## Exercise Sheet 9

1. (Length-Minimization) Here is an alternate procedure for constructing minimizing geodesics in a complete Riemannian manifold $M$.

A curve $\gamma:[a, b] \rightarrow M$ is called piecewise smooth if it is continuous and there is a partition $a=t_{0}<t_{1}<\cdots<t_{k}=b$ such that $\gamma \mid\left[t_{i}, t_{i+1}\right]$ is smooth. Fix $p, q \in M$ and let $\mathcal{C}$ be the set of all piecewise-smooth curves connecting $p$ and $q$.
(a) A sequence $\left(\gamma_{i}\right)_{i \geqslant 1}$ in $\mathcal{C}$ such that $L\left(\gamma_{i}\right) \rightarrow \mathrm{d}(p, q)$ is called a minimizing sequence. Show there is $r>0, k<\infty$, and a minimizing sequence $\left(\gamma_{i}\right)_{i \geqslant 1}$ such that each $\gamma_{i}$ is a broken geodesic with at most $k$ breaks and lies in $B_{r}(p)$.
(b) Show that a subsequence of $\left(\gamma_{i}\right)_{i \geqslant 1}$ converges to a length-minimizing broken geodesic $\gamma$ in $\mathcal{C}$.
(c) Show that $\gamma$ is smooth. Thus, $\gamma$ is a minimizing geodesic connecting $p$ and $q$.
2. (Rays) Let $M$ be a complete, non-compact Riemannian manifold. A half-infinite geodesic $\gamma:[0, \infty) \rightarrow M$ is called a ray if it is length-minimizing (i.e. each finite segment is length-minimizing).

Show that for each $p \in M$ there is a ray emanating from $p$.
3. (Two-Manifolds with a Killing Field) Let $M$ be a complete, connected, orientable Riemannian 2-manifold. Suppose $M$ has a non-trivial Killing field $X$ with at least one zero, say $X(p)=0$. Prove that $M$ is diffeomorphic to $\mathbb{R}^{2}$ or $S^{2}$.

The basic idea is to show that geodesic polar coordinates at $p$ cover all of $M$ except possibly one point. The implementation is a bit tricky.
(a) Write $D_{r}:=B_{r}^{T_{p} M}(0)$. If $\exp _{p} \mid D_{r}$ is a diffeomorphism, show that $X$ is given in geodesic coordinates $z=x+i y$ on the image of $D_{r}$ by

$$
X(z)=a i z, \quad|z|<r
$$

for some $a \in \mathbb{R}$.
(b) Show that $\gamma:=\exp _{p}\left(\partial D_{r}\right)$ is either a single point, or a smooth, embedded curve. In the latter case, $\exp _{p} \mid D_{s}$ is a diffeomorphism for some $s>r$. Hint: Examine the value of $|X|$ on $\gamma$. Recall that $M$ is orientable. What might go wrong otherwise?
(c) Complete the proof.
4. (Holonomy in Surfaces of Revolution)
(a) Find the holonomy around a latitude circle $\gamma$ in a surface of revolution. Hint: Let $C$ be the cone tangent to the surface $M$ along $\gamma$. Compare the holonomy around $\gamma$ in $C$ with that in $M$.
(b) Apply this to show that for a circle in $S^{2}$, we again have $\vartheta=A$, where $A$ is the enclosed area (cf. Sheet 6, Exercise 1 and Sheet 8 Exercise 4).

