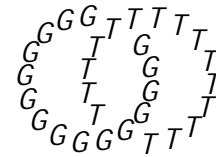


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To Ada

A few remarks about symplectic filling

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Abstract

We show that any compact symplectic manifold $(W; \omega)$ with boundary embeds as a domain into a closed symplectic manifold, provided that there exists a contact plane ξ on ∂W which is weakly compatible with ω , i.e. the restriction $\omega|_{\xi}$ does not vanish and the contact orientation of ξ and its orientation as the boundary of the symplectic manifold W coincide. This result provides a useful tool for new applications by Ozsvath{Szabo of Seiberg{Witten Floer homology theories in three-dimensional topology and has helped complete the Kronheimer{Mrowka proof of Property P for knots.

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1 Introduction

All manifolds which we consider in this article are assumed oriented. A contact manifold V of dimension three carries a canonical orientation. In this case we will denote by $-V$ the contact manifold with the opposite orientation. Contact plane fields are assumed co-oriented, and therefore oriented. Symplectic manifolds are canonically oriented, and so are their boundaries.

We prove in this article the following theorem:

Theorem 1.1 *Let $(V; \xi)$ be a contact manifold and λ a closed 2-form on V such that $\int_V \lambda > 0$. Suppose that we are given an open book decomposition of V with a binding B . Let V^θ be obtained from V by a Morse surgery along B with a canonical framing, so that V^θ is fibered over S^1 . Let W be the corresponding cobordism, $\partial W = (-V) \cup V^\theta$. Then W admits a symplectic form such that $\int_V \lambda = \int_{V^\theta} \lambda$ and λ is positive on fibers of the fibration $V^\theta \rightarrow S^1$.*

Remark 1.2 Note that the binding B has a canonical decomposition of its tubular neighborhood given by the pages of the book. The framing surgery along B is the Morse surgery associated with this decomposition. If the binding is disconnected then we assume that the surgery is performed simultaneously along all the components of B .

We will deduce the following result from Theorem 1.1:

Theorem 1.3 *Let $(V; \xi)$ and λ be as in Theorem 1.1. Then there exists a symplectic manifold $(W^\theta; \omega^\theta)$ such that $\partial W^\theta = -V$ and $\int_{V^\theta} \lambda = \int_{V^\theta} \omega^\theta$. Moreover, one can arrange that $H_1(W^\theta) = 0$,¹ and that $(W^\theta; \omega^\theta)$ contains the symplectic cobordism $(W; \omega)$ constructed in Theorem 1.1 as a subdomain adjacent to the boundary. In particular, any symplectic manifold which weakly fills (see Section 4 below) the contact manifold $(V; \xi)$ can be symplectically embedded as a subdomain into a closed symplectic manifold.*

Corollary 1.4 *Any weakly (resp. strongly) semi-fillable (see [10]) contact manifold is weakly (resp. strongly) fillable.*

Remark 1.5 Theorem 1.1 serves as a missing ingredient in proving that the Ozsvath-Szabo contact invariant $c(\cdot)$ does not vanish for weakly symplectically fillable (and hence for non-existing anymore semi-fillable) contact structures.

¹This observation is due to Kronheimer and Mrowka, see [20].

This and other applications of the results of this article in the Heegaard Floer homology theory are discussed in the paper of Peter Ozsvath and Zoltan Szabo, see [27]. The observation made in this paper also helped to streamline the program of Peter Kronheimer and Tomasz Mrowka for proving the Property P for knots, see their paper [20].

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2 Proof of Theorem 1.1

We begin with the following lemma which is a slight reformulation of Proposition 3.1 in [6]. A similar statement is contained also in [19].

Lemma 2.1 *Let (V, ξ) and $! \xi$ be as in Theorem 1.1. Then given any contact form η for $! \xi$ and any $C > 0$ one can find a symplectic form ω on $V \times [0; 1]$ such that*

- a) $j_V|_{t=0} = ! \xi$;
- b) $\omega|_{[1-\epsilon; 1]} = ! \xi + Cd(\eta)$, where $t \in [1-\epsilon; 1]$ and $0 < \epsilon < 1$;
- c) ω induces the negative orientation on $V \times \{0\}$ and positive on $V \times \{1\}$.

Proof By assumption

$$! \xi = f d \eta = d(f \eta)$$

for a positive function $V \in \mathbb{R}$. Set $\tilde{\omega} = f \cdot \omega$. Then $\tilde{\omega} = d\tilde{\alpha} + \tilde{\omega} \wedge \tilde{\alpha}$. Take a smooth function $h: V \times [0; 1] \rightarrow \mathbb{R}$ such that

$$h|_{V \times \{0\}} = 0; \quad h|_{V \times \{1\}} = \frac{Ct}{f}; \quad \frac{dh}{dt} > 0;$$

where t is the coordinate corresponding to the projection $V \times [0; 1] \rightarrow [0; 1]$. Consider the form $\tilde{\omega} = \tilde{\omega} + d(h\tilde{\alpha})$. Here we keep the notation $\tilde{\omega}$ and $\tilde{\alpha}$ for the pull-backs of ω and α to $V \times [0; 1]$. Then we have

$$\tilde{\omega} = d\tilde{\alpha} + \tilde{\omega} \wedge \tilde{\alpha} + d_V h \wedge \tilde{\alpha} + \frac{dh}{dt} dt \wedge \tilde{\alpha};$$

where $d_V h$ denotes the differential of h along V . Then

$$\tilde{\omega} \wedge \tilde{\alpha} = 2 \frac{dh}{dt} dt \wedge \tilde{\alpha} \wedge \tilde{\alpha} + d\tilde{\alpha} \wedge \tilde{\alpha} > 0;$$

Hence $\tilde{\omega}$ is symplectic and it clearly satisfies the conditions a)–c). □

Let us recall that a contact form ω on V is called *compatible* with the given open book decomposition (see [14]) if

- a) there exists a neighborhood U of the binding B , and the coordinates $(r; \theta; u) \in [0; R] \times \mathbb{R} \times \mathbb{R}^2$ such that

$$U = fr + Rg \quad \text{and} \quad j_U = h(r)(du + r^2 d\theta);$$

where the positive C^1 function h satisfies the conditions

$$h(r) - h(0) = -r^2 \quad \text{near } r = 0 \quad \text{and} \quad h'(r) < 0 \quad \text{for all } r > 0;$$

- b) the parts of pages of the book in U are given by equations $\theta = \text{const}$;
- c) $d\theta$ does not vanish on the pages of the book (with the binding deleted).

Remark 2.2 An admissible contact form defines an orientation of pages and hence an orientation of the binding B as the boundary of a page. On the other hand, the form defines a co-orientation of the contact plane field, and hence an orientation of B as a transversal curve. These two orientations of B coincide.

Remark 2.3 By varying admissible forms for a given contact plane field one can arrange any function h with the properties described in a). Indeed, suppose we are given another function \tilde{h} which satisfies a). We can assume without loss of generality that $\tilde{\omega}$ has the presentation a) on a bigger domain $U^\theta = fr + R^\theta g$ for $R^\theta > R$. Let us choose $c > 0$ such that $\tilde{h}(R) > ch(R)$ and extend \tilde{h} to $[0; R^\theta]$ in such a way that $\tilde{h}'(r) < 0$ and $\tilde{h}(r) = ch(r)$ near R^θ . Then the form $\tilde{\omega}$ on U^θ extended to the rest of the manifold V as $c\omega$ is admissible for the given open book decomposition.

Now we are ready to prove Theorem 1.1.

Proof of Theorem 1.1 Take a constant $a > 0$ and consider a smooth on $[0; 1]$ function $g: [0; 1] \rightarrow \mathbb{R}$ such that $g|_{[0; 1/2]} = a$, $g(t) = \frac{a}{1-t^2}$ for t near 1 and $g' < 0$ on $(1/2; 1)$.

In the standard symplectic \mathbb{R}^4 which we identify with \mathbb{C}^2 with coordinates $(z_1 = r_1 e^{i\theta_1} = x_1 + iy_1; z_2 = r_2 e^{i\theta_2} = x_2 + iy_2)$ let us consider a domain

$$\tilde{P} = \{r_1 \leq a; r_2 \leq 2g(r_1)\}$$

The domain \tilde{P} is contained in the polydisc $P = \{r_1 \leq a; r_2 \leq 1\}$ and can be viewed as obtained by smoothing the corners of P .

Let us denote by $\partial\tilde{P}$ the part of the boundary of \tilde{P} given by

$$\partial\tilde{P} = \{r_1 = a; r_2 \leq 2g(a)\} \cup \{r_1 \leq 2g(r_2); r_2 = 1\}$$

Note that $\partial\tilde{P}$ is C^1 {tangent to ∂P near its boundary. The primitive

$$j = \frac{1}{2} (r_1^2 d\theta_1 + r_2^2 d\theta_2)$$

of the standard symplectic form

$$\omega_0 = dx_1 \wedge dy_1 + dx_2 \wedge dy_2 = r_1 dr_1 \wedge d\theta_1 + r_2 dr_2 \wedge d\theta_2$$

restricts to $\partial\tilde{P}$ as a contact form

$$j|_{\partial\tilde{P}} = \frac{r_1^2}{2} d\theta_1 + \frac{g^2(r_1)}{r_1^2} d\theta_2$$

Consider the product $G = S^2 \times D^2$ with the split symplectic structure $\omega_0 = \omega_1 + \omega_2$, where the total area of the form ω_1 on S^2 is equal to 2π and the total area of the form ω_2 on the disc D^2 is equal to πa^2 . Note that if S_+^2 and S_-^2 denote the upper and lower hemispheres of S^2 of equal area, then there exists a symplectomorphism

$$\psi: P \rightarrow S_+^2 \times D^2 \cup S_-^2 \times D^2 = G$$

Let H be the closure of $\psi^{-1}(\partial\tilde{P})$ and ∂H denote the image $\psi(\partial\tilde{P}) \subset \partial H$. Note that

$$\partial H = \overline{\psi^{-1}(\partial\tilde{P})} = \mathbb{S}_-^2 \times D^2 \cup \left[\mathbb{S}_-^2 \times x = \left[\begin{array}{c} \mathbb{S}_-^2 \\ x \in D^2 \end{array} \right] \cup \left[\begin{array}{c} \mathbb{S}_-^2 \\ x \in D^2 \end{array} \right] \cup D_x;$$

where $\mathbb{S}_-^2, S_-^2, \mathbb{S}_-^2, S_-^2$, is a disc of area $\frac{9}{4}$. Thus H is a 2-handle whose boundary ∂H consists of $\partial\tilde{P}$ and ∂D_x which meets along an infinitely sharp corner $\partial\tilde{P} \cap \partial D_x$. The part ∂H is covered by discs $D_x; x \in D^2$, which are symplectic with respect to the form ω_0 .

Consider now a contact form α on V compatible with the given open book decomposition. In particular, on a neighborhood

$$U = [0; R] \times \mathbb{R}^2 \times \mathbb{Z} \times \mathbb{R}^2 \times \mathbb{Z} \times V$$

of the binding B we have $j_U = h(r)(du + r^2 d')$, where the positive C^1 function h satisfies the conditions

$$h(r) - h(0) = -r^2 \text{ near } r = 0 \text{ and } h'(r) < 0 \text{ for all } r > 0:$$

Let us choose $a = \frac{R}{2}$, and consider a diffeomorphism $F: U \rightarrow V$ given by the formula

$$r = \frac{g(r_2)}{r_2}; \quad r' = r'_1; \quad u = r'_2:$$

The function

$$r_2 \mapsto \frac{g(r_2)}{r_2}$$

maps $[1; \frac{1}{2}]$ onto $[0; 2a] = [0; R]$. Let $\psi: [0; R] \rightarrow [1; \frac{1}{2}]$ be the inverse function. Then

$$F^* \alpha = \frac{\psi^2(r)}{2} r^2 d' + du$$

Hence F is a contactomorphism

$$(\psi; f = 0g) \circ (U; f = 0g = \alpha):$$

Moreover, the form $F^* \alpha$, extended to V as α on $V \cap U$, defines on V a smooth contact form compatible with the given open book decomposition.

Now we use Lemma 2.1 to define on the collar $V \times [0; 1]$ a symplectic form which satisfies the conditions 2.1a)(c), where the constant C will be chosen later. In particular, near $V \times 1$ we have $\omega = C dt + \dots$. Viewing ω as a part of the boundary of the handle H , we can extend F to a symplectomorphism, still denoted by F , of a neighborhood of H endowed with the standard symplectic structure $C \omega$ to a neighborhood of $U \cup V = V \times 1$ in $V \times [0; 1]$ endowed with the symplectic structure $C d(t)$. Note that the closed form $F^* \omega$ is exact:

$$F^* \omega = d \psi;$$

and hence it extends to H as $\psi = d(\dots)$ where \dots is a cut-off function equal to 0 outside a neighborhood of \dots in H . If C is chosen sufficiently large then the form $\omega_0 = C \omega + \psi$ is symplectic, and its restrictions to the discs $D_x \times \dots$, $\times 2 @ D^2$, are symplectic as well. Hence the map F can be used for attaching the symplectic handle $(H; C \omega + \psi)$ to $V \times [0; 1]$ along U . The resulted symplectic manifold

$$W = V \times [0; 1] \cup_{U=F^{-1}(U)} H$$

is the required symplectic cobordism. Indeed we have

$$\partial(W; \emptyset) = (-V; !) \cup (V^0; !^0);$$

where the component V^0 of its boundary is fibered over S^1 by closed surfaces formed by parts of pages of the book inside $V \cap U$ and discs D_x . These surfaces are symplectic with respect to the form $!^0 = \omega|_{V^0}$. \square

3 Filling of symplectic fibrations over circle

A pair $(V; !)$, where V is an oriented 3-manifold fibered over $S^1 = \mathbb{R}/\mathbb{Z}$, and $!$ is a closed 2-form which is positive on the fibers of the fibration, will be referred to as a *symplectic fibration over S^1* . The projection $V \rightarrow S^1$ will be denoted by π . We will assume that all symplectic fibrations we consider are normalized by the condition that the integral of $!$ over a fiber is equal to 1. The form $!$ induces a 1-dimensional *characteristic* foliation $F_!$ on V generated by the kernel of $!$. This foliation is transversal to the fibers of the fibration. The orientation of V together with the symplectic orientation of the fibers defines an orientation of $F_!$. Fixing a fiber F_0 over $0 \in \mathbb{R}/\mathbb{Z}$ we can define the *holonomy diffeomorphism* $\text{Hol}_{V;!} : F_0 \rightarrow F_0$. This is an area preserving diffeomorphism which defines $(V; !)$ uniquely up to a fiber preserving diffeomorphism fixed on F_0 . Note that $\text{Hol}_{-V;!} = \text{Hol}_{V;!}^{-1}$. Two symplectic fibrations are equivalent via an equivalence fixed on F_0 if and only if their holonomy diffeomorphisms coincide. If for symplectic fibrations $(V; !_0)$ and $(V; !_1)$ the holonomy diffeomorphisms $\text{Hol}_{V;!_0}$ and $\text{Hol}_{V;!_1}$ are symplectically (resp. Hamiltonian) isotopic then $(V; !_0)$ and $(V; !_1)$ are called isotopic (resp. Hamiltonian isotopic). For a fixed smooth fibration $V \rightarrow S^1$ the isotopy between $(V; !_0)$ and $(V; !_1)$ is equivalent to a homotopy of forms $!_0$ and $!_1$ through closed forms positive on fibers of the fibration.

We will prove in this section

Theorem 3.1 *For any symplectic fibration $(V; !)$ over S^1 there exists a compact symplectic 4-manifold $(W; \omega)$ with*

$$\partial(W; \omega) = (V; !);$$

One can additionally arrange that $H_1(W; \mathbb{Z}) = 0$.²

The first ingredient in the proof in the following theorem of Akbulut and Ozbagci.

²This was observed by Kronheimer and Mrowka, see [20].

Theorem 3.2 (See [2], Theorem 2.1) *Theorem 3.1 holds up to homotopy. More precise, for any symplectic fibration $(V; \omega)$ as above there exists a compact symplectic 4-manifold $(W; \omega)$ with $H_1(W) = 0$ which has a structure of a symplectic Lefschetz fibration over D^2 and which restricts to $S^1 = \partial D^2$ as a symplectic fibration $(V; \omega)$ homotopic to $(V; \omega)$.*

The proof of this theorem is based on an observation (which the authors said they learned from Ivan Smith) that any element of the mapping class group of a closed surface can be presented as a composition of *positive* Dehn twists,³ WP Thurston's construction (see [28]) of symplectic structure on surface fibrations, and its adaptation by RE Gompf (see [15]) for Lefschetz fibrations with positive Dehn twists around exceptional fibers. Exploring the freedom of the construction one can arrange that $H_1(W; \mathbb{Z}) = 0$. Indeed, for a Lefschetz fibration over D^2 we have $H_1(W) \cong H_1(F_0) = C$, where $C \subset H_1(F_0)$ is the subgroup generated by the vanishing cycles. But the already mentioned above fact that the mapping class group is generated as a monoid by positive Dehn twists allows us to make any cycle in $H_1(F_0)$ vanishing.

The second ingredient in the proof of Theorem 3.1 is the following proposition based on a variation of an argument presented in [20], see Lemma 3.4 below.

Proposition 3.3 *Let $(W; \omega)$ be a Lefschetz fibration over D^2 and $(V; \omega)$ a symplectic fibration over S^1 which bounds it, $\omega(W; \omega) = (V; \omega)$. Then for any symplectic fibration $(V; \omega)$ homotopic to $(V; \omega)$ there exists a symplectic form ω on W such that $\omega(W; \omega) = (V; \omega)$ where $(V; \omega)$ is Hamiltonian isotopic to $(V; \omega)$.*

In other words, Proposition 3.3 together with Theorem 3.2 imply Theorem 3.1 up to *Hamiltonian isotopy*. Before proceeding with the proof we recall some standard facts about the flux homomorphism.

Let F_0 be a closed oriented surface of genus g with an area form ω . We denote by $D = D(F_0)$ the group of area preserving diffeomorphisms of F_0 and by D_0 its identity component. The Lie algebra of D_0 consists of symplectic vector fields, i.e. the vector fields, ω -dual to closed forms. Hence, given an isotopy

³Here is a simple argument due to Peter Kronheimer which shows this. Take any generic genuine (i.e. having exceptional fibers) Lefschetz fibration over CP^1 with the number of prescribed genus. Then the product of $+1$ -twists corresponding to vanishing cycles is the identity. Therefore, a -1 -twist (and hence any -1 -twist) is a product of $+1$ -twists.

$f_t \in D_0$ which connects $f_0 = \text{Id}$ with $f_1 = f$ then for the time-dependent vector field v_t which generates f_t , i.e.

$$v_t(f_t(x)) = \frac{df_t(x)}{dt}; \quad t \in [0; 1]; \quad x \in F_0; \tag{1}$$

the form $\omega_t = v_t \lrcorner \omega$ is closed for all $t \in [0; 1]$. Diffeomorphisms generated by time-dependent vector fields (1) dual to exact 1-forms form a subgroup D_H of Hamiltonian diffeomorphisms. This subgroup is the kernel of a flux, or Calabi homomorphism (see [5]) which is defined as follows. Given v_t generating f as in (1) as its time-one map, we define

$$\text{Flux}(f) = \int_0^1 [v_t \lrcorner \omega] dt$$

where $[v_t \lrcorner \omega] \in H^1(F_0; \mathbb{R})$ is the cohomology class of the closed form $v_t \lrcorner \omega$. Though $\text{Flux}(f)$, as defined by the above formula, is independent of the choice of the path f_t up to homotopy, it may depend on the homotopy class of this path. Note, however, that when the genus of F_0 is > 1 then D_0 is contractible, and hence $\text{Flux}(f)$ is well defined as an element of $H^1(F_0; \mathbb{R})$. If F_0 is the torus then $\text{Flux}(f)$ is defined only modulo the total area of the torus, and hence it can be viewed as an element of $H^1(F_0; \mathbb{R}=\mathbb{Z})$. According to [5],

$$D_H = \text{KerFlux};$$

i.e. two diffeomorphisms $f, g \in D$ are Hamiltonian isotopic if and only if $\text{Flux}(f \circ g^{-1}) = 0$.⁴

Therefore, Proposition 3.3 is equivalent to

Lemma 3.4 *Suppose $(V; \omega)$ is a symplectic manifold over S^1 and $(W; \omega)$ is a symplectic Lefschetz manifold over D^2 such that $\partial(W; \omega) = (V; \omega)$ and $H_1(W) = 0$. Then for any $a \in H^1(F_0; \mathbb{R})$ (or $H^1(F_0; \mathbb{R}=\mathbb{Z})$ if F_0 is the torus) there exists a symplectic form ω on W such that*

$$\text{Flux}(\text{Hol}_{V; \omega} \circ \text{Hol}_{V; \omega}^{-1}) = a;$$

where $\omega = \omega_V$.

⁴This can be verified as follows. Let $f_t \in D_0; t \in [0; 1]$, be any symplectic isotopy connecting $f_0 = f$ and $f_1 = g$. Denote $a_t = \text{Flux}(f_t)$ and choose a harmonic (for some metric) 1-form α_t representing $a_t \in H^1(F_0; \mathbb{R})$. Set $\omega_t = \omega - \alpha_t$. By assumption we have $\alpha_1 = 0$. Let ϕ_t be the time-one map of the symplectic flow generated by the symplectic vector field v_t dual to α_t . Then for all $t \in [0; 1]$ we have $\text{Flux}(\phi_t^{-1} \circ f_t) = a_0$, and hence $\phi_t^{-1} \circ f_t$ is a Hamiltonian isotopy between f and g .

Proof Let us recall that given an embedded path γ from a critical value $p \in D^2$ of the Lefschetz fibration to a boundary point $q \in \partial D^2$ there exists a Lagrangian disc Σ , called *thimble*, which projects to the path γ and whose boundary $\partial \Sigma = F_q = \pi^{-1}(q)$ is a vanishing cycle. This thimble is formed by leaves of the characteristic foliation of the form $\gamma^{-1}(\cdot)$ emanating from the corresponding critical point. Let us choose disjoint embedded paths $\gamma_1, \dots, \gamma_N$ from all critical values of the Lefschetz fibration to points inside the arc $I = [0; 1=2] \subset \mathbb{R}=\mathbb{Z} = \partial D^2$. Let $\Sigma_i = \Sigma_{\gamma_i}$ and $\gamma_i = \partial \Sigma_i$, $i = 1, \dots, N$, be the corresponding thimbles and vanishing cycles. Using characteristics of Σ_i as horizontal lines we can trivialize the fibration $V_{1=2} = \pi^{-1}(I) \cup I$. Note that the inclusion $H_1(F_0) \rightarrow H_1(W)$ is surjective, and the kernel of this map is generated by the vanishing cycles (independently of paths along which they are transported to F_0 from a critical point). By the assumption, we have $H_1(W) = 0$ and hence the projections of Σ_i to F_0 generate $H_1(F_0)$. Then the cohomology classes $D_i \in H^1(F_0)$, $i = 1, \dots, N$, Poincaré dual to $[\Sigma_i] \in H_1(F_0)$, generate $H^1(F_0)$. In particular, we can write

$$a = \sum_{i=1}^N a_i D_i$$

Let us recall that there exists a neighborhood U_i of Σ_i symplectomorphic to a disc bundle in $T(\Sigma_i)$. Let $(q_1; q_2; p_1; p_2)$ be the canonical coordinates in $T(\Sigma_i)$ such that

$$j_{\Sigma_i} = dp_1 \wedge dq_1 + dp_2 \wedge dq_2; \quad i \quad f p_1 = p_2 = 0g \tag{2}$$

and $U_i = \{j_{\Sigma_i} = p_1^2 + p_2^2 < \epsilon^2 g\}$. Let $\rho : [0; \epsilon] \rightarrow \mathbb{R}$ be a non-negative function constant near 0 and equal to 1 near ϵ and such that

$$\int_{\Sigma_i} (\rho^2 p_1^2 + \rho^2 p_2^2) dp_1 dp_2 = 1$$

Consider a supported in U_i closed 2-form

$$e_i = dp_1 \wedge dp_2 \tag{3}$$

Note that the form

$$e = \sum_{i=1}^N a_i e_i$$

is symplectic, as it follows from the explicit expressions (2) and (3). Note also that the restriction of the form e_i to the fiber containing Σ_i vanishes, and hence for a sufficiently small $\epsilon > 0$ the form $e = \sum e_i$ is positive on the fibers of the

This finishes the proof of Theorem 3.1. □

Before proving Theorem 1.3 let us make a general remark on gluing of symplectic manifolds along their boundaries.

Remark 3.6 Let $(W_1; \omega_1)$ and $(W_2; \omega_2)$ be two symplectic manifolds, and $V_1 \subset \partial W_1$ and $V_2 \subset \partial W_2$ be components of their boundaries. Suppose we are given an orientation reversing diffeomorphism $f: V_1 \rightarrow -V_2$ such that $f^*\omega_2 = \omega_1$. Then the manifold $W = W_1 \cup_{f(V_1)=V_2} W_2$ inherits a canonical, up to a Hamiltonian diffeomorphism, symplectic structure. Indeed, according to the symplectic neighborhood theorem the restriction $\omega|_{V_i}; i = 1, 2$, determines ω_i on a neighborhood of V_i in W_i uniquely up to a symplectomorphism fixed on V_i .

Proof of Theorem 1.3 Let $(\bar{W}; \omega)$ be a cobordism between $(-V; \omega)$ and a symplectic 4-manifold $(W^0; \omega^0)$ which is provided by Theorem 1.1, and $(W; \omega)$ be a symplectic manifold bounded by $(-V; \omega)$ which we constructed in Theorem 3.1. The required cobordism $(W^0; \omega^0)$ we then obtain by gluing $(\bar{W}; \omega)$ and $(W; \omega)$ along their common boundary, see above Remark 3.6. Moreover, note that $H_1(W^0; \mathbb{Z}) = H_1(W; \mathbb{Z})$. Hence, one can arrange that $H_1(W^0; \mathbb{Z}) = 0$. □

Proof of Corollary 1.4 According to a theorem of Giroux (see [14]), any contact manifold $(V; \xi)$ admits an open book decomposition. Hence, for any symplectic form which is positive on ξ we can use Theorem 1.3 to find a symplectic manifold $(W; \omega)$ with $\partial(W; \omega) = (-V; \omega)$. Attaching $(W; \omega)$ to a non-desirable component (or components) of the boundary of a semi-illing we will transform it to a filling. □

An alternative proof of Theorem 3.1

The following lemma of Kotschick and Morita (see [18]) gives an alternative proof of Theorem 3.1.

Lemma 3.7 *Let D be the group of symplectic (i.e. area and orientation preserving) transformations of a closed surface $(F_0; \omega)$ where ω is an area form with $\int_{F_0} \omega = 1$. Then the commutator $[D; D]$ contains the identity component D_0 . If the genus of F_0 is > 2 then the group D is perfect, i.e. $D = [D; D]$.*

The proof of this lemma is based on Banyaga's theorem [3] which states that $[D_0; D_0] = D_H$, a theorem of Harer (see [17]) that the group

$$H_1(\mathcal{M}_g) = \mathcal{M}_g/[g; g];$$

where \mathcal{M}_g is the mapping class group of the surface of genus g , is trivial if $g > 2$ (and it is finite for $g = 2$), and the following formula of Lalonde and Polterovich from [21]. For any symplectomorphism $g \in D$ and any $f \in D_0$ we have $[g; f] = gfg^{-1}f^{-1} \in D_0$ and

$$\text{Flux}([g; f]) = g(\text{Flux}(f)) - \text{Flux}(f) :$$

In particular, if the linear operator $g : H^1(F_0; \mathbb{R}) \rightarrow H^1(F_0; \mathbb{R})$ has no eigenvalues $\neq 1$ then the formula

$$f \notin \text{Flux}([g; f])$$

defines a surjective map of D_0 onto $H^1(F_0; \mathbb{R})$ (or $H^1(F_0; \mathbb{R} = \mathbb{Z})$ if F_0 is the torus). Clearly, there are a lot of diffeomorphisms g with this property, and therefore one can represent any Hamiltonian isotopy class from D_0 as a commutator of a fixed $g \in D$ and a Hamiltonian diffeomorphism.

Lemma 3.7 allows us to extend any symplectic fibration over a circle whose fiber has genus ≥ 2 to a symplectic fibration over a surface with boundary. The minimal genus of this surface is equal $1 + m$, where m is the minimal number of commutators needed to decompose the class of $\text{Hol}_{V; !}$ in the mapping class group into a product of commutators. This gives an alternative proof of Theorem 3.1 for the case when $\text{genus}(F_0) \geq 2$. The genus restriction is not a serious obstruction for applications. However, it is unclear whether it is possible to improve this construction to accommodate the condition $H_1(W) = 0$.

4 Different flavors of symplectic fillings

We conclude this article by summarizing the known relations between all existing notions of symplectic filling which were introduced in my earlier papers.

A contact manifold $(V; \xi)$ is called

(Weak) *Weakly symplectically fillable* if there exists a symplectic manifold $(W; \omega)$ with $\partial W = V$ and with $\int j > 0$;

(Strong) *Strongly symplectically fillable* if there exists a symplectic manifold $(W; \omega)$ with $\partial W = V$ such that ω is exact near the boundary and there exists its primitive λ such that $\lambda|_V = f j_V = 0g$ and $d j > 0$;

(Stein-1) *Stein (or Weinstein) fillable* if it can be filled by Weinstein symplectic manifold, i.e. an exact symplectic manifold $(W; \omega)$ such that ω admits a primitive λ such that the Liouville vector field X_λ which is ω -dual to λ (i.e. $X_\lambda \lrcorner \omega = \lambda$) is gradient-like for a Morse function on W which is constant and attains its maximum value on the boundary.

Stein fillability admits several equivalent reformulations. $(V; \xi)$ is Stein fillable if and only if

(Stein-2) $(V; \xi)$ can be obtained by a sequence of index 1 contact surgeries and index 2 surgeries along Legendrian knots with the (-1) -framing with respect to the framing given by the vector field normal to the contact structure;

(Stein-3) $(V; \xi)$ is compatible with an open book decomposition which arises on the boundary of a Lefschetz fibration over a disc such that the holonomy diffeomorphisms around singular fibers are positive Dehn twists;

(Stein-4) $(V; \xi)$ is *holomorphically fillable* i.e. there exists a complex manifold W which has V as its strictly pseudo-convex boundary and ξ is realized as the fields complex tangencies to the boundary.

The equivalence of (Stein-1) and (Stein-2) follows from [9] or [29]. The equivalence between (Stein-2) and (Stein-3) is established in [1] and [24]. The implication (Stein-1) \Rightarrow (Stein-4) is established in [9], while the opposite implication follows from [4].

Clearly,

$$(\text{Stein}) \Rightarrow (\text{Strong}) \Rightarrow (\text{Weak});$$

and all these notions imply the tightness, see [7] and [16]. As it is shown in this paper the notion of (weak/strong) semi-fillability introduced in [10] is equivalent to (weak/strong) fillability, and hence from now on it should disappear.

Here is a summary of what is known about the relation between three above notions of fillability and the notion of tightness.

Tightness does not imply weak fillability. Such an example was first constructed by John Etnyre and Ko Honda in [11]. More examples were constructed by Paolo Lisca and Andras Stipsicz in [23].

Weak fillability does not imply strong fillability. For instance, it was shown in [8] that the contact structures ξ_n on the 3-torus induced from the standard contact structure by a n -sheeted covering are all weakly symplectically fillable, but not strongly fillable if $n > 1$.

It is not known whether strong fillability implies Stein fillability. There are, however, examples of strong symplectic fillings which are not Stein fillings. The first example of this kind is due to Dusa McDuff from [25] who constructed an exact symplectic manifold $(W; \omega)$ with a disconnected contact boundary $\partial W = V_1 \cup V_2$. This manifold cannot carry a Stein structure because it is not homotopy equivalent to a 2-dimensional cell complex. Let us also point out that for $\dim V > 3$ the notions of Stein and strong symplectic fillability *do not coincide*: using a modification of the above McDuff's argument one can construct a strongly fillable contact manifold which cannot be a boundary of a manifold homotopy equivalent to a half-dimensional cell complex.

We will finish this section by showing that one possible notion of fillability which seems to be intermediate between the conditions (Weak) and (Strong) is, in fact, equivalent to strong fillability. The Proposition 4.1 is equivalent to Lemma 3.1 in [6]. It also appeared in [26].

Proposition 4.1 *Suppose that a symplectic manifold $(W; \omega)$ weakly fills a contact manifold $(V; \eta)$. Then if the form ω is exact near $\partial W = V$ then it can be modified into a symplectic form ϵ such that $(W; \epsilon)$ is a strong symplectic filling of $(V; \eta)$.*

Proof Let η be a contact form which defines η such that $d\eta = \omega|_V$. According to Lemma 2.1 for a sufficiently small $\epsilon > 0$ and an arbitrarily large constant $C > 0$ there exists a symplectic form ω_ϵ on W which coincides with ω outside the 2ϵ -tubular neighborhood $U_{2\epsilon}$ of ∂W , and is equal to

$$Cd(t) + \eta; t \in [1 - \epsilon; 1];$$

inside the 2ϵ -tubular neighborhood $U_{2\epsilon}$ of ∂W . By assumption, ω is exact near the boundary. Hence, we can assume that $\omega = d\alpha$ in U_ϵ . Let χ be a cut-off function on U_ϵ which is equal to 0 near ∂W , and is equal to 1 near the other component of the boundary of U_ϵ . Then if C is large the form

$$\epsilon = Cd(t) + d(\chi \alpha)$$

is symplectic, and together with η on $W \setminus U_\epsilon$ defines a strong symplectic filling of $(V; \eta)$. □

Remark 4.2 There are known several results concerning so-called *concave* symplectic fillings (which means $\partial(W; \omega) = (-V; \eta)$). Paolo Lisca and Gordana Matic proved in [22] that any Stein fillable contact manifold embeds as a separating hypersurface of contact type into a closed symplectic manifold (in fact a

complex projective manifold). Selman Akbulut and Burak Ozbagci gave in [2] a more constructive proof of this fact. Their construction topologically equivalent to one considered in this paper, though they did not consider the problem of extension of the taming symplectic form ω . John Etnyre and Ko Honda showed (see [12]) that any contact manifold admits a concave symplectic filling which implies that a symplectic manifold which strongly fills a contact manifold can be realized as a domain in a closed symplectic manifold. A different proof of this result is given by David Gay in [13]. Theorem 1.3 proven in this paper asserts a similar result for weak symplectic fillings. After learning about this article John Etnyre sent me an argument which shows that the weak case can be deduced from the strong one, thus giving an alternative proof of Theorem 1.3. His idea is that by performing a sequence of Legendrian contact surgeries it is possible to transform a contact manifold into a homology sphere and thus, taking into account an argument from Proposition 4.1, to reduce the problem to the case considered in their paper [12] with Ko Honda.

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