

$$\| (Id - \rho T T^*)^n g \|_Y \leq C \left(\frac{1}{2n} \right)^{k+1} \| f \|_V^2 \frac{1}{\rho^{k+1}} \stackrel{!}{=} (\tau-1)^2 \delta^2$$

$$\Rightarrow \boxed{n \sim \delta^{-2/(k+1)} \cdot C}$$

More, since Landweber has infinite qualification order (1.4.4.A) will yield an optimal regularization method (\rightarrow 1.4.2)

Inverse Problems

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STOP iteration, when $\| g^\delta - T R_n g^\delta \|_Y \leq \tau \delta$

Landweber: if $f^+ \in K_{V, \delta}$ then $\| f^+ - R_{n_{\text{stop}}} g^\delta \|_X \leq C \delta^{\frac{k}{2k+1}} \delta^{\frac{1}{2k+1}}$
 $n_{\text{stop}} \approx \delta^{-2/(2k+1)}$

↑
order optimality

CG: [Plato 1992]: If $g \in \mathcal{R}(T)$, $f^+ \in K_{V, \delta}$
 $(\hat{f}_n) \stackrel{\hat{!}}{=} \text{CG sequence with } \hat{f}_0 = 0,$
 $n_{\text{stop}} = n_{\text{stop}}(\delta, g^\delta)$ by discrepancy principle
 $\| f^+ - \hat{f}_{n_{\text{stop}}} \|_X \leq C \delta^{\frac{k}{2k+1}} \delta^{\frac{1}{2k+1}}$

[Nemirovski 1986]: $n_{\text{stop}} \approx \delta^{-\frac{1}{2k+1}}$ ($< \delta^{-\frac{2}{2k+1}}$ for Landweber)

1.5 Linear Stochastic Inverse Problems

1.5.1 Estimation of probability density

estimation is the equivalent of reconstruction

Related to differentiation

Setting: $(\Omega, \mathcal{A}, \mathbb{P}) \hat{=} \text{probability space}$

Random variable (RV) $X: \Omega \rightarrow [0, 1]$

X has (probability) density $f \in \mathcal{L}^1(\mathbb{R})$

$$\mathbb{P}(X \in [a, b]) = \int_a^b f(t) dt$$

Cumulative distribution function (CDF) F

$$F(x) = \mathbb{P}(X \leq x) = \int_0^x f(t) dt =: (Tf)(x)$$

Given: sample of n iid copies of X :

RV X_1, \dots, X_n

Sought: Estimate for $f \in \mathcal{L}^2(0, 1)$

Estimate for CDF: $\hat{F}(x; \omega) = \frac{1}{n} \# \{i: X_i(\omega) \leq x\}$

↑
this is a random variable
a step function (for ω fixed)

$$\hat{F}(x, \omega) = \frac{1}{n} \sum_{i=1}^n \chi_{\{x_i(\omega) \leq x\}}(x)$$

characteristic function

$$\begin{aligned} \text{Expectation: } E(\hat{F}(x, \omega)) &= \frac{1}{n} \sum_{i=1}^n E(\chi_{\{x_i \leq x\}}(x)) = F(x) \\ &= \int \mathbb{1} dP = P(X_i \leq x) = F(x) \\ &\quad \{\omega: X_i(\omega) \leq x\} \end{aligned}$$

→ \hat{F} unbiased estimator

$$\begin{aligned} \text{Var}(\hat{F}(x, \omega)) &= \frac{1}{n^2} \text{Var}\left(\sum_i \chi_{\{x_i \leq x\}}\right) = \frac{1}{n^2} \sum_i \text{Var}(\chi_{\{x_i \leq x\}}) \\ &\quad \chi_{\{x_i \leq x\}} \text{ independent} \\ &= \frac{1}{n^2} \sum_i E(\chi_{\{x_i \leq x\}}^2) - E(\chi_{\{x_i \leq x\}})^2 \\ &= \frac{1}{n^2} \sum_i (F(x) - F(x)^2) \\ &= \frac{1}{n} \underbrace{(F(x) - F(x)^2)}_{\leq 1/4} \end{aligned}$$

Recovery of f through difference quotient

$$\begin{aligned} \hat{f}_{\Delta t}(x, \omega) &= \frac{\hat{F}(x + \Delta t, \omega) - \hat{F}(x - \Delta t, \omega)}{2\Delta t} =: R_{\Delta t} \hat{F} \\ &= \frac{1}{2\Delta t n} \# \left\{ x - \Delta t \leq X_i(\omega) \leq x + \Delta t \right\} \quad \text{"Histogram estimator"} \end{aligned}$$

$$\begin{aligned} E(\hat{f}_{\Delta t}(x, \omega)) &= \frac{1}{2\Delta t n} \sum_{i=1}^n P(x - \Delta t \leq X_i(\omega) \leq x + \Delta t) \\ &= \frac{1}{2\Delta t} (F(x + \Delta t) - F(x - \Delta t)) = R_{\Delta t} F \end{aligned}$$

Wrap up. Perturbed ill-posed operator equation

$$Tf = F + \underbrace{(\hat{F} - F)}_{\substack{\text{RV with values in } L^2(\Omega), \\ E(\cdot) = 0 \\ \uparrow \\ \text{exact data}}}$$

$$\begin{aligned} \text{Noise level: } \delta &\sim \sqrt{\text{Var}(\|\hat{F} - F\|_Y^2)} \\ &\approx \frac{1}{\sqrt{n}} \end{aligned}$$

Gauging the estimation error $f(x) - \hat{f}_{\Delta t}(x, \omega)$

Mean integrated square error (MISE)

$$E(\|f - \hat{f}_{\Delta t}\|_{L^2}^2) = E(\|f - R_{\Delta t} F + R_{\Delta t} F - \hat{f}_{\Delta t}\|_{L^2}^2)$$

$$= \underbrace{\mathbb{E}(\|f - R_{\Delta t} F\|_{L^2}^2)}_{\text{approximation error (or bias)}} + 2 \underbrace{\mathbb{E}((f - R_{\Delta t} F, R_{\Delta t} F - \hat{f}_{\Delta t}))_{L^2}}_{\substack{\text{Fubini} \\ = 0}} + \underbrace{\mathbb{E}(\|R_{\Delta t} F - R_{\Delta t} \hat{F}\|_{L^2}^2)}_{\text{Variance}}$$

$$= (f - R_{\Delta t} F, \underbrace{\mathbb{E}(R_{\Delta t} F - \hat{f}_{\Delta t})}_{=0})_{L^2}$$

$$= \mathbb{E}(R_{\Delta t} \hat{F})$$

Examine Variance

$$\int_0^1 \int_0^1 |R_{\Delta t} F(x) - \hat{f}_{\Delta t}(x, \omega)|^2 dx dP(\omega)$$

$$\int_0^1 \int_0^1 |(\mathbb{E} \hat{f}_{\Delta t})(x) - \hat{f}_{\Delta t}(x, \omega)|^2 dP(\omega) dx$$

$$= \int_0^1 \text{Var} \hat{f}_{\Delta t}(x, \omega) dx =$$

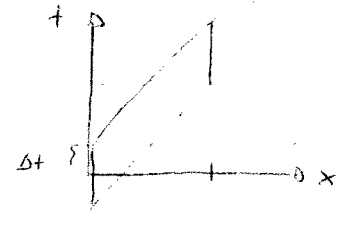
$$\text{Var}(\hat{f}_{\Delta t}(x, \omega)) = \frac{1}{4\Delta t^2 u^2} \sum_{i=1}^k \text{Var}(X_{\{x-\Delta t \leq X_i(\omega) \leq x+\Delta t\}})$$

↑
use independence

$$= \frac{1}{4\Delta t^2 u} \text{Var}(X_{[x-\Delta t, x+\Delta t]}) = \frac{1}{4\Delta t^2 u} (\mathbb{E}(X_{[x-\Delta t, x+\Delta t]}^2) - \mathbb{E}(X_{[x-\Delta t, x+\Delta t]})^2) =$$

$$= \frac{1}{4\Delta t^2 u} (\mathbb{P}(x-\Delta t \leq X \leq x+\Delta t) - \mathbb{P}(x-\Delta t \leq X \leq x+\Delta t)^2)$$

$$\leq \frac{1}{4\Delta t^2 u} \int_{x-\Delta t}^{x+\Delta t} f(t) dt$$



$$\leq \int_0^1 \frac{1}{4\Delta t^2 u} \int_{x-\Delta t}^{x+\Delta t} f(t) dt dx$$

$$\leq \frac{1}{4\Delta t^2 u} \int_{-\Delta t}^{1+\Delta t} f(t) dt \cdot 2\Delta t \leq \frac{1}{2\Delta t u} \underbrace{\|f\|_{L^1(0,1)}}_{=1} = \frac{1}{2\Delta t u}$$