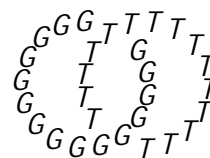


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## Examples of Riemannian manifolds with positive curvature almost everywhere

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### Abstract

We show that the unit tangent bundle of  $S^4$  and a real cohomology  $CP^3$  admit Riemannian metrics with positive sectional curvature almost everywhere. These are the only examples so far with positive curvature almost everywhere that are not also known to admit positive curvature.

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## 0 Introduction

A manifold is said to have quasi-positive curvature if the curvature is nonnegative everywhere and positive at a point. In analogy with Aubin's theorem for manifolds with quasi-positive Ricci curvature one can use the Ricci flow to show that any manifold with quasi-positive scalar curvature or curvature operator can be deformed to have positive curvature.

By contrast no such result is known for sectional curvature. In fact, we do not know whether manifolds with quasi-positive sectional curvature can be deformed to ones with positive curvature almost everywhere, nor is it known whether manifolds with positive sectional curvature almost everywhere can be deformed to have positive curvature. What is more, there are only two examples ([12] and [11]) of manifolds with quasi-positive curvature that are not also known to admit positive sectional curvature. The example in [11] is a fake quaternionic flag manifold of dimension 12. It is not known if it has positive curvature almost everywhere. The example in [12] is on one of Milnor's exotic 7-spheres. It was asserted without proof, in [12], that the Gromoll-Meyer metric has positive sectional curvature almost everywhere, but this assertion was disproven by Mandell, a student of Gromoll ([16], cf also [25]). Thus there is no known example of a manifold with positive sectional curvature at almost every point that is not also known to admit positive curvature. We will rectify this situation here by proving the following theorem.

**Theorem A** *The unit tangent bundle of  $S^4$  admits a metric with positive sectional curvature at almost every point with the following properties.*

- (i) *The connected component of the identity of the isometry group is isomorphic to  $SO(4)$  and contains a free  $S^3$  subaction.*
- (ii) *The set of points where there are 0 sectional curvatures contains totally geodesic flat 2-tori and is the union of two copies of  $S^3$  that intersect along a  $S^2$ .*

**Remark** In the course of our proof we will also obtain a precise description of the set of 0-curvature planes in the Grassmannian. This set is not extremely complicated, but the authors have not thought of a description that is succinct enough to include in the introduction.

**Remark** In the sequel to this paper, [25], the second author shows that the metric on the Gromoll-Meyer sphere can be perturbed to one that has positive sectional curvature almost everywhere. In contrast to [25] the metric we construct here is a perturbation of a metric that has zero curvatures at every point.

By taking a circle subgroup of the free  $S^3$  action in Theorem A(i) we get the following.

**Corollary B** *There is a manifold  $M^6$  with the homology of  $CP^3$  but not the cohomology ring of  $CP^3$ , that admits a metric with positive sectional curvature almost everywhere.*

There are also flat totally geodesic 2-tori in  $M^6$  so as a corollary of Lemma 4.1 in [22] (cf also Proposition 3 in [5]) we have the following.

**Corollary C** *There are no perturbations of our metrics on the unit tangent bundle and  $M^6$  whose sectional curvature is positive to first order.*

*That is, there is no smooth family of metrics  $f_t g_t$  with  $g_0$  the metric in Theorem A or Corollary B so that*

$$\frac{d}{dt} \text{sec}_{g_t}(P)|_{t=0} > 0$$

*for all planes  $P$  that satisfy  $\text{sec}_{g_0}(P) = 0$ .*

**Remark** Although the unit tangent bundle of  $S^4$  is a homogeneous space (see below), the metric of Theorem A is obviously inhomogeneous. What is more if the unit tangent bundle of  $S^4$  admits a metric with positive sectional curvature, then it must be for some inhomogeneous metric see [6]. The space in Corollary B is a biquotient of  $Sp(2)$ . It follows from [19, Theorem 6] that  $M^6$  does not have the homotopy type of a homogeneous space.

Before outlining the construction of our metric we recall that the  $S^3$  bundles over  $S^4$  are classified by  $\mathbb{Z} \times \mathbb{Z}$  as follows ([14], [21]). The bundle that corresponds to  $(n; m) \in \mathbb{Z} \times \mathbb{Z}$  is obtained by gluing two copies of  $\mathbb{R}^4 \times S^3$  together via the diffeomorphism  $g_{n,m}: (\mathbb{R}^4 \times S^3) \rightarrow (\mathbb{R}^4 \times S^3)$  given by

$$g_{m;n}(u; v) = \left( \frac{u}{|u|^2}, \frac{u^m v u^n}{|u|^{n+m}} \right); \tag{0.1}$$

where we have identified  $\mathbb{R}^4$  with  $\mathbb{H}$  and  $S^3$  with  $\mathbb{H} / \mathbb{Z} |j| v j = 1g$ . We will call the bundle obtained from  $g_{m;n}$  the bundle of type  $(m; n)$ , and we will denote it by  $E_{m;n}$ .

Translating Theorem 9.5 on page 99 of [15] into our classification scheme (0.1) shows that the unit tangent bundle is of type  $(1; 1)$ . We will show it is also the quotient of the  $S^3$  action on  $Sp(2)$  given by

$$A_{2,0}(p; \begin{pmatrix} a & b \\ c & d \end{pmatrix}) = \begin{pmatrix} pa & pb \\ pc & pd \end{pmatrix} :$$

(It was shown in [20] that this quotient is also the total space of the bundle of type  $(2;0)$ , so we will call it  $E_{2,0}$ .)

The quotient of the biinvariant metric via  $A_{2,0}$  is a normal homogeneous space with nonnegative, but not positive sectional curvature. To get the metric of Theorem A we use the method described in [8] to perturb the biinvariant of  $Sp(2)$  using the commuting  $S^3$  actions

$$\begin{aligned} A^u \left( \begin{matrix} a & b \\ c & d \end{matrix} \right) &= \begin{matrix} \rho_1 a & \rho_1 b \\ c & d \end{matrix} \\ A^d \left( \begin{matrix} a & b \\ c & d \end{matrix} \right) &= \begin{matrix} a & b \\ \rho_2 c & \rho_2 d \end{matrix} \\ A^l \left( \begin{matrix} a & b \\ c & d \end{matrix} \right) &= \begin{matrix} a q_1 & b \\ c q_1 & d \end{matrix} \\ A^r \left( \begin{matrix} a & b \\ c & d \end{matrix} \right) &= \begin{matrix} a & b q_2 \\ c & d q_2 \end{matrix} : \end{aligned}$$

We call the new metric on  $Sp(2)$ ,  $g_{1;2;l_1^u;l_1^d}$ , and will observe in Proposition 1.14 that  $A_{2,0}$  is by isometries with respect to  $g_{1;2;l_1^u;l_1^d}$ . Our metric on the unit tangent bundle is the one induced by the Riemannian submersion  $(Sp(2); g_{1;2;l_1^u;l_1^d}) \xrightarrow{q_2} Sp(2) = A_{2,0} = E_{2,0}$ .

In section 1 we review some generalities of Cheeger's method. In section 2 we study the symmetries of  $E_{2,0}$ . In section 3 we analyze the infinitesimal geometry of the Riemannian submersion  $Sp(2) \xrightarrow{p_2} S^7$ , given by projection onto the first column. This will allow us to compute the curvature tensor of the metric,  $g_{1;2}$ , obtained by perturbing the biinvariant metric via  $A^l$  and  $A^r$ . In section 4 we compute the A-tensor of the Hopf fibration  $S^7 \rightarrow S^4$ , because it is the key to the geometry of  $g_{1;2}$ . In section 5 we specify the zero curvatures of  $g_{1;2}$ , and in section 6 we describe the horizontal space of  $q_2: Sp(2) \rightarrow E_{2,0}$  with respect to  $g_{1;2}$  and hence (via results from section 1) with respect to  $g_{1;2;l_1^u;l_1^d}$ . In section 7 we specify the zero curvatures of  $E_{2,0}$ , first with respect to  $g_{1;2}$  and then with respect to  $g_{1;2;l_1^u;l_1^d}$ , proving Theorem A. In section 8 we establish the various topological assertions that we made above, that  $E_{2,0}$  is the total space of the unit tangent bundle and that while the cohomology modules of  $E_{2,0} = S^1$  are the same as  $CP^3$ 's the ring structure is different. Using these computations we will conclude that  $E_{2,0}$  and  $E_{2,0} = S^1$  do not have the homotopy type of any known example of a manifold of positive curvature.

We assume that the reader has a working knowledge of O'Neill's "fundamental equations of a submersion" [18] and the second author's description of the

tangent bundle of  $Sp(2)$ , [24], we will adopt results and notation from both papers, in most cases without further notice. It will also be important for the reader to keep the definitions of the five  $S^3$  actions  $A^u, A^d, A^l, A^r$  and  $A_{2,0}$  straight. To assist we point out that the letters  $u, d, l$  and  $r$  stand for "up", "down", "left" and "right" and are meant to indicate the row or column of  $Sp(2)$  that is acted upon.

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*Dedicated to Detlef Gromoll on his sixtieth birthday*

## 1 Cheeger's Method

In [8] a general method for perturbing the metric on a manifold,  $M$ , of non-negative sectional curvature is proposed. Various special cases of this method were first studied in [4] and [7].

If  $G$  is a compact group of isometries of  $M$ , then we let  $G$  act on  $G \times M$  by

$$g(p; m) = (pg^{-1}; gm): \tag{1.1}$$

If we endow  $G$  with a biinvariant metric and  $G \times M$  with the product metric, then the quotient of (1.1) is a new metric of nonnegative sectional curvature on  $M$ . It was observed in [8], that we may expect the new metric to have fewer 0 curvatures and symmetries than the original metric.

In this section we will describe the effect of certain Cheeger perturbations on the curvature tensor of  $M$ . Most of the results are special cases of results of [8], we have included them because they can be described fairly succinctly and are central to all of our subsequent computations.

The quotient map for the action (1.1) is

$$q_{G \times M}: (p; m) \mapsto pm: \tag{1.2}$$

The vertical space for  $q_{G \times M}$  at  $(p; m)$  is

$$V_{q_{G \times M}} = \{(-k; k) \mid k \in \mathfrak{g}\}$$

where the  $-k$  in the first factor stands for the value at  $p$  of the Killing field on  $G$  given by the circle action

$$(\exp(tk); p) \nabla_p \exp(-kt) \tag{1.3}$$

and the  $k$  in the second factor is the value of the Killing field

$$\frac{d}{dt} \exp(tk) m \tag{1.4}$$

on  $M$  at  $m$ .

Until further notice all Cheeger perturbations under consideration will have the property:

$$\text{For all } k_1, k_2 \in \mathfrak{g} \text{ if } h(k_1; 0); (k_2; 0) i = 0, \text{ then } h(0; k_1); (0; k_2) i = 0, \tag{1.5}$$

where  $\mathfrak{g}$  is the Lie algebra of  $G$ . Notice that  $A^u, A^d, A^r$  and  $A^l$  have this property.

In this case the horizontal space for  $q_G : M \rightarrow G$  is the direct sum

$$H_{q_G : M} = \mathfrak{f} \left( \begin{smallmatrix} 2 \\ 2 \end{smallmatrix} k; \begin{smallmatrix} 2 \\ 1 \end{smallmatrix} k \right) \oplus \mathfrak{g} \oplus ( \mathfrak{f} \cap \mathfrak{g} \perp H_{O_G} ); \tag{1.6}$$

where  $\begin{smallmatrix} 1 \\ 1 \end{smallmatrix} = j(-k; 0)j$  and  $\begin{smallmatrix} 2 \\ 2 \end{smallmatrix} = j(0; k)j$  and  $H_{O_G}$  is the space that is normal to the orbit of  $G$ . The image of  $( \begin{smallmatrix} 2 \\ 2 \end{smallmatrix} k; \begin{smallmatrix} 2 \\ 1 \end{smallmatrix} k )$  under  $dq_G : M$  is

$$dq_G : M \left( \begin{smallmatrix} 2 \\ 2 \end{smallmatrix} k; \begin{smallmatrix} 2 \\ 1 \end{smallmatrix} k \right) = \frac{d}{dt} \rho \exp \left( \begin{smallmatrix} 2 \\ 2 \end{smallmatrix} kt \right) \exp \left( \begin{smallmatrix} 2 \\ 1 \end{smallmatrix} kt \right) m \Big|_{t=0} = dL_{\rho; \left( \left( \begin{smallmatrix} 2 \\ 1 \end{smallmatrix} + \begin{smallmatrix} 2 \\ 2 \end{smallmatrix} \right) k \right); \tag{1.7}$$

It follows that the effect of Cheeger's perturbation is to keep  $H_{O_G}$  perpendicular to the orbits of  $G$ , to keep the metric restricted to  $H_{O_G}$  unchanged and to multiply the length of the vector  $dL_{\rho; \left( \begin{smallmatrix} 2 \\ 2 \end{smallmatrix} k \right)}$  by the factor

$$\frac{\rho \left( \left( \begin{smallmatrix} 2 \\ 2 \end{smallmatrix} \right)^2 + \left( \begin{smallmatrix} 2 \\ 1 \end{smallmatrix} \right)^2 \right)^2}{\left( \begin{smallmatrix} 2 \\ 1 \end{smallmatrix} + \begin{smallmatrix} 2 \\ 2 \end{smallmatrix} \right)^2} = \frac{\rho \left( \frac{4}{1} + \frac{2}{2} \frac{2}{1} \right)}{\left( \begin{smallmatrix} 2 \\ 1 \end{smallmatrix} + \begin{smallmatrix} 2 \\ 2 \end{smallmatrix} \right)^2} = \frac{\rho \frac{2}{1}}{\frac{2}{1} + \frac{2}{2}} \neq 1 \text{ as } \begin{smallmatrix} 1 \\ 1 \end{smallmatrix} \neq \begin{smallmatrix} 1 \\ 1 \end{smallmatrix}; \tag{1.8}$$

If  $b$  is a fixed biinvariant metric on  $G$  and  $l_1$  is a positive real number, then we let  $g_{l_1}$  denote the metric we obtain on  $M$  via the Riemannian submersion  $q_G : M \rightarrow G$  when the metric on the  $G$ -factor in  $G \times M$  is  $l_1^2 b$ . When  $G = S^3$ ,  $b$  will always be the unit metric. As pointed out in (1.8),  $g_{l_1}$  converges to the original metric,  $g$ , as  $l_1 \rightarrow 1$ . To emphasize this point we will also denote  $g$  by  $g_1$ .

Let  $TO_G$  denote the tangent distribution in  $M$  to the orbits of  $G$ . Then any plane  $P$  tangent to  $M$  can be written as

$$P = \text{span} \{ z + k^a; + k^b g; \tag{1.9}$$

where  $z \in H_{O_G}$  and  $k^a, k^b \in T_{O_G}$ . We let  $\hat{P}$  denote the plane in  $T(G \times M)$  that is horizontal with respect to  $q_{G \times M}$  and satisfies  $dp_2(\hat{P}) = P$  where  $p_2: G \times M \rightarrow M$  denotes the projection onto the second factor. If  $\hat{P} \in T(G \times M)$ , then  $\hat{P} \in T(G \times M)$  has the analogous relationship to  $\hat{P}$  as  $\hat{P}$  has to  $P$ . As pointed out in [8] we have the following result.

**Proposition 1.10** Let  $l_1^a$  and  $l_2^a$  denote the lengths of the Killing fields on  $G$  and  $M$  corresponding to  $k^a$  via the procedures described in (1.3) and (1.4). Let  $l_1^b$  and  $l_2^b$  have the analogous meaning with respect to  $k^b$ .

(i) If the curvature of  $P$  is positive with respect to  $g_1$ , then the curvature of

$$dq_{G \times M}(\hat{P}) = \text{span}\left\{ z + \frac{l_1^a + l_2^a}{l_1^a} k^a; \quad z + \frac{l_1^b + l_2^b}{l_1^b} k^b \right\} \quad (1.11)$$

is positive with respect to  $g_1$ .

- (ii) The curvature of  $dq_{G \times M}(\hat{P})$  is positive with respect to  $g_1$  if the  $A$ -tensor,  $A^{q_{G \times M}}$ , of  $q_{G \times M}$  is nonzero on  $\hat{P}$ .
- (iii) If  $G = S^3$ , then the curvature of  $dq_{G \times M}(\hat{P})$  is positive if the projection of  $P$  onto  $T_{O_G}$  is nondegenerate.
- (iv) If the curvature of  $\hat{P}$  is 0 and  $A^{q_{G \times M}}$  vanishes on  $\hat{P}$ , then the curvature of  $dq_{G \times M}(\hat{P})$  is 0.

**Proof** (ii) and (iv) are corollaries of O'Neill's horizontal curvature equation.

To prove (i) notice that the curvature of  $dq_{G \times M}(\hat{P})$  is positive if the curvature of its horizontal lift,  $\hat{P}$ , is positive. The curvature of  $\hat{P}$  is positive if its image,  $P$ , under  $dp_2$  has positive curvature, proving (i).

Let  $p_1: G \times M \rightarrow G$  be the projection onto the first factor. The curvature of  $\hat{P}$  is also positive if its image under  $dp_1$  is positively curved. If  $G = S^3$ , then this is the case, provided the image of  $\hat{P}$  is nondegenerate, proving (iii).  $\square$

Using (1.8) we get the following.

**Proposition 1.12** Let  $A_H: H \times M \rightarrow M$  be an action that is by isometries with respect to both  $g_1$  and  $g_1$ . Let  $H_{A_H}$  denote the distribution of vectors that are perpendicular to the orbits of  $A_H$ .

$P$  is in  $H_{A_H}$  with respect to  $g_1$  if and only if  $dq_{G \times M}(\hat{P})$  is in  $H_{A_H}$  with respect to  $g_1$ .

**Proof** Just combine our description of  $g_1$  with the observation that if we square the expression in (1.8) we get the reciprocal of the quantity in (1.11).  $\square$

Ultimately we will be studying Cheeger Perturbations via commuting group actions,  $A_{G_1}; A_{G_2}$ , that individually have property (1.5). Generalizing our formulas to this situation is a simple matter once we observe the following result.

**Proposition 1.13** *Let  $G_1, G_2$  act isometrically on  $(M; g)$ . Fix biinvariant metrics  $b_1$  and  $b_2$ , on  $G_1$  and  $G_2$ . Let  $g_1$  and  $g_2$  be the metrics obtained by doing Cheeger perturbations of  $(M; g)$  with  $G_1$  and  $G_2$  respectively.*

- (i)  $G_2$  acts by isometries on  $(M; g_1)$  and  $G_1$  acts by isometries on  $(M; g_2)$ .
- (ii) Let  $g_{1,2}$  denote the metric obtained by doing the Cheeger perturbation with  $G_2$  on  $(M; g_1)$  and let  $g_{2,1}$  denote the metric obtained by doing the Cheeger perturbation with  $G_1$  on  $(M; g_2)$ . Then

$$g_{1,2} = g_{2,1}.$$

In fact  $g_{1,2}$  coincides with the metric obtained by doing a single Cheeger perturbation of  $(M; g)$  with  $G_1 \times G_2$ .

- (iii)  $(k_u^1; k_u^2; u)$  is horizontal for  $G_1 \times G_2 \rightarrow M \xrightarrow{q_{G_1 \times G_2}} M$  with respect to  $b_1 \times b_2 \times g$  if and only if  $(k_u^1; u)$  is horizontal for  $G_1 \rightarrow M \xrightarrow{q_{G_1}} M$  with respect to  $b_1 \times g$  and  $(k_u^2; u)$  is horizontal for  $G_2 \rightarrow M \xrightarrow{q_{G_2}} M$  with respect to  $b_2 \times g$ .

**Proof** The proof of (i) is a routine exercise in the definitions which we leave to the reader.

Part (i) gives us a commutative diagram

$$\begin{array}{ccccc}
 G_1 & \times & G_2 & \rightarrow & M & \xrightarrow{id} & q_{G_1 \times G_2} & M & \rightarrow & G_1 \times G_2 & \rightarrow & M \\
 & & \downarrow \text{?} & & \downarrow \text{?} & & \downarrow \text{?} & & \downarrow \text{?} & & & \\
 id & \rightarrow & q_{G_2} & \rightarrow & M & & & & & & & \\
 & & & & & & & & & & & \\
 & & & & G_1 & \rightarrow & M & \xrightarrow{q_{G_1}} & M & & & 
 \end{array}$$

of Riemannian submersions from which (ii) readily follows.

It follows from the diagram that if  $(k_u^1; k_u^2; u)$  is horizontal for  $q_{G_1 \times G_2} : M \rightarrow M$  with respect to  $b_1 \times b_2 \times g$ , then  $(k_u^1; u)$  is horizontal for  $q_{G_1} : M \rightarrow M$  with respect to  $b_1 \times g$  and  $(k_u^2; u)$  is horizontal for  $q_{G_2} : M \rightarrow M$  with respect to  $b_2 \times g$ . This proves the "only if" part of (iii).

The "if" part of (iii) follows from the "only if" part and the observation that  $H_{q_{G_1 \times G_2} : M \rightarrow M} \cap T(G_1 \times G_2) = 0$  via a dimension counting argument.  $\square$



Rather than changing the metric of  $E_{2,0}$  directly with a Cheeger perturbation, we will change the metric on  $Sp(2)$  and then mod out by  $A_{2,0}$ . The constraint to this approach is that the Cheeger perturbations that we use can not destroy the fact that  $A_{2,0}$  is by isometries.

Fortunately it was observed in [8] that if the metric on the  $G$  factor in  $G \times M$  is biinvariant, then  $G$  acts by isometries with respect to  $g_{l_1}$ . Therefore we have the following result.

**Proposition 1.14** *Let  $g_{l_1, l_2, l_1^d, l_1^d}$  denote a metric obtained from the biinvariant metric on  $Sp(2)$  via Cheeger's method using the  $S^3 \times S^3 \times S^3 \times S^3$  action,  $A^u \times A^d \times A^l \times A^r$ .*

*Then  $A^u \times A^d \times A^l \times A^r$  is by isometries with respect to  $g_{l_1, l_2, l_1^d, l_1^d}$ . In particular,  $A_{2,0}$  is by isometries with respect to  $g_{l_1, l_2, l_1^d, l_1^d}$ .*

We include a proof of Proposition 1.14 even though it follows from an assertion on page 624 of [8]. We do this to establish notation that will be used in the sequel, and because the assertion in [8] was not proven.

**Proof** Throughout the paper we will call the tangent spaces to the orbits of  $A^l$  and  $A^r$ ,  $V_1$  and  $V_2$ . The orthogonal complement of  $V_1 \times V_2$  with respect to the biinvariant metric will be called  $H$ . According to Proposition 2.1 in [24],  $Sp(2)$  is diffeomorphic to the pull back of the Hopf fibration  $S^7 \rightarrow S^4$  via  $S^7 \xrightarrow{a} S^4$ , where  $a: S^7 \rightarrow S^4$  is the antipodal map and  $S^7 \rightarrow S^4$  is the Hopf fibration that is given by right multiplication by  $S^3$ . Moreover, the metric induced on the pull back by the product of two unit  $S^7$ 's is biinvariant. Through out the paper our computations will be based on perturbations of the biinvariant metric,  $b_{\frac{1}{2}}$ , induced by  $S^7(\frac{1}{2}) \times S^7(\frac{1}{2})$ , where  $S^7(\frac{1}{2})$  is the sphere of radius  $\frac{1}{2}$ .

Observe that if  $k$  is a killing field on  $S^3$  whose length is 1 with respect to the unit metric, then the corresponding killing field on  $Sp(2)$  with respect to either  $A^l$  or  $A^r$  has length  $\frac{1}{2}$  with respect to  $b_{\frac{1}{2}}$ . It follows from this that the quantity (1.8) is constant when we do a Cheeger perturbation on  $b_{\frac{1}{2}}$  via either  $A^l$  or  $A^r$ . Thus the effect of these Cheeger perturbations is to scale  $V_1$  and  $V_2$ , and to preserve the splitting  $V_1 \times V_2 \times H$  and  $b_{\frac{1}{2}}|_H$ . The amount of the scaling is  $< 1$  and converges to 1 as the scale,  $l_1$ , on the  $S^3$  factor in  $S^3 \times Sp(2)$  converges to  $\infty$  and converges to 0 as  $l_1 \rightarrow 0$ . We will call the

resulting scales on  $V_1$  and  $V_2$ ,  $\rho_1$  and  $\rho_2$ , and call the resulting metric  $g_{1;2}$ . With this convention the biinvariant metric  $b_{\frac{1}{\sqrt{2}}}$  is  $g_{\frac{1}{\sqrt{2}};\frac{1}{\sqrt{2}}}$ .

It follows that  $g_{1;2}$  is the restriction to  $Sp(2)$  of the product metric  $S^7_1 \times S^7_2$  where  $S^7$  denotes the metric obtained from  $S^7(\frac{1}{\sqrt{2}})$  by scaling the fibers of  $h$  by  $\frac{1}{\sqrt{2}}$ . Since  $A^l$  and  $A^r$  are by symmetries of  $h$  in each column, they are by isometries on  $S^7_1 \times S^7_2$  and hence also on  $(Sp(2); g_{1;2})$ .

Let  $g_{I_1^u; I_1^d}$  denote the metric obtained from  $b_{\frac{1}{\sqrt{2}}}$  via the Cheeger perturbation with  $A^u \times A^d$  when the metric on the  $S^3 \times S^3$  factor in  $S^3 \times S^3 \times Sp(2)$  is  $S^3(I_1^u) \times S^3(I_1^d)$ . An argument similar to the one above, using rows instead of columns, shows that  $A^u \times A^d$  is by isometries on  $(Sp(2); g_{I_1^u; I_1^d})$ .

Since  $A^u \times A^d$  commutes with  $A^l \times A^r$ , it follows that  $A^u \times A^d$  acts by isometries on  $(Sp(2); g_{1;2})$ . Doing a Cheeger perturbation with  $A^u \times A^d$  on  $(Sp(2); g_{1;2})$  produces a metric  $g_{1;2; I_1^u; I_1^d}$  which can also be thought of as obtained from  $Sp(2)$  via a single Cheeger perturbation with  $A^l \times A^r \times A^u \times A^d$ . Since  $A^l \times A^r$  acts by isometries on  $(Sp(2); g_{1;2})$  and commutes with  $A^u \times A^d$ ,  $A^l \times A^r$  acts by isometries with respect to  $g_{1;2; I_1^u; I_1^d}$ .

But  $g_{1;2; I_1^u; I_1^d}$  can also be obtained by first perturbing with  $A^u \times A^d$  and then perturbing with  $A^l \times A^r$ . So repeating the argument of the preceding paragraph shows that  $A^u \times A^d$  acts by isometries with respect to  $g_{1;2; I_1^u; I_1^d}$ .  $\square$

It follows that  $q_{2,0}: Sp(2) \rightarrow E_{2,0} = Sp(2)/A_{2,0}$  is a Riemannian submersion with respect to both  $g_{1;2}$  and  $g_{1;2; I_1^u; I_1^d}$ . We will abuse notation and call the induced metrics on  $E_{2,0}$ ,  $g_{1;2}$  and  $g_{1;2; I_1^u; I_1^d}$ .

## 2 Symmetries and their effects on $E_{2,0}$

Since  $A^l \times A^r$  commutes with  $A_{2,0}$  and is by isometries on  $(Sp(2); g_{1;2; I_1^u; I_1^d})$ , it is by isometries on  $(E_{2,0}; g_{1;2; I_1^u; I_1^d})$ . However on the level of  $E_{2,0}$  it has a kernel that at least contains  $\mathbb{Z}_2$ . To see this just observe that the action of  $(-1; -1)$  on  $Sp(2)$  via  $A^l \times A^r$  is the same as the action of  $-1$  via  $A_{2,0}$ . It turns out that the kernel is exactly  $\mathbb{Z}_2$ , and that  $A^l \times A^r$  induces the  $SO(4)$  action whose existence was asserted in Theorem A(i).

**Proposition 2.1** (i)  $A^l$  and  $A^r$  act freely on  $E_{2,0}$ .

- (ii)  $E_{2,0}=A^l$  is diffeomorphic to  $S^4$  and the quotient map  $p_{2,0}: E_{2,0} \rightarrow E_{2,0}=A^l$  is the bundle of type  $(2;0)$ .
- (iii)  $A^r$  acts by symmetries of  $p_{2,0}$ . The induced map on  $S^4$  is the join of the standard  $\mathbb{Z}_2$  effective  $S^3$  action on  $S^2$  with the trivial action on  $S^1$ .
- (iv) The kernel of the action  $A^l \times A^r$  on  $E_{2,0}$  is generated by  $(-1; -1)$ , so  $A^l \times A^r$  induces an effective  $SO(4)$  action on  $E_{2,0}$ .

**Proof** It is easy to see that  $A_{2,0} \times A^l$  and  $A_{2,0} \times A^r$  are free on  $Sp(2)$  and hence that  $A^l$  and  $A^r$  are free on  $E_{2,0}$ , proving (i).

It was observed in [12] that  $Sp(2)/(A_{2,0} \times A^l) = E_{2,0}=A^l$  is diffeomorphic to  $S^4$  and in [20] that  $p_{2,0}$  is the bundle of type  $(2;0)$ . Combining these facts proves (ii).

Part (iii) is a special case of Proposition 5.5 in [24].

It follows from (iii) that if  $(q;p)$  is in the kernel of  $A^l \times A^r$ , then  $p = -1$ . On the other hand,  $A^l$  is the principal  $S^3$  action for  $E_{2,0} \xrightarrow{p_{2,0}} S^4$ . Combining these facts we see that the kernel has order 2, and we observed above that  $(-1; -1)$  is in the kernel. □

The  $O(2)$  action on  $Sp(2)$ ,  $A_{O(2)}: O(2) \rightarrow Sp(2) \rightarrow S(2)$ , that is given by

$$A_{O(2)}: (A; U) \mapsto AU$$

commutes with  $A_{2,0}$  and so is by symmetries of  $q_{2,0}: Sp(2) \rightarrow E_{2,0}$ . Since it also commutes with  $A^l \times A^r$  it acts by isometries on  $(E_{2,0}; g_{1;2})$ . It is also acts by symmetries of  $p_{2,0}$  according to Proposition 5.5 in [24]. We shall see, however, that it is not by isometries on  $(Sp(2); g_{1;2}; I_1^u; I_1^d)$ . (Note that it commutes with neither  $A^u$  nor  $A^d$ . This is one of the central ideas behind the curvature computations in the proof of Theorem A.)

We may nevertheless use  $A_{O(2)}$  to find the 0-curvatures of  $(E_{2,0}; g_{1;2})$ . (We will then use Proposition 1.10 to see that most of them are not 0 with respect to  $g_{1;2}; I_1^u; I_1^d$ .)

A special case of Proposition 5.7 in [24] is the following.

**Proposition 2.2** Every point in  $E_{2,0}$  has a point in its orbit under  $A_{SO(2)}$   $A^l \times A^r$  that can be represented in  $Sp(2)$  by a point of the form

$$\begin{pmatrix} \cos t & \sin t \\ \sin t & \cos t \end{pmatrix} ; \begin{pmatrix} \sin t & \cos t \\ \cos t & \sin t \end{pmatrix} ; \tag{2.3}$$

with  $t \in [0; \frac{\pi}{4}]$ ;  $re(\ ) = 0$  and  $j \cdot j = 1$ .

We will call points of the form (2.3) representative points.

**Notational Convention** We have seen that  $A^r$ ,  $A^l$  and  $A_{SO(2)}$  all induce actions on  $E_{2,0}$ , and that  $A^r$  and  $A_{SO(2)}$  even induce actions on  $S^4$ . To simplify the exposition we will make no notational distinction between these actions and their induced actions. Thus  $A^r$  stands for an action on  $Sp(2)$ ,  $E_{2,0}$ , or  $S^4$ . The space that is acted on will be clear from the context.

### 3 The curvature tensor of $(Sp(2), g_{1;2})$

We will study the curvature of  $(Sp(2), g_{1;2})$  by analyzing the geometry of the riemannian submersion  $p_{2,1}: Sp(2) \rightarrow S^7$  given by projection onto the first column.

The moral of our story is that the geometry of  $p_{2,1}$  resembles the geometry of  $h: S^7 \rightarrow S^4$  very closely.  $p_{2,1}$  is a principal bundle with a "connection metric". That is the metric is of the form

$$h\langle X; Y \rangle_{t;1} = h\langle dp_E(X); dp_E(Y) \rangle_B + t^2 h\langle X; Y \rangle_G$$

where  $G \rightarrow E \xrightarrow{p} B$  is a principal bundle,  $h; \langle \cdot; \cdot \rangle_G$  is a biinvariant metric on  $G$ ,  $h; \langle \cdot; \cdot \rangle_B$  is an arbitrary metric on  $B$ , and  $\tau: VE \rightarrow TE$  is a connection map. In the case of  $p_{2,1}$ ,  $G = S^3$  and the action is given by  $A^r$ .

It will be important for us to understand how the infinitesimal geometry of  $p_{2,1}$  changes as  $t_1$  and  $t_2$  change. Combining 2.1{2.3 of [17] with a rescaling argument we get the following.

**Proposition 3.1** *Let  $G \rightarrow E \xrightarrow{p} B$  be a principal bundle with a connection metric  $h; \langle \cdot; \cdot \rangle_{t;1}$ . Let  $r^t$ ,  $A^t$  and  $R^t$  denote the covariant derivative, A{tensor and curvature tensor of  $h; \langle \cdot; \cdot \rangle_{t;1}$ . If the parameter  $t$  is omitted from the superscript of one of the objects  $r^t$ ,  $A^t$ ,  $R^t$ , or  $h; \langle \cdot; \cdot \rangle_{t;1}$ , then implicitly that parameter has value 1.*

If  $e_1, e_2$  and  $Z$  are horizontal fields and  $U$  and  $V$  are vertical fields, then:

- (i) The fibers of  $p_E$  are totally geodesic.
- (ii)  $A^t_{e_1} e_2 = A_{e_1} e_2$ ,  $A^t_{e_1} U = t^2 A_{e_1} U$ ,  $r^t_{e_1} e_2 = r_{e_1} e_2$ ,  $(r^t_{e_1})^V = (r_{e_1})^V$ ,  $(r^t_{e_1})^U = (r_{e_1})^U$ ,
- (iii)  $hR^t(e_1; e_2) e_2; e_1 i_t = hR^B(dp_E(e_1); dp_E(e_2)) dp_E(e_2); dp_E(e_1) i - 3t^2 kA_{e_1} e_2 k^2$ ,

- (iv)  $hR^t(\cdot; \cdot) ; i_t = t^2 hR(\cdot; \cdot) ; i,$
- (v)  $hR^t(e_1; \cdot) ; e_1 i_t = t^4 k A_{e_1} k^2,$
- (vi)  $hR^t(\cdot; \cdot) U; e_1 i_t = 0,$  and
- (vii)  $hR^t(e_1; e_2) Z; i_t = t^2 hR(e_1; e_2) Z; i.$

The next step is to determine the  $A$  and  $T$  tensors of  $p_{2,1}$ .

The vertical space of  $p_{2,1}$  is

$$V_{p_{2,1}} = f(0; \cdot) \times TSp(2) \times V_h \times V_2;$$

where  $V_h$  is the vertical space for the Hopf fibration  $h: S^7 \rightarrow S^4$  that is given by left quaternionic multiplication. We will also denote vectors in  $V_{p_{2,1}}$  by  $(0; \cdot)$ , and we will often abuse notation and write just  $\cdot$  for  $(0; \cdot)$ .

**The T{tensor}** Given two vector fields,  $(0; \cdot_1), (0; \cdot_2)$ , with values in  $V_{p_{2,1}}$  we compute

$$T_{(0; \cdot_1)}^{p_{2,1}}(0; \cdot_2) = (0; r_{\cdot_1 \cdot_2})^h = (0; 0)$$

since  $V_h$  is totally geodesic. Therefore

$$T = 0; \tag{3.2}$$

**The A{tensor}**  $H_{p_{2,1}}$  splits as the direct sum  $H_{p_{2,1}} = V_1 \oplus H$  where  $V_1$  and  $H$  are as defined on page 339. So any vector field with values in  $H_{p_{2,1}}$  can be written uniquely as  $z + w$  where  $z$  takes values in  $H$  and  $w$  takes values in  $V_1$ . Given two such vector fields  $z_1 + w_1$  and  $z_2 + w_2$  we compute

$$\begin{aligned} A_{z_1 + w_1}^{p_{2,1}}(z_2 + w_2) &= (r_{z_1 + w_1} z_2 + w_2)^v = (r_{z_1} z_2)^v = \\ &= (0; (r_{\frac{S^7}{dp_2^2(z_1)}} dp_2^2(z_2))^v) = (0; \frac{1}{2} [dp_2^2(z_1); dp_2^2(z_2)]^v) = \\ &= (0; r_{\frac{1}{dp_2^2(z_1)}}^1 dp_2^2(z_2)); \end{aligned} \tag{3.3}$$

where  $p_2^2: Sp(2) \rightarrow S^7$  denotes the projection of  $Sp(2)$  onto its last factor. The second equality is due to the fact that a vector in  $V_2$  is 0 in the first entry and a vector in  $V_1$  is 0 in the last entry.

The upshot of (3.2) and (3.3) is that the  $T$  and  $A$  tensors of  $p_{2,1}$  are essentially the  $T$  and  $A$  tensors of  $h$  in the last factor". The only difference is that  $A^{p_{2,1}}$  has a 3-dimensional kernel,  $V_1$ , and  $A^h$  has kernel = 0.

This principal also holds for the vertical  $A$ {tensor. If  $\cdot = (0; \cdot)$  is a vector field with values in  $V_2$  and  $z + w$  is a vector field with values in  $H_{p_{2,1}} = H \oplus V_1$ , then

$$A_{z+w}^{p_{2,1}} = (0; r_{\frac{S^7}{dp_2^2(z)}}^2)^h = 2 \frac{2}{2} (0; r_{\frac{S^7(1)}{dp_2^2(z)}})^h; \tag{3.4}$$

The only components of the curvature tensor of  $Sp(2)$  which are not mentioned in (3.1) are those of the form  $hR(e_1; \cdot)e_2; \cdot$  and  $hR(\cdot; \cdot)e_1; e_2$ . According to formulas  $f_2g$  and  $f_2^l g$  in [18] these are

$$hR(e_1; \cdot)e_2; \cdot = -h(r A)_{e_1} e_2; \cdot - hA_{e_1} \cdot; A_{e_2} \cdot$$

and

$$hR(\cdot; \cdot)e_1; e_2 = -h(r A)_{e_1} e_2; \cdot - hA_{e_1} \cdot; A_{e_2} \cdot + h(r A)_{e_1} e_2; \cdot + hA_{e_1} \cdot; A_{e_2} \cdot \quad (3.5)$$

(We use the opposite sign convention for the curvature tensor than O'Neill.)

If we choose  $e_1$  and  $e_2$  to be basic horizontal fields the first equation simplifies to

$$\begin{aligned} hR(e_1; \cdot)e_2; \cdot &= \\ -hr(A_{e_1} e_2); \cdot + hA_{r_{e_1} e_2}; \cdot + hA_{e_1} r^t e_2; \cdot - hA_{e_1} \cdot; A_{e_2} \cdot &= \\ -hr(A_{e_1} e_2); \cdot - hA_{e_2} (r_{e_1})^h; \cdot + hA_{e_1} (r_{e_2})^h; \cdot - hA_{e_1} \cdot; A_{e_2} \cdot &= \\ -hr(A_{e_1} e_2); \cdot + hA_{e_1} \cdot; A_{e_2} \cdot - hA_{e_2} \cdot; A_{e_1} \cdot - hA_{e_1} \cdot; A_{e_2} \cdot &= \\ -hr(A_{e_1} e_2); \cdot - hA_{e_2} \cdot; A_{e_1} \cdot & \end{aligned} \quad (3.6)$$

where the superscript  $h$  denotes the component in  $H$ . It appears in the formula because the orthogonal complement of  $H$  in the horizontal space for  $p_{2,1}$ ,  $V_1$ , is the kernel of  $A$ .

Similarly (3.5) simplifies to

$$hR(\cdot; \cdot)e_1; e_2 = -hr(A_{e_1} e_2); \cdot - hA_{e_2} \cdot; A_{e_1} \cdot + hr(A_{e_1} e_2); \cdot + hA_{e_2} \cdot; A_{e_1} \cdot \quad (3.7)$$

According to O'Neill, the curvatures with exactly three horizontal terms are

$$\begin{aligned} hR(e_1; e_2)e_3; \cdot &= -h(r_{e_3} A)_{e_1} e_2; \cdot \\ -hr_{e_3}(A_{e_1} e_2); \cdot + hA_{(r_{e_3} e_1)^h} e_2; \cdot + hA_{e_1} (r_{e_3} e_2)^h; \cdot & \end{aligned} \quad (3.8)$$

Through out the rest of this section we will let the superscript  $v$  denote the component in  $V_1$ .

By (3.3) and the fact that the analogous equation holds for the Hopf fibration we have

$$\begin{aligned} hR(e_1^h; e_2^h)e_3^h; \cdot &= \\ -hr_{e_3^h}(A_{e_1^h} e_2^h); \cdot + hA_{(r_{e_3^h} e_1^h)^h} e_2^h; \cdot + hA_{e_1^h} (r_{e_3^h} e_2^h)^h; \cdot &= 0 \end{aligned} \quad (3.9)$$

Of course

$$hR(e_1^V; e_2^V)e_3; \quad i = 0 \tag{3.10}$$

since  $V_1$  is the kernel of  $A$ . Using this again we get

$$hR(e_1^h; e_2^V)e_3^V; \quad i = hA_{e_1^h}(r_{e_3^V}e_2^V)^h; \quad i = 0; \tag{3.11}$$

where the last equality is because  $(r_{e_3^V}e_2^V)^h = 0$ , since the orbits of  $A^h$  are totally geodesic.

Also

$$\begin{aligned} & hR(e_1^h; e_2^V)e_3^h; \quad i = \\ -hr_{e_3^h}(A_{e_1^h}e_2^V); \quad i + hA_{(r_{e_3^h}e_1^h)^h}e_2^V; \quad i + hA_{e_1^h}(r_{e_3^h}e_2^V)^h; \quad i = & \tag{3.12} \\ & hA_{e_1^h}(r_{e_3^h}e_2^V)^h; \quad i = -h(r_{e_3^h}e_2^V)^h; A_{e_1^h} \quad i: \end{aligned}$$

Keeping in mind that  $H$  is the horizontal space for  $h \rho_{2,1}$  and that  $V_1$  is in the vertical space for  $h \rho_{2,1}$  we can rewrite the right hand side of (3.12) and get

$$hR(e_1^h; e_2^V)e_3^h; \quad i = -hA_{e_3^h}^{h \rho_{2,1}}e_2^V; A_{e_1^h} \quad i: \tag{3.13}$$

Using (3.13) and the antisymmetry of the curvature tensor we get

$$hR(e_1^V; e_2^h)e_3^h; \quad i = hA_{e_3^h}^{h \rho_{2,1}}e_1^V; A_{e_2^h} \quad i: \tag{3.14}$$

Combining the first Bianchi identity with (3.13) and (3.14) we find that

$$\begin{aligned} hR(e_1^h; e_2^h)e_3^V; \quad i = -hR(e_3^V; e_1^h)e_2^h; \quad i - hR(e_2^h; e_3^V)e_1^h; \quad i = \\ -hA_{e_2^h}^{h \rho_{2,1}}e_3^V; A_{e_1^h} \quad i + hA_{e_1^h}^{h \rho_{2,1}}e_3^V; A_{e_2^h} \quad i: \end{aligned} \tag{3.15}$$

It turns out that the sum of the two terms on the right is always 0 and hence that

$$hR(e_1^h; e_2^h)e_3^V; \quad i = 0: \tag{3.16}$$

This can be seen by direct computation combining Proposition 4.1 (below) with section 6 of [24], but there are many details to check. A less direct, but much quicker proof begins by using the second equation in 3.1(ii) to observe that the right hand side of (3.15) is  $4 \frac{2}{1} \frac{2}{2}$  times the corresponding curvature quantity for the biinvariant metric. Therefore it suffices to prove (3.16) for the biinvariant metric. To do this observe that distributions  $V_1$  and  $V_2$  have the form

$$V_{1;\mathcal{Q}} = \begin{matrix} L_{\mathcal{Q}} & 0 \\ 0 & 0 \end{matrix} \quad 2\mathbb{H} \text{ and } re(\ ) = 0$$

$$V_{2;Q} = L_Q \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \in 2\mathbb{H} \text{ and } \operatorname{re}(\cdot) = 0;$$

where  $L_Q$  denotes the differential of left translation by  $Q$ .

Thus  $[E_3^V] = 0$ , where  $E_3^V$  and  $\cdot$  denote the extensions of  $e_3^V$  and  $\cdot$  to left invariant fields. Therefore

$$hR(e_1^h; e_2^h)e_3^V; i = -\frac{1}{4}h[E_1^h; E_2^h]; [E_3^V]i = 0;$$

where  $E_1^h$  and  $E_2^h$  denote the extensions of  $e_1^h$  and  $e_2^h$  to left invariant fields, proving (3.16).

Combining (3.10), (3.11), and (3.16) gives us

$$hR(e_1; e_2)e_3^V; i = 0; \tag{3.17}$$

A review of the results of this section shows that the only difference between the infinitesimal geometries of  $h$  and  $p_{2,1}$  is the fact that for  $p_{2,1}$  the terms (3.13) and (3.14) are not always 0 but for  $h$  the curvatures terms with exactly three horizontal vectors are always 0. This is the root cause of many of the 0 curvatures in  $(Sp(2); g_{1; 2})$ .

### 4 The $A\{$ tensor of $h$

In section 3 we showed that the  $A\{$ tensor of  $p_{2,1}$  is essentially the  $A\{$ tensor of the Hopf fibration,  $h$ , in the last factor.  $A^h$  certainly ought to be very well known, but the authors are not aware of any computation of it in the literature. So for completeness we prove the following.

**Proposition 4.1** *Let  $N$  be a point in  $S^7$ .*

(i) *The vertical space of  $h$  at  $N$ ,  $V_{h;N}$ , is*

$$fN \cdot j \in 2\mathbb{H}; \operatorname{re}(\cdot) = 0g;$$

(ii) *If  $z$  is in the horizontal space,  $H_{h;N}$ , for  $h$  at  $N$ , then*

$$A_z^h N = z \cdot$$

**Proof** A proof of this for the case of the complex Hopf fibration can be found in [18]. The proof for the quaternionic case is nearly identical.

(i) is an immediate consequence of the definition  $h$ .



To prove (ii) we let a superscript  $^h$  denote the horizontal component with respect to  $h$  and we compute

$$(r_z^{S^7} N)^h = (r_z^{\mathbb{R}^8} N)^h = ((r_z^{\mathbb{R}^8} N))^h = (z)^h = z;$$

where for the last equality we have used the fact that  $H_{h;N}$  is invariant under right quaternionic multiplication.  $\square$

### 5 The Curvature of Generic Planes in $Sp(2)$

Because the metric  $g_{1;2}$  is a simpler metric than  $g_{1;2}^{u;v}$ , we study its 0 curvatures in this section. Where all statements about curvatures of  $Sp(2)$  are understood to be with respect to  $g_{1;2}$ , for some  $1;2 < \frac{1}{2}$ .

A plane  $P$  tangent to  $Sp(2)$  has the form

$$P = \text{span}\{z + w; v + vg\} \tag{5.1}$$

where  $z; 2 H$  and  $w; v \in V_1 \cup V_2$ .

**Theorem 5.2**

- (i) *The curvature of  $P$  is positive if the projection of  $P$  on to one of  $H, V_1,$  or  $V_2$  is two dimensional.*
- (ii) *If all three projections in (i) are degenerate, then the curvature of  $P$  is 0, if its projection onto  $H$  is 0.*
- (iii) *If all three projections in (i) are degenerate and the projection of  $P$  onto  $H$  is one dimensional, then we may assume that  $z \notin 0$  and  $v = 0$ . The curvature of  $P$  is positive unless*

$$A_z^h \rho_{2;1} v^1 + A_z^{\rho_{1;2}} v^2 = 0; \tag{5.3}$$

- (iv) *If all of the hypotheses of (iii) hold and (5.3) holds, then the curvature of  $P$  is 0.*

**Remark** Since  $v^2$  is vertical for  $h \rho_{1;2}$  and  $A_z^{\rho_{1;2}} v^2 = A_z^h \rho_{1;2} v^2$ , (5.3) can be thought of as  $A_z^h \rho_{1;2} (v^1 + v^2) = 0$ . Since the fibers of  $h \rho_{1;2}$  are totally geodesic this version of (iii) is a corollary of 3.1(v). We give an alternative proof below.

**Proof of (iii) and (iv)** If the projection of  $P$  onto  $H$ ,  $V_1$  and  $V_2$  is degenerate, then by replacing the second vector with the appropriate linear combination of the vectors in (5.1) we may assume that  $P$  has the form

$$P = \text{span}\{z + w^1 + w^2; v^1 + v^2\}g; \tag{5.4}$$

where  $w^1; v^1 \in V_1$  and  $w^2; v^2 \in V_2$  are multiples of each other.

By replacing the first vector in (5.4) by the appropriate vector in  $P$  we can further assume that  $w^2 = 0$ , so  $P$  has the form

$$P = \text{span}\{z + w^1; v^1 + v^2\}g;$$

where  $w^1$  and  $v^1$  are multiples of each other.

It follows that

$$\begin{aligned} & h R(z + w^1; v^1 + v^2) v^1 + v^2; z + w^1 i = \\ & h R(z; v^1) v^1; z i + 2h R(z; v^1) v^2; z i + h R(z; v^2) v^2; z i = \\ & k A_z^{h \rho_{2;1}} v^1 k^2 + 2h A_z^{h \rho_{2;1}} v^1; A_z^{\rho_{1;2}} v^2 i + k A_z^{\rho_{1;2}} v^2 k^2 = \tag{5.5} \\ & k A_z^{h \rho_{2;1}} v^1 + A_z^{\rho_{1;2}} v^2 k^2; \end{aligned}$$

where we have used the results of section 3 to conclude that many terms are 0.

(iii) and (iv) follow from (5.5). □

**Notation** Since the  $A$ {tensors in (5.5) are essentially the  $A$ {tensors of  $h$  in the first and second factor we will shorten the notation and set

$$\begin{aligned} A^1 &= A^{h \rho_{2;1}} \text{ and} \\ A^2 &= A^{\rho_{1;2}}; \end{aligned}$$

and we will denote the inner product in (5.5) by

$$h A_z^{h \rho_{2;1}} v^1; A_z^{\rho_{1;2}} v^2 i = h A_z^1 v^1; A_z^2 v^2 i_a;$$

The idea behind this notation is that we are taking a certain type of inner product between the  $A$ {tensors of  $h$  in the first and second factors. The subscript  $_a$  is meant to remind us of the role that the antipodal map of  $S^4$  plays in determining this inner product.

**Proof of (i)** If the projection of  $P$  onto either  $V_1$  or  $V_2$  is nondegenerate, then according to 1.10(iii) the curvature of  $P$  is positive.

So we may assume that the projection of  $P$  onto  $H$  is nondegenerate and the projections onto both  $V_1$  and  $V_2$  are degenerate. Since the projection of  $P$  onto

$V_2$  is degenerate we may replace the first vector with another vector in  $P$  that satisfies

$$w^2 = 0; \tag{5.6}$$

Since the projection onto  $V_1$  is also degenerate we may replace our vectors by appropriate linear combinations to get that either

$$v^1 = 0 \text{ or } w^1 = 0; \tag{5.7}$$

If  $v^1 = 0$ ,  $P$  is spanned by

$$fz + w^1; + v^2g;$$

It follows that

$$\begin{aligned} & hR(z + w^1; + v^2) + v^2; z + w^1 i_{g_{1;2}} \\ & \quad jz^{\flat}j \text{ }^{\flat}j^{\flat} + jA^1w^1j^{\flat} + jA_z^2v^2j^{\flat} + \\ & hR(z; )v^2; w^1i + hR(z; v^2) ; w^1i + hR(w^1; v^2) ; zi + hR(w^1; )v^2; zi + \\ & \quad hR(z; v^2)v^2; w^1i + hR(w^1; v^2)v^2; zi; \end{aligned}$$

where  $\text{ }^{\flat}$  denotes the component of that is perpendicular to  $z$ , and we have relied heavily on results of the previous two sections to conclude that many of the components of this curvature are 0.

Using (3.17) and the symmetries of the curvature tensor we see that the fourth and the sixth terms on the right are 0. The last two terms are also 0. One way to see this is to combine (3.6) with the fact that  $w^1$  is in the kernel of  $A^{p_{2;1}}$ .

Use (3.13) to evaluate the other two terms to get

$$\begin{aligned} & hR(z + w^1; + v^2) + v^2; z + w^1 i_{g_{1;2}} \\ & \quad jz^{\flat}j \text{ }^{\flat}j^{\flat} + jA^1w^1j^{\flat} + jA_z^2v^2j^{\flat} - 2hA_z^1w^1; A v^2i_a; \end{aligned} \tag{5.8}$$

For  $2 TSp(2)$  let  $j j_{1;1} = jdp_{2;1} j_1$  and  $j j_{1;2} = jdp_2^2 j_1$  where  $j j_1$  denotes the unit norm on  $S^7$ . Combining 3.1(v), (3.4) and (4.1) and meticulously chasing through the definitions we get that

$$\begin{aligned} & jA^1w^1j^{\flat} = \frac{4}{1} j j_{1;1}^{\flat} jw^1j_{1;1}^{\flat}; \\ & \quad jA_z^2v^2j^{\flat} = \frac{4}{2} jzj_{1;2}^{\flat} jv^2j_{1;2}^{\flat}; \text{ and} \\ & \quad j 2hA_z^1w^1; A v^2i_a j \text{ }^2 \frac{2}{1} \frac{2}{2} j j_{1;1} jw^1j_{1;1} jzj_{1;2} jv^2j_{1;2}; \end{aligned} \tag{5.9}$$

From (5.9) we see that sum of the last three terms in (5.8) is always nonnegative so

$$hR(z + w^1; + v^2) + v^2; z + w^1 i_{g_{1;2}} \quad jz^{\flat}j \text{ }^{\flat}j^{\flat} > 0; \tag{5.10}$$

where the last inequality is due to our hypothesis that the projection of  $P$  onto  $H$  is nondegenerate.

It remains to consider the case  $w^1 = 0$  in (5.7). If so, our plane is spanned by

$$fz; + v^1 + v^2 g;$$

Arguing as in (5.8) and (5.10) we can show that

$$\begin{aligned} hR(z; + v^1 + v^2) + v^1 + v^2; zi \\ jz^2 j^2 + jA_z^1 v^1 j^2 + jA_z^2 v^2 j^2 + 2hA_z^1 v^1; A_z^2 v^2 i_a \\ jz^2 j^2 > 0: \end{aligned} \quad \square$$

**Proof of (ii)** If  $P = spanfv^1; w^2 g$  where  $v^1 \in V_1$  and  $w^2 \in V_2$ , then  $curv(P) = 0$  because the  $T$ {tensor of  $\rho_{2,1}$  is 0 and  $V_1$  is the kernel of the  $A$ {tensor of  $\rho_{2,1}$ . □

## 6 Horizontal space of $q_{2,0}$

From this point forward we will use the notation from section 6 in [24] for specific tangent vectors to  $Sp(2)$ . Recall that  $t \in [0; \frac{\pi}{4}]$  is one of the coordinates of our representative points (see Proposition 2.3).

**Proposition 6.1** For  $t \in [0; \frac{\pi}{4})$  the horizontal space of  $q_{2,0}$  with respect to  $g_{1;2}$  is spanned by

$$\begin{aligned} f(x; x); (-y; y); (v_1; 1 + \tan(2t)\frac{\#_1}{2}); (v_2; 2 + \tan(2t)\frac{\#_2}{2}); \\ (-\frac{v}{1}; \frac{v}{2}); (-\frac{\#_1}{1}; \frac{\#_1}{2}); (-\frac{\#_2}{1}; \frac{\#_2}{2}) g; \end{aligned}$$

**Notation** We will call the seven vectors in (6.1)  $x^{2,0}; y^{2,0}; \frac{2,0}{1}; \frac{2,0}{2}; v^{2,0}; \frac{\#_1^{2,0}}{1};$  and  $\frac{\#_2^{2,0}}{2}$  respectively. We will call the set consisting of the first four  $basis(H_{2,0})$ , and the set consisting of the last three  $basis(V_{2,0})$ .

**Sketch of Proof** The proof is just straight forward computations of inner products. Many of the required computations were done in Proposition 6.5 of [24]. □

A corollary of 5.2(i) is the following.

**Corollary 6.2** Let  $P$  be a plane in  $E_{2,0}$  whose  $t$ -coordinate is in  $[0; \frac{1}{4})$ .

If the horizontal lift of  $P$  with respect to  $g_{1;2}$  has a nondegenerate projection onto either  $H_{2,0}$  or  $V_{2,0}$ , then  $P$  is positively curved with respect to  $g_{1;2}$ .

**Proof** We will combine Theorem 5.2(i) with the following observations.

(a) Any plane in  $H_{2,0}$  has a nondegenerate projection (with respect to the splitting  $H = V_1 \oplus V_2$ ) onto  $H$ .

(a<sup>0</sup>)  $V_{2,0} = V_1 \oplus V_2$ .

It follows from (a) and (a<sup>0</sup>) that if the projection of  $P$  onto  $H_{2,0}$  is nondegenerate, then so is the projection onto  $H$  (with respect to the splitting  $H = V_1 \oplus V_2$ ).

(b) Any plane in  $V_{2,0}$  has a nondegenerate projection (with respect to the splitting  $H = V_1 \oplus V_2$ ) onto  $V_1$ .

(b<sup>0</sup>)  $H_{2,0} = H \oplus V_2$ .

It follows from (b) and (b<sup>0</sup>) that if the projection of  $P$  onto  $V_{2,0}$  is nondegenerate, then so is the projection of  $P$  onto  $V_1$  (with respect to the splitting  $H = V_1 \oplus V_2$ ). □

**Proposition 6.3** For  $t = \frac{1}{4}$  the horizontal space of  $q_{2,0}$  with respect to  $g_{1;2}$  is spanned by

$$\begin{aligned} &(x; x); (-y; y); (0; \frac{\#_1}{2}); (0; \frac{\#_2}{2}); \\ &(-\frac{v}{2}; \frac{v}{2}); (-\frac{\#_1}{2}; \frac{\#_1}{2}); (-\frac{\#_2}{2}; \frac{\#_2}{2}); \end{aligned}$$

**Sketch of proof** Again the proof is just straight forward computations of inner products. In fact the computations that proved (6.1) will suffice for all of the vectors except  $(0; \frac{\#_1}{2})$  and  $(0; \frac{\#_2}{2})$ . These are just multiples of the limits of  $\frac{2,0}{j_1^2; j}$  and  $\frac{2,0}{j_2^2; j}$  as  $t \rightarrow \frac{1}{4}$ . □

**Notational Convention** Let  $\pi : M \rightarrow B$  be a riemannian submersion. To simplify the exposition we will make no notational distinction between a vector that is tangent to  $B$  and its horizontal lift to  $M$ .

**Remark** Since the seven vectors listed in (6.3) are limits of (function multiples of) the seven vectors listed in (6.1) we will call them  $x^{2,0}; y^{2,0}; \frac{2,0}{1}; \frac{2,0}{2}$ ,

$v^{2,0}$ ,  $\#_1^{2,0}$ ; and  $\#_2^{2,0}$ . Notice that via  $q_{2,0}$ ,  $\rho_{2,0}$ ,  $x^{2,0}$  and  $y^{2,0}$  project to the unit normals of  $S_{im}^2$ , where  $S_{im}^2$  is the 2-sphere in  $S^4$  that is fixed by the action induced on  $S^4$  by  $A^r$  via  $\rho_{2,0}: E_{2,0} \rightarrow S^4$  (cf the notational remark in section 6 of [24]). Because of this their definitions do not seem to be very canonical when  $t = \frac{1}{4}$ . The approach we have taken is to define them at representative points with  $t = \frac{1}{4}$  as extensions of their definitions at representative points when  $t$  is generic. We will extend these definitions (as needed) to all points with  $t = \frac{1}{4}$  by letting the isometry group act.

Also notice that the vectors  $(\frac{\#_1}{1}; 0); (\frac{\#_2}{1}; 0)$  are in  $H_{q_{2,0}}$  when  $t = \frac{1}{4}$ . Notice furthermore that at  $t = \frac{1}{4}$

$$curv_{1; 2}((\frac{\#_i}{2}; 0); \frac{2,0}{j}) = 0; \tag{6.4}$$

for any  $(\frac{\#_i}{2}; 0) \in \text{span}\{(\frac{\#_1}{2}; 0); (\frac{\#_2}{2}; 0)\}g$  and any  $\frac{2,0}{j} \in \text{span}\{f_{1; 2}^{2,0}; \frac{2,0}{2}g\}$ . Here and in the sequel  $curv(v; w)$  stands for  $\langle R(v; w)w; v \rangle$ .

### 7 Zero Curvatures of $(E_{2,0}; g_{1; 2})$ and $(E_{2,0}; g_{1; 2}; l_1^u; l_1^d)$

It follows from (6.2) that any 0-curvature planes for  $(E_{2,0}; g_{1; 2})$  have the form

$$P = \text{span}\{v; w\}; \tag{7.1}$$

where  $v \in H_{2,0}$ ,  $w \in V_{2,0}$  and  $t \in [0; \frac{1}{4})$ . About such planes we will prove the following.

**Proposition 7.2**

- (i) For  $t \in [0; \frac{1}{4})$  the 0-curvature planes of  $(E_{2,0}; g_{1; 2})$  satisfy (7.1) and also,

$$\begin{aligned} & \in \text{span}\{x^{2,0}; y^{2,0}\}g \\ & w \in \text{span}\{\#^{2,0}\}g; \end{aligned} \tag{7.3}$$

where  $\frac{2,0}{z}$  is a convex combination of  $f_{1; 2}^{2,0}; \frac{2,0}{2}g$  and  $\#^{2,0}$  is the same convex combination of  $f_{1; 2}^{2,0}; \#_2^{2,0}g$ .

- (ii) When  $t = \frac{1}{4}$  the planes of the form (6.4) have 0 curvature in  $Sp(2)$  with respect to  $g_{1; 2}$ , and, in addition, given any convex combination  $z$  of  $f_{1; 2}^{2,0}; y^{2,0}g$  and any convex combination  $w$  of  $f(-\frac{\#_1}{1}; 0); (-\frac{\#_2}{1}; 0)g$ ,

there is a unique convex combination  $v_{W;Z}$  of  $f(0; \frac{\#_1}{1}); (0; \frac{\#_2}{1})g$ , so that

$$\text{CURV}_{(Sp(2);g)}(z + w; w + v_{W;Z}) = 0 \tag{7.4}$$

for all  $z \in \mathbb{R}$ .

There are no other zero curvatures when  $t = \frac{1}{4}$ .

**Proof** To prove (i) split  $\gamma = z + w$  where  $z \in \text{span}\{x^{2,0}; y^{2,0}\}g$  and  $w \in \text{span}\{f_1^{2,0}; f_2^{2,0}\}g$ . To be more concrete suppose that  $w$  is a multiple of  $f_1^{2,0}$ .

Suppose  $w$  has the form  $w = (-\frac{N_1}{1}; \frac{N_2}{2})$  for some purely imaginary unit quaternion  $i$ . Notice that

$$hA_{y^{2,0}}^1(-\frac{N_1}{1}); A_{y^{2,0}}^2 \frac{N_2}{2} i = 1; \tag{7.5}$$

and

$$hA_{y^{2,0}}^1(-\frac{N_1}{1}); A^2 \frac{N_2}{2} i = hA^1(-\frac{N_1}{1}); A_{y^{2,0}}^2 \frac{N_2}{2} i = 0; \tag{7.6}$$

if  $\gamma \in \text{span}\{x^{2,0}; f_1^{2,0}; f_2^{2,0}\}g$ . Combining 5.2(iii),(iv) with (7.5) and (7.6) we get that the curvature of  $P$  is positive except possibly if  $\gamma \in \text{span}\{x^{2,0}\}g$ .

On the other hand, the projection of  $P$  onto  $V_2$  is nondegenerate unless  $\gamma = 0$  or

$$p_{V_2}(\gamma) \text{ and } p_{V_2}(w) \text{ are multiples of each other.} \tag{7.7}$$

So  $P$  is positively curved unless  $\gamma = 0$  or  $w$  is a multiple of the same convex combination of  $f_1^{2,0}; f_2^{2,0}g$  as  $\gamma$  is of  $f_1^{2,0}; f_2^{2,0}g$ .

To complete the proof of (i) it remains to consider the case when  $\gamma = x^{2,0}$  in which it is easy to see, using 5.2(iii),(iv) that  $P$  is positively curved unless  $w \in \text{span}\{f_1^{2,0}; f_2^{2,0}\}g$ .

We saw in (6.3) that at points where  $t = \frac{1}{4}$ ,

$$H_{q_{2,0}} = \text{span}\{f(x; x); (-y; y); (0; \frac{\#_1}{2}); (0; \frac{\#_2}{2}); (-\frac{v}{1}; \frac{v}{2}); (-\frac{\#_1}{1}; 0); (-\frac{\#_2}{1}; 0)\}g; \tag{7.8}$$

Using (7.8) it is easy to see that the only planes in  $H_{q_{2,0}} \setminus (V_1 \cup V_2)$  whose projections onto both  $V_1$  and  $V_2$  are degenerate are those of the form (6.4).

It follows that the only other possible 0's are of the type described in 5.2(iii), (iv). Combining this with straightforward computations of  $A$ {tensors completes the proof of (ii), and even supplies explicit solutions for  $v_{W;Z}$  in terms of  $W$  and  $Z$ . For example when  $Z = x^{2,0}$  and  $W = (-\frac{\#1}{2}; 0)$ ,  $v_{W;Z} = (0; \frac{\#1}{2})$ , and when  $Z = y^{2,0}$  and  $W = (-\frac{\#1}{1}; 0)$ ,  $v_{W;Z} = (0; -\frac{\#1}{2})$ . □

**Remark** We have shown that the planes in (7.2) have 0 curvature in  $(Sp(2); g_{1;2})$ . They also have zero curvature in  $(E_{2,0}; g_{1;2})$ . To verify this we have to evaluate the  $A$ {tensor of  $q_{2,0}$  on these planes. It turns out that it is 0. We will not verify this since most of these planes become positively curved with respect to  $g_{1;2;l_1^u;l_1^d}$ .

Now we study the zero curvatures of  $(E_{2,0}; g_{1;2;l_1^u;l_1^d})$ . To do this we adopt the following convention.

**Notational Convention** Let  $H_{q_{2,0}; g_{1;2}}$  denote the horizontal space of  $q_{2,0}$  with respect to  $g_{1;2}$  and  $H_{q_{2,0}; g_{1;2;l_1^u;l_1^d}}$  the horizontal space of  $q_{2,0}$  with respect to  $g_{1;2;l_1^u;l_1^d}$ . Let  $q_{A^u A^d}^{diag}: S^3 \rightarrow S^3 \times Sp(2) \rightarrow Sp(2)$  be the quotient map given in (1.1) for  $A^u = A^d$ . According to (1.12)  $P$  is in  $H_{q_{2,0}; g_{1;2}}$  if and only if  $dq_{A^u A^d}^{diag}(\dot{P})$  is in  $H_{q_{2,0}; g_{1;2;l_1^u;l_1^d}}$ . To keep the notation simpler we will think of this correspondence as a parameterization of  $H_{q_{2,0}; g_{1;2;l_1^u;l_1^d}}$  by  $H_{q_{2,0}; g_{1;2}}$  and we will denote vectors and planes in  $H_{q_{2,0}; g_{1;2;l_1^u;l_1^d}}$  by the corresponding vectors and planes in  $H_{q_{2,0}; g_{1;2}}$ . We will do this without any further mention or change in notation. For example  $x^{2,0}$  now stands for  $dq_{A^u A^d}^{diag}(x^{2,0})$ .

With this convention it follows from 1.10(i) that the zero curvatures of  $g_{1;2;l_1^u;l_1^d}$  are a subset of the zero curvatures of  $g_{1;2}$ . We will show that most of the planes in (7.2) have nondegenerate projections onto the orbits of  $A^u$  and hence are positively curved with respect to  $g_{1;2;l_1^u;l_1^d}$  according to 1.10(iii). The root cause of this is that  $A_{SO(2)}$  is not by isometries with respect to  $g_{1;2;l_1^u;l_1^d}$ . This seems extremely plausible because  $A_{SO(2)}$  commutes with neither  $A^u$  nor  $A^d$ . A rigorous proof that it does not act by isometries follows from our curvature computations.

In any case we no longer know that  $A_{SO(2)}$  is by isometries, so (2.3) are no longer our representative points.

The representative points are now

$$\begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} ; \begin{pmatrix} \cos t & \sin t \\ \sin t & \cos t \end{pmatrix} =$$



$$\begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} ; \quad \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} ; \quad (N_1(\cdot); N_2(\cdot)); \quad (7.9)$$

for all  $t \in [0; \frac{\pi}{4}]$  and for all  $\lambda \in [0; 1]$ . The interval for  $\lambda$  is  $[0; 1]$  because  $A_{SO(2)}$  is  $\mathbb{Z}_2$  {invariant}.

Using this we will show the following.

**Proposition 7.10** For any  $t \in [0; \frac{\pi}{4})$  the planes of the form

$$P = \text{span}\{f^{2,0}; \#^{2,0}g\} \quad (7.11)$$

have positive curvature with respect to  $g$  unless  $\lambda = 0; \frac{3}{4};$  or  $\frac{\pi}{2}$ .

Here  $f^{2,0}$  and  $\#^{2,0}$  stand for (the same) convex combinations of  $f_1^{2,0}; \frac{2,0}{2}g$  and  $f_{\#_1}^{2,0}; \#_2^{2,0}g$  respectively.

**Proof** The main idea is that most planes are eliminated because their projection onto the orbits of  $A^U$  are nondegenerate. Combining 1.10(iii) with (1.13) we see that it is actually enough to check that a projection is degenerate with respect to  $b_{\frac{\pi}{2}}$ .

The tangent space to the orbit of  $A^U$  is spanned by the  $b_{\frac{\pi}{2}}$  {orthogonal basis

$$\begin{pmatrix} fU; U_1; U_2g \\ \begin{pmatrix} \cos t & \sin t \\ 0 & 0 \end{pmatrix} ; \quad \begin{pmatrix} \cos t & \sin t \\ 0 & 0 \end{pmatrix} ; \\ \lambda_1 \begin{pmatrix} \cos t & \sin t \\ 0 & 0 \end{pmatrix} ; \quad \lambda_1 \begin{pmatrix} \cos t & \sin t \\ 0 & 0 \end{pmatrix} ; \\ \lambda_2 \begin{pmatrix} \cos t & \sin t \\ 0 & 0 \end{pmatrix} ; \quad \lambda_2 \begin{pmatrix} \cos t & \sin t \\ 0 & 0 \end{pmatrix} \end{pmatrix} ; \quad (7.12)$$

where  $\lambda_1$  and  $\lambda_2$  are purely imaginary, unit quaternions that satisfy  $\lambda_1 \lambda_2 = 1$ .

Before we can find the projections we also need a formula for  $(\lambda_1; \lambda_2)$  along the orbits of  $A_{SO(2)}$ . At points of the form (7.9)  $(\lambda_1; \lambda_2)$  is

$$\begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} ; \quad \begin{pmatrix} -\lambda_1 \sin t & \lambda_2 \cos t \\ \lambda_2 \cos t & -\lambda_1 \sin t \end{pmatrix} = \\ \begin{pmatrix} -\lambda_1 \cos t & \lambda_2 \sin t \\ \lambda_1 \sin t & \lambda_2 \cos t \end{pmatrix} ; \quad \begin{pmatrix} \lambda_2 \cos t & -\lambda_1 \sin t \\ -\lambda_2 \sin t & \lambda_1 \cos t \end{pmatrix} ;$$

To find the projections we compute

$$\begin{aligned}
 & h(\begin{matrix} 1 \\ 1 \end{matrix}); U_1 i = \\
 & \begin{matrix} -1 \cos \sin t + 2 \sin \cos t \\ 1 \sin \sin t + 2 \cos \cos t \\ 1 \cos \cos t - 2 \sin \sin t \\ 0 \end{matrix} ; \begin{matrix} 2 \cos \cos t - 1 \sin \sin t \\ -2 \sin \cos t - 1 \cos \sin t \\ -2 \cos \sin t + 1 \sin \cos t \\ 0 \end{matrix} ; \\
 & = \\
 & \frac{1}{2} ( -\cos^2 \sin t \cos t - \sin^2 \cos t \sin t - \cos^2 \sin t \cos t - \sin^2 \cos t \sin t ) = \\
 & -\sin t \cos t = -\frac{1}{2} \sin 2t; \quad (7.13)
 \end{aligned}$$

According to (6.1) we should compute the inner products of  $(-\frac{\#_1}{\#_2}; \frac{\#_1}{\#_2})$  and  $(-\frac{\#_2}{\#_1}; \frac{\#_2}{\#_1})$  with the vectors in (7.12) with respect to  $b_{\frac{1}{\sqrt{2}}}$ . These are the same as the inner products of  $(-\#_1; \#_1)$  and  $(-\#_2; \#_2)$  with the vectors in (7.12) with respect to  $b_1$ , where  $b_1 = 2b_{\frac{1}{\sqrt{2}}}$ . We will compute the latter inner products since the notation is simpler. We will only do this explicitly for  $(-\#_1; \#_1)$ , since the computations for  $(-\#_2; \#_2)$  are the same modulo obvious changes in notation.

$$\begin{aligned}
 & h(0; \#_1); U_1 i = \\
 & \begin{matrix} 0 \\ 0 \end{matrix} ; \begin{matrix} 2 \cos \sin t + 1 \sin \cos t \\ Blah \\ -2 \cos \sin t + 1 \sin \cos t \\ 0 \end{matrix} ; \\
 & \begin{matrix} 1 \cos \cos t - 2 \sin \sin t \\ 0 \end{matrix} ; \\
 & = \\
 & -\cos^2 \sin^2 t + \sin^2 \cos^2 t; \quad (7.14)
 \end{aligned}$$

where "Blah" stands for a nonzero, but irrelevant term.

Combining the previous 2 equations we get

$$h \begin{matrix} 2,0 \\ 1 \end{matrix}; U_1 i = -\frac{1}{2} \sin 2t + \tan(2t) ( -\cos^2 \sin^2 t + \sin^2 \cos^2 t ) \quad (7.15)$$

$$\begin{aligned}
 & hU_1; (-\#_1; 0) i = \\
 & \begin{matrix} 1 \cos \cos t - 2 \sin \sin t \\ 0 \end{matrix} ; \begin{matrix} -2 \cos \sin t + 1 \sin \cos t \\ 0 \\ -1 \cos \cos t - 2 \sin \sin t \\ Blah \\ -\cos^2 \cos^2 t + \sin^2 \sin^2 t \end{matrix} ; \\
 & = \\
 & -\cos^2 \cos^2 t + \sin^2 \sin^2 t; \quad (7.16)
 \end{aligned}$$

Combining (7.14) and (7.16) we get

$$h(-\#_1; \#_1); U_1 i =$$

$$\begin{aligned}
 & -\cos^2 \sin^2 t + \sin^2 \cos^2 t - \cos^2 \cos^2 t + \sin^2 \sin^2 t = \\
 & -\cos^2 (\sin^2 t + \cos^2 t) + \sin^2 (\cos^2 t + \sin^2 t) = \\
 & -\cos 2t : \tag{7.17}
 \end{aligned}$$

$$\begin{aligned}
 & hU_{2'} : ( \#_1 ; \#_1 ) i = \\
 & \begin{matrix} 2 \cos & \cos t + & 1 \sin & \sin t \\ & 0 & & \end{matrix} ; \begin{matrix} 1 \cos & \sin t + & 2 \sin & \cos t \\ & 0 & & \end{matrix} ; \\
 & - \begin{matrix} 1 \cos & \sin t + & 2 \sin & \cos t \\ 1 \sin & \sin t + & 2 \cos & \cos t \end{matrix} ; \begin{matrix} 2 \cos & \cos t - & 1 \sin & \sin t \\ - 2 \sin & \cos t - & 1 \cos & \sin t \end{matrix} = \\
 & \frac{1}{2} ( \cos^2 t \cos \sin - \sin^2 t \cos \sin - \sin^2 t \cos \sin + \cos^2 t \cos \sin ) = \\
 & \frac{1}{4} \sin 2 ( 2 \cos^2 t - 2 \sin^2 t ) = \\
 & \frac{1}{2} \sin 2 \cos 2t : \tag{7.18}
 \end{aligned}$$

$$\begin{aligned}
 & hU_{2'} : ( 0 ; \#_1 ) i = \\
 & \begin{matrix} 2 \cos & \cos t + & 1 \sin & \sin t \\ & 0 & & \end{matrix} ; \begin{matrix} 1 \cos & \sin t + & 2 \sin & \cos t \\ & 0 & & \end{matrix} ; \\
 & \begin{matrix} 0 \\ 0 \end{matrix} ; \begin{matrix} 2 \cos & \sin t + & 1 \sin & \cos t \\ & \text{blah} & & \end{matrix} = \\
 & 2 \sin \cos \sin t \cos t = \frac{1}{2} \sin 2 \sin 2t : \tag{7.19}
 \end{aligned}$$

Combining (7.18) and (7.19) we get

$$\begin{aligned}
 & hU_{2'} : ( \#_1 ; \#_1 ) i = \\
 & \frac{1}{2} \sin 2 \cos 2t + \frac{1}{2} \tan 2t \sin 2 \sin 2t = \\
 & \frac{\sin 2}{2} ( \cos 2t + \tan 2t \sin 2t ) : \tag{7.20}
 \end{aligned}$$

$$\begin{aligned}
 & hU_{2'} : ( -\#_1 ; 0 ) i = \\
 & \begin{matrix} 2 \cos & \cos t + & 1 \sin & \sin t \\ & 0 & & \end{matrix} ; \begin{matrix} 1 \cos & \sin t + & 2 \sin & \cos t \\ & 0 & & \end{matrix} ; \\
 & - \begin{matrix} 1 \cos & \cos t - & 2 \sin & \sin t \\ & \text{Blah} & & \end{matrix} ; \begin{matrix} 0 \\ 0 \end{matrix} = \\
 & -2 \cos \sin \cos t \sin t = -\frac{1}{2} \sin 2 \sin 2t : \tag{7.21}
 \end{aligned}$$

Combining (7.19) and (7.21) we see that

$$h( -\#_1 ; \#_1 ) ; U_{2'} i = 0 : \tag{7.22}$$

Combining (7.17), (7.20), and (7.22) we see that the projection of  $P$  onto  $TO_{A^u}$  is nondegenerate unless  $\cos 2\theta = 0$  or  $\sin 2\theta = 0$ , proving the proposition.  $\square$

**Remark** One might hope to show that the planes from (7.10) with  $\theta = 0; \frac{\pi}{4}; \frac{\pi}{2}$ , and  $\frac{3\pi}{4}$  are positively curved by studying the projections onto  $TO_{Ad}$ . These are also nondegenerate for most values of  $\theta$ . Unfortunately they are degenerate precisely when  $\theta = 0; \frac{\pi}{4}; \frac{\pi}{2}$ , and  $\frac{3\pi}{4}$ .

**Proposition 7.23** Let  $X^{2,0}$  and  $\#^{2,0}$  be as in (7.10). For  $t \in [0; \frac{\pi}{4})$  if

$$P = \text{span}\{f; \#^{2,0}g\} \tag{7.24}$$

where  $X^{2,0} = \text{span}\{X^{2,0}; \#^{2,0}g\}$ , then the curvature of  $P$  is positive with respect to  $g_{1; 2; 1^u; 1^d}$  unless  $\theta = 0; \frac{\pi}{4}; \frac{\pi}{2}$  or  $\frac{3\pi}{4}$ .

**Proof** Along the orbit of  $SO(2)$  the formula for  $X^{2,0}$  is

$$\begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} \begin{pmatrix} -\sin t \\ \cos t \end{pmatrix} ; \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} = \begin{pmatrix} -\cos t \sin t + \sin t \cos t \\ \sin t \sin t + \cos t \cos t \end{pmatrix} ; \begin{pmatrix} \cos t \cos t - \sin t \sin t \\ -\sin t \cos t - \cos t \sin t \end{pmatrix} :$$

So

$$\begin{aligned} hU; X^{2,0}i &= \begin{pmatrix} \cos t \cos t - \sin t \sin t \\ 0 \end{pmatrix} ; \begin{pmatrix} -\cos t \sin t + \sin t \cos t \\ 0 \end{pmatrix} ; \\ &= \begin{pmatrix} -\cos t \sin t + \sin t \cos t \\ \sin t \sin t + \cos t \cos t \end{pmatrix} ; \begin{pmatrix} \cos t \cos t - \sin t \sin t \\ -\sin t \cos t - \cos t \sin t \end{pmatrix} = \\ &= \frac{1}{2}(\cos^2 t \sin^2 \cos^2 + \sin^2 t \cos^2 \sin^2 + \sin^2 t \cos^2 \sin^2 + \cos^2 t \sin^2 \cos^2) = \\ &= \frac{1}{2} \sin 2\theta ; \tag{7.25} \end{aligned}$$

Similar computations show that

$$hU; X^{2,0}i = hU; \#^{2,0}i = hU; \#^{2,0}i = 0: \tag{7.26}$$

Combining (7.17), (7.25), and (7.26) we see that the projection of  $P$  onto  $TO_{A^u}$  is nondegenerate unless  $\sin 2\theta = 0$  or  $\cos 2\theta = 0$ , proving the proposition.  $\square$

**Remark** One might hope that there really is positive curvature on these planes when  $\alpha = 0; \frac{1}{4}; \frac{3}{2}$  and  $\frac{3}{4}$  because perhaps the projection of these planes onto  $TO_{A^d}$  is nondegenerate. While this is true for most values of  $\alpha$ , it is false precisely when  $\alpha = 0; \frac{1}{4}; \frac{3}{2}$  and  $\frac{3}{4}$ .

Finally we study the zero curvatures of  $(E_{2,0}; g_{1; 2; l_1^u; l_2^d})$  at points when  $t = \frac{1}{4}$ . At such points the action induced by  $A_{SO(2)}$  on  $S^4$  via  $\rho_{2,0}: E_{2,0} \rightarrow S^4$  fixes  $S_{im}^2$ , so the orbits of  $A_{SO(2)}$  are vertical with respect to  $\rho_{2,0}$  when  $t = \frac{1}{4}$ . Combining this with the fact that  $A^l$  acts transitively on the fibers of  $\rho_{2,0}$ , we see that to study the curvature of these points we may assume that  $\alpha = 0$ , in other words we are back to representative points of the form (2.3) with  $t = \frac{1}{4}$ . At such points we get the following as a corollary of (7.14), (7.16), (7.19) and (7.21).

**Corollary 7.27** *When  $t = \frac{1}{4}$  and  $\alpha = 0$  the planes of the form (6.4) have positive curvature except if they have the form*

$$P = \text{span}\{(\#; 0); (0; \#)g\} \tag{7.28}$$

where  $\#$  is any convex combination of  $f\#_1; \#_2g$ .

To determine which of the planes in (7.4) still have 0{curvature we prove the following.

**Proposition 7.29** *At points with  $t = \frac{1}{4}$  and  $\alpha = 0$ , the only planes of the form (7.4) that have 0{curvature with respect to  $g_{1; 2; l_1^u; l_1^d}$  are those of the form*

$$P = \text{span}\{x^{2,0} + (-\#; 0); (-\#; \#)g\} \tag{7.30}$$

and

$$P = \text{span}\{y^{2,0} + (-\#; 0); (\#; \#)g\} \tag{7.31}$$

where  $\#$  stands for any convex combination of  $f\#_1; \#_2g$  and  $\alpha$  is any real number.

**Proof** The point is that if  $z$  is any other convex combination of  $fX^{2,0}; y^{2,0}g$ , then the projection of the plane in (7.4) onto  $TO_{A^u}$  is nondegenerate. To see this we will need to compute the projection of  $y^{2,0}$  onto  $TO_{A^u}$ . Although we

will only need to know its values for  $(t; \cdot) = (\frac{\pi}{4}; 0)$ , we will do the computation for arbitrary  $(t; \cdot)$ , since it may be of interest to some readers.

Along the orbit of  $SO(2)$  the formula for  $y^{2,0}$  is

$$\begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} \begin{pmatrix} \sin t \\ \cos t \end{pmatrix} = \begin{pmatrix} -\cos t \\ -\sin t \end{pmatrix}$$

$$\begin{pmatrix} \cos t \sin t + \sin t \cos t \\ -\sin t \sin t + \cos t \cos t \end{pmatrix} = \begin{pmatrix} -\cos t \cos t - \sin t \sin t \\ \sin t \cos t - \cos t \sin t \end{pmatrix}$$

So

$$\begin{aligned} hU_{(\cdot; y^{2,0})} i &= \begin{pmatrix} \cos t \cos t - \sin t \sin t \\ 0 \end{pmatrix} = \begin{pmatrix} -\cos t \sin t + \sin t \cos t \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} \cos t \sin t + \sin t \cos t \\ -\sin t \sin t + \cos t \cos t \end{pmatrix} = \begin{pmatrix} -\cos t \cos t - \sin t \sin t \\ \sin t \cos t - \cos t \sin t \end{pmatrix} \\ &= \frac{1}{2} (\cos^2 t \sin t \cos t - \sin^2 t \cos t \sin t + \cos^2 t \sin t \cos t - \sin^2 t \cos t \sin t) = \\ &= \frac{1}{2} \sin t \cos t (2 \cos^2 t - 2 \sin^2 t) = \\ &= \frac{1}{2} \sin 2t \cos 2t \end{aligned} \tag{7.32}$$

Similar computations show that

$$hU_{(\cdot; y^{2,0})} i = hU_{(\cdot; \#; 0)} i = hU_{(0; \cdot; \#)} i = 0 \tag{7.33}$$

Combining (7.32) and (7.33) with (7.14), (7.16), (7.19), (7.21), (7.25) and (7.26) we see that if  $P$  is any plane of the form of (7.4) and not of the form of either (7.30) or (7.31), then the projection of  $P$  onto  $TO_{A^u}$  is nondegenerate and hence  $P$  is positively curved.  $\square$

**Remark** As was the case with our previous results one could study projections onto  $TO_{A^d}$  to prove (7.27) and (7.29). Unfortunately these projections are degenerate on the same planes as the projections onto  $TO_{A^u}$  and hence do not give us additional positive curvature.

The curvature computations for the proof of Theorem A are completed with the following.

**Proposition 7.34**

- (i) The planes in (7.11), (7.24), (7.28), (7.30) and (7.31) all have 0 curvature in  $(E_{2,0}; \mathcal{G}_{1; 2}; l_1^u, l_1^d)$ .

- (ii) The plane spanned by  $x^{2,0}$  and  $\#_1^{2,0}$  in  $E_{2,0}$  is tangent to a totally geodesic flat 2-torus.
- (iii) Let  $Z$  be the pointwise zero locus in  $(E_{2,0}; g_{1,2}; I_1^u; I_1^d)$ , then  $Z$  is the union of two copies of  $S^3 \times S^3$  that intersect along a copy of  $S^2 \times S^3$ .

**Sketch of proof** To prove (i) we must check that the  $A$ -tensors of  $q_{Au}^{diag}$  and  $q_{2,0}$  vanish on these planes. These computations are rather long, but are quite straight forward so we leave them to the reader.

Recall [24] that  $S_{\mathbb{R}}^1$  denotes the circle in  $S^4$  that is fixed by the action induced from  $A^r$  via  $\rho_{2,0}$ .

It is easy to see that  $x^{2,0}$  and  $\#_1^{2,0}$  span a 2-torus,  $T$ , in  $Sp(2)$  whose tangent plane is horizontal with respect to  $q_{2,0}$  at every point. Since  $T$  is horizontal,  $q_{2,0}|_T$  is a covering map. The order of the covering is at least two because  $-1$  leaves  $T$  invariant under  $A_{2,0}$ . We show next that the order is exactly two.

Let  $c_x$  and  $c_{\#_1^{2,0}}$  be the geodesic circles that are generated by  $x^{2,0}$  and  $\#_1^{2,0}$ . Then with respect to the join decomposition  $S^4 = S_{im}^2 \times S_{\mathbb{R}}^1$ ,  $\rho_{2,0}(c_x)$  is a radial circle and for  $t > 0$ ,  $\rho_{2,0}(c_{\#_1^{2,0}})$  is an intrinsic geodesic in a copy of  $S^2$ . Using these observations we see that a point in  $\rho_{2,0}(q_{2,0}(T))$  has only two preimages under  $\rho_{2,0} \circ q_{2,0}$  from which it follows that  $q_{2,0}|_T$  is a two fold covering.

The fields  $x^{2,0}$  and  $\#_1^{2,0}$  are both parallel along  $T$ . Straightforward computation shows that the results of transporting them from a point  $z \in T$  to  $-z$  agrees with their images under the differential of the map induced on  $T$  by  $-1$  via  $A_{2,0}$ . Therefore  $q_{2,0}|_T$  is a 2-fold orientation preserving cover, and  $q_{2,0}(T)$  is a torus rather than a Klein bottle.

It follows from (i) that  $q_{2,0}(T)$  is flat and computations similar to those in the proof of (i) show that  $q_{2,0}(T)$  is totally geodesic.

Combining part (i) with (7.2), (7.10) and (7.23), we see that  $Z$  consists of the points with  $\theta = 0; \frac{\pi}{4}; \frac{3\pi}{4}$  or  $t = \frac{\pi}{4}$ . Using the join structure  $S^4 = S_{\mathbb{R}}^1 \times S_{im}^2$  we see that the union of the points with  $\theta = 0$ ,  $\theta = \frac{\pi}{2}$  and  $t = \frac{\pi}{4}$  is a 3-sphere in  $S^4$ . (Keep in mind that  $A_{SO(2)}$  is  $\mathbb{Z}_2$ -invariant on  $S^4$ .) For similar reasons the union of the points with  $\theta = \frac{\pi}{4}$ ,  $\theta = \frac{3\pi}{4}$  and  $t = \frac{\pi}{4}$  is another 3-sphere. These two three spheres intersect along the common 2-sphere  $S_{im}^2$  and their inverse images via  $\rho_{2,0}$  are of course diffeomorphic to  $S^3 \times S^3$ . Finally notice that every point in this inverse image has zero curvatures because  $\rho_{2,0}$  is the quotient map of  $A^r$  and  $A^r$  acts by isometries. □

The example,  $M^6$ , of Corollary B is

$$M^6 = E_{2,0} = A^I$$

where  $I$  is any purely imaginary, unit quaternion, and  $A^I$  is the circle subaction of  $A^1$  that is generated by  $I$ . When  $I = 1$  the torus  $q_{2,0}(T) = E_{2,0}$  is normal to the orbit of  $A^1$ . Some further curvature computations show that its image in  $M^6$  is totally geodesic and flat.

### 8 Topological Computations

**Proposition 8.1**  $E_{2,0}$  is diffeomorphic to the total space of the unit tangent bundle of  $S^4$ . In fact, the Riemannian submersion  $\rho_{1,1}: E_{2,0} \rightarrow S^4$  that is given by

$$\rho_{1,1}: \text{orbit} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mapsto h(c; d)$$

is bundle isomorphic to the unit tangent bundle of  $S^4$ , where  $h: S^7 \rightarrow S^4$  is the Hopf fibration given by left multiplication.

**Proof** Translating Theorem 9.5 on page 99 of [15] into our classification scheme (0.1) shows that the unit tangent bundle is the bundle of type (1;1). We will show via direct computations (similar to those in [12]) that  $(E_{2,0}; \rho_{1,1})$  is also the bundle of type (1;1).

As in [24] we define  $\sigma: \mathbb{R}^4 \rightarrow \mathbb{R}$  by

$$\sigma(u) = \frac{1}{1 + |u|^2};$$

and we define explicit bundle charts  $h_1, h_2: \mathbb{R}^4 \rightarrow S^3 \rightarrow E_{2,0}$  by

$$h_1(u; q) = \text{orbit} \begin{pmatrix} -q & qu \\ u & 1 \end{pmatrix} \quad (u)$$

and

$$h_2(v; r) = \text{orbit} \begin{pmatrix} -rv & r \\ 1 & v \end{pmatrix} \quad (v);$$



$h_1$  and  $h_2$  are embeddings onto the open sets

$$U_1 = \text{orbit} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad jd \neq 0$$

and

$$U_2 = \text{orbit} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad jc \neq 0$$

In fact their inverses are given by

$$h_1^{-1} \left( \text{orbit} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \right) = \left( \frac{cd}{jd^2}; \frac{-da}{jdjj} \right)$$

and

$$h_2^{-1} \left( \text{orbit} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \right) = \left( \frac{cd}{jc^2}; \frac{cb}{jcjj} \right):$$

Thus

$$h_2^{-1} \circ h_1(u; q) = h_2^{-1} \left( \text{orbit} \begin{pmatrix} -q & qu \\ u & 1 \end{pmatrix} (u) \right) = \left( \frac{u}{juj^2}; \frac{uqu}{juj^2} \right):$$

So  $(E_{2,0}; p_{1,1})$  is the bundle of type  $(1; 1)$  and hence is the unit tangent bundle of  $S^4$ . □

Next we compute the homology and first few homotopy groups of  $S^3$  bundles over  $S^4$  to distinguish  $E_{2,0}$  from the known examples of 7-manifolds with positive sectional curvature.

**Proposition 8.2** Let  $E_{m;-n}$  denote the  $S^3$  bundle over  $S^4$  of type  $(m; -n)$ .

(i) The integral homology groups of  $E_{m;-n}$  are

$$H_0(E_{m;-n}; \mathbb{Z}) = H_7(E_{m;-n}; \mathbb{Z}) = \mathbb{Z}$$

$$H_3(E_{m;-n}; \mathbb{Z}) = \frac{\mathbb{Z}}{(m-n)\mathbb{Z}}; \text{ and}$$

$$H_q(E_{m;-n}; \mathbb{Z}) = 0 \text{ for all } q \neq 0, 3, 7,$$

if  $m \neq n$ .

- (ii)  $H_1(E_{m;-n}) = H_2(E_{m;-n}) = \mathbb{Z}$  and  $H_3(E_{m;-n}) = \frac{\mathbb{Z}}{(m-n)\mathbb{Z}}$
- (iii)  $E_{2,0}$  does not have the homotopy type of any known example of a manifold with positive curvature.

**Proof** To compute the homology of  $E_{m;-n}$  we decompose it as

$$E_{m;-n} = D^4 \cup_{g_{m;-n}} (S^3 \times D^4) \cup_{\text{id}} (S^3 \times S^3) \tag{8.3}$$

where the gluing map  $g_{m;-n}: S^3 \times S^3 \rightarrow S^3 \times S^3$  is given by  $g_{m;-n}(u; v) = (u; u^m v U^{-n})$ . From (8.3) and the Seifert-Van Kampen theorem it follows that  $E_{m;-n}$  is simply connected.

The Mayer-Vietoris sequence for the decomposition (8.3) is

$$\begin{aligned} \dots \rightarrow H_q(S^3 \times S^3) \xrightarrow{!} H_q(D^4 \times S^3) \oplus H_q(D^4 \times S^3) \\ \xrightarrow{!} H_q(E_{m;-n}) \xrightarrow{!} H_{q-1}(S^3 \times S^3) \xrightarrow{!} \dots \end{aligned} \tag{8.4}$$

Since  $H_2(D^4 \times S^3) = H_1(S^3 \times S^3) = \mathbb{Z}$ ,  $H_2(E_{m;-n}) = \mathbb{Z}$ .

Also since  $H_2(S^3 \times S^3) = \mathbb{Z}$ ,  $H_3(E_{m;-n}) = \frac{H_3(D^4 \times S^3) \oplus H_3(D^4 \times S^3)}{\text{image}(\beta)}$ . The next step is to compute  $\text{image}(\beta)$ .

Suppose  $f = 1; 1$  and  $g$  is a set of generators for  $H_3(S^3 \times S^3)$ , and  $f(0; 0); (0; 0)g$  generates  $H_3(D^4 \times S^3) \oplus H_3(D^4 \times S^3)$ . Then using the fact that the map  $P_k: S^3 \rightarrow S^3$  given by  $P_k(q) = q^k$  has degree  $k$  we can see that

$$\begin{aligned} \beta(f) &= (m-n)(0; 0) \quad \text{and} \\ \beta(g) &= (0; 0) + (0; 0) \end{aligned}$$

(To evaluate the first map represent  $\beta$  by  $S^3 \times S^3 \rightarrow S^3 \times S^3$ .)

Put another way, the matrix of  $\beta$  with respect to our sets of generators is

$$\begin{pmatrix} 0 & 1 \\ m-n & 1 \end{pmatrix} \tag{8.5}$$

From this point a routine algebraic computation shows that

$$H_3(E_{m;-n}) = \frac{H_3(D^4 \times S^3) \oplus H_3(D^4 \times S^3)}{\text{image}(\beta)} = \frac{\mathbb{Z}}{(m-n)\mathbb{Z}}$$

It follows from (8.5) that  $\beta$  is injective if  $m \neq n$ , and hence we get using (8.4) that

$$H_4(E_{m;-n}) = H_5(E_{m;-n}) = H_6(E_{m;-n}) = 0;$$

completing the proof of (i).

Part (ii) is a corollary of (i).

The known examples of simply connected 7-manifolds with positive curvature are given in [3], [9] and [2]. With the exception of  $S^7$  and the example,  $V_1$ , of Berger none of them are 2-connected. Since  $H_3(E_{2,0}; \mathbb{Z}) = \mathbb{Z}_2$ ,  $E_{2,0}$  is not a homotopy sphere. It is not homotopy equivalent to  $V_1$  since, according to Proposition 40.1 in [3],  $V_1$  is not a  $\mathbb{Z}_5$ -cohomology sphere.  $\square$

Our last topological computation is the following (cf also [13] Corollary 3.9).

**Proposition 8.6**

- (i)  $M^6$  has the same integral cohomology modules as  $CP^3$  but not the same integral cohomology algebra.
- (ii)  $M^6$  does not have the homotopy type of any known example of a manifold of positive curvature.

**Proof** From the long exact homotopy sequence of the fibration  $S^1 \rightarrow E_{2,0} \rightarrow M^6$  we see that  $H_1(M^6) = 0$  and  $H_2(M^6) = \mathbb{Z}$ . Thus  $H^1(M^6; \mathbb{Z}) = 0$  and  $H^2(M^6; \mathbb{Z}) = \mathbb{Z}$ . To compute  $H^3(M^6; \mathbb{Z})$  and the cup products we appeal to the Gysin sequence

$$\dots \rightarrow H^1(M^6; \mathbb{Z}) \rightarrow H^3(M^6; \mathbb{Z}) \rightarrow H^3(E_{2,0}; \mathbb{Z}) \rightarrow H^2(M^6; \mathbb{Z}) \rightarrow \dots$$

of the fiber bundle  $S^1 \rightarrow E_{2,0} \rightarrow M^6$  with integer coefficients. We already know that  $H^1(M^6; \mathbb{Z}) = 0$ . Moreover, it follows from the universal coefficient theorem that  $H^3(E_{2,0}; \mathbb{Z}) = 0$  since  $H_2(E_{2,0}; \mathbb{Z})$  has no torsion and  $H_3(E_{2,0}; \mathbb{Z})$  is a torsion group. Thus the Gysin sequence shows that  $H^3(M^6; \mathbb{Z}) = 0$  and hence that  $M^6$  has the same integral cohomology groups as  $CP^3$ . To see that  $M^6$  does not have the cohomology ring of  $CP^3$  we look at the Gysin sequence again:

$$\begin{aligned} 0 &= H^3(E_{2,0}; \mathbb{Z}) \rightarrow H^2(M^6; \mathbb{Z}) \xrightarrow{f^e} H^4(M^6; \mathbb{Z}) \rightarrow H^4(E_{2,0}; \mathbb{Z}) \rightarrow H^3(M^6; \mathbb{Z}) = 0; \\ 0 &= H^5(E_{2,0}; \mathbb{Z}) \rightarrow H^4(M^6; \mathbb{Z}) \xrightarrow{f^e} H^6(M^6; \mathbb{Z}) \rightarrow H^6(E_{2,0}; \mathbb{Z}) = 0. \end{aligned}$$

We therefore have

$$\begin{aligned} 0 &\rightarrow H^2(M^6; \mathbb{Z}) \xrightarrow{f^e} H^4(M^6; \mathbb{Z}) \rightarrow \mathbb{Z}_2 \rightarrow 0; \\ 0 &\rightarrow H^4(M^6; \mathbb{Z}) \xrightarrow{f^e} H^6(M^6; \mathbb{Z}) \rightarrow 0. \end{aligned}$$

This means that  $H^2(M^6; \mathbb{Z}) \xrightarrow{f^e} H^4(M^6; \mathbb{Z})$  maps the generator  $x$  for  $H^2(M^6; \mathbb{Z})$  to twice a generator  $y$  for  $H^4(M^6; \mathbb{Z})$ : If we let  $e = kx$  we therefore have  $x \lrcorner kx = 2y$ : Therefore, it suffices to show that  $k = 1$  in order to show that the cohomology ring of  $M^6$  is not that of  $\mathbb{C}P^3$ : We have that  $H^4(M^6; \mathbb{Z}) \xrightarrow{f^e} H^6(M^6; \mathbb{Z})$  is an isomorphism. Thus  $(x \lrcorner kx) \lrcorner kx = k^2x \lrcorner x \lrcorner x$  must also be twice a generator for  $H^6(M^6; \mathbb{Z})$ : Therefore, if  $k = 2$  we would have that  $2x \lrcorner x \lrcorner x$  generates  $H^6(M^6; \mathbb{Z})$ : This, however, is impossible.

Besides  $S^6$  and  $\mathbb{C}P^3$ , there are two examples given in [23] and [10] of simply connected 6-manifolds with positive curvature. Neither of these has the cohomology modules of  $\mathbb{C}P^3$  so  $M^6$  does not have the homotopy type of any known example.  $\square$

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