

Exercise Sheet 11

$$1) \text{ We use } L_X Y = \left. \frac{d}{dt} \right|_{t=0} (\phi_t^X)^* Y \equiv \left. \frac{d}{dt} \right|_{t=0} (\phi_t)^* Y$$

$$[X, [Y, Z]] = L_X [Y, Z]$$

↑ we remove X on the top

$$= \left. \frac{d}{dt} \right|_{t=0} (\phi_t^X)^* [Y, Z]$$

$$= \left. \frac{d}{dt} \right|_{t=0} [(\phi_t^X)^* X, (\phi_t^X)^* Z] = (X)$$

Now:

$$[\phi_t^X Y, \phi_t^X Z]^\flat = [(\phi_t(\rho))^{-1} Y(\phi_t(\rho)), (\phi_t(\rho))^{-1} Z(\phi_t(\rho))]^\flat$$

its j -component is given by: (Einstein convention)

$$[(\phi_t(\rho))^{-1} Y(\phi_t(\rho))]^\flat \cdot \frac{\partial [(\phi_t(\rho))^{-1} Z(\phi_t(\rho))]^\flat}{\partial x^j} - [(\phi_t(\rho))^{-1} Z(\phi_t(\rho))]^\flat \cdot \frac{\partial [(\phi_t(\rho))^{-1} Y(\phi_t(\rho))]^\flat}{\partial x^j}$$

we can denote $[(\phi_t(\rho))^{-1} Y(\phi_t(\rho))]^\flat$ with $f^j(t, \rho)$

$[(\phi_t(\rho))^{-1} Z(\phi_t(\rho))]^\flat$ with $g^j(t, \rho)$

Then:

$$\left. \frac{d}{dt} \right|_{t=0} \left(\underbrace{f^j(t, \rho)}_A \cdot \frac{\partial}{\partial x^i} g^i(t, \rho) - \underbrace{g^j(t, \rho)}_B \cdot \frac{\partial}{\partial x^i} f^i(t, \rho) \right)$$

Substituting

$$= \left. \frac{d}{dt} \right|_{t=0} f^j(t, \rho) \cdot \frac{\partial}{\partial x^i} g^i(t, \rho) + f^j(t, \rho) \cdot \left. \frac{d}{dt} \right|_{t=0} \frac{\partial}{\partial x^i} g^i(t, \rho)$$

$$- \left. \frac{d}{dt} \right|_{t=0} g^j(t, \rho) \cdot \frac{\partial}{\partial x^i} f^i(t, \rho) - g^j(t, \rho) \cdot \left. \frac{d}{dt} \right|_{t=0} \frac{\partial}{\partial x^i} f^i(t, \rho)$$

$$= (A - D) + (B - C)$$

Since $\phi_0 = id$ we have

$$(*) = \left[\frac{d}{dt} \Big|_{t=0} (\phi_t^*) Y, z \right] + \left[Y, \frac{d}{dt} \Big|_{t=0} \phi_t^* z \right]$$

$$= \left[[X, Y], z \right] + \left[Y, [X, z] \right]$$

$$= -[z, [X, Y]] - [[X, z], Y]$$

□

② Prmk: The Jacobi identity may be proven in the following way

Explicit: compute using $[-, -]$

Indirectly: using $L_{(-)}(-) = [-, -]$ (Ex 2)

a) Let $Y \in C^0(TM)$, $f: M \rightarrow N$ local diffeom, then

$$f^*(Y)(p) := (df_p)^{-1}(Y(f(p))), \quad p \in M.$$

Recall the property of the pullback in Exercise sheet 8, Exercise 4.

Lemma 1: $f: M \rightarrow N$ diffeom, then for $X, Y \in C^0(M)$

$$f^*(L_X Y) = L_{f^*(X)} f^*(Y)$$

(or you can simply use $L_X Y = [X, Y]$, $f^*[X, Y] = [f^*X, f^*Y]$.)

pf: Sch:
 $\tilde{X} := f^*(X), \quad \tilde{Y} := f^*(Y), \quad f^*(L_X Y) := \tilde{L}_{\tilde{X}} \tilde{Y}$

Recall that the flow of X is given by a local expression, i.e.

$\forall p \in M \exists U$ open and $\delta > 0$ s.t.

$$\Phi: U \times (-\delta, \delta) \rightarrow N \quad \text{smooth}$$

$$(x, t)$$

in this situation

$$\begin{cases} \frac{\partial \Phi(x, t)}{\partial t} = X(\Phi(x, t)) \\ \Phi(x, 0) = x \end{cases} \quad (\text{fixed } t)$$

we prefer to use the notation $\Phi_x(-)$ for $\Phi(-, t)$. In particular we have

$$p \in M \rightsquigarrow \left(\underset{N}{\overset{U_p}{M}}, \underset{V}{\delta_p}, \Phi_x(b, t): U_p \times (-\delta_p, \delta_p) \rightarrow N \right)$$

Now consider $\tilde{\Phi}_x$ defined as follows

• for $p \in M$, set $p := f^{-1}(q)$, $V_q := f^{-1}(U_p)$

• let $\tilde{\Phi}_x$ be the concatenation of:

$$V_q \times (-\delta_p, \delta_p) \xrightarrow{(f \times \text{id})} U_p \times (-\delta_p, \delta_p) \xrightarrow{\Phi} N \xrightarrow{f^{-1}} M$$

$$\text{where } (f \times \text{id})(a, t) = (f(a), t).$$

Thm: $\tilde{\Phi} := f^{-1} \circ \Phi \circ (f \times \text{id}) : V_q \times (-\delta_\epsilon, \delta_\epsilon) \rightarrow M$

$\tilde{\Phi}_t = \tilde{\Phi}(t, -) = f^{-1} \circ \Phi_t \circ f : V_q \rightarrow M$

WARNING: In the lecture we denote $\Phi(x, t)$ with $\Phi_t(x)$ (even if t is not fixed)

Claim: $\tilde{\Phi}$ is the flow of $f^*(X)$.

pf: $\frac{\partial}{\partial t} \tilde{\Phi}(x, t) = d f^{-1} (\Phi \circ (f \times \text{id})) \left(\frac{\partial}{\partial t} (\Phi \circ (f \times \text{id})) (x, t) \right)$

$$= \left(d f \circ f^{-1} \circ \Phi (f \times \text{id}) \right)^{-1} \cdot X (\Phi (f \times \text{id}) (x, t))$$

$$= \left(d f \tilde{\Phi} (x, t) \right)^{-1} \cdot X (f (f^{-1} (\Phi (f \times \text{id})) (x, t)))$$

$$= \left(d f \tilde{\Phi} (x, t) \right)^{-1} \cdot X (f (\tilde{\Phi} (x, t)))$$

$$= f^*(X) (\tilde{\Phi} (t, x)) = \tilde{X} (\tilde{\Phi} (t, x))$$

Proof of Lemma:

$$L_{\tilde{X}} \tilde{Y} = \frac{d}{dt} \Big|_{t=0} \tilde{\Phi}_t^* (\tilde{Y}) \stackrel{\text{chain}}{=} \frac{d}{dt} \Big|_{t=0} (f^{-1} \circ \Phi_t \circ f) f^*(Y)$$

property of pull back \rightarrow

$$= \frac{d}{dt} \Big|_{t=0} (f \circ f^{-1} \circ \Phi_t \circ f) (Y)$$

$$= \frac{d}{dt} \Big|_{t=0} (\Phi_t \circ f) (Y)$$

$$= \frac{d}{dt} \Big|_{t=0} (f)^* \cdot \Phi_t^* (Y)$$

$$= f^* \left(\frac{d}{dt} \Big|_{t=0} \Phi_t^* (Y) \right)$$

$$= f^* (L_X Y)$$

20) Now let $X, Y \in C^0(M)$ s.t. $[X, Y] = 0$

Claim: $(\phi_t^X)^* Y = Y \quad \forall t$ (where defined)

[Mean: let $p \in M$ and let $\phi^X: U_p \times (-\delta_p, \delta_p) \rightarrow M$ be the flow of X at p . $U_p \subset M, p \in U_p$.

$$\forall p \in M \quad (\phi_t^X)^* Y = Y, \quad \forall t \in (-\delta_p, \delta_p)$$

Pf: To show $\frac{d}{dt} (\phi_t^X)^* Y = 0$ on U_p .

$$\begin{aligned} \frac{d}{dt} (\phi_t^X)^* Y &= \frac{d}{ds} \Big|_{s=t} (\phi_s^X)^* Y = \frac{d}{d\varepsilon} \Big|_{\varepsilon=0} (\phi_{t+\varepsilon}^X)^* Y \\ &= \frac{d}{d\varepsilon} \Big|_{\varepsilon=0} (\phi_{\varepsilon+t}^X)^* Y = \frac{d}{d\varepsilon} \Big|_{\varepsilon=0} (\phi_\varepsilon^X)^* (\phi_t^X)^* Y = [X, (\phi_t^X)^* Y] \end{aligned}$$

Since $(\phi_0^X)^* X = 0$ and $0 = [X, X] = \frac{d}{dt} \Big|_{t=0} (\phi_t^X)^* X \Rightarrow (\phi_t^X)^* X = X$

Thus: $[X, (\phi_t^X)^* Y] = [(\phi_t^X)^* X, (\phi_t^X)^* Y] = (\phi_t^X)^* [X, Y] = 0$

Since $(\phi_0^X)^* Y = Y \Rightarrow (\phi_t^X)^* Y = Y$.

Conclusion: $\phi_t^X \circ \phi_s^Y = \phi_s^Y \circ \phi_t^X$ where one defined

Pf: by doing $\phi_s^Y = \phi_s^{(\phi_t^X)^* Y}$ we conclude

, since $\phi_t^X: U_p \rightarrow M$ for fixed t is a diffeom onto its image, we can use

Claim 2: $\frac{d}{ds} (\phi_s^X)^* Y = (\phi_s^X)^* \frac{d}{ds} Y = (\phi_s^X)^* Y$

$$\Rightarrow \phi_s^Y = (\phi_t^X)^{-1} \circ \phi_s^Y \circ \phi_t^X$$

Since the map holds for any $p \in M$, we are done.

2.b) This is theorem 18.6 in Lee "intro to C^∞ mfd"

Proposition: $[X, Y] = 0$, $p \in M$, $X(p), Y(p)$ lin independent

$\exists U \subset M$, $p \in U$ and $\psi: U \rightarrow \mathbb{R}^n$ s.t. $\varphi(p) = (y^1(p), \dots, y^n(p))$
with $y^i: U \rightarrow \mathbb{R}$ s.t.

a) ψ is a chart.

b) $X = \frac{\partial}{\partial y^1}$, $Y = \frac{\partial}{\partial y^2}$ in U .

Prnh: This is enough for an $f: M \rightarrow \mathbb{R}$ $f \in C^\infty(M)$ $q \in U$

$$X(f)(q) = \frac{\partial}{\partial y^1} f$$

$$\frac{\partial}{\partial y^1} (f \circ \psi^{-1})$$

$\in C^\infty(\psi(U), \mathbb{R})$

pf: Let $\psi: \tilde{U} \rightarrow \mathbb{R}^n$ be a chart, $p = \psi^{-1}(0)$
Let $\phi^X: U_p \times (-\delta_1, \delta_1) \rightarrow M$, $\phi^Y: V_p \times (-\delta_2, \delta_2) \rightarrow M$

Fix: $\tilde{U} \cap U_p \cap V_p =: \mathcal{U}$, then

$$\phi: (-\delta_1, \delta_1) \times (-\delta_2, \delta_2) \times \mathbb{R}^{n-2} \rightarrow M$$

$$(x^1, x^2, x^3, \dots, x^n) \longrightarrow \phi_{x^2}^X \circ \phi_{x^1}^Y \circ \psi^{-1}(0, x^3, \dots, x^n)$$

Claim: $d\phi_0: \mathbb{R}^n \rightarrow T_p M$ is an isom

pf: $\mathbb{R}^n = T_0 \mathbb{R}^n$, $e_1 = \left(\frac{\partial}{\partial x^1} \right) = (1, 0, \dots, 0)$, $e_2 = \left(\frac{\partial}{\partial x^2} \right) = (0, 1, 0, \dots, 0)$ s.t. on \mathbb{R}^n . $e_j = (0, \dots, 0, 1, 0, \dots, 0)$
Let $\gamma_1: (-\epsilon, \epsilon) \rightarrow \mathbb{R}^n$, $\gamma_1(t) = (t, 0, \dots, 0)$, then $\gamma_1'(0) = \gamma_1'(1) = e_1$

$$d\mathbb{I}_0 e_1 = \frac{d}{dt} \Big|_{t=0} \mathbb{I}(\gamma_1(t)) = \frac{d}{dt} \Big|_{t=0} \phi_0^X \circ \phi_0^Y \circ \psi^{-1}(0, \dots, 0) = \frac{d}{dt} \Big|_{t=0} \phi_0^X(p) = X(p)$$

Let $\gamma_2: (-\epsilon, \epsilon) \rightarrow \mathbb{R}^n$, $\gamma_2(t) = (0, t, 0, \dots, 0)$, $\gamma_2'(0) = 0$, $\gamma_2'(1) = e_2$, then

$$d\mathbb{I}_0 e_2 = \frac{d}{dt} \Big|_{t=0} \mathbb{I}(\gamma_2(t)) = \frac{d}{dt} \Big|_{t=0} \phi_0^X \circ \phi_0^Y \circ \psi^{-1}(0, \dots, 0) = \frac{d}{dt} \Big|_{t=0} \phi_0^Y(p) = Y(p)$$

For $i > 2$, let $\gamma_j: (-\epsilon, \epsilon) \rightarrow \mathbb{R}^n$, $\gamma_j(t) = (0, \dots, 0, t, 0, \dots, 0)$, $\gamma_j'(0) = 0$, $\gamma_j'(1) = e_j$

$$d\mathbb{I}_0 e_j = \frac{d}{dt} \Big|_{t=0} \mathbb{I}(\gamma_j(t)) = \frac{d}{dt} \Big|_{t=0} \phi_0^X \circ \phi_0^Y \circ \psi^{-1}(0, \dots, 0, t, 0, \dots, 0) = \frac{\partial}{\partial x^j}$$

Note 1.1: $\phi \Big|_{(0,0, \mathbb{R}^{n-2})} = \psi^{-1} \Big|_{(0,0, \mathbb{R}^{n-2})}$

since ϕ is a diffeomorphism we conclude:

1) $\left(\frac{\partial}{\partial x^i}\right)_{2 \leq i \leq n}$ are linearly indep at p

2) $X(p), Y(p)$ lin indep $\Rightarrow X(p), Y(p), \frac{\partial}{\partial x^3}, \dots, \frac{\partial}{\partial x^n}$ are lin indep vectors on $T_p M$

Claim 1

By inverse fcn thm $\exists \tilde{V} \subset U$ s.t. $p \in \tilde{V}$ and

$\phi: \tilde{V} \rightarrow \phi(\tilde{V})$

ϕ a diffeom. Note you don't use condition $[X, Y] = 0$ for the moment you have more:

Claim 2: Let X, Y lin independent vector fields, then for any $p \in M \exists \psi: \mathcal{U} \rightarrow \mathbb{R}^n$ s.t. $\psi(p) = (b_1(p), \dots, b_n(p))$ and

at p . $X = \frac{\partial}{\partial y^1}, Y = \frac{\partial}{\partial y^2}$

(i.e. $X(p) = \left(\frac{\partial}{\partial y^1}\right)_{p, \psi}, Y(p) = \left(\frac{\partial}{\partial y^2}\right)_{p, \psi}$)

pf: Let $\psi = \phi^{-1} \Big|_{\tilde{V}}$ Claim 2

Note: $0 = [X, Y] \Rightarrow$ we can extend the condition at p to near p

pf of Claim 0: Let $\psi := \phi^{-1} \Big|_{\tilde{V}}, \psi: \phi(\tilde{V}) \rightarrow \tilde{V} \cong \mathbb{R}^n$

Let $(b_1, \dots, b_n) \in \tilde{V}$, let $\gamma_1: (-\epsilon, \epsilon) \rightarrow \tilde{V}$ $\gamma_1(t) = (b_1+t, b_2, \dots, b_n)$

$q := \psi(b_1, \dots, b_n)$, then

$$\begin{aligned} \left(\frac{\partial}{\partial b^2}\right)_{q, \psi} &= \frac{d}{dt} \Big|_{t=0} \psi(\gamma_1(t)) = \frac{d}{dt} \Big|_{t=0} \phi^X_{b_1+t} \circ \phi^Y_{b_2} \circ \psi^{-1}(0, 0, b_2, \dots, b_n) \\ &= \frac{d}{dt} \Big|_{t=0} \phi^X_t \left(\underbrace{\phi^Y_{b_2} \circ \psi^{-1}(0, 0, b_2, \dots, b_n)}_{\psi^{-1}(b_1, b_2, \dots, b_n)} \right) \\ &= \frac{d}{dt} \Big|_{t=0} \phi^X_t(q) = X(q) \end{aligned}$$

Let $\gamma_j: (-\epsilon, \epsilon) \rightarrow M$, $\gamma_j(t) = (b_1, b_2, \dots, b_{j-1}, b_j+t, b_{j+1}, \dots, b_n)$ then

$i=1$

$$\frac{\partial}{\partial y^1}(\gamma) = \frac{d}{dt} \Big|_{t=0} \phi_{y_1}^X \circ \phi_{y_2+t}^Y \circ \varphi^{-1}(a, a, b_3, \dots, b_n)$$

2.0)

Critical
point

$$= \frac{d}{dt} \Big|_{t=0} \phi_{y_2+t}^Y \circ \phi_{y_1}^X \circ \varphi^{-1}(a, a, b_3, \dots, b_n)$$

$$= \frac{d}{dt} \Big|_{t=0} \phi_{y_1}^X \circ \underbrace{\phi_{y_2}^Y \circ \phi_{y_2+t}^Y \circ \varphi^{-1}(a, a, b_3, \dots, b_n)}_{= \gamma}$$

$$= \frac{d}{dt} \Big|_{t=0} \phi_{y_1}^X(\gamma) \quad \varphi^{-1}(y_1, y_2, y_3, \dots, b_n) = \gamma$$

$$= X(\gamma)$$

$i \geq 2$

$$\frac{\partial}{\partial y^i}(\gamma) = \frac{d}{dt} \Big|_{t=0} \phi_{y_1}^X \circ \phi_{y_2}^Y \circ \varphi^{-1}(a, a, y_3, \dots, y_{i-1}+t, \dots, b_n)$$

$$= \frac{d}{dt} \Big|_{t=0} \varphi^{-1}(a, a, \dots, b_n)$$

USE

3.6) The idea is the same, now $\phi: (-\delta_1, \delta_1) \times \dots \times (-\delta_n, \delta_n) \rightarrow M$
given by:

$$\phi(x_1, \dots, x_n) = \phi_{x_1}^{X_1} \circ \phi_{x_2}^{X_2} \circ \dots \circ \phi_{x_n}^{X_n} (\varphi^{-1}(a, \dots, a))$$

3) Let $X \in C^0(TM)$, let $\psi: U \rightarrow \mathbb{R}^n$ be a chart $p \xrightarrow{\psi} (x^1, \dots, x^n)$
 Then on U X may be expressed as: $U \subseteq M \rightarrow \mathbb{R}^n$

$$X = \sum x^i(p) \left(\frac{\partial}{\partial x^i} \right)_p \circ \psi$$

where

1) $x^i: U \rightarrow \mathbb{R} \quad C^0$

2) $\left(\frac{\partial}{\partial x^i} \right)_p$: directional derivative in direction x^i near p

3) $X: C^0(M)^1 \rightarrow C^0(M)$ via

$$f \mapsto Xf$$

$$Xf(p) = X(p) \cdot f = \sum x^i(p) \left(\frac{\partial}{\partial x^i} \right)_p f = \sum \underbrace{x^i}_{C^0} \left(\underbrace{\psi^{-1}(x^1, \dots, x^n)}_{C^0} \right) \cdot \underbrace{\frac{\partial f \circ \psi^{-1}(x^1, \dots, x^n)}{\partial x^i}}_{C^0}$$

s.t. $p = \psi^{-1}(x^1, \dots, x^n)$.

Thus in coordinates we write $X = \sum X^i(\psi^{-1}(x^1, \dots, x^n)) \frac{\partial}{\partial x^i}$ (little abuse of notation :))
 and in this case $X \in C^0(T\psi(U))$.

A more concrete definition is given

① Consider the following concatenation of smooth maps

$$\psi(U) \xrightarrow{\psi^{-1}} U \xrightarrow{j} M$$

② thm: X in local coordinates is simply $(j \circ \psi^{-1})^* X$ (pull back)

Namely: $(j \circ \psi^{-1})^* X(p) = \left(d(j \circ \psi^{-1}) \right)_p^{-1} X(j \circ \psi^{-1})$ (*)

Supplementary exercises: Check that the two things agree 😊

consequence:

	M	$\psi(U)$	
vector field:	X	$(j \circ \psi^{-1})^* X$	\rightsquigarrow
flows:	ϕ_t^X	$(\psi \circ j^{-1})_* \phi_t^X (j \circ \psi^{-1})$	

Now by abuse of notation let $X \in C^0(T\psi(U))$ with flow ϕ_t^X (where t is in \mathbb{R}^n)

By a Taylor series argument we have:

$$\begin{aligned} \phi_t^X(x_1, \dots, x_n) &= (x_1, \dots, x_n) + \underbrace{t \cdot X(x_1, \dots, x_n)}_{t \cdot \frac{d}{dt} \Big|_{t=0} \phi_t^X(x_1, \dots, x_n)} + \frac{t^2}{2} \cdot \frac{d^2}{dt^2} \Big|_{t=0} \phi_t^X(x_1, \dots, x_n) + \dots \\ &= \phi_0^X(x_1, \dots, x_n) + \underbrace{t \cdot \frac{d}{dt} \Big|_{t=0} \phi_t^X(x_1, \dots, x_n)}_{(where \ O(\rho(t)) \text{ is the big O notation})} + O(|t|^3) \end{aligned}$$

Now: consider $\left. \frac{d}{dt} \right|_{t=0} \phi_t^X(x_1, \dots, x_n)$, we have

1) $X: M \rightarrow TM$ smooth map
 $p \rightarrow (p, X(p))$

2) $\phi_t^X: (-\delta, \delta) \rightarrow M$ for a fixed p may be considered as a path (= integral curve)
 $t \rightarrow \phi_t^X(p)$ with $\left. \frac{d}{dt} \right|_{t=0} \phi_t^X = X(p)$

3) ϕ_t^X are solutions of an ODE: $\dot{\cdot}$

$$\left. \frac{d}{dt} \right|_{t=0} \phi_t^X = X(\phi_t^X(p)) \Rightarrow \left. \frac{d^2}{dt^2} \right|_{t=0} \phi_t^X = \left. \frac{d}{dt} \right|_{t=0} X(\phi_t^X(p))$$

Thus we conclude

$$\left. \frac{d^2}{dt^2} \right|_{t=0} \phi_t^X(p) = \left. \frac{d}{dt} \right|_{t=0} X(\phi_t^X(p)) = (dX)_p \left(\left. \frac{d}{dt} \right|_{t=0} \phi_t^X(p) \right) \stackrel{\text{②}}{=} (dX)_p X(p) \stackrel{\text{③}}{=} D_X X$$

① "rule" ② "+" ③

where $D_X X = X(X)$. Working in \mathbb{R}^2 we have:

Thus we have $\phi_t^X(p) = p + tX(p) + \frac{t^2}{2} D_X X(p) + O(t^3)$

where the big O notation means:

$$\exists C > 0 \exists t_0 > 0 \text{ s.t. } \forall t \in [-t_0, t_0], \left| \phi_t^X(p) - p - tX(p) - \frac{t^2}{2} D_X X(p) \right| \leq C \cdot t^3$$

Now let consider

$$\phi_s^Y \circ \phi_t^X(p) = p + \phi_t^X(p) + sY(\phi_t^X(p)) + \frac{s^2}{2} D_Y Y(\phi_t^X(p)) + O(s^3)$$

we expand the first term:

$$\phi_t^X(p) = p + tX + \frac{t^2}{2} D_X X(p) + O(t^3)$$

the second:

$$sY(\phi_t^X(p)) = sY(p) + t \left. \frac{d}{dt} \right|_{t=0} Y(\phi_t^X(p)) + O(t^2)$$

$t \cdot D_Y X(p)$
 (same argument as above)

the last:

$$D_Y Y(\phi_t^X(p)) = D_Y Y(p) + O(t)$$

we have:

$$\begin{aligned} \phi_s^Y \circ \phi_t^X(p) &= \phi_t^X(p) + sY(\phi_t^X(p)) + \frac{s^2}{2} D_Y Y(\phi_t^X(p)) + O(s^3) \\ &= p + tX + \frac{t^2}{2} D_X X(p) + O(t^3) \\ &\quad + sY(p) + ts D_Y Y(p) + O(st^2) \\ &\quad + \frac{s^2}{2} D_Y Y(p) + O(\frac{s^2}{2} \cdot t) \end{aligned}$$

[if you want this is just the Taylor formula in 2 variables]

3.a)

$$\Rightarrow \phi_s^Y \circ \phi_t^X(p) = p + tX + \frac{t^2}{2} D_X X(p) + sY(p) + ts D_Y Y(p) + \frac{s^2}{2} D_Y Y(p) + O(s^3 + t^3)$$

$$\phi_{-t}^X \circ \phi_s^Y \circ \phi_t^X(p) = \phi_s^Y \circ \phi_t^X(p) + -tX(\phi_s^Y \circ \phi_t^X(p)) + \frac{t^2}{2} D_X X(\phi_s^Y \circ \phi_t^X(p)) + O(t^3)$$

again with a Taylor formula.

1 term: $p + tX + \frac{t^2}{2} D_X X(p) + sY(p) + ts D_Y Y(p) + \frac{s^2}{2} D_Y Y(p) + O(s^3 + t^3)$

2 term: $X(p) + \frac{s}{\partial s} \Big|_{s=0} X(\phi_s^Y \circ \phi_t^X(p)) + t \cdot \frac{\partial}{\partial t} \Big|_{t=0} X(\phi_s^Y \circ \phi_t^X(p)) + O(s^2 + t^2)$

(Taylor in two variables) $= X(p) + s D_Y X + t D_X X + O(s^2 + t^2)$

3 term $D_X X(p + O(\|H\|)) = D_X X(p) + O(\|H\|)$

Ans: the above expression is

$$\begin{aligned} &p + tX + \frac{t^2}{2} D_X X(p) + sY(p) + ts D_Y Y(p) + \frac{s^2}{2} D_Y Y(p) + O(s^3 + t^3) \\ &+ -tX(p) - st D_Y X(p) - t^2 D_X X(p) - t O(s^2 + t^2) \\ &+ \frac{t^2}{2} D_X X(p) + \frac{t^2}{2} O(t) \\ &= p + sY + ts D_Y Y + \frac{s^2}{2} D_Y Y + (D_X Y - D_Y X)st + O((s^3 + t^3)) \end{aligned}$$

Analogue argument (use if you want Taylor series with 3 variables)

Tell us:

$$\int_{-s}^s \phi_{-t}^X \circ \phi_{-t}^Y \circ \phi_{-s}^Y \circ \phi_t^X (p) = p + st [D_X Y - D_Y X] + s^2 D_Y Y - s^2 D_X X + O(|s|^3 + |t|^3)$$

(3.5)

Note:

(3.5)

- The last expression is coordinate invariant because it is $[D_X Y - D_Y X] = [X, Y]$
- The 2nd expression (3.5) is not! In particular because $D_X Y$ (with our naive definition is not coordinate invariant)

⇒ to make $D_X Y$ coordinate invariant you need to add other expression Γ called Cristoffel symbol

~~AAAAA~~

A more clear way

Let $X, Y \in C^\infty(T\mathbb{R}^n)$, let

$$\begin{aligned} \psi_t &: \mathbb{R}^n \rightarrow \mathbb{R}^n && \text{flow of } Y \\ \phi_s &: \mathbb{R}^n \rightarrow \mathbb{R}^n && \text{flow of } X \end{aligned}$$

for s, t small, look at $f: (-\delta, \delta) \times (-\delta, \delta) \rightarrow \mathbb{R}^n$

$$(s, t) \longmapsto \phi_s \circ \psi_t (x)$$

Taylor exp of f at $(0,0)$

$$\begin{aligned} f(s, t) &= f(0,0) + s \partial_s f(0,0) + t \partial_t f(0,0) + \frac{s^2}{2} \partial_s^2 f(0,0) \\ &\quad + \frac{t^2}{2} \partial_t^2 f(0,0) + st \partial_s \partial_t f(0,0) + O(|t|^3 + |s|^3) \end{aligned}$$

Let $p = f(0,0)$, then

$$\partial_t f(0,0) = \frac{d}{d\epsilon} \Big|_{\epsilon=0} f(0, \epsilon) = \frac{d}{d\epsilon} \Big|_{\epsilon=0} \psi_\epsilon(p) = Y(p)$$

$$\partial_s f(0,0) = X(p)$$

$$\begin{aligned} \partial_s^2 f(0,0) &= \frac{d}{d\epsilon} \Big|_{\epsilon=0} \frac{d}{d\eta} \Big|_{\eta=\epsilon} \phi_s(p) = dX_p \frac{d}{d\epsilon} \Big|_{\epsilon=0} \phi_\epsilon(p) = dX_p X(p) \\ &= D_X X(p) \end{aligned}$$

Analogously

$$\partial_s^2 f(0,0) = D_Y X(p)$$

$$\begin{aligned} \partial_t \partial_s f(0,0) &= \left. \frac{\partial}{\partial t} \right|_{t=0} \underbrace{\left. \frac{\partial}{\partial s} \right|_{s=0} \psi_t \circ \phi_s(p)}_{= X(\phi_s(p))} \\ &= dX_p Y(p) = D_Y X(p) \end{aligned}$$

\Rightarrow the same as

b) Some idea! Consider the function

$$g(x_1, x_2, x_3, x_4) = \psi_{-x_1} \circ \phi_{-x_2} \circ \psi_{x_3} \circ \phi_{x_4}(p)$$

$$\text{Set } f(s,t) = g(t, s, t, s)$$

$$\begin{aligned} \text{Note } g(t, 0, t, 0) &= p & \Rightarrow \partial_s f &= \partial_s^2 f = 0 \\ g(0, s, 0, s) &= p & \Rightarrow \partial_t f &= \partial_t^2 f = 0 \end{aligned}$$

By Taylor around 0:

$$f(s,t) = p + st \partial_s \partial_t f(0,0) + O(|s|^3 + |t|^3)$$

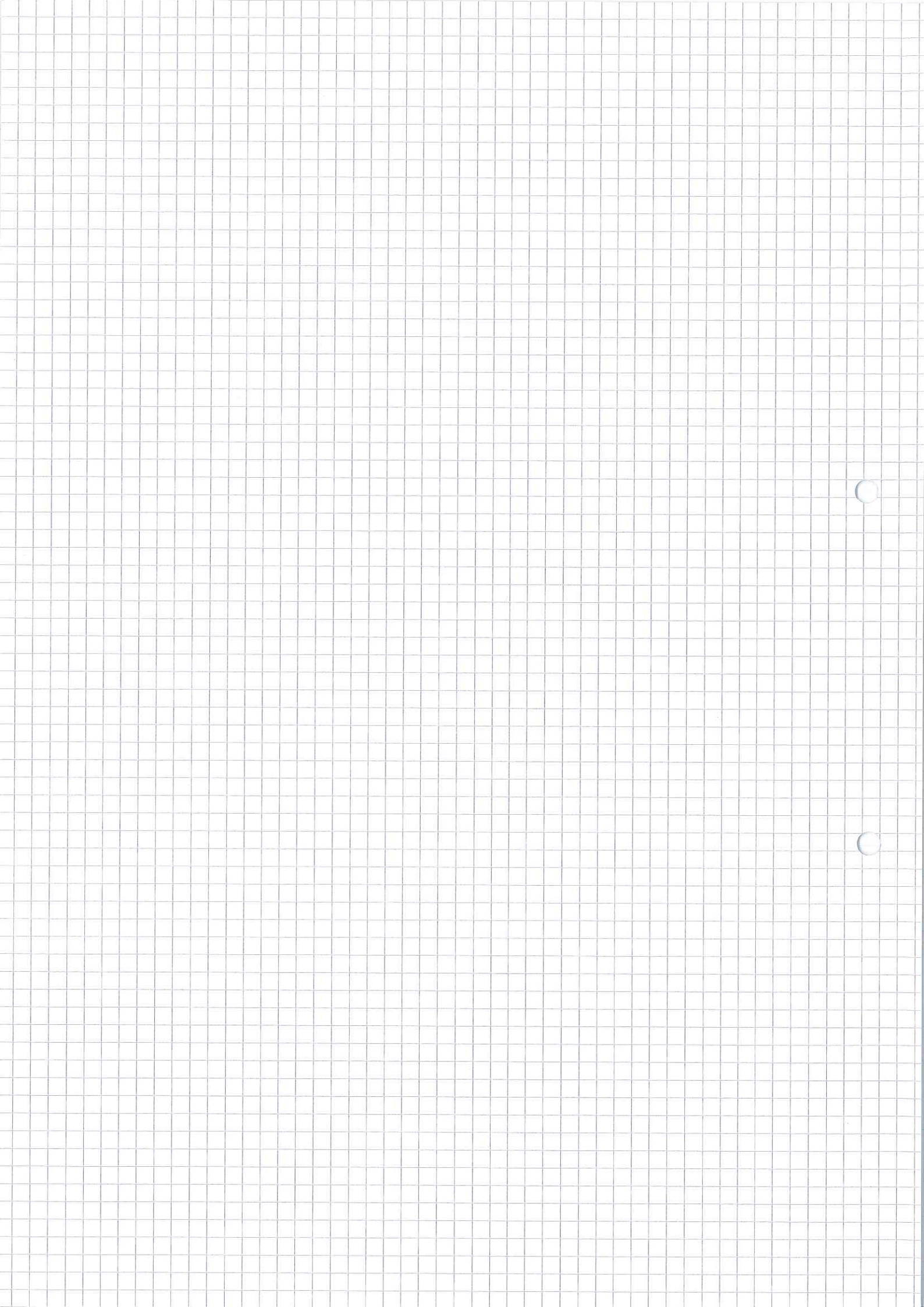
$$\partial_s \partial_t f(0,0) = \left. \frac{\partial}{\partial s} \right|_{s=0} \left. \frac{\partial}{\partial t} \right|_{t=0} g(t, s, t, s) = \left. \frac{\partial}{\partial s} \right|_{s=0} \underbrace{\left(\partial_t g \right)}_{\text{chain rule}}(0, s, 0, s) + \left(\partial_s g \right)(0, s, 0, s) = (*)$$

$$\partial_t g(0, s, 0, s) = \left. \frac{\partial}{\partial x_1} \right|_{x_1=0} \underbrace{\psi_{-x_1} \circ \phi_{-s} \circ \psi_0 \circ \phi_s(p)}_{= p} = -X(p)$$

$$\begin{aligned} \left(\partial_s g \right)(0, s, 0, s) &= d \left(\psi_{-1} \circ \phi_{-s} \right) \left. \frac{\partial}{\partial x_3} \right|_{x_3} \psi_{x_3} \circ \phi_s(x) = d \left(\phi_{-s} \right)_{\phi_s(p)} X(\phi_s(p)) \\ &= X(\phi_s(p)) \end{aligned}$$

$$= \phi_s^* (X)(p)$$

$$\underline{\text{Thm.}} (*) = \left. \frac{\partial}{\partial s} \right|_{s=0} \left[(-X(p) + \phi_s^* (X)(p)) \right]_{s=0} = 0 + [X_s Y](p)$$



4.a) $M = \mathbb{R}^2 \times S^1$

$X(x_1, x_2, e^{i\theta}) = (\cos \theta, \sin \theta, i \cdot e^{i\theta})$

$Y(x_1, x_2, e^{i\theta}) = (\cos \theta, \sin \theta, -i \cdot e^{i\theta})$

Let $\phi_t^X(x_1, x_2, e^{i\theta})$ be the flow of X with in $\phi_0(x_1, x_2, e^{i\theta}) = (x_1, x_2, e^{i\theta})$

Claim 1 $\phi_t^X(x_1, x_2, e^{i\theta}) = (x_1 - \sin \theta + \sin(t+\theta), x_2 + \cos \theta - \cos(t+\theta), e^{i(t+\theta)})$

pf: $\frac{d}{dt} \phi_t^X(x_1, x_2, e^{i\theta}) = (\cos(t+\theta), \sin(t+\theta), i \cdot e^{i(t+\theta)})$
 $= X(\phi_t^X(x_1, x_2, e^{i\theta}))$

obviously:

The flow of Y with $\phi_0^Y(x_1, x_2, e^{i\theta}) = (x_1, x_2, e^{i\theta})$ is

$\phi_t^Y(x_1, x_2, e^{i\theta}) = (x_1 + \sin \theta - \sin(\theta-t), x_2 - \cos \theta + \cos(\theta-t), e^{i(\theta-t)})$

By looking at the first two coordinates (in \mathbb{R}^2)

ϕ_t^X is a rotation around $(x_1 - \sin \theta, x_2 + \cos \theta)$ with $\Delta t \uparrow$ (counter-clock)

ϕ_t^Y " " " $(x_1 + \sin \theta, x_2 - \cos \theta)$ " $\Delta t \downarrow$ (clock)

b) $XY(p) = dY_p \cdot X(p) = \frac{d}{dt} \Big|_{t=0} X(\phi_t^Y(p)) = \frac{d}{dt} \Big|_{t=0} (\cos(\theta-t), \sin(\theta-t), i \cdot e^{i(\theta-t)})$

same explanation

or for exercise 3!

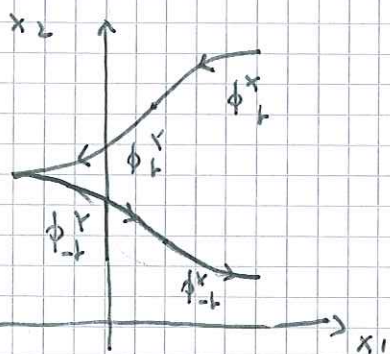
$= (\sin \theta, -\cos \theta, e^{i\theta})$

$YX(p) = dX_p \cdot Y(p) = \frac{d}{dt} \Big|_{t=0} Y(\phi_t^X(p)) = \frac{d}{dt} \Big|_{t=0} (\cos(\theta+t), \sin(\theta+t), -i \cdot e^{i(\theta+t)})$

$= (-\sin \theta, \cos \theta, e^{i\theta})$

$[X, Y](p) = -dX_p Y(p) + dY_p X(p) = -(2 \sin \theta, -2 \cos \theta, 0)$

4.c) $\gamma(t) := \phi_{-t}^X \circ \phi_{-t}^X \circ \phi_t^X \circ \phi_t^X$ is a "parking trajectory" (looking only in \mathbb{R}^2 !)



Explicit

$$(x_1, x_2, e^{i\theta}) \xrightarrow{\phi_t^X} (x_1 - \sin\theta + \sin(t+\theta), x_2 + \cos\theta - \cos(t+\theta), e^{i(t+\theta)})$$

$$\xrightarrow{\phi_{-t}^X} (x_1 - \sin\theta + \sin(t+\theta) + \sin(t+\theta) - \sin((t+\theta)-t), x_2 + \cos\theta - \cos(t+\theta) - \cos(t+\theta) + \cos((t+\theta)-t), e^{i((t+\theta)-t)})$$

$$= (x_1 - 2\sin\theta + 2\sin(t+\theta), x_2 + 2\cos\theta - 2\cos(t+\theta), e^{i\theta})$$

$$\xrightarrow{\phi_t^X} (x_1 - 2\sin\theta + 2\sin(\theta+t) - \sin\theta + \sin(-t+\theta), x_2 + 2\cos\theta - 2\cos(\theta+t) + \cos\theta - \cos(-t+\theta), e^{i(\theta-t)})$$

$$\xrightarrow{\phi_{-t}^X} (x_1 - 3\sin\theta + 2\sin(t+\theta) + \sin(-t+\theta) + \sin(-t+\theta) - \sin(\theta+t-t), x_2 + 2\cos\theta - 2\cos(t+\theta) - \cos(-t+\theta) - \cos(-t+\theta) + \cos(-t+\theta+t))$$

$$= (x_1 - 4\sin\theta(1 - \cos(t)), x_2 + 4\cos\theta(1 - \cos(t)), e^{i\theta})$$

By exercise 3.b

$[X, Y]$

\parallel

$$\gamma(t) = (x_1, x_2, e^{i\theta}) + t^2 (-2\sin\theta, 2\cos\theta, 0) + O(t^3)$$

Interpretation: think about ☺ !