

Boundary condition: $f(1) = 0, f'(0)$

$$\frac{1}{\sqrt{\lambda}} \in (\mathbb{Z} + \frac{1}{2})\pi \quad \downarrow \quad B=0$$

$$\Rightarrow f_j, \quad \lambda > 0 \Rightarrow \frac{1}{\sqrt{\lambda}} \in (\mathbb{N}_0 + \frac{1}{2})\pi$$

$$\Rightarrow f_j(x) = \sqrt{2} \cos\left(\left(j - \frac{1}{2}\right)\pi x\right), \quad j \in \mathbb{N} \quad \left. \vphantom{\begin{matrix} \Rightarrow f_j(x) \\ \Rightarrow g_j(x) \end{matrix}} \right\} \text{"Fourier singular system"}$$

$$\Rightarrow g_j(x) = \sqrt{2} \sin\left(\left(j - \frac{1}{2}\right)\pi x\right)$$

$$\sigma_j = \frac{1}{(j - \frac{1}{2})\pi} \rightarrow 0 \quad j \rightarrow \infty$$

polynomial decay of sing. values \rightarrow mildly ill-posed

Inverse Problems

18 10 2013

Example: Backward heat equation $X = Y = L^2(0,1)$

$$\partial_t u = \partial_{xx} u \quad \text{on }]0,1[\times]0,T[$$

$$u(0,t) = u(1,t) = 0 \quad \forall 0 \leq t \leq T$$

Data: $u(x,T), T > 0$ fixed

Unknown: $u(x,0)$

Forward operator: $(Tf)(x) = \int_0^1 \underbrace{\left\{ \sum_{n=1}^{\infty} e^{-n^2 \pi^2 T} \sin(n\pi x) \sin(n\pi y) \right\}}_{\text{kernel } k(x,y) \in L^2(]0,1[^2)} f(y) dy$

$$k(x,y) = k(y,x) \Rightarrow T \text{ is self-adjoint}$$

and compact (kernel in L^2)

$$\Rightarrow f_j = g_j \text{ and } \sigma_j \stackrel{\text{correspond to}}{=} \text{eigenvalues of } T$$

SVD = spectral decomposition

$$Tf = \sum_{j=1}^{\infty} \lambda_j (f, f_j) f_j$$

concrete $(Tf)(x) = \sum_{n=1}^{\infty} \underbrace{e^{-n^2 \pi^2 T}}_{\text{eigenvalues}} \left(\underbrace{\int_0^1 \sqrt{2} \sin(n\pi y) f(y) dy}_{(f, f_j)} \right) \underbrace{\sqrt{2} \sin(n\pi x)}_{f_j}$

$$\text{Here: } \sigma_j = e^{-j^2 \pi^2 T}, \quad f_j = g_j = \sqrt{2} \sin\left(\frac{j}{2}\pi x\right)$$

more than exponential decay \rightarrow severely ill-posed

1.3.5 Convergence of linear regularization method

$$\{R_\alpha\}_{\alpha \in \mathcal{A}} \subset \mathcal{L}(X, Y)$$

1.3.5.1 Reconstruction by filters

Singular system for $T \in \mathcal{K}(X, Y)$ given by $(\sigma_j, f_j, g_j)_{j=1}^{\infty}$

$\mathcal{A} \hat{=} \text{parameter set with accumulation point } 0, \text{ e.g. } \mathcal{A} = \mathbb{R}^+$

\Rightarrow Given $\{q_\alpha\}_{\alpha \in \mathcal{A}}$, $q_\alpha: \mathbb{R}_0^+ \rightarrow \mathbb{R}$, define

$$R_\alpha g^\delta = \sum_{j=1}^{\infty} q_\alpha(\sigma_j^2) (T^* g^\delta, f_j) f_j \quad g^\delta \in Y$$

Recall: "functional calculus"

$T \in \mathcal{K}(X)$, $T = T^*$, $\phi: \mathbb{R} \rightarrow \mathbb{R}$, ϕ bounded

$$\underbrace{\phi(T)}_{\in \mathcal{L}(X)} f = \sum \underbrace{\phi(\lambda_j)}_{\text{eigenvalues}} \underbrace{(f, f_j)}_{\text{eigenfunctions}} f_j$$

Γ $A \in \mathbb{C}^{n \times n}$, $A = A^H \Rightarrow A = U D U^H$

$$\exp(A) = U \exp(D) U^H$$

$$\phi(A) = U \left(\begin{matrix} \phi(\lambda_1) & & \\ & \ddots & \\ & & \phi(\lambda_n) \end{matrix} \right) U^H$$

\perp

$$\Rightarrow R_\alpha = q_\alpha(T^* T) T^*$$

Approximation error: $g = T f^+$

$$\begin{aligned} f^+ - R_\alpha T f^+ &= (Id - q_\alpha(T^* T) T^* T) f^+ \\ &= r_\alpha(T^* T) f^+ \end{aligned}$$

with $r_\alpha(\lambda) = 1 - \lambda q_\alpha(\lambda)$

Def 1.3.5.1 (Filter) A family of measurable functions

$q_\alpha: \mathbb{R}_0^+ \rightarrow \mathbb{R}$, $\alpha \in \mathcal{A}$, is a filter, if

$$(F1) \lim_{\lambda \rightarrow 0} r_\alpha(\lambda) = \begin{cases} 0 & \text{for } \lambda > 0 \\ 1 & \text{for } \lambda = 0 \end{cases}$$

$$(F2) \exists C_r > 0: |r_\alpha(\lambda)| \leq C_r \quad \forall \alpha \in \mathcal{A}, \lambda \geq 0, \text{ where } r_\alpha(\lambda) = 1 - \lambda q_\alpha(\lambda)$$

$$(F3) \sqrt{\lambda} |q_\alpha(\lambda)| \leq \frac{C_q}{\sqrt{\lambda}} \text{ for some } C_q > 0 \text{ and all } \alpha \in \mathcal{A}, \lambda \geq 0$$

$$(F1) \rightarrow \lim_{\alpha \rightarrow 0} q_\alpha(\lambda) = \frac{1}{\lambda}, \lambda > 0 \quad [\text{Blow-up is necessary!}]$$

Example: Tikhonov regularization ($f_0 = 0$)
 $R_\alpha g^\delta := \arg \min_f \{ \|g^\delta - Tf\|_Y^2 + \alpha \|f\|_X^2 \}$

$$\Leftrightarrow R_\alpha = (T^*T + \alpha \text{Id})^{-1} T^*$$

$$\Rightarrow R_\alpha = q_\alpha(T^*T) T^* \quad \text{with} \quad q_\alpha(\lambda) = \frac{1}{\lambda + \alpha}$$

$$\Rightarrow r_\alpha(\lambda) = 1 - \frac{\lambda}{\lambda + \alpha} = \frac{\alpha}{\lambda + \alpha} \Rightarrow (F1) \checkmark$$

(F2) satisfied with $C_r = 1$

$$(F3) \quad 2\lambda q_\alpha(\lambda)^2 = 2\lambda \frac{1}{(\lambda + \alpha)^2} = \frac{2\lambda}{\lambda^2 + 2\lambda\alpha + \alpha^2} \leq \frac{2\lambda}{2\alpha\lambda} = \frac{1}{\alpha}$$

Example: Landweber

$$f_0^+ := 0$$

$$f_{k+1}^+ := f_k^+ - \mu T^*(Tf_k^+ - g^\delta), \quad \mu \leq \|T^*T\|_X$$

$$\alpha = \frac{1}{j}: \quad R_\alpha g^\delta := f_j^+ = \sum_{k=0}^{j-1} (\text{Id} - \mu T^*T)^k T^* g^\delta$$

$$A = \{1/j\}_{j \in \mathbb{N}}$$

wlog: $\mu = 1$
 $(\|T^*T\| \leq 1)$

$$R_\alpha = q_\alpha(T^*T) T^* \quad \text{with}$$

can always be achieved rescaling the norm $\|\cdot\|_X$

$$q_\alpha(\lambda) = \sum_{k=0}^{j-1} (\text{Id} - \lambda)^k \stackrel{\lambda \in (0,1)}{=} \frac{1 - (\lambda - 1)^j}{\lambda}$$

$$\Rightarrow r_\alpha(\lambda) = (1 - \lambda)^j$$

• (F1): here $j \rightarrow \infty$ ✓

• (F2): $C_r = 1$

• (F3): ~~$\frac{1}{j} \left[\frac{1 - (1-\lambda)^j}{\lambda} \right]^2 = \frac{1}{j\lambda} (1 - 2(1-\lambda)^j + (1-\lambda)^{2j})$~~

we know $\lambda |q_\alpha(\lambda)| \leq 1$

$$|q_\alpha(\lambda)| \leq j \quad \left(q_\alpha(\lambda) = \sum_{k=0}^{j-1} (1-\lambda)^k \right)$$

multiply $\lambda |q_\alpha(\lambda)|^2 \leq j = \frac{1}{\alpha}$

$$\Rightarrow C_q = 1$$

Example: Regularization by truncated SVD

$$\text{Motivated by: } T^*g = \sum_{j: \sigma_j \neq 0} \sigma_j^{-1} (g, g_j) f_j$$

$$\rightarrow R_\alpha g := \sum_{j: \sigma_j^2 > \alpha} \sigma_j^{-1} (g, g_j) f_j, \alpha > 0$$

$$\text{Recall: } g_j = \frac{1}{\sigma_j} T f_j$$

$$(g, g_j)_Y = (g, \frac{1}{\sigma_j} T f_j)_Y = (\frac{1}{\sigma_j} T^* g, f_j)_X$$

Related filter

$$R_\alpha g = \sum_{j: \sigma_j^2 > \alpha} \frac{1}{\sigma_j^2} (T^* g, f_j) f_j$$

$$q_\alpha(\lambda) = \frac{1}{\lambda} \chi_{[\alpha, \infty)}(\lambda)$$

$$r_\alpha(\lambda) = 1 - \lambda q_\alpha(\lambda) = \chi_{[0, \alpha]}(\lambda)$$

$$(F_1) - (F_2) - (F_3) \text{ with } C_r = 1, C_q = 1$$

$T \in \mathcal{K}(X, Y)$ with singular system $\{\sigma_j, f_j, g_j\}$

Reconstruction operator induced by filter fct $q_\alpha: \mathbb{R}^+ \rightarrow \mathbb{R}$

$$\begin{aligned} R_\alpha g &:= q_\alpha(T^*T)T^*g \\ &= \sum_{j=1}^{\infty} q_\alpha(\sigma_j^2) (T^*g, f_j) f_j \end{aligned}$$

Approximation error:

$$f - R_\alpha T f = f - q_\alpha(T^*T)T^*T f = r_\alpha(T^*T)f$$

$$\text{with } r_\alpha(\lambda) = 1 - \lambda q_\alpha(\lambda)$$

$$\text{residual: } T R_\alpha g^\delta - g^\delta = \sum_k \sigma_k (R_\alpha g^\delta, f_k)_X g_k - (g^\delta, g_k)_Y g_k$$

$$= \sum_k \sigma_k q_\alpha(\sigma_k^2) (T^*g^\delta, f_k)_X g_k - (g^\delta, g_k)_Y g_k$$

$$\begin{aligned} & \stackrel{[T f_k = \sigma_k g_k]}{=} \sum_k \underbrace{(\sigma_k^2 q_\alpha(\sigma_k^2) - 1)}_{-r_\alpha(\sigma_k^2)} (g^\delta, g_k)_Y g_k \quad [\sigma_k^2 \text{ EV of } T T^*] \\ & = -r_\alpha(T T^*) g \end{aligned}$$

$\boxed{T T^*}$ because g_k are its eigenfcts