 3.4). We have

$$\bar{Z}^0(y^+; i; j) = g_{ij}(y) = Z(ty; ij) = Z^0(y^+; i; j)$$

and

$$\bar{Z}^0(y^-; i; j) = \bar{Z}^0(y^+; i; j)^{-1} = Z^0(y^+; i; j)^{-1} = Z^0(y^-; i; j);$$

using Proposition 3.3 c), d) and

$$\begin{aligned} Z(\rho; T) &= \exp i \int_{x_0}^{x_1} \rho(A_{i_1}) : g_{i_1 i_2}(\rho(x_1)) : \exp i \int_{x_1}^{x_2} \rho(A_{i_2}) : g_{i_2 i_3}(\rho(x_2)) : \dots \\ &= Z(\rho_1; i_1) Z^0(\rho(x_1)^+; i_1; i_2) Z(\rho_2; i_2) \dots \\ &= Z(\rho; T) \end{aligned}$$

where, in the second equality, we have written $(\rho; T) = (\rho_1; i_1) (\rho_2; i_2) \dots$, and used Proposition 3.3 c), together with a calculation below, and in the third equality, we have used iii) of Definition 3.2. The calculation required is:

$$\exp i \int_a^b \rho(A_j) = Z(\rho; j) \tag{7}$$

for a path $\rho : [a; b] \rightarrow M$, which is shown as follows. First we have

$$\begin{aligned} i \int \rho(A_j) &= \int i(A_j)_{\rho(x)}(\rho(x)) dx \\ &= \frac{d}{dt} \log Z(q_t; j) \Big|_{t=0} dx \\ &= \frac{d}{dx} \log Z(\rho_x; j) dx \end{aligned}$$

where, in the second equality, we have introduced $q : (-;) \rightarrow M$, defined by $q(s) = \rho(x + s)$, and $q_t : [0; 1] \rightarrow M$ given by $q_t(s) = q(ts)$, reparametrized to be constant at the endpoints, and in the third equality, we have introduced $\rho_x : [0; 1] \rightarrow M$, defined by $\rho_x(s) = \rho(a + s(x - a))$, reparametrized to be constant at the endpoints, and used the relation

$$\begin{aligned} \log Z(q_t; j) &= \log Z(\rho_x - q_t; j) - \log Z(\rho_x; j) \\ &= \log Z(\rho_{x+t}; j) - \log Z(\rho_x; j) \end{aligned}$$

in the limit $t \rightarrow 0$, where the first equality follows from iii) of Definition 3.2 and the second equality follows from the thin equivalence of $\rho_x - q_t$ and ρ_{x+t} and the thin invariance of Z . Thus we have

$$\exp i \int_a^b \rho(A_j) = Z(\rho_b; j) Z(\rho_a; j)^{-1} = Z(\rho; j)$$

where the final equality follows from the thin equivalence of ρ_b and ρ and the thin invariance of Z , as well as from Proposition 3.3 b), since ρ_a is a trivial path. This completes the proof that the maps given by equations (2) and (3) on the one hand and equations (4) and (5) on the other hand are mutual inverses, i.e. that the correspondence is one-to-one. \square

Remark 3.9 In the approach of Mackaay and the author in [16], the role of TQFT's was played by holonomies, which assign a group element to each based loop, up to certain conditions such as multiplicativity. The reconstruction of transition functions g_{ij} was ambiguous there, since it depended on fixing paths from the basepoint to each point of M , and similarly for the reconstruction of the connection 1-forms A_i . Thus the correspondence between bundles with connection and holonomies (Theorem 3.9 of [16]) was necessarily only up to equivalence. The advantage of the TQFT approach here, based on paths, is that there is a natural path associated to each point of M , namely the trivial path at that point, and there are natural families of paths associated to each vector at a point, namely the paths q_t of the above proof. Thus here the correspondence works without having to descend to equivalence classes. Indeed a TQFT can be regarded as the extension to all paths $(\rho; T)$ of assignments to certain trivial and infinitesimal paths given by g_{ij} and A_i .

4 Embedded TQFT's and gerbes

We will now sketch the analogous picture for gerbes. The irreducible subobjects are now 1-dimensional, and of the form

$$(\gamma; T)$$

where $\gamma: S^1 \rightarrow M$ is a smooth map from the $+$ (anticlockwise) or $-$ (clockwise) oriented circle to M , and T is a labelled partition of S^1 given by a choice of points a_1, \dots, a_N on S^1 , ordered cyclically, together with an assignment to the edge (arc) e_i , between a_{i-1} and a_i , of $i \in J$, such that $\gamma(e_i) \subset U_i$. General subobjects are finite disjoint unions of irreducible subobjects. An irreducible 2-dimensional object is of the form

$$(X; T);$$

where X maps from an oriented surface with or without boundary S to M , satisfying the following "constant at the boundary" condition: at any boundary circle of S with local coordinates a around the circle and r transversal to the circle, with the boundary circle itself being $r = r_0$, X is constant in r for a

neighbourhood of r_0 . The labelled partition T of S is given by a 3-valent embedded graph in S , and a labelling of the regions (faces) f by $i \in J$, such that $X(f) \subset U_i$, and such that the partition looks like Figure 3 within the constant neighbourhood of any boundary circle.

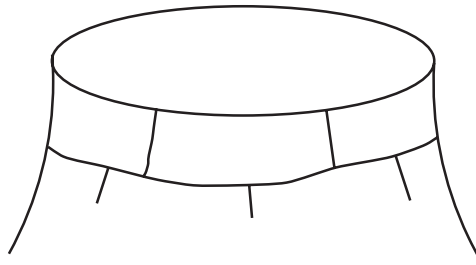


Figure 3: Partition near a boundary circle

As before we will consider isomorphisms between subobjects, basic isomorphisms between objects and basic gluing morphisms between objects, and will also introduce a fourth type of morphism, called partial gluing morphisms. (This last type of morphism was not considered in [18], since it belongs more to the realm of extended TQFT, but we will see that it fits into the picture very naturally here.) Isomorphisms between (irreducible) subobjects are described by

$$(X; T) \xrightarrow{\text{id}} (X'; T')$$

which will be denoted

$$(X; T; T')$$

Basic isomorphisms between 2-dimensional objects are given by

$$(X; T) \xrightarrow{f} (X'; T')$$

where $f : S \rightarrow S'$ is orientation-preserving, and restricts to the identity at the boundary circles, i.e. $f(a; r_0) = (a; r'_0)$ with respect to the local coordinates introduced in the neighbourhood of the boundary circles. Next, basic gluing morphisms between 2-dimensional objects are given by

$$(X; T) \xrightarrow{f} (X'; T')$$

where $X : S \rightarrow M; X' : S' \rightarrow M$, S is obtained from S' by cutting along a circle C in S' , which becomes two boundary circles in S , and f is the identity map everywhere, except at the cut where f maps the pair of boundary

circles arising from the cut to C in S^θ . The partition T^θ in a neighbourhood of C should be as in Figure 4, with the labelled partitions in the constant regions to the left and right of C denoted $T_L^\theta; T_R^\theta$ respectively. The labelled partitions T and T^θ are identical except from the different interpretations at the cut. Note that we have not written the domain of the gluing morphism as a disjoint union, since there is the possibility of self-gluing, a point which is emphasized in [18]. Finally, a partial gluing morphism is given in the same way as a gluing morphism, except that the cut is along a curve in S^θ which intersects the boundary of S^θ transversally, and the labelled partitions on both sides of the curve are identical. Here we will assume that S^θ is divided into two pieces by the cut, i.e. $S^\theta = S_1 \dot{\cup} S_2$, and $(X; T)$ also splits into two objects $(X_1 : S_1 \dot{\cup} M; T_1)$ and $(X_2 : S_2 \dot{\cup} M; T_2)$. An example of a partial gluing morphism is when S_1 and S_2 are triangular surfaces and are glued along one edge to form a square surface S^θ . Such examples will appear in the proof of Theorem 4.6.

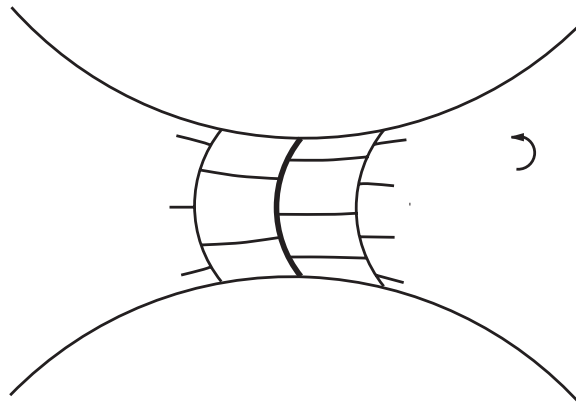


Figure 4: Partition in the neighbourhood of a cut

Definition 4.1 A rank-1, embedded, 2-dimensional TQFT is a pair of assignments

$$\begin{aligned} (\cdot; T; T^\theta) &\mapsto Z^\theta(\cdot; T; T^\theta) \in U(1) \\ (X; T) &\mapsto Z(X; T) \in U(1) \end{aligned}$$

such that

- i) for isomorphisms between subobjects

$$Z^\theta(\cdot; T; T^\theta) Z^\theta(\cdot; T^\theta; T^{\theta\theta}) = Z^\theta(\cdot; T; T^{\theta\theta});$$

ii) for basic isomorphisms $(X; T) \xrightarrow{f} (X^\theta; T^\theta)$

$$Z(X^\theta; T^\theta) = \prod_{C \in \mathcal{C} \circ S} Z^\theta(X^\theta|_{J_C^{o(C)}}; T|_{J_C}; T^\theta|_{J_C}) Z(X; T);$$

where $o(C) =$ is the orientation of C induced from the orientation of S ,

iii) for basic gluing morphisms as described above, corresponding to a cut along C in S^θ

$$Z(X^\theta; T^\theta) = Z^\theta(X^\theta|_{J_C}; T^\theta|_{J_C}) Z(X; T);$$

iv) for partial gluing morphisms as described above

$$Z(X^\theta; T^\theta) = Z(X_1; T_1) Z(X_2; T_2);$$

We remark that the assignment of a phase to a loop with two labelled partitions in i) of the above definition, suggests a notion of transition functions for bundles on the loop space of the target manifold, and indeed this was made precise in [12, 13]. We now state some analogous properties to Proposition 3.3.

Proposition 4.2 *For a rank-1, embedded, 2-dimensional TQFT $(Z^\theta; Z)$ the following properties hold:*

- a) $Z^\theta(\cdot; T; T) = 1,$
- b) *for any $\gamma : S^1 \rightarrow M$ and interval $I = [b; c]$ define $L_I : S^1 \rightarrow M$ by $L_I(a; x) = \gamma(a)$. Then*

$$Z(L_I; T) = 1;$$

where T is any partition consisting of regions separated by lines of constant angle a ,

- c) $Z(L; T \sqcup T^\theta) = Z^\theta(\gamma^+; T; T^\theta),$ *where $L : S^1 \rightarrow [0; 1] \rightarrow M$ is given by $L(a; x) = \gamma(a)$ and the partition of the annulus $T \sqcup T^\theta$ is depicted in Figure 5 (the inner decomposition is T and the outer is T^θ),*
- d) $Z^\theta(\gamma^-; T; T^\theta) = Z^\theta(\gamma^+; T; T^\theta)^{-1}.$

Proof a) is immediate, from i) of Definition 4.1. To show b), we have $Z(L_I; T) = Z(L_{I^\theta}; T)$ for any two intervals $I; I^\theta$, by Definition 4.1 ii) and a). For $I = [b; d]$ and $I^\theta = [d; c]$ we have

$$Z(L_I \sqcup I^\theta) \stackrel{ii) b)}{=} Z(L_I; T) Z(L_{I^\theta}; T)$$

and the result follows. c) follows from

$$Z(L; T [T^0) \stackrel{iii)}{=} Z^0(' + ; T; T^0) Z(L_{[0;1=2]}; T) Z(L_{[1=2;1]}; T^0) \stackrel{b)}{=} Z^0(' ; T; T^0):$$

To show d), we apply ii) of Definition 4.1 as follows:

$$Z(L; T^0) = Z^0(' - ; T; T^0) Z^0(' + ; T; T^0) Z(L; T)$$

where L is defined in c), and use b). □

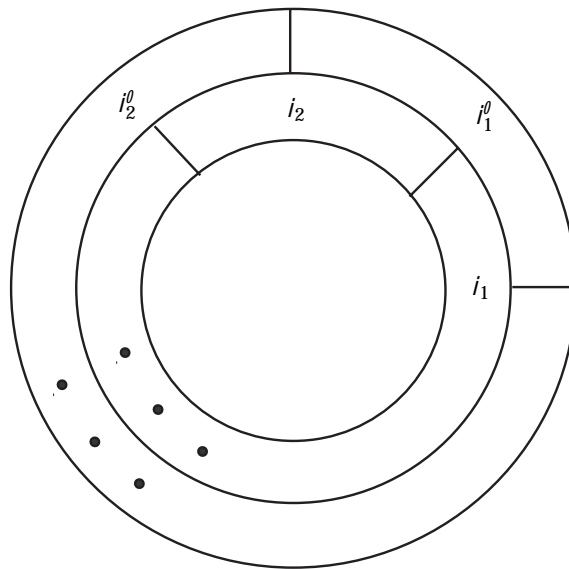


Figure 5: Partition of the annulus $T [T^0$

Suppose we are given a $U(1)$ -gerbe with connection on the target manifold M , i.e. a collection of transition functions on triple intersections

$$g_{ijk} : U_{ijk} \rightarrow U(1)$$

and local connection 1- and 2-forms

$$A_{jk} \in \Omega^1(U_{jk}); F_k \in \Omega^2(U_k);$$

satisfying

- G1) $g_{ijk} = 1$ for $i = j$, $i = k$, or $j = k$,
- G2) $g_{ijk}g_{ikl} = g_{jkl}g_{ijl}$ on U_{ijkl} ,
- G3) $i(A_{jk} + A_{kl} + A_{lj}) = -d \log g_{jkl}$ on U_{jkl} ,

G4) $(F_k - F_j) = dA_{jk}$ on U_{jk} .

G2) is called the cocycle condition. The curvature of this gerbe-connection is the globally-defined 3-form $G \in \Omega^3(M)$, given locally by

$$G = dF_i;$$

In the same way as before, we have

Theorem 4.3 *A $U(1)$ -gerbe with connection on M gives rise to a rank-1, embedded, 2-dimensional TQFT with target M via*

$$Z^0(\Sigma; T; T^b) = \exp i \int_{(\Sigma; T^b)} (g; A) \tag{8}$$

$$Z(X; T) = \exp i \int_{(X; T)} (g; A; F); \tag{9}$$

where

$$\begin{aligned} \exp i \int_{(\Sigma; T^b)} (g; A) &= g_{i_1 i_1^b i_2}(\alpha_1) \exp i \int_{a_1}^{a_1^b} (A_{i_2 i_1^b}); \\ &g_{i_2 i_1^b i_2^b}(\alpha_1^b) \exp i \int_{a_1^b}^{a_2^b} (A_{i_2 i_2^b}) \dots \\ &g_{i_N i_1^b i_1}(\alpha_N^b) \exp i \int_{a_N^b}^{a_1} (A_{i_1 i_1^b}); \end{aligned}$$

(see Figure 6, where we assume that the partitions can be put in the general position indicated by subdividing and shifting regions), and

$$\begin{aligned} \exp i \int_{(X; T)} (g; A; F) &= \prod_v^{int} g_{i i i} (X(v)); \\ &\prod_e^{int} \exp i \int_e^R X (A_{i i}); \\ &\prod_f^{int} \exp i \int_f^R X (F_i); \end{aligned}$$

where the superscript on the products denotes that they are over internal vertices, edges and faces, respectively (see Figure 7 for the orientations).

Proof i) and ii) will be shown using a Lemma to follow. iii) is immediate, since the factor $Z^0(X^b j_C; T_L^b; T_R^b)$ gives precisely the missing internal contributions in $Z(X^b; T^b)$ which come from the vertices and edges along C , as the contributions from the transversal edges and the faces adjacent to C vanish due to the "constant at the boundary" condition for $(X; T)$, and iv) is also immediate since

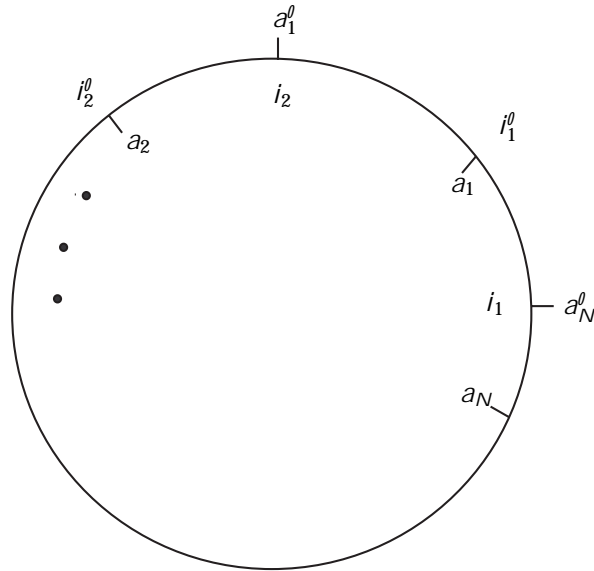


Figure 6: Partitions for $\exp i_{(\cdot; T; T^\theta)}^R(g; A)$

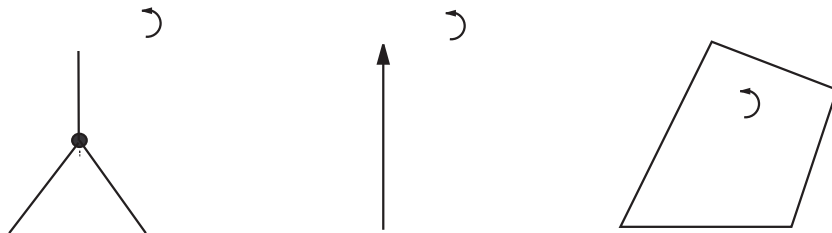


Figure 7: Orientations for v , e and f

there are no missing internal contributions in $Z(X^\theta; T^\theta)$, because the partitions on both sides of the curve are the same.

Indeed, to help prove the other two properties it is useful to observe

$$\exp i_{(\cdot; T; T^\theta)}(g; A) = \exp i_{(L; T \sqcup T^\theta)}(g; A; F)$$

where $L : S^1 \rightarrow M$ is given by $L(a; x) = \gamma(a)$ and the partition of the annulus $T \sqcup T^\theta$ is depicted in Figure 5. This statement corresponds to c) of Proposition 4.2 above.

We now introduce 3-dimensional objects $(H; T)$, where H is a smooth map from an oriented 3-manifold V with or without boundary to M , and T is a labelled partition of V into regions R , such that $H(R) \subset U_i$, by means of an embedded 4-valent 2-graph, which at each internal vertex has four adjacent regions separated by six incident faces and four incident edges. Each internal edge has three incident faces. When V has a boundary, we will denote by $(@H; @T)$ the 2-dimensional object obtained by restricting H and the labelled partition T to the oriented boundary $@V$ of V .

The Lemma from the previous section, one dimension up, now reads as follows.

Lemma 4.4 For a 3-dimensional object $(H; T)$, with $H : V \rightarrow M$

$$\exp i \int_{(@H; @T)} (g; A; F) = \exp i \int_V H (G):$$

Proof The contributions from the external transition functions may be cancelled by introducing factors

$$\exp i \int_e H (A_{i-1} + A_{i+1} + A_{i-1})$$

along each internal edge, using G3), since the product of transition functions at each internal vertex is 1 because of the cocycle condition G2). Using Stokes' theorem and G4), the contributions of all integrals along edges may be replaced by factors

$$\exp i \int_f H (F_i - F_{i-1})$$

for each internal face. Again using Stokes' theorem, these face integrals may be replaced by

$$\exp i \int_R H (G) = \exp i \int_V H (G): \quad \square$$

We now use the Lemma to prove the rest of Theorem 4.3.

Proof of Theorem 4.3 (continued) i) Using the remark after the proof of iii), apply the Lemma to the map H from the cylindrical shell $S^1 \times [0; 1]^2$ to M , given by $H(a; x; y) = \rho(a)$, with the partition on the top and bottom boundaries indicated in Figure 8, and a vertical partition with constant labelling on the inside and outside of the shell. It is easy to obtain an appropriate partition of the cylindrical shell itself, by making a v-shaped ditch below the annulus corresponding to T^0 in the top boundary, and connecting the circular bottom

of the ditch via vertical surfaces to the middle circle of the annulus in the bottom boundary.

ii) Apply the Lemma to a homotopy H from X to X^θ , whose image is contained in the joint image of X and X^θ . The boundary circle contributions in ii) come from the annuli connecting the boundary circles of S and S^θ . It is always possible to obtain an appropriate partition of the domain of H , since the partitions T and T^θ can be obtained from each other by a sequence of elementary moves on labelled partitions of surfaces, namely subdividing a labelled face into faces with the same label or recombining faces with the same label, and changing the label of a face. It is simple to construct labelled volume partitions corresponding to these moves. \square

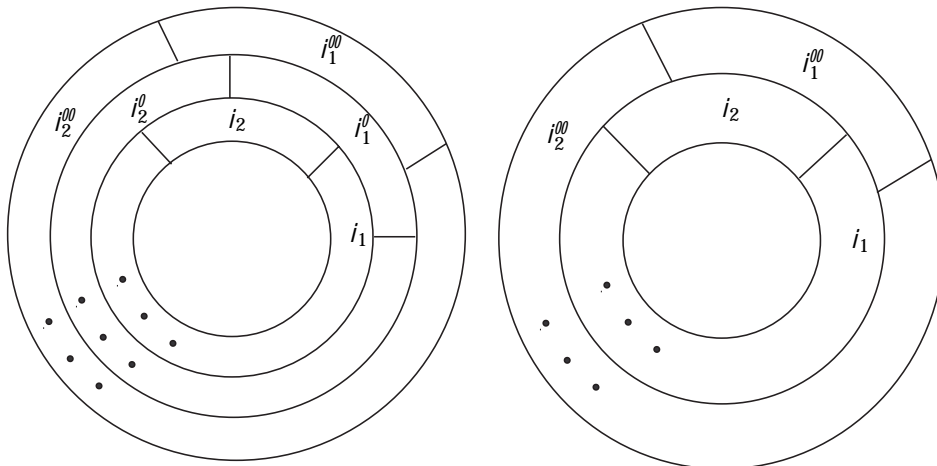


Figure 8: Partition on the top and bottom boundaries

Again the gerbe-induced embedded TQFT's have special properties, which are proved in analogous fashion to Theorem 3.7.

Theorem 4.5 *The rank-1, embedded, 2-dimensional TQFT's of Theorem 4.3 satisfy*

- 1) *thin invariance: when $(X; T)$ and $(X^\theta; T^\theta)$ have the same labelled partition at their boundaries and there is a relative homotopy $(H; \mathcal{F})$ from $(X; T)$ to $(X^\theta; T^\theta)$ satisfying $\text{rank } DH = 2$, then*

$$Z(X; T) = Z(X^\theta; T^\theta);$$

- 2) *smoothness*: for any smooth k -dimensional family of objects $(X(u); T(u))$: $u \in U \subset \mathbb{R}^k$, $Z(X(u); T(u))$ depends smoothly on u .

We will conclude this section with the analogous theorem to Theorem 3.8.

Theorem 4.6 *There is a one-to-one correspondence between gerbes with connection on M and smooth, thin invariant, rank-1, embedded, 2-dimensional TQFT's with target M .*

Proof We have already seen the correspondence in one direction. Suppose we are given an embedded TQFT with the stated properties. We may reconstruct a gerbe with connection on M as follows.

$$g_{ijk}(y) = Z(\sigma_y; ijk); \tag{10}$$

where σ_y is the constant map from a standard 2-simplex to y , and ijk denotes the labelled partition obtained from connecting the midpoint of each edge of σ_y to a trivalent vertex at the centre of σ_y , and assigning $i; j$ and k to the three regions of this partition (Figure 9). Properties G1) and G2) now follow from applying Z to the partial gluing morphisms and isomorphisms depicted in Figures 10 and 11. Note that we need partial gluing morphisms here, and not gluing morphisms, since only a part of the boundary of the simplices is glued.

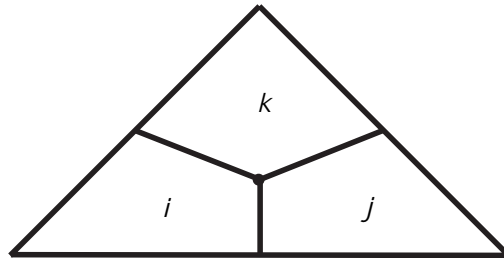


Figure 9: Labelled partition of σ_y for the gerbe transition function

Next, the connection 1-forms are defined as follows:

$$i(A_{jk})_y(v) = \frac{d}{dt} \log Z(Q_t; jk) \Big|_{t=0} \tag{11}$$

where we take a smooth path $q : (-\epsilon; \epsilon) \rightarrow U_{jk}$ such that $q(0) = y$; $q'(0) = v$, and Q_t is a map from $[0; 1]_u \times [0; 1]_s$ to U_{jk} which does not depend on u , and as a function of s is a path from y to $q(t)$ along q , reparametrized to be constant



Figure 10: Proof of G1)

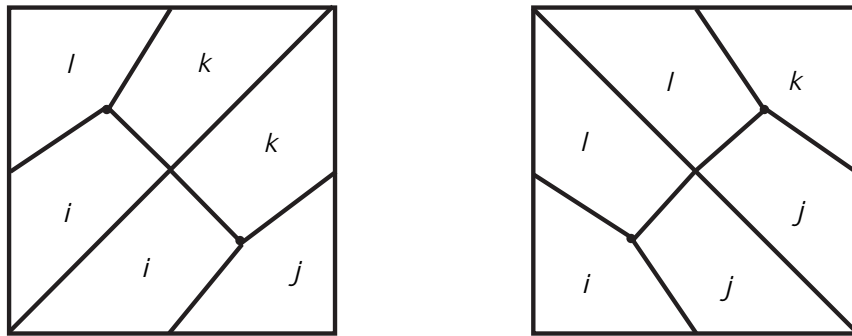


Figure 11: Proof of G2)

at the endpoints. Furthermore, jk denotes the labelled partition which assigns j to the region $u \in [0; 1/2]$ and k to the region $u \in [1/2; 1]$. A_{jk} is well-defined by an identical argument to that used to show that A_j is well-defined in the proof of Theorem 3.8. In particular we have

$$\frac{d}{dt} \log Z(Q_t; jk)|_{t=0} = -\frac{d}{dt} \log Z(R_{Q(t)}; jk)|_{t=0} = -(dh)_y(v);$$

where $R_x : [0; 1]_u \rightarrow [0; 1]_s \rightarrow M$ is defined in terms of the radial paths of that proof, namely $R_x(u; s) = r_x(s)$, and the function h is given by $h(x) = \log Z(R_x; jk)$ in a neighbourhood of y .

To show that the transition functions and connection 1-forms satisfy G3), consider the function $\psi : (-\infty; \infty) \rightarrow \mathbb{R}$ defined by

$$\psi(t) = \log Z(P_t; jkl);$$

where P_t is the map from the prism surface to U_{ijk} given by γ and $q(t)$ on the two triangular faces, and Q_t on the three square faces, and the labelled partition ijk is indicated in Figure 12. By the thin invariance of Z , ψ is constant, since there are natural thin homotopies between P_t 's for different

values of t (the image of these homotopies is contained in the image of q). Thus

$$\begin{aligned} 0 &= \frac{d}{dt} [-\log Z(y; jkl) + \log Z(q(t); jkl) + \\ &\quad \log(Z(Q_t; jk) + \log(Z(Q_t; kl) + \log(Z(Q_t; lj)))]_{t=0} \\ &= i(A_{jk} + A_{kl} + A_{lj})_y(v) + (d \log g_{jkl})_y(v); \end{aligned}$$

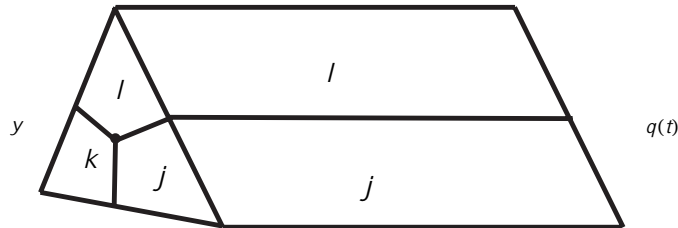


Figure 12: Labelled partition for the proof of G3)

Finally, the connection 2-forms are defined as follows:

$$i(F_j)_y(v; w) = \frac{\partial^2}{\partial t \partial u} \log Z(Q_{t,u}; j)_{j(t,u)=(0,0)}; \tag{12}$$

where we take a smooth map $Q: (-;)_r \rightarrow (-;)_s \rightarrow U_j$ such that

$$Q(0;0) = y; \quad \frac{\partial Q}{\partial r}(0;0) = v; \quad \frac{\partial Q}{\partial s}(0;0) = w;$$

and set $Q_{t,u}$ to be a 2-path (map from the Cartesian product of two intervals to M) from $Q(0; \cdot)$ to $Q(\cdot; \cdot)$ and from $Q(\cdot; 0)$ to $Q(\cdot; u)$ along Q , reparametrized to be constant on the boundary. Furthermore, j denotes the labelled partition which assigns j to the whole domain of $Q_{t,u}$.

We sketch the proof that F_j is well-defined. First, given Q , F_j does not depend on the choice of $Q_{t,u}$ because of the thin invariance of Z . Thus it remains to show that the definition does not depend on the choice of Q . We construct a second family of maps $\mathcal{Q}_{t,u}: D \rightarrow M$, where D denotes the unit disk, such that $\mathcal{Q}_{t,u}(1;0) = y$, $\mathcal{Q}_{t,u}$ restricted to the four quadrants of ∂D coincides with $Q_{t,u}$ restricted to the four edges of the square, in an obvious sense, and $\mathcal{Q}_{t,u}$ restricted to any chord in D ending at $(1;0)$ is the radial path in M (as in the proof of Theorem 3.8) from the image of the starting point of the chord to y . Combining the maps $Q_{t,u}$ and $\mathcal{Q}_{t,u}$ gives a 2-parameter family of maps from S^2 to M , equal to the trivial map at $t = u = 0$. Applying the higher version of Barrett's lemma proved in [16], we have

$$\frac{\partial^2}{\partial t \partial u} \log Z(Q_{t,u}; j)_{j(t,u)=(0,0)} = \frac{\partial^2}{\partial t \partial u} \log Z(\mathcal{Q}_{t,u}; j)_{j(t,u)=(0,0)};$$

The right-hand-side can be shown to be equal to $(dB)_y(v; w)$, where B is a smooth 1-form defined in a neighbourhood of y , and is thus independent of the choice of Q .

To show that equation G4) holds for the connection 1- and 2-forms, consider the function

$$: (-;) \quad (-;) ! \mathbb{R}; \quad (t; u) = \log Z(B_{t,u}; jk);$$

where $B_{t,u}$ maps from the boundary of the cube $[0; t]_r \times [0; u]_s \times [0; 1]_p$ to U_{ij} , and is given by $Q_{t,u}$ on $p = 0; 1$, and is constant in p on the sides $r = 0; 1; s = 0; 1$. Furthermore, jk denotes the labelled partition indicated in Figure 13. is constant, by the thin invariance of Z , since the images for all arguments are contained in the image of Q , and G4) follows from writing out the equation $@^2 = @t@u(0; 0) = 0$.

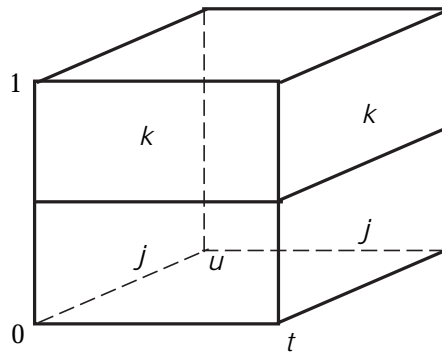


Figure 13: Labelled partition for the proof of G4)

Finally we show the correspondence is one-to-one. Let $(g_{ijk}; A_{jk}; F_k)_{i;j;k \in J}$ be a gerbe with connection, and let $(Z^0; Z)$ be the TQFT which arises from it (Theorem 4.3). Now take $(g_{ijk}; A_{jk}; F_k)_{i;j;k \in J}$ to be the gerbe and connection reconstructed from $(Z^0; Z)$ via equations (10), (11) and (12). We have

$$g_{ijk}(y) = Z(y; jk) = g_{ijk}(y)$$

using equation (9) in the second equality, since the edge and face integrals on the right-hand-side don't contribute, as the map y is constant. Next we have

$$\begin{aligned} i(A_{jk})_y(v) &= \frac{d}{dt} \log Z(Q_t; jk)_{j_{t=0}} = i \frac{d}{dt} \int_0^1 Q_t(A_{jk})_{j_{t=0}} \\ &= i \frac{d}{dt} \int_0^1 q(A_{jk})_{j_{t=0}} = i(A_{jk})_y(v) \end{aligned}$$

where, in the first equality, we choose $Q_t : [0; 1]^2 \rightarrow M$ defined by $Q_t(u; s) = q(st)$, reparametrized to be constant at the boundary, in the second equality we use equation (9), and the fact that there are no vertices and the face integrals don't contribute as Q_t is constant in u , and, in the third equality, we use the reparametrization invariance of the integral and make a substitution. Thirdly, we have

$$\begin{aligned} i(F_k)_y(v; w) &= \frac{\partial^2}{\partial t \partial u} \log Z(Q_{t;u}; k) j_{(t;u)=(0,0)} \\ &= i \frac{\partial^2}{\partial t \partial u} Z^{[0;1]^2}_{t,u} Q_{t;u}(F_k) j_{(t;u)=(0,0)} \\ &= i \frac{\partial^2}{\partial t \partial u} Z_{0,0} Q(F_k) j_{(t;u)=(0,0)} = (F_k)_y(v; w) \end{aligned}$$

where in the first equality we choose $Q_{t;u} : [0; 1]^2 \rightarrow M$ defined by $Q_{t;u}(r; s) = Q(rt; su)$, reparametrized to be constant at the boundary, in the second equality we use equation (9), and in the third equality we use the reparametrization invariance of the integral and make two substitutions.

Conversely, let $(Z^\theta; Z)$ be a TQFT, as specified, and let $(g_{ijk}; A_{jk}; F_k)_{i,j,k \in 2J}$ be the gerbe with connection reconstructed from it via equations (10), (11) and (12). Now take $(Z^\theta; Z)$ to be the TQFT that this bundle with connection gives rise to (Theorem 4.3). We have

$$\begin{aligned} Z^\theta(\cdot^+; T; T^\theta) &= g_{i_1 i_1^\theta i_2}(\cdot(a_1)) \exp i \int_{a_1}^{a_1^\theta} \cdot (A_{i_2 i_1^\theta}) ::: \\ &= Z(\cdot(a_1); i_1 i_1^\theta i_2) Z(L_{11^\theta}; i_2 i_1^\theta) ::: \\ &= Z(L; T \sqcup T^\theta) = Z^\theta(\cdot^+; T; T^\theta). \end{aligned}$$

Here in the second equality we use equation (10) and the relation

$$\exp i \int_{a_1}^{a_1^\theta} \cdot (A_{i_2 i_1^\theta}) = Z(L_{11^\theta}; i_2 i_1^\theta)$$

where $L : S^1 \rightarrow M$ is given by $L(a; x) = \cdot(a)$, L_{11^θ} denotes L restricted to the interval $[a_1; a_1^\theta]$, and $i_2 i_1^\theta$ denotes the partition with i_2 on the inside and i_1^θ on the outside of the strip (see Figures 6 and 5). This relation is shown in analogous fashion to equation (7) in the proof of Theorem 3.8. In the third equality we use the partial gluing property iv) of Definition 4.1 to put all the pieces together, as well as an isomorphism between L with the partition it acquires in this way, and L with the partition $T \sqcup T^\theta$ of Figure 5. The last equality is Proposition 4.2 c). Next we have

$$Z^\theta(\cdot^-; T; T^\theta) = Z^\theta(\cdot^+; T; T^\theta)^{-1} = Z^\theta(\cdot^+; T; T^\theta)^{-1} = Z^\theta(\cdot^-; T; T^\theta);$$

using Proposition 4.2 d) in the last equality. Finally we have

$$\begin{aligned} Z(X; T) &= \exp \int_{(X; T)}^R (g; A; F) \\ &= \int_v^{int} Z(\chi_{(v)}; i, i, i): \\ &= \int_e^{int} Z(\chi_e; i, i): \\ &= \int_f^{int} Z(\chi_f; i) = Z(X; T) \end{aligned}$$

where we have used equation (10) for the vertex factors, we have introduced the 2-path $\chi_e : [0; 1]_s \rightarrow [0; 1]_t \rightarrow M$, constant in t and equal to the path X restricted to the edge e as a function of s , and the labelling i, i, i which denotes assigning i to the region $t = 1=2$ and i to the region $t = 1=2$. We have also introduced $\chi_f : f \rightarrow M$ being X restricted to f , and the labelling i which denotes assigning i to the whole of f . The equality for the edge factors is shown in analogous fashion to equation (7) in the proof of Theorem 3.8 and the equality for the face factors is shown by an analogous argument for 2-forms. The final equality uses iv) of Definition 4.1 to put all the pieces together, as well as an isomorphism between the 2-dimensional object thus obtained and $(X; T)$. \square

5 Comments

In this direct approach using the local functions and forms which make up bundles or gerbes with connection, we were able to avoid the use of trivializations of the pull-back bundle or gerbe, which appeared in various proofs in [16]. Indeed these trivializations may not exist if the topology of the object's domain is non-trivial. We note that the integral formulae given here do not require $\pi_1(M)$ to be trivial, whereas non-simply-connected manifolds M created some technical hurdles in [16].

Bundles, gerbes and higher generalizations sit nicely inside a variety of dimensional ladders, and several people have conjectured links between this chain of higher-order geometries and state-sum models of TQFT. The constructions and methods of proof here have a distinct state-sum flavour, and there are intriguing suggestions of a graded integration theory, involving objects of all dimensions up to the dimension being integrated. This could be useful for understanding broader dimensional ladders for TQFT [4], which normally involves just the top dimension and one dimension lower, or TQFT with corners. It would also be

interesting to see whether there are links between these constructions and the state-sum models for quantum gravity proposed by Barrett and Crane [6] and Mikovic [17].

Approaches to non-abelian gerbes with connection have been studied by various authors [7, 2, 3]. We could have obtained solutions of the higher-rank 1-dimensional embedded TQFT equations, mentioned after Definition 3.2, from nonabelian bundles with connection, via path-ordered exponentials. The geometric-combinatorial approach in this article may suggest non-abelian solutions for the higher-rank 2-dimensional embedded TQFT equations, which would then be strong candidates to be called non-abelian gerbes with connection.

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