

A1:

a) richtig

b) falsch

c) falsch (Matrixstruktur von $D+L$)

d) falsch,

$$\delta(a-b) = \frac{a}{a-b} \frac{\Delta a}{a} - \frac{b}{a-b} \cdot \frac{\Delta b}{b} \quad ; \quad \begin{array}{l} 10^{-3} = 1-a \Rightarrow a = 1-10^{-3} \\ 10^{-2} = 0.9-b \Rightarrow b = 0.9-10^{-2} \end{array} \Rightarrow \delta(a-b) = -8\%$$

e) richtig,

$$F(x) = \frac{1}{5} \cos^2(x), \quad F(x) \in [0, 1] \quad ; \quad F'(x) = \frac{2}{5} \cos(x) \sin(x) < 1 \Rightarrow \text{Lipschitz}$$

f) richtig,

$$f'(z) \approx \frac{f(z+\Delta z) - f(z)}{\Delta z} = \frac{\frac{1}{2}(z^2 + 2z\Delta z + \Delta z^2) - \frac{1}{2}z^2}{\Delta z} = \underbrace{z + \frac{\Delta z}{2}}_{f'(z)}$$

g) richtig

h) falsch

a)

$$\text{Einsetzen: } \frac{\Delta}{8} \cdot (0 + 3 \cdot (\frac{2}{3})^2 + 3 \cdot (\frac{2}{3} \cdot 2)^2 + 2^2) = \underline{\underline{\frac{1}{3} 2^3}}$$

Da eine quadratische Funktion exakt integriert wird, ist der Genauigkeitsgrad der Quadraturformel mind. 2.

b) Genauigkeitsgrad Gauss: $2n - 1 \stackrel{!}{=} 9 \Rightarrow \underline{\underline{n = 5}}$

c)

$$\begin{array}{l} h_0 \\ h_1 = \frac{h_0}{2} \\ h_2 = \frac{h_0}{4} \end{array} \left| \begin{array}{l} R_{0,0} = 2 \\ R_{1,0} = 15 \\ R_{2,0} = 1,3 \end{array} \right. \begin{array}{l} R_{1,1} = \frac{R_{1,0} - 4^{-1} R_{0,0}}{1 - 4^{-1}} = \frac{4}{3} \\ R_{2,1} = \frac{R_{2,0} - 4^{-1} R_{1,0}}{1 - 4^{-1}} = 1,2333 \\ R_{2,2} = \frac{R_{2,1} - 4^{-2} R_{1,1}}{1 - 4^{-2}} \\ = \underline{\underline{1,2266}} \end{array}$$

(Skript p. 98)

a) (Skript p. 68)

$$P_2(x) = f_0 l_0(x) + f_1 l_1(x) + f_2 l_2(x)$$

mit Stützstellen $x_0 = 1$, $x_1 = 1.5$, $x_2 = 2$,

$$f_0 = f(x_0) = 1, \quad f_1 = f(x_1) = \frac{2}{3}, \quad f_2 = f(x_2) = \frac{1}{2}.$$

$$\text{Also: } l_0(x) = \frac{x - x_1}{x_0 - x_1} \cdot \frac{x - x_2}{x_0 - x_2} = + \frac{x - 1.5}{0.5} \cdot \frac{x - 2}{1}$$

$$l_1(x) = \frac{x - x_0}{x_1 - x_0} \cdot \frac{x - x_2}{x_1 - x_2} = - \frac{x - 1}{0.5} \cdot \frac{x - 2}{1}$$

$$l_2(x) = \frac{x - x_0}{x_2 - x_0} \cdot \frac{x - x_1}{x_2 - x_1} = \frac{x - 1}{1} \cdot \frac{x - 1.5}{0.5}$$

$$\Rightarrow P_2(x) = \left(\frac{x - 1.5}{0.5} \right) (x - 2) - \frac{2}{3} \left(\frac{x - 1}{0.5} \right) (x - 2) + \frac{1}{2} (x - 1) \left(\frac{x - 1.5}{0.5} \right)$$

alternativ: Parabel durch die Funktionswerte in x_0, x_1, x_2 legen.

$$b) \| f(x) - P_2(x) \| = \left\| \frac{f^{(2+1)}(\xi)}{(2+1)!} (x-1)(x-1.5)(x-2) \right\| \leq \| (x-1)(x-1.5)(x-2) \|.$$

$$\| f^{(3)}(\xi) \| = \left\| \left(-\frac{1}{\xi^2} \right)'' \right\| = \left\| \left(2 \frac{1}{\xi^3} \right)' \right\| = \left\| -6 \frac{1}{\xi^4} \right\| \leq 6$$

a) Fehlergleichungen:

$$a \cdot 0 + b \cdot 0 + c - 10^3 = r_1$$

$$a \cdot 1 + b \cdot 1 + c - 3 \cdot 10^3 = r_2$$

$$a \cdot 2 + b \cdot 4 + c - 6 \cdot 10^3 = r_3$$

$$a \cdot 3 + b \cdot 9 + c - 10^4 = r_4$$

$$a \cdot 4 + b \cdot 16 + c - 10^5 = r_5$$

$$\rightarrow A = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 1 & 1 \\ 2 & 4 & 1 \\ 3 & 9 & 1 \\ 4 & 16 & 1 \end{pmatrix}$$

$$b) A = Q \cdot R \Rightarrow R = Q^T \cdot A = \begin{pmatrix} -1/\sqrt{2} & 0 & 1/\sqrt{2} \\ 0 & -1 & 0 \\ 1/\sqrt{2} & 0 & 1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & \sqrt{2} \\ 0 & 2\sqrt{2} \\ -1/\sqrt{2} & -\sqrt{2} \end{pmatrix} = \begin{pmatrix} -1 & -2 \\ 0 & -2\sqrt{2} \\ 0 & 0 \end{pmatrix}$$

$$\|Ax - c\| = \|QRx - c\| = \|Rx - Q^T c\| \rightarrow \min.$$

$$Q^T c = \begin{pmatrix} -1/\sqrt{2} & 0 & 1/\sqrt{2} \\ 0 & -1 & 0 \\ 1/\sqrt{2} & 0 & 1/\sqrt{2} \end{pmatrix} \begin{pmatrix} \sqrt{2} \\ 3 \\ \sqrt{2} \end{pmatrix} = \begin{pmatrix} 0 \\ -3 \\ 2 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} -1 & -2 \\ 0 & -2\sqrt{2} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \stackrel{!}{=} \begin{pmatrix} 0 \\ -3 \end{pmatrix} \Rightarrow \underline{x_2 = \frac{3}{2\sqrt{2}}}$$

$$\underline{x_1 = -2x_2 = -\frac{3}{\sqrt{2}}}$$

A5:

NM WS 2012

a) (Skript p. 121) $k_1 = f(t + \frac{1}{4}h, x_0 + \frac{1}{4}hk_1)$
 $\bar{x} = x_0 + hk_1$

$$\Rightarrow k_1 = (t + \frac{1}{4}h)^2 + 5(x_0 + \frac{1}{4}hk_1)$$

$$\Rightarrow k_1 = \frac{(t + \frac{1}{4}h)^2 + 5x_0}{1 - \frac{5}{4}h} \Rightarrow \bar{x} = x_0 + h \frac{(t + \frac{1}{4}h)^2 + 5x_0}{1 - \frac{5}{4}h}$$

b) (Skript p. 126) $f(t, x) = \lambda x$

$$\Rightarrow k_1 = \lambda x$$

$$k_2 = \lambda(x + hk_1)$$

$$k_3 = \lambda(x + \frac{h}{3}\lambda x + \frac{h}{3}k_2) \Rightarrow k_3 = \frac{\lambda(x + \frac{h}{3}\lambda x)}{1 - \frac{2h}{3}}$$

$$\bar{x} = x + \frac{h}{2}\lambda(x + hk_1) + \frac{h}{2} \frac{\lambda(x + \frac{h}{3}\lambda x)}{1 - \frac{2h}{3}}$$

$$= x \left(1 + \frac{2h}{2} + \frac{(2h)^2}{2} + \frac{\frac{2h}{2}}{1 - \frac{2h}{3}} \left(1 + \frac{2h}{3} \right) \right)$$

Stabilitätsfunktion.

$$a) \quad x = 0 : dx : 2;$$

$$N_x = \text{length}(x);$$

$$b) \quad q = \left((x .* y) \geq 0 \right) - \left((x .* y) < 0 \right);$$